

# 1. Deligne - Mumford compactification

$(\Sigma_g, j)$  : closed Riem surface with genus  $g$ .

$\Theta = \Theta(p_1, \dots, p_l)$  : an ordered set of  $l$ -many pts on  $\Sigma_g$

$(\Sigma_g, j, \Theta)$  called a pointed Riem surface

distinct  $\nwarrow$  marked pts and view it as  $l$ -tuple  $\in \Sigma_g^l$

Define  $(\Sigma_{g_1}, j_1, \Theta_1) \sim (\Sigma_{g_2}, j_2, \Theta_2)$  iff  $\exists$  a biholomorphism  $\varphi$

from  $(\Sigma_{g_1}, j_1)$  to  $(\Sigma_{g_2}, j_2)$  (so  $g_1 = g_2$ ) and  $\varphi(\Theta_1) = \Theta_2$  with respect

to ordering.

$$\Rightarrow M_{g,l} = \{(\Sigma_g, j, \Theta)\} / \sim$$

$\nwarrow$  this already fixes  $\Sigma_g$  topologically  
 $\uparrow$  # of marked pts

Remark One can equip some geometric str on  $M_{g,l}$ .

Recall a groupoid is a cat where all morphisms are isomorphisms

i.e. space of orbits  $\nearrow$  invertible

Then Grothendieck says any moduli = an orbit space under the action of a groupoid.

Rewrite  $\mathcal{I}(\Sigma_g) = \{\text{all cpx strs on } \Sigma_g\}$

$\text{Diff}(\Sigma_g) = \{\text{all differs on } \Sigma_g\} \Rightarrow \varphi^*j$  defines an

$\forall g \in \text{Diff}(\Sigma_g)$

element in  $\mathcal{I}(\Sigma_g)$   
 $(\varphi^*j)_x := (d\varphi)_x^{-1} \cdot j_{\varphi(x)} \cdot (d\varphi)_x$   
 $\stackrel{(d\varphi)_x}{\approx}$

Then to take care of the flexibility of  $j$  in  $(\Sigma_g, j)$ , one

can consider quotient space  $\mathcal{T}(\Sigma_g)/\text{Diff}(\Sigma_g)$  (usually defined by  $M_g$ , the moduli space of cpx str on  $\Sigma_g$ )

$$\text{Quotient} \simeq \begin{cases} \text{orbit 1} & j_1 \xrightarrow{\varphi^*} j_2 \xrightarrow{\varphi^*} \dots \\ \text{orbit 2} & j_2 \xrightarrow{\varphi^*} j_3 \xrightarrow{\varphi^*} \dots \\ \dots & \dots \end{cases}$$

This confirms what Grothendieck's statement above

In the same way, one can add ordered pts  $\Theta$  and consider

$$(\mathcal{T}(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \leftarrow \text{acting by diagonal.}$$

- It is  $\subseteq \mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$  for any fixed  $\Theta$ .

where  $\text{Diff}(\Sigma_g, \Theta) \subseteq \text{Diff}(\Sigma_g)$  that fixes  $\Theta$  (stabilizer of  $\text{Diff}(\Sigma_g)$  w.r.t  $\Theta$ ).

- It can also be identified with  $M_{g,l}$ :  $(\Sigma_g, j) \xrightarrow{\varphi} (\Sigma_g, j')$  iff  $d\varphi \cdot j = j' \cdot d\varphi$  iff  $j' = d\varphi \cdot j \cdot (d\varphi)^{-1}$ .

In other words,

$$M_{g,l} \simeq (\mathcal{T}(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \simeq \mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta) //$$

Introducing notation  $\chi(\Sigma_g \setminus \Theta)$  = Euler char of punctured  $\Sigma_g$   
 $= 2 - 2g - l$ .

FACT (Prop 7.9 in [Lur]) When  $\chi(\Sigma_g \setminus \Theta) < 0$ , for each  $j \in \mathcal{T}(\Sigma_g)$

It is a Lie group as another fact  $\rightarrow \text{Aut}(\Sigma_g, j, \Theta) = \text{stabilizer of } \text{Diff}(\Sigma_g, \Theta) \text{ is finite w.r.t } j$