

can consider quotient space $\mathcal{T}(\Sigma_g)/\text{Diff}(\Sigma_g)$ (usually defined by M_g , the moduli space of cpx str on Σ_g)

$$\text{Quotient} \simeq \left\{ \begin{array}{l} \text{orbit 1} \\ \text{orbit 2} \\ \dots \end{array} \right. \begin{array}{l} j_1 \xrightarrow{\varphi^*} j_2 \xrightarrow{\varphi^*} \dots \\ j_2 \xrightarrow{\varphi^*} j_3 \xrightarrow{\varphi^*} \dots \\ \dots \end{array}$$

This confirms what Grothendieck's statement above

In the same way, one can add ordered pts Θ and consider

$$(\mathcal{T}(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \leftarrow \text{acting by diagonal.}$$

- It is $\subseteq \mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$ for any fixed Θ .

where $\text{Diff}(\Sigma_g, \Theta) \subseteq \text{Diff}(\Sigma_g)$ that fixes Θ (stabilizer of $\text{Diff}(\Sigma_g)$ w.r.t Θ).

- It can also be identified with $M_{g,l}$: $(\Sigma_g, j) \xrightarrow{\varphi} (\Sigma_g, j')$ iff $d\varphi \cdot j = j' \cdot d\varphi$ iff $j' = d\varphi \cdot j \cdot (d\varphi)^{-1}$.

In other words,

$$M_{g,l} \simeq (\mathcal{T}(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \simeq \mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta) //$$

Introducing notation $\chi(\Sigma_g \setminus \Theta)$ = Euler char of punctured Σ_g
 $= 2 - 2g - l$.

FACS (Prop 7.9 in [Lur]) When $\chi(\Sigma_g \setminus \Theta) < 0$, for each $j \in \mathcal{T}(\Sigma_g)$

It is a Lie group as another fact $\rightarrow \text{Aut}(\Sigma_g, j, \Theta) = \text{stabilizer of } \text{Diff}(\Sigma_g, \Theta) \text{ is finite w.r.t } j$

Riemann-Roch.

$$\Rightarrow \dim_{\mathbb{R}} M_{g,l} = 6g - 6 + 2l$$

(The intermediate step is in general, $\dim \text{Aut}(\Sigma_g, \theta) - \dim M_{g,l} = 3\alpha(\Sigma) - 2l$.)

Ex $\chi(\Sigma_g|\theta) \geq 0 \Leftrightarrow 2-2g-l \geq 0$ where both $g, l \geq 0$

$$\Leftrightarrow (g, l) = (0, 0), (1, 0), (0, 1), (g \geq 2)$$

$\chi(\Sigma_0|\theta)=2 \quad \chi(\Sigma_1|\theta)=0 \quad \chi(\Sigma_0|\theta)=1 \quad \chi(\Sigma_g|\theta)=0$

Usually, we call (Σ_g, θ) stable if $\chi(\Sigma_g|\theta) < 0$. Hence

- being stable is common
- being stable $\Rightarrow \text{Aut}(\Sigma_g, \theta)$ is a finite set.

for $g=0$
case, being
stable \Leftrightarrow
 $l \geq 3$

Link (famous name/term)

$$\text{Diff}_0(\Sigma_g, \theta) \subseteq \text{Diff}(\Sigma_g, \theta) \quad \text{identity component}$$

$$\Rightarrow M(\Sigma_g, \theta) := \text{Diff}(\Sigma_g, \theta) / \text{Diff}_0(\Sigma_g, \theta) \quad \text{mapping class group}$$

$$\Rightarrow T(\Sigma_g, \theta) := \mathcal{T}(\Sigma_g) / \text{Diff}_0(\Sigma_g, \theta) \quad \text{Teichmüller space.}$$

(One can define the $T(\Sigma_g)$ in the same way without θ .)

Then $T(\Sigma_g, \theta) / M(\Sigma_g, \theta) \stackrel{\text{check the group action descends}}{=} \mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \theta) = M_{g,l}$.

\uparrow a surjective map as a classical result
 \uparrow usually a discrete group
 \uparrow usually not a manifold but an orbifold

In general, $M_{g,l}$ is a finite-dim' orbifold.
(locally modelled by $\mathbb{R}^{\dim}/\text{group}$)

One way to compactify $M_{g,l}$ is called the Deligne-Mumford compactification. $\overline{M}_{g,l}$ ($= M_{g,l} \cup$ "singular curves").

Def A nodal Riem surface with $l \geq 0$ marked pts and $N \geq 0$ nodes is a tuple (S, j, Θ, Δ) :

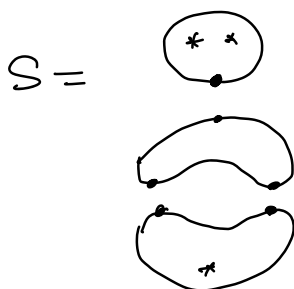
- A closed but not nec connected Riem surface (S, j)
- An ordered set of l pts $\Theta \subset S$
- An unordered set of $2N$ pts $\Delta \subset S \setminus \Theta$ equipped with involution $\sigma: \Delta \rightarrow \Delta$. Each pair $\{z, \sigma(z)\}$ for $z \in \Delta$ is (often referred as z^+, z^-) referred to as a node

Here we use S instead of Σ to indicate S is not nec connected.

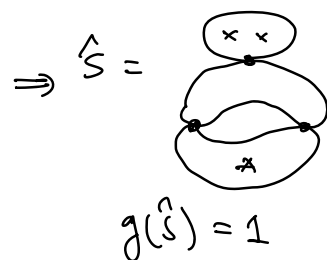
$\Rightarrow \hat{S} =$ closed surface by performing connected sums on S at each node $\{z^+, z^-\} \subset \Delta$.
All

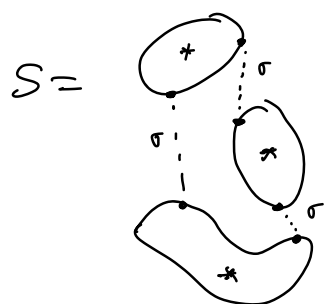
(Then $z^+ \sim z^-$ in \hat{S} as a "double pt".) the easiest singular pt

e.g.



3 connected components
 $l = 3$
 $N = 3$ (3 pairs)
(Each connected component has genus 0)





3 connected components

$$l = 3$$

$$N = 3 \quad (3 \text{ parts})$$

$$\Rightarrow \hat{S} =$$



Terms

(1) (S, j, θ, Δ) is connected if \hat{S} is connected.

(2) In the connected case, $g(\hat{S})$ is called the arithmetic genus of (S, j, θ, Δ)

(3) (S, j, θ, Δ) is stable if each connected component of $S \setminus (\theta \cup \Delta)$ has negative Euler char.

(4) $(S, j, \theta, \Delta) \sim (S', j', \theta', \Delta')$ iff \exists bihol $\varphi: (S, j) \rightarrow (S', j')$ taking θ to θ' w.r.t order and taking Δ to Δ' s.t. nodes mapped to nodes.

e.g. Every element in $M_{g,l}$ is a nodal Riem surface that has $N=0$, connected, and arithmetic genus g .
(so $\Delta = \emptyset$)

Note that so far this is just a notation, no properties proved yet.

Def $\overline{M}_{g,l} = \{ \text{equ classes of stable } \overset{\text{connected}}{\text{nodal Riem surface}} \text{ with } l \text{ marked pts and arithmetic genus } g \}$

assume $2g + l \geq 3$
(stable condition)

$$(\text{so } M_{g,l} \subset \overline{M}_{g,l}).$$

Example $g=0, l=3: M_{g,l} = M_{0,3} \simeq \{pt\}$

since for $(S^2, j, (p_1, p_2, p_3)) \xrightarrow{\exists!} (S^2, j, (0, 1, \infty))$

$$\Rightarrow \overline{M}_{0,3} = M_{0,3}.$$

dim $M_{0,4}$
 $\leftarrow = 6 \cdot 0 - 6 + 2 \cdot 4 = 2$

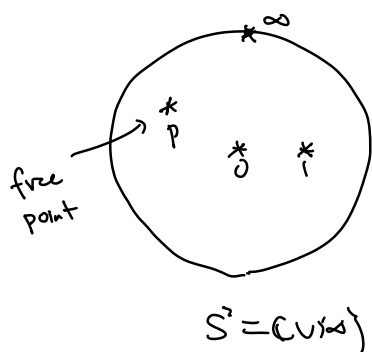
Example $g=0, l=4: M_{g,l} = M_{0,4} \simeq S^2 \setminus \{0, 1, \infty\}.$

$$\{[(S^2, j, (p_1, p_2, p_3, p_4))]\} = \{[(S^2, j, (0, 1, \infty, p))]\}$$

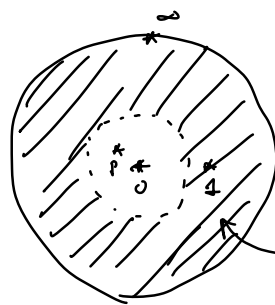
where $p \neq 0, 1, \infty$.

* Note that $S^2 \setminus \{0, 1, \infty\}$ is not cpt and a naive way to compactify it is by adding "3 pts" back and get S^2 .

A standard argument to find out these extra pts is by a limit argument:

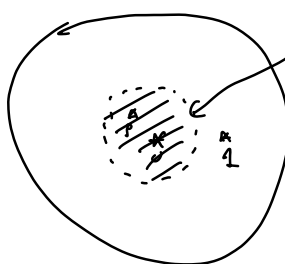


Let $p \rightarrow 0$
 \rightarrow
 investigate
 local charts
 (depending on p)



$$U = \{z \in S^2 \mid |z| \geq |1| \}$$

$\mathbb{C} \cup \{\infty\}$



$$V = \{z \in \mathbb{C} \mid |z| < 2\}$$

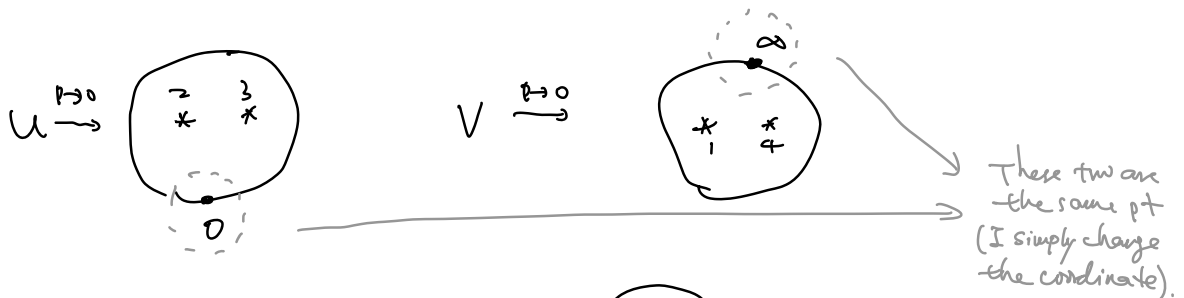
- $U \cap V = \emptyset$.

- $\{0, p\} \notin U$ and $\{1, \infty\} \in U$

when $p \rightarrow 0$, $0, p$ coincide (at 0)

- coordinate in V is $(\frac{0}{p}, \frac{1}{p}, \frac{\infty}{p}, \frac{p}{p}) = (0, \frac{1}{p}, \infty, 1)$

In V , $0, 1$ never coincide, so $\frac{1}{p}, \infty$ coincide (at ∞)
when $p \rightarrow 0$



$\Rightarrow p \rightarrow 0$ the limit is

Note that there are three ways to have such "2-spheres breaking"
so $\overline{M}_{0,4} = M_{0,4} \cup \{3 \text{ pts}\} (\cong S^1)$.

Example $g=0, l=5$

$$M_{0,5} = \{[(S^2, j, (0, 1, \infty, p, q))] \mid p \neq 0, 1, \infty, q \neq 0, 1, \infty, p \neq q\}$$

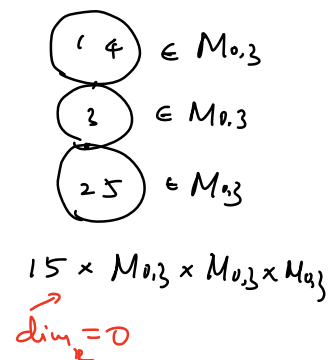
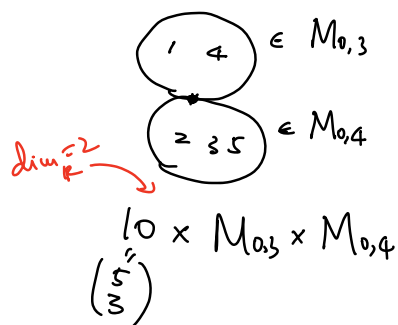
$\dim_{\mathbb{R}} M_{0,5}$
 $= 6 \cdot 0 - 6 + 2 \cdot 5 = 4$

$$\simeq (S^2 \setminus \{0, 1, \infty\}) \times (S^2 \setminus \{0, 1, \infty\}) - \underbrace{\Delta}_{\text{previous product}} \simeq S^1 \setminus \{0, 1, \infty\}$$

$$\overline{M}_{0,5} = M_{0,5} \cup \left(\begin{smallmatrix} \text{codim}_{\mathbb{R}} 2 \\ \text{stratum} \end{smallmatrix} \right) \cup \left(\begin{smallmatrix} \text{codim}_{\mathbb{R}} 4 \\ \text{stratum} \end{smallmatrix} \right)$$

\updownarrow
 1 pairs of
 marked pts coincide

\updownarrow
 2 pairs of
 marked pts coincide



One can check that $\overline{M}_{0,5}$ is not a wfd.

$$\begin{aligned}
 (\text{In fact, } \overline{M}_{0,5} = S^2 \times S^2 - 7 \times (S^3 \setminus \{0, 1, \infty\}) - 9 \text{ pts.} \\
 + 10 \times (S^3 \setminus \{0, 1, \infty\}) + 15 \text{ pts.})
 \end{aligned}$$

Remark One can use graph to describe elements in $\overline{M}_{g,n} \setminus M_{g,n}$.

Vertices \longleftrightarrow component in (S, j, i)

edges \longleftrightarrow nodal pts in \mathcal{E} .

