

can consider quotient space  $J(\Sigma_g)/\text{Diff}(\Sigma_g)$  (usually defined by  $M_g$ , the moduli space of cpx str on  $\Sigma_g$ )

$$\text{Quotient} \simeq \left\{ \begin{array}{l} \text{orbit 1} \\ \text{orbit 2} \\ \dots \end{array} \right. \quad \begin{array}{c} j_1 \xrightarrow{\varphi^*} p^* j_1 \xrightarrow{\dots} \\ j_2 \xrightarrow{\varphi^*} p^* j_2 \xrightarrow{\dots} \end{array}$$

This confirms what Gromov's statement above

In the same way, one can add ordered pts  $\Theta$  and consider

$$(J(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \leftarrow \text{acting by diagonal.}$$

- It is  $\simeq J(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$  for any fixed  $\Theta$ .

where  $\text{Diff}(\Sigma_g, \Theta) \leq \text{Diff}(\Sigma_g)$  that fixes  $\Theta$  (stabilizer of  $\text{Diff}(\Sigma_g)$  w.r.t  $\Theta$ )

- It can also be identified with  $M_{g,l}$ :  $(\Sigma_g, j) \xrightarrow{\varphi} (\Sigma_g, j')$  if  $d\varphi \cdot j = j' \cdot d\varphi$  iff  $j' = d\varphi \cdot j \cdot (\varphi)^{-1}$ .

In other words,

$$M_{g,l} \simeq (J(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \simeq J(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$$

Introducing notation  $\chi(\Sigma_g | \Theta)$  = Euler char of punctured  $\Sigma_g$   
 $= 2 - 2g - l$ .

Facts (Prop 7.9 in [Cew]) When  $\chi(\Sigma_g | \Theta) < 0$ , for each  $j \in J(\Sigma_g)$

*It is a Lie group as another fact*  $\rightarrow \text{Act}(\Sigma_g, j, \Theta) = \text{stabilizer of } \text{Diff}(\Sigma_g, \Theta) \text{ w.r.t } j$  is finite

Riemann-Roch.

$$\Rightarrow \dim_{\mathbb{R}} M_{g,l} = 6g - 6 + 2l$$

(The intermediate step is in general,  $\dim \text{Aut}(\Sigma_g, \Theta) - \dim M_{g,l}$   
 $= 2\chi(\Sigma_g) - 2l$ .)

Ex  $\chi(\Sigma_g | \Theta) \geq 0 \Leftrightarrow 2 - 2g - l \geq 0$  where both  $g, l \geq 0$

$$\Leftrightarrow (g, l) = (0, 0), (1, 0), (0, 1), (0, 2)$$

$$\chi(\Sigma_0 | \Theta) = 2 \quad \chi(\Sigma_1 | \Theta) = 0 \quad \chi(\Sigma_2 | \Theta) = 1 \quad \chi(\Sigma_3 | \Theta) = 0$$

Usually, we call  $(\Sigma_g, \Theta)$  stable if  $\chi(\Sigma_g | \Theta) < 0$ . Hence

for  $g=0$   
 case being  
 stable  $\Leftrightarrow$   
 $l \geq 3$

- being stable is common
- being stable  $\Rightarrow \text{Aut}(\Sigma_g, \Theta)$  is a finite set.

Rank (famous name/term)

$\text{Diff}_0(\Sigma_g, \Theta) \leq \text{Diff}(\Sigma_g, \Theta)$  identity component

$\Rightarrow M(\Sigma_g, \Theta) := \text{Diff}(\Sigma_g, \Theta) / \text{Diff}_0(\Sigma_g, \Theta)$  mapping class group

$\Rightarrow T(\Sigma_g, \Theta) := \mathcal{T}(\Sigma_g) / \text{Diff}_0(\Sigma_g, \Theta)$  Teichmüller space.

(One can define the  $T(\Sigma_g)$  in the same way without  $\Theta$ .)

Then  $T(\Sigma_g, \Theta) / M(\Sigma_g, \Theta) \xrightarrow{\text{check the group action descents}}$   $\mathcal{T}(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta) \cong M_{g,l}$ .

$\uparrow$  a smooth manifold  
 as a classical result

$\uparrow$  usually a discrete group

$\uparrow$  usually not a manifold but an orbifold

In general,  $M_{g,l}$  is a finite-dim'l orbifold.  
 (usually modelled by  $\mathbb{R}^{\dim \text{group}}$ )

One way to compactify  $M_{g,l}$  is called the Deligne-Mumford compactification.  $\overline{M}_{g,l}$  ( $= M_{g,l} \cup \text{"singular curves"}$ ).

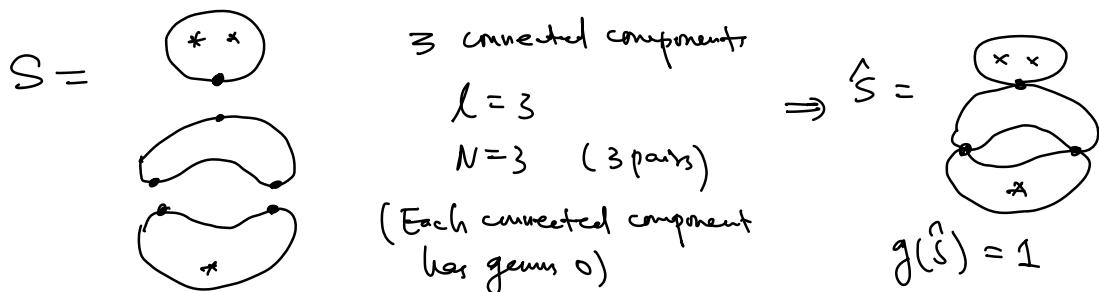
Def A nodal Riemann surface with  $l \geq 0$  marked pts and  $N \geq 0$  nodes is a tuple  $(S, j, \Theta, \Delta)$ :

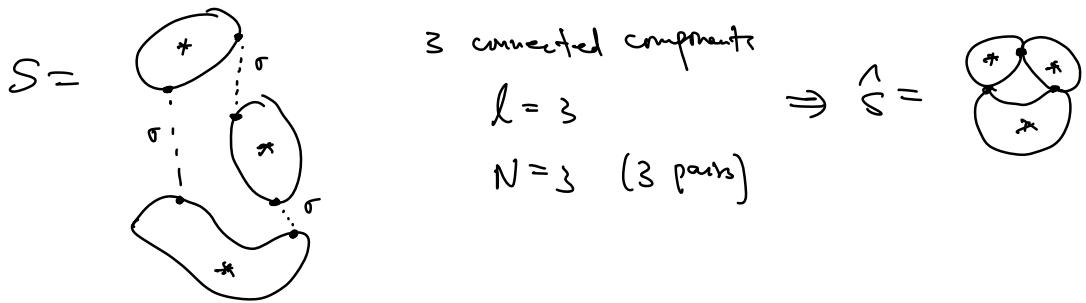
- A closed but not nec connected Riemann surface  $(S, j)$
  - An ordered set of  $l$  pts  $\Theta \subset S$
  - An unordered set of  $2N$  pts  $\Delta \subset S \setminus \Theta$  equipped with involution  $\sigma: \Delta \rightarrow \Delta$ . Each pair  $\{z, \sigma(z)\}$  for  $z \in \Delta$  is referred to as a node
- Here we use  $S$  instead of  $\Sigma$  to indicate  $S$  is not nec connected.

$\Rightarrow \hat{S} = \text{closed surface by performing connected sums on } S \text{ at each node } \{z^+, z^-\} \subset \Delta.$

(Then  $z^+ \sim z^-$  in  $\hat{S}$  as a "double pt".)

e.g.





## Terms

- (1)  $(S, j, \Theta, \Delta)$  is connected if  $\hat{S}$  is connected.
  - (2) In the connected case,  $g(\hat{S})$  is called the arithmetic genus of  $(S, j, \Theta, \Delta)$ .
  - (3)  $(S, j, \Theta, \Delta)$  is stable if each connected component of  $S \setminus (\Theta \cup \Delta)$  has negative Euler char.
  - (4)  $(S, j, \Theta, \Delta) \sim (S', j', \Theta', \Delta')$  iff  $\exists$  bihol  $\varphi : (S, j) \rightarrow (S', j')$  taking  $\Theta$  to  $\Theta'$  w.r.t order and taking  $\Delta$  to  $\Delta$  s.t. nodes mapped to nodes.

e.g. Every element in  $M_g, l$  is a nodal Riemann surface that has  $N = 0$ , connected, and arithmetic genus  $g$ .

(so  $\Delta = \emptyset$ )

Note that so far this is just a definition, no properties proved yet.

Def  $\overline{M}_{g,l} = \{ \text{equ. classes of stable, connected nodal Riemann surfaces with } l \text{ marked pts and arithmetic genus } g \}$

$(\hookrightarrow M_{g,l} \subset \overline{M}_{g,l})$ .

Example  $g=0, l=3: M_{g,l} = M_{0,3} \cong \{3 \text{ pts}\}$

since for  $(S^2, j, (p_1, p_2, p_3)) \xrightarrow{\exists!} (S^2, j, (0, 1, \infty))$

$$\Rightarrow \overline{M}_{0,3} = M_{0,3}.$$

$$\leftarrow \begin{matrix} \text{dim } M_{0,4} \\ = 6 \cdot 0 - 6 + 2 \cdot 4 = 2 \end{matrix}$$

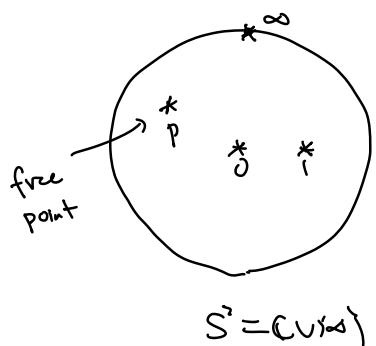
Example  $g=0, l=4: M_{g,l} = M_{0,4} \cong S^2 \setminus \{0, 1, \infty\}$ .

$$\{[(S^2, j, (p_1, p_2, p_3, p_4))] \} = \{[(S^2, j, (0, 1, \infty, p))] \}$$

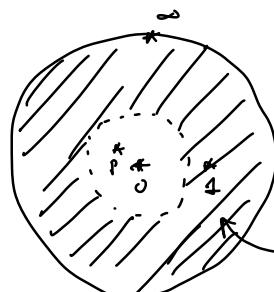
when  $p \neq 0, 1, \infty$ .

\* Note that  $S^2 \setminus \{0, 1, \infty\}$  is not cpt and a naive way to compactify it is by adding "3 pts" back and get  $S^2$ .

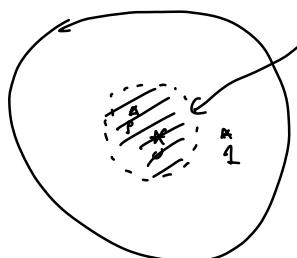
A standard argument to find out these extra pts is by a limit argument:



Let  $p \rightarrow 0$   
 investigate local charts  
 (depending on  $p$ )



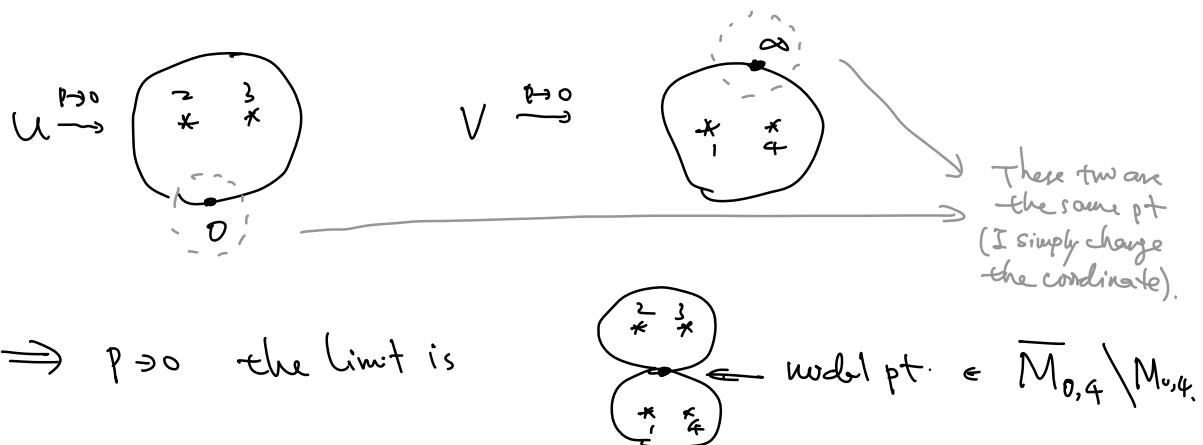
$$U = \{z \in S^2 \mid |z| > \epsilon(p)\} \cup \{\infty\}$$



$$V = \{z \in \mathbb{C} \mid |z| < 1\}$$

- $U \cap V = \emptyset$ .
- $\{0, p\} \not\subset U$  and  $\{1, \infty\} \subset U$
- when  $p \rightarrow 0$ ,  $0, p$  coincide (at 0)
- coordinate in  $V$  is  $(\gamma_p, \gamma_p, \gamma_p, \frac{p}{p}) = (0, \frac{1}{p}, \infty, 1)$

In  $V$ ,  $0, 1$  never coincide, so  $\frac{1}{p}, \infty$  coincide (at  $\infty$ )  
 when  $p \rightarrow 0$



Note that there are three ways to have such "z-spheres breaking"  
 $\Rightarrow \overline{M}_{0,4} = M_{0,4} \cup \{3\text{pts}\} (\cong S^2)$ .

Example  $g=0, l=5$

$$M_{0,5} = \left\{ \left[ (S^2, j, (0, 1, \infty, p, q)) \right] \mid \begin{array}{l} p \neq 0, 1, \infty, q \neq 0, 1, \infty \\ p \neq q \end{array} \right\}$$

dim<sub>Q</sub> M<sub>0,5</sub>  
 $= 6 \cdot 0 - 6 + 2 \cdot 5 = 4$

$$\simeq (S^2 \setminus \{0, 1, \infty\}) \times (S^2 \setminus \{0, 1, \infty\}) - \underbrace{\Delta}_{\text{of the previous product}} \simeq S^2 \setminus \{0, 1, \infty\}$$

$$\overline{M}_{0,5} = M_{0,5} \cup \left( \begin{array}{c} \text{codim}_{\mathbb{R}} 2 \\ \text{statum} \end{array} \right) \cup \left( \begin{array}{c} \text{codim}_{\mathbb{R}} 4 \\ \text{statum} \end{array} \right)$$

↓                                    ↓

1 pairs of  
marked pts coincide                2 pairs of  
marked pts coincide

$\in M_{0,3}$

$\in M_{0,4}$

$\dim_{\mathbb{R}} = 2$

$\in M_{0,3}$

$\in M_{0,3}$

$\in M_{0,3}$

$\dim_{\mathbb{R}} = 0$

$10 \times M_{0,3} \times M_{0,4}$   
 $\binom{5}{3}$                                $15 \times M_{0,3} \times M_{0,3} \times M_{0,3}$

One can check that  $\overline{M}_{0,5}$  is not a mfld.

(Infact,  $\overline{M}_{0,5} = S^2 \times S^2 - 7 \times (S^3 \setminus \{0, 1, \infty\}) - 9$  pts.  
 $+ 10 \times (S^3 \setminus \{0, 1, \infty\}) + 15$  pts.)

Rank One can use graph to describe elements in  $\overline{M}_{g,n} \setminus M_{g,l}$ .

Vertices  $\longleftrightarrow$  component in  $(S, j)$   
edges  $\longleftrightarrow$  nodal pts in  $\mathfrak{F}$ .

