

Pick $\{J_+\}_{t \in [-1, 1]} \sim \mathbb{R}/2$, define a metric on $1M$ by

$$\langle \xi, \eta \rangle := \int_{S^1} \omega_{J_+(t)}(\xi(t), \eta(t)) dt$$

for any $\xi, \eta \in T_{\gamma} 1M (\cong \Gamma(\gamma^* TM) = \{ \text{vector fields } \}$ along $\gamma(t)$)

then by computation,

$$\nabla_{\frac{\partial}{\partial t}} A_H(\gamma) = J_+(\gamma - X_{H_+}(\gamma)) \Rightarrow \text{the negative flowline } u: \mathbb{R} \times S^1 \rightarrow M \text{ is}$$

$$\partial_s u = -\nabla A_H(u(s, t)) = J_+(u(s, t)) (\partial_t u - X_{H_+}(u(s, t))) \quad (*)$$

which is a perturbed version of J-hol curve!

Again, one needs to study the moduli space

$$M(\gamma, \gamma') = \{ u: \mathbb{R} \times S^1 \rightarrow M \mid (*) \}$$

☺: experience of J-hol curves can be borrowed

☹: the domain $\mathbb{R} \times S^1$ is non-cpt! \leftarrow study asymptotic behavior of such solutions

Assume things worked out, then

$$\partial \gamma = \sum_{\substack{\gamma' \\ \text{ind diff} = 1}} M(\gamma, \gamma') / \hbar \cdot \gamma' \quad \text{is well-defined}$$

and $\partial \cdot \partial = 0$

$$\Rightarrow CF_*(M, \omega, J, H) = \mathbb{Z}_2 \langle \gamma \mid \deg(\gamma) = * \rangle \hookrightarrow \partial$$

$$\Rightarrow HF_*(M, \omega, J, H) \text{ is well-defined.}$$

Thm (M, ω) symplectic, then $HF_*(M, \omega, J, H) \cong H_*(M; \mathbb{Z}_2)$

\Rightarrow Arnold conj b/c

$$\begin{aligned} \# \text{Fix}(\varphi_H^1) &\geq \# \{ \text{closed orbits of } X_H \}^{\text{contractible}} \geq \text{total rank of } HF_* \\ &= \sum b_i(M; \mathbb{Z}_2) \end{aligned}$$

Remark There are many other versions of Floer homologies, with generators admitting different dyn/gen meanings.

Remark Recall that in Morse theory, the key result is not the well-definedness of Morse homology $HM_*(X, f)$, instead it's the iso: $HM_*(X, f) \cong H_*(X; \mathbb{Z}_2)$. //

Remark Working over (M, ω, J) (instead of (M, J)) allows us to define/consider "metric" and "energy" of a J -hol curve.
(on XM)

2. Contact geometry

(X^{2n-1}, \mathfrak{f}) \mathfrak{f} a hyperplane field and called a (co-oriented) contact structure if $\exists \alpha \in \mathcal{U}^1(X)$ s.t.

$$\ker \alpha = \mathfrak{f} \quad \text{and} \quad \alpha \wedge \underbrace{d\alpha \wedge \dots \wedge d\alpha}_{n-1} \text{ is a volume form}$$

$\nwarrow \alpha$ is called a contact form

Ex. $(\mathbb{R}^{2n-1}, \mathfrak{f}_{\text{std}})$ $\mathfrak{f}_{\text{std}} = \ker \left(dz - \sum_{i=1}^{n-1} y_i dx_i \right)$
 \uparrow
 $x_1, y_1, \dots, x_{n-1}, y_{n-1}, z$

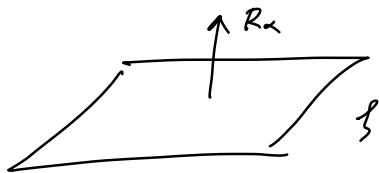
Link All are encouraged to draw $(\mathbb{R}^3, \mathfrak{f}_{\text{std}})$ by hand.

Link The data of contact forms is auxiliary. If α is a contact form of \mathfrak{f} , then $e^f \alpha$ is also a contact form of \mathfrak{f} .

Any contact manifold (X, \mathfrak{f}) admits a dyn system itself: fix α s.t. $\mathfrak{f} = \ker \alpha$, one can solve a vector field R_α from

$$d\alpha(R_\alpha, -) = 0 \quad \text{and} \quad \alpha(R_\alpha) = 1.$$

$\nwarrow d\alpha|_{\mathfrak{f}}$ is non-deg.
 in a unique way. It is called the Reeb vector field of α .



$\varphi_{R_\alpha}^+$ the Reeb flow (w.r.t. α)

Again, one should be interested in closed orbits of $\varphi_{R\alpha}^+$.

Conjecture (Weinstein) For any closed contact mfd (X, β) , for any fixed α s.t. $\beta = \ker \alpha$, there \exists at least 1 closed orbit of $\varphi_{R\alpha}^+$.

Remark. Different from Arnold conj, we do not restrict to time-one.

Remark. Conclusion is wrong if (X, β) is non-cpt; $R\alpha$ in

$(\mathbb{R}^3, \beta_{std})$ is $\partial \mathbb{D}$, so $\varphi_{R\alpha}^+(\mathbb{D}) = \mathbb{D} + t$.

Remark In dim 3, this has been proved by Taubes.

Other dims have individual results, but in general it is controversial.

Ex. (M^4, ω) symplectic mfd, $H: M \rightarrow \mathbb{R}$ autonomous Ham. func. //

Consider the level set $H^{-1}(c) \subset M$, where c is regular.

- $H^{-1}(c)$ is a mfd of dim 3.
- flowlines of X_H stay inside $H^{-1}(c)$ $\leftarrow dH(X_H) = -\omega(X_H, X_H) = 0$

Suppose near $H^{-1}(c)$, \exists a vector field $Y \lrcorner H^{-1}(c)$ and $L_Y \omega = \omega$ (*)

$$(*) \Leftrightarrow d \underbrace{L_Y \omega}_{=: \lambda} + \underbrace{L_Y \omega}_{=: \lambda} = \omega$$

$$\Leftrightarrow \exists \text{ 1-form } \lambda \text{ (near } H^{-1}(c) \text{) s.t. } \omega = d\lambda.$$

↑
called a Liouville form

Then one can check that $\left(H^{-1}(c), \underbrace{\lambda|_{H^{-1}(c)}}_{\text{dim 2 hyperplane field}} \right)$ is a contact wfd. Moreover,

$$R_\lambda = \frac{X_H}{dH(r)} \leftarrow \text{non-zero b/c } r \notin H^{-1}(c)$$

Verify:

$$\begin{aligned} \lambda(R_\lambda) &= (r\omega) \left(\frac{X_H}{-dH(r)} \right) \quad \text{no minus sign} \\ &= \omega(r, \frac{X_H}{dH(r)}) \\ &= -\frac{1}{dH(r)} \omega(X_H, r) = 1. \end{aligned}$$

$$\underbrace{\iota_{X_H} d\lambda}_{\lambda|_{H^{-1}(c)}} = \iota_{X_H} \omega|_{H^{-1}(c)} = \omega|_{H^{-1}(c)}(X_H, \underbrace{-}_{\substack{\uparrow \\ \text{input from } H^{-1}(c)}}) = -dH(-) = 0$$

Then Tanabe's result implies that \exists a ^{closed characteristic} orbit of the Ham flow X_H (not nec at $t=1$) on $H^{-1}(c)$!

Remark Weinstein, Rabinowitz proved this \exists -result in 1978.
for any dim. (Of course, not every cpt contact str can be viewed as the level set of a Ham system).

Example above gives a hint that symplectic geometry is related with contact geometry in a natural way.

Def A Liouville domain is a symplectic manifold with boundary (W, ω)
 s.t. $\exists \gamma$ a v.f. on \underline{W} , $\uparrow \partial W$, and $\underline{L_\gamma \omega = \omega}$.
 ω exponentially grows or shrinks.

By discussion above, $(\partial W, \mathcal{F} = \ker(L_\gamma \omega)|_{\partial W})$ is a contact manifold.

Ex. $(W, \omega) = (\{\sum_{i=1}^n x_i^2 + y_i^2 \leq 1\}, \omega_{std}|_{\{ \dots \}})$ is a Liouville domain
 $(\mathbb{R}^{2n}, \omega_{std})$

and $\gamma = \frac{1}{2} \sum_{i=1}^n (x_i \partial_{x_i} + y_i \partial_{y_i})$ radial vector field.

$\Rightarrow (\partial W, \mathcal{F}) = (S^{2n-1}, \mathcal{F}_{std})$ contact manifold with the standard contact structure.

Observation: $\lambda = L_\gamma \omega$ is fixed but $\lambda|_{\partial W}$ varies, depending on ∂W .



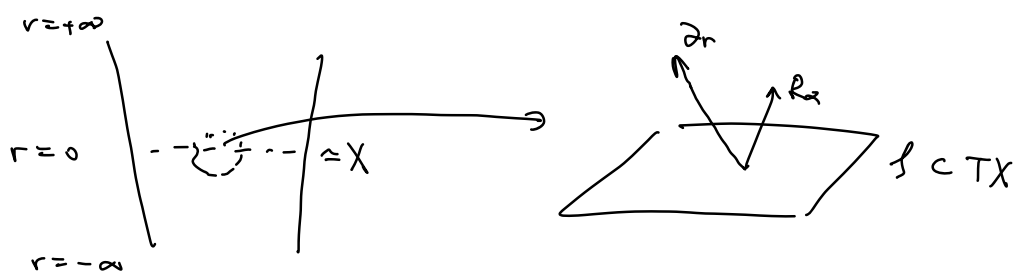
One can also fix S^{2n-1} but deform \mathcal{F}_{std} to \mathcal{F}_+ (through contact structures),
 via deforming γ , then Gray's stability theorem (Thm 1.6 in [Wen])

shows that $\exists \varphi_+ : S^{2n-1} \hookrightarrow S^{2n-1}$ s.t. $(\varphi_+)_* \mathcal{F}_+ = \mathcal{F}_{std}$.
 \uparrow
 contactomorphism

//

From contact wfol (X, ζ) , one can build a symp wfol via "symplectization": fix α s.t. $\zeta = \ker \alpha$, then

$$M := \mathbb{R} \times_r X \quad \text{and} \quad \omega = d(e^r \alpha) \quad e^r dr \wedge \alpha$$



Remark Sometimes papers use another convention $M = [0, \infty) \times X$ and $\omega = dr \wedge \alpha$ and $X \subseteq \{1\} \times X$.

How does a J-hol curve look like in a symplectization?

Pick J on $\mathbb{R} \times X$ s.t.

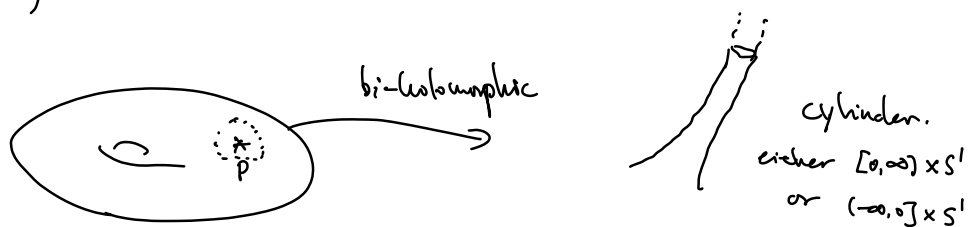
- J is invariant under translation in r , i.e. $J(a, x) = J(a+r, x)$
- $J(\partial_r) = R_x$ and $J(R_x) = -\partial_r$
- Restricted at ζ , $\omega(\cdot, J\cdot)$ is a metric (on bundle $\zeta \downarrow X$)

Prop $u: (\Sigma, j) \rightarrow (\mathbb{R} \times X, \omega)$ by (u_R, u_X) . if u is J-hol, then

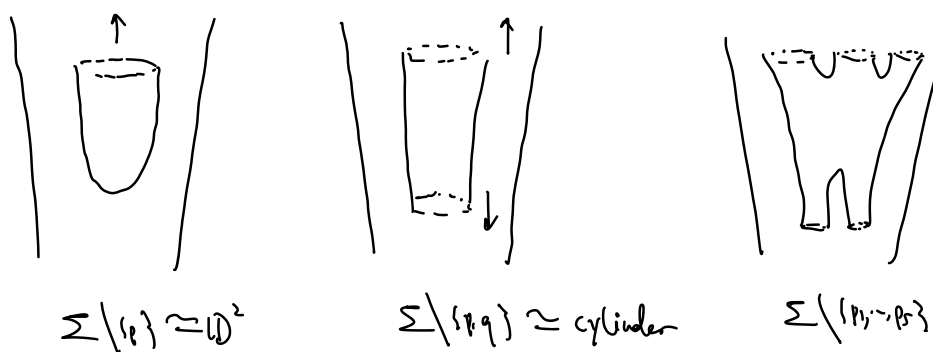
u_R is a subharmonic function ($\Delta u_R \geq 0$)

$\Rightarrow \Sigma$ can not be compact.

Modify Σ to be punctured $\dot{\Sigma} = \Sigma \setminus \{p_1, \dots, p_n\}$.



Ex



$$\lim_{s \rightarrow \infty} u(s, t) = \gamma(t) \quad \text{positive (asymptotic) end}$$

$$\lim_{s \rightarrow -\infty} u(s, t) = \gamma(t) \quad \text{negative (asymptotic) end.}$$

Thm. Under a finite energy condition, $\gamma(t)$ is a closed Reeb orbit.
(later)

Remark Recall that in (Ham) Floer homology, ∂ is also involving the study of asymptotic behavior when $s \rightarrow \pm \infty$.

Remark Similarly to symplectic geometry situation, studying the moduli space of punctured $u: (\dot{\Sigma}, j) \rightarrow (\mathbb{R} \times M, J)$ is also crucial.

↖ need to add asymp. cond.

3. Symplectic embedding

Given two Liouville domain (U, ω_U) and (V, ω_V) , a symplectic emb is an emb $\varphi: U \hookrightarrow V$ s.t. $\varphi^* \omega_V = \omega_U$.

Ex. $(\mathbb{R}^{2n}, \omega_{std}) (\simeq (\mathbb{C}^n, \omega_{std}))$

$$E(a_1, \dots, a_n) = \left\{ (z_1, \dots, z_n) \in \mathbb{C}^n \mid \frac{\pi |z_1|^2}{a_1} + \dots + \frac{\pi |z_n|^2}{a_n} \leq 1 \right\} \leftarrow \text{symplectic ellipsoid}$$

$$B(r) = E(r, \dots, r), \quad Z(R) = E(R, \infty, \dots, \infty)$$

\uparrow symplectic ball \uparrow symplectic cylinder. $\underbrace{\hspace{10em}}$ no constraint on z_2, \dots, z_n .

$$P(a_1, \dots, a_n) = \left\{ (z_1, \dots, z_n) \in \mathbb{C}^n \mid \pi |z_1|^2 \leq a_1, \dots, \pi |z_n|^2 \leq a_n \right\} \leftarrow \text{polydisk}$$

Prk. $\partial P(a_1, \dots, a_n)$ is not smooth.

Prk. All cases above admit \mathbb{T}^n -action by $(\theta_1, \dots, \theta_n) \cdot (z_1, \dots, z_n)$ defined by $(e^{i\theta_1} z_1, \dots, e^{i\theta_n} z_n) \Rightarrow$ toric domain

Finding obstructions of embedding is a central topic in symplectic geometry.

