

1. Deligne - Mumford compactification

(Σ_g, j) , closed Riemann surface with genus g .

$\Theta = \Theta(p_1, \dots, p_l)$: an ordered set of l -many pts on Σ_g
 distinct

(Σ_g, j, Θ) called a pointed Riemann surface

marked pts
and view it
as l -tuple $\in \Sigma^l \setminus \emptyset$

Define $(\Sigma_{g_1}, j_1, \Theta_1) \sim (\Sigma_{g_2}, j_2, \Theta_2)$ iff \exists a biholomorphism φ

from $(\Sigma_{g_1}, j_1) \rightarrow (\Sigma_{g_2}, j_2)$ ($\text{so } g_1 = g_2$) and $\varphi(\Theta_1) = \Theta_2$ with respect

to ordering.

$$\Rightarrow M_{g,l}^d = \{(\Sigma_g, j, \Theta)\} / \sim$$

this already fixes Σ_g holomorphically
of marked pts

Punk One can equip some geometric str on $M_{g,l}$.

Recall a groupoid is a cat where all morphisms are isomorphisms
 i.e. space of orbits $\xrightarrow{\text{invertible}}$

Then Grothendieck says any moduli = an orbit space under
 the action of a groupoid.

Rewrite $J(\Sigma_g) = \{ \text{all cpz str's on } \Sigma_g \}$

$\forall g \in \text{Diff}(\Sigma_g)$

$\text{Diff}(\Sigma_g) = \{ \text{all diff's on } \Sigma_g \} \Rightarrow \varphi^* j$ defines an

element in $J(\Sigma_g)$

$$(\varphi^* j)_x := (dp)_x^{-1} \circ j_{\varphi(x)} \circ (dp)_x$$

Then to take care of the flexibility of j in (Σ_g, j) , one

$\xrightarrow{(dp)_x \circ j_{\varphi(x)}}$

can consider quotient space $J(\Sigma_g)/\text{Diff}(\Sigma_g)$ (usually defined by M_g , the moduli space of cpx str on Σ_g)

$$\text{Quotient} \simeq \left\{ \begin{array}{l} \text{orbit 1} \\ \text{orbit 2} \\ \dots \end{array} \right. \quad \begin{array}{c} j_1 \xrightarrow{\varphi^*} p^* j_1 \xrightarrow{\dots} \\ j_2 \xrightarrow{\varphi^*} p^* j_2 \xrightarrow{\dots} \end{array}$$

This confirms what Gromov's statement above

In the same way, one can add ordered pts Θ and consider

$$(J(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \leftarrow \text{acting by diagonal.}$$

- It is $\simeq J(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$ for any fixed Θ .

where $\text{Diff}(\Sigma_g, \Theta) \leq \text{Diff}(\Sigma_g)$ that fixes Θ (stabilizer of $\text{Diff}(\Sigma_g)$ w.r.t Θ)

- It can also be identified with $M_{g,l}$: $(\Sigma_g, j) \xrightarrow{\varphi} (\Sigma_g, j')$ if $d\varphi \cdot j = j' \cdot d\varphi$ iff $j' = d\varphi \cdot j \cdot (\varphi)^{-1}$.

In other words,

$$M_{g,l} \simeq (J(\Sigma_g) \times (\Sigma_g^l \setminus \Delta)) / \text{Diff}(\Sigma_g) \simeq J(\Sigma_g) / \text{Diff}(\Sigma_g, \Theta)$$

Introducing notation $\chi(\Sigma_g | \Theta)$ = Euler char of punctured Σ_g
 $= 2 - 2g - l$.

Facts (Prop 7.9 in [Cew]) When $\chi(\Sigma_g | \Theta) < 0$, for each $j \in J(\Sigma_g)$

It is a Lie group as another fact $\rightarrow \text{Act}(\Sigma_g, j, \Theta) = \text{stabilizer of } \text{Diff}(\Sigma_g, \Theta) \text{ w.r.t } j$ is finite