

# Supplementary Material of Handling Slice Permutations Variability in Tensor Recovery

Jingjing Zheng,<sup>1,2</sup> Xiaoqin Zhang,<sup>2,\*</sup> Wenzhe Wang,<sup>2</sup> Xianta Jiang<sup>1</sup>

<sup>1</sup> Department of Computer Science, Memorial University of Newfoundland, Newfoundland and Labrador, Canada

<sup>2</sup> College of Computer Science and Artificial Intelligence, Wenzhou University, Zhejiang, China  
jjzheng233@gmail.com, zhangxiaoqinnan@gmail.com, woden3702@gmail.com, xiantaj@mun.ca

**Property 7.** (Zhang 2017) If  $P \in \mathbb{R}^{n \times n}$  is a permutation matrix, then  $P^T P = P P^T = I$ .

**Property 1.** For  $A \in \mathbb{R}^{n_1 \times n_2}$ , then nuclear norm satisfy row (or column) permutations invariance, i.e.  $\|PA\|_* = \|A\|_*$  for any permutation matrix  $P \in \mathbb{R}^{n_1 \times n_1}$  (or  $\|AP\|_* = \|A\|_*$  for any permutation matrix  $P \in \mathbb{R}^{n_2 \times n_2}$ ).

*Proof.*  $\|PA\|_* = \|A\|_*$  by Property 7 and the unitary invariant norm property.

Similarly, we can get  $\|AP\|_* = \|A\|_*$  for any permutation matrix  $P \in \mathbb{R}^{n_2 \times n_2}$ .  $\square$

**Theorem 2.** For  $Y \in \mathbb{R}^{n_1 \times n_2}$ ,  $\mathcal{D}_\tau(Y) = P^{-1} \mathcal{D}_\tau(PY)$  for any permutation matrix  $P \in \mathbb{R}^{n_1 \times n_1}$  (and  $\mathcal{D}_\tau(Y) = \mathcal{D}_\tau(YP)P^{-1}$  for any permutation matrix  $P \in \mathbb{R}^{n_2 \times n_2}$ ), where  $\mathcal{D}_\tau(Y) = \arg \min_X \frac{1}{2} \|Y - X\|_F^2 + \tau \|X\|_*$ , and  $P^{-1}$  is an inverse operator of  $P$ .

*Proof.*

$$\begin{aligned} P^{-1} \mathcal{D}_\tau(PY) &= P^{-1} \arg \min_Z \frac{1}{2} \|PY - Z\|_F^2 + \tau \|Z\|_* \\ &= \arg \min_X \frac{1}{2} \|PY - PX\|_F^2 + \tau \|PX\|_* \\ &= \arg \min_X \frac{1}{2} \|Y - X\|_F^2 + \tau \|X\|_*, \end{aligned} \quad (1)$$

where the second equation holds by letting  $X = P^{-1}Z$ , and the third equation holds by the Property 7 and Property 1.

Similarly, we can get  $\mathcal{D}_\tau(Y) = \mathcal{D}_\tau(YP)P^{-1}$  for any permutation matrix  $P \in \mathbb{R}^{n_2 \times n_2}$ .  $\square$

**Property 2.** For  $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ , then  $\sum_{i=1}^3 \alpha_i \|(\mathcal{A} \circ \mathcal{P}^{(k)})_{(i)}\|_* = \sum_{i=1}^3 \alpha_i \|\mathcal{A}_{(i)}\|_*$  for any slice permutations  $\mathcal{P}^{(k)}$  i.e. ( $k = 1, 2, 3$ ), where  $\mathcal{A}_{(i)}$  represents the mode- $i$  unfolding matrix of  $\mathcal{A}$ ,  $(\mathcal{A} \circ \mathcal{P}^{(k)})_{(k)} (k = 1, 2, 3)$  stands for the result by perform horizontal slice permutations, lateral slice permutations and frontal slice permutations on  $\mathcal{A}$ , respectively.

*Proof.* For any slice permutations  $\mathcal{P}^{(k)} (k = 1, 2, 3)$ , exist permutation matrices  $P_i$  and  $Q_i$  makes  $(\mathcal{A} \circ \mathcal{P}^{(k)})_{(i)} = P_i \mathcal{A}_{(i)} Q_i$  for  $i = 1, 2, 3$ . Therefore,  $\sum_{i=1}^3 \alpha_i \|(\mathcal{A} \circ \mathcal{P}^{(k)})_{(i)}\|_* = \sum_{i=1}^3 \alpha_i \|P_i \mathcal{A}_{(i)} Q_i\|_* = \sum_{i=1}^3 \alpha_i \|\mathcal{A}_{(i)}\|_*$ .  $\square$

**Theorem 3.**  $\mathcal{S}_\tau(\mathcal{Y}) = \mathcal{S}_\tau(\mathcal{Y} \circ \mathcal{P}^{(k)}) \circ (\mathcal{P}^{(k)})^{-1} (k = 1, 2, 3)$ , where  $\mathcal{S}_\tau(\mathcal{Y}) = \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \sum_{i=1}^3 \alpha_i \|\mathcal{X}_{(i)}\|_*$ .

*Proof.*

$$\begin{aligned} &\mathcal{S}_\tau(\mathcal{Y} \circ \mathcal{P}^{(k)}) \circ (\mathcal{P}^{(k)})^{-1} \\ &= (\arg \min_{\mathcal{Z}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}^{(k)} - \mathcal{Z}\|_F^2 + \tau \sum_{i=1}^3 \alpha_i \|\mathcal{Z}_{(i)}\|_*) \circ (\mathcal{P}^{(k)})^{-1} \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}^{(k)} - \mathcal{X} \circ \mathcal{P}^{(k)}\|_F^2 + \tau \sum_{i=1}^3 \alpha_i \|(\mathcal{X} \circ \mathcal{P}^{(k)})_{(i)}\|_* \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \sum_{i=1}^3 \alpha_i \|\mathcal{X}_{(i)}\|_*, \end{aligned} \quad (2)$$

where the second equation holds by letting  $\mathcal{X} = \mathcal{Z} \circ (\mathcal{P}^{(k)})^{-1}$ , and the third equation holds by the property of  $\mathcal{P}^{(k)}$  and Property 2.  $\square$

**Property 3.** (Horizontal SPI of tensor nuclear norm) Tensor nuclear norm satisfy HSPI (Horizontal SPI), i.e.  $\|\mathcal{A}\|_* = \|\mathcal{A} \circ \mathcal{P}^{(1)}\|_*$ , for any horizontal slice permutations  $\mathcal{P}^{(1)}$ .

*Proof.* By the definition of  $\text{bcirc}(\mathcal{A})$ , exist two permutation matrices  $P$  and  $Q$  such that  $\text{bcirc}(\mathcal{A} \circ \mathcal{P}^{(1)}) = P \cdot \text{bcirc}(\mathcal{A}) \cdot Q$ . Therefore,  $\|\mathcal{A} \circ \mathcal{P}^{(1)}\|_* = \|\mathcal{A} \circ \mathcal{P}^{(1)}\|_{a,*} = \frac{1}{n_3} \|\text{bcirc}(\mathcal{A} \circ \mathcal{P}^{(1)})\|_* = \frac{1}{n_3} \|P \cdot \text{bcirc}(\mathcal{A}) \cdot Q\|_* = \frac{1}{n_3} \|\text{bcirc}(\mathcal{A})\|_* = \|\mathcal{A}\|_{a,*} = \|\mathcal{A}\|_*$ . Thus  $\|\mathcal{A} \circ \mathcal{P}^{(1)}\|_* = \|\mathcal{A}\|_*$ .  $\square$

**Property 4.** (Lateral SPI of tensor nuclear norm) tensor nuclear norm satisfy LSPI (Lateral SPI), i.e.  $\|\mathcal{A}\|_* = \|\mathcal{A} \circ \mathcal{P}^{(2)}\|_*$ , for any lateral slices permutations  $\mathcal{P}^{(2)}$ .

*Proof.* Similar to the proof of Property 3.  $\square$

\* Corresponding author  
Copyright © 2022, Association for the Advancement of Artificial Intelligence (www.aaai.org). All rights reserved.

**Property 5.** For same circle  $\mathbf{C}^1 = \{i_1, i_2, \dots, i_{n_3}, i_1\}$  and  $\mathbf{C}^2 = \{i_k, i_{k+1}, \dots, i_{n_3}, \dots, i_{k-1}, i_k\}$ ,

$$\|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_* = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_*,$$

where  $\mathbf{Or}^1 = \{i_1, i_2, \dots, i_{n_3}\}$  is obtained by  $\mathbf{C}^1$ , and  $\mathbf{Or}^2 = \{i_k, i_{k+1}, \dots, i_{n_3}, \dots, i_{k-1}\}$  is obtained by  $\mathbf{C}^2$ .

*Proof.*

$$\begin{aligned} & \text{bcirc}(\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}) \\ &= \begin{pmatrix} \mathcal{A}_{:,i_1} & \mathcal{A}_{:,i_{n_3}} & \cdots & \mathcal{A}_{:,i_3} & \mathcal{A}_{:,i_2} \\ \mathcal{A}_{:,i_2} & \mathcal{A}_{:,i_1} & \cdots & \mathcal{A}_{:,i_4} & \mathcal{A}_{:,i_3} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \mathcal{A}_{:,i_{n_3}-1} & \mathcal{A}_{:,i_{n_3}-2} & \cdots & \mathcal{A}_{:,i_1} & \mathcal{A}_{:,i_{n_3}} \\ \mathcal{A}_{:,i_{n_3}} & \mathcal{A}_{:,i_{n_3}-1} & \cdots & \mathcal{A}_{:,i_2} & \mathcal{A}_{:,i_1} \end{pmatrix} \\ &\longrightarrow \begin{pmatrix} \mathcal{A}_{:,i_k} & \mathcal{A}_{:,i_{k-1}} & \cdots & \mathcal{A}_{:,i_{k+2}} & \mathcal{A}_{:,i_{k+1}} \\ \mathcal{A}_{:,i_{k+1}} & \mathcal{A}_{:,i_k} & \cdots & \mathcal{A}_{:,i_{k+3}} & \mathcal{A}_{:,i_{k+2}} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ \mathcal{A}_{:,i_{k-2}} & \mathcal{A}_{:,i_{k-3}} & \cdots & \mathcal{A}_{:,i_k} & \mathcal{A}_{:,i_{k-1}} \\ \mathcal{A}_{:,i_{k-1}} & \mathcal{A}_{:,i_{k-2}} & \cdots & \mathcal{A}_{:,i_{k+1}} & \mathcal{A}_{:,i_k} \end{pmatrix} \\ &= \text{bcirc}(\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}). \end{aligned} \quad (3)$$

Therefore  $\|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_* = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_{a,*} = \frac{1}{n_3} \|\text{bcirc}(\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)})\|_* = \frac{1}{n_3} \|\text{bcirc}(\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)})\|_* = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_{a,*} = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_*$ .  $\square$

**Theorem 4.** For same circle  $\mathbf{C}^1 = \{i_1, i_2, \dots, i_{n_3}, i_1\}$  and  $\mathbf{C}^2 = \{i_k, i_{k+1}, \dots, i_{n_3}, \dots, i_{k-1}, i_k\}$ ,

$$\mathcal{D}_\tau(\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}) \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)-1} = \mathcal{D}_\tau(\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}) \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)-1} \quad (4)$$

where  $\mathcal{D}_\tau(\mathcal{A}) = \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{A} - \mathcal{X}\|_F^2 + \tau \|\mathcal{X}\|_*$ ,  $\mathbf{Or}^1 = \{i_1, i_2, \dots, i_{n_3}\}$  is obtained by  $\mathbf{C}^1$ , and  $\mathbf{Or}^2 = \{i_k, i_{k+1}, \dots, i_{n_3}, \dots, i_{k-1}\}$  is obtained by  $\mathbf{C}^2$ .

*Proof.*

$$\begin{aligned} & (\arg \min_{\mathcal{Z}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)} - \mathcal{Z}\|_F^2 + \tau \|\mathcal{Z}\|_*) \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)-1} \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)} - \mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_* \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_*, \end{aligned}$$

where the first equation holds by letting  $\mathcal{X} = \mathcal{Z} \circ (\mathcal{P}_{\mathbf{Or}^1}^{(3)})^{-1}$ .

By Property 5,  $\|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_* = \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_*$ . Therefore,

$$\begin{aligned} & \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^1}^{(3)}\|_* \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_* \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)} - \mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)}\|_* \\ &= (\arg \min_{\mathcal{Z}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)} - \mathcal{Z}\|_F^2 + \tau \|\mathcal{Z}\|_*) \circ \mathcal{P}_{\mathbf{Or}^2}^{(3)-1}, \end{aligned}$$

where the third equation holds by letting  $\mathcal{Z} = \mathcal{X} \circ (\mathcal{P}_{\mathbf{Or}^2}^{(3)})^{-1}$ . The conclusion holds.  $\square$

**Property 6.** For  $\mathcal{A} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ , if  $n_3 \leq 3$ , then tensor nuclear norm satisfy frontal slice permutations invariance (FSPI), i.e.  $\|\mathcal{A}\|_* = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}}^{(3)}\|_*$  for any frontal slice permutations  $\mathcal{P}_{\mathbf{Or}}^{(3)}$ .

*Proof.* For  $n_3 = 2$ , let  $\mathcal{B}_{:,1} = \mathcal{A}_{:,2}$  and  $\mathcal{B}_{:,2} = \mathcal{A}_{:,1}$ . Thus  $\text{bcirc}(\mathcal{B}) = \begin{pmatrix} \mathcal{B}_{:,1} & \mathcal{B}_{:,2} \\ \mathcal{B}_{:,2} & \mathcal{B}_{:,1} \end{pmatrix} = \begin{pmatrix} \mathcal{A}_{:,2} & \mathcal{A}_{:,1} \\ \mathcal{A}_{:,1} & \mathcal{A}_{:,2} \end{pmatrix} \rightarrow \begin{pmatrix} \mathcal{A}_{:,1} & \mathcal{A}_{:,2} \\ \mathcal{A}_{:,2} & \mathcal{A}_{:,1} \end{pmatrix} = \text{bcirc}(\mathcal{A})$ . Therefore,  $\|\mathcal{A}\|_* = \|\mathcal{A}\|_{*,a} = \|\mathcal{B}\|_{*,a} = \|\mathcal{B}\|_*$ .

For  $n_3 = 3$ , there is only one circle. Therefore,  $\|\mathcal{A}\|_* = \|\mathcal{A} \circ \mathcal{P}_{\mathbf{Or}}^{(3)}\|_*$  by Property 5.

Thus, the conclusion holds.  $\square$

**Theorem 5.** For  $\mathcal{Y} \in \mathbb{R}^{n_1 \times n_2 \times n_3}$ , if  $n_3 \leq 3$ , then

$$\mathcal{D}_\tau(\mathcal{Y}) = \mathcal{D}_\tau(\mathcal{Y} \circ \mathcal{P}^{(k)}) \circ \mathcal{P}^{(k)-1} \quad (5)$$

for  $k = 1, 2, 3$ .

*Proof.*

$$\begin{aligned} & \mathcal{D}_\tau(\mathcal{Y} \circ \mathcal{P}^{(k)}) \circ (\mathcal{P}^{(k)})^{-1} \\ &= (\arg \min_{\mathcal{Z}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}^{(k)} - \mathcal{Z}\|_F^2 + \tau \|\mathcal{Z}\|_*) \circ (\mathcal{P}^{(k)})^{-1} \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} \circ \mathcal{P}^{(k)} - \mathcal{X} \circ \mathcal{P}^{(k)}\|_F^2 + \tau \|\mathcal{X} \circ \mathcal{P}^{(k)}\|_* \\ &= \arg \min_{\mathcal{X}} \frac{1}{2} \|\mathcal{Y} - \mathcal{X}\|_F^2 + \tau \|\mathcal{X}\|_*, \end{aligned} \quad (6)$$

where the second equation holds by letting  $\mathcal{X} = \mathcal{Z} \circ (\mathcal{P}^{(k)})^{-1}$ , and the third equation holds by the property of  $\mathcal{P}^{(k)}$  and Property 3, 4 and 6.  $\square$

## References

Zhang, X.-D. 2017. *Matrix analysis and applications*. Cambridge University Press.