DEADIOCKS

Ruben Acuña Spring 2018

3 SYSTEM MODEL (7.1)

MODELING DEADLOCKS

- We will say that a system has n running processes $P_0 \dots P_n$, and m resource types $R_0 \dots R_n$. A resource may be unique, in which case some R_i has only one instance, otherwise we say there are o instances $W_0 \dots W_0$ of that resource.
- Using a resource involves three steps: request, use, and release.
- What was the example of a concrete deadlock situation we saw earlier?
- How are the three steps above defined in that example?



MUTEX SAMPLE

Is it possible for these threads to deadlock? How?

- and -

Is it possible for these threads to run without deadlocking? How?

```
/* thread one runs in this function */
void *do_work_one(void *param) {
         pthread mutex lock(&first mutex);
         pthread mutex lock(&second mutex);
         // Do some work
         pthread mutex unlock(&second mutex);
         pthread_mutex_unlock(&first_mutex);
         pthread exit(0);
}
/* thread two runs in this function */
void *do work two(void *param) {
         pthread mutex lock(&second mutex);
         pthread mutex lock(&first mutex);
         // Do some work
         pthread mutex unlock(&first mutex);
         pthread mutex unlock(&second mutex);
         pthread exit(0);
}
```

NECESSARY CONDITIONS

For deadlock to occur, a system must demonstrate the following behaviors:

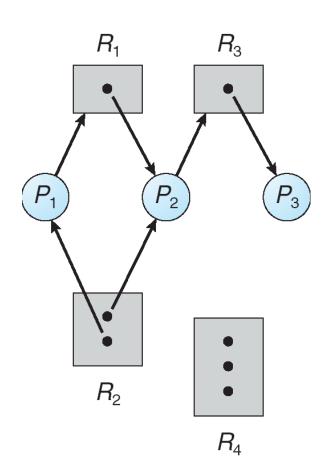
- 1. Mutual exclusion
- 2. Hold and wait
- 3. No preemption
- 4. Circular wait

How does each of these lead to a deadlock state?

If we can address any of these, then we should have a system that won't be held back by deadlocks.

RESOURCE ALLOCATION GRAPHS

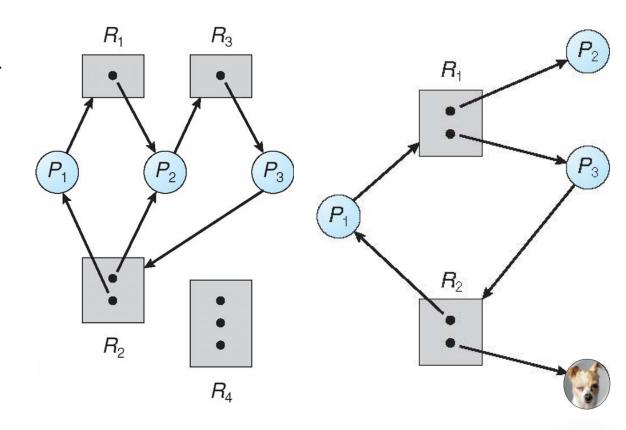
- Consider constructing a graph with nodes that correspond to elements of P and R.
- An edge from P_i to R_j represents that P_i is requesting an instance of R_i .
- An edge from $W_k \in R_j$ to P_i represents that resource instance is assigned to P_i .
- For visualization purposes we show processes as circles and resources as rectangles.
 - Each resource is a supernode that contains each instance of the resource type. Each dot within it represents a specific resource instance.



RESOURCE ALLOCATION GRAPHS

- A resource allocation graph can potentially tell us if there is a deadlock in a system.
- Does the left graph have a deadlock?

• Any general rule?





METHODS

- There are a few ways we can
 - Prevention: prevent one of the four necessary conditions from being possible.
 - Avoidance: check to see if a new process will create a deadlock and stop it from running.
 - Recovery: check if a set of processes is deadlocked and kill a process if needed.
 - None: assuming a reboot will eventually fix everything.



DEADLOCK PREVENTION (7.4)

PREVENTION METHODS

- Note that some of these methods may not apply to every process/resource combination. A practical goal is to prevent as many deadlocks as possible and then "do nothing" for the rest.
- Mutual Exclusion: instead, try to support sharable resources.
- Hold and Wait: prevent a process from acquiring a resource and then waiting for another to become available. Can require process to acquire entire sets of resources, instead of doing so piecewise.

PREVENTION METHODS

- No Preemption: instead, provide a method to allow resources to preempted by another process. Prevent sources from being about to hold on to some resources when they can't obtain all that they need to execute.
- Circular Wait: Can require all processes in the system to request resources in the same order. Hmm...

MUTEX SAMPLE PART 2

Any ideas how we can fix the example from earlier?

```
/* thread one runs in this function */
void *do_work_one(void *param) {
         pthread mutex lock(&first mutex);
         pthread mutex lock(&second mutex);
         // Do some work
         pthread_mutex_unlock(&second_mutex);
         pthread_mutex_unlock(&first_mutex);
         pthread exit(0);
}
/* thread two runs in this function */
void *do work two(void *param) {
         pthread mutex lock(&second mutex);
         pthread mutex lock(&first mutex);
         // Do some work
         pthread mutex unlock(&first mutex);
         pthread_mutex_unlock(&second_mutex);
         pthread exit(0);
```

MUTEX SAMPLE 2

- Now, the last sample was problematic because we had two threads executing functions with different orders for resource acquisition.
- This sample is a single function, and it runs in two threads.
- Will everything be fine?

DEADLOCK AVOIDANCE (7.5)

This diagram is from the textbook. It has only been included so Ruben can rant about how poor a visualization it is.

SAFE VS UNSAFE SYSTEM STATES

- For this section, we will consider the case where a process can share information on how it will access resources. Here, that means maximum usage.
- If the process's usage would lead to deadlock, then we can avoid it systematically.
- Definition: a safe system is system with safe sequence $\langle P_1, P_2, ..., P_n \rangle$, where P_i can be satisfied by available resources plus resources held by P_i , s.t.j < i.
- If a system is safe, then there is no deadlock. If it is unsafe, then a deadlock may occur.
- Consider the following two allocations: are the systems in a safe state? Assume 12 resources exist.
 - Sample 1

	Maximum	Currently
	Needs	Holding
P0	10	5
P1	4	2
P2	9	2

Sample 2

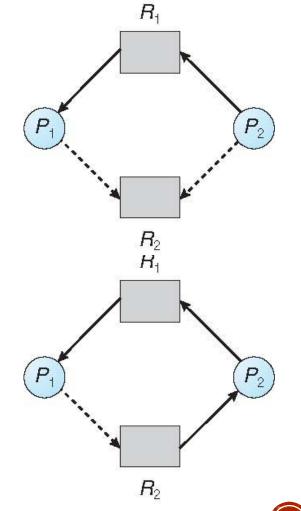
	Maximum Needs	Currently Holding
P0	10	5
P1	4	2
P2	9	4



deadlock	unsafe
	safe

RESOURCE ALLOCATION GRAPH ALGORITHM

- Can extend the previous concept of a resource allocation graph with the idea of a claim edge.
 - We will show these as dashed edges.
- A claim edge, $P_i \rightarrow R_j$ represents that P_i may request R_i in the future.
- When the resource is made, the claim edge may be converted to an assignment edge.
- Claim edges give us a new way to prevent deadlocks since we can check if converting them to a assignment edge would introduce a cycle into the graph.



BANKER'S ALGORITHM

- This is an algorithm that can analyze systems with multiple resource instances and if a process will create a deadlock.
- Basic idea: make a process define its resource resources before committing to its execution, and see if allocating those resources would give an unsafe state.
- We must represent available resources, maximum resources required by processes, resources currently allocated to processes, and remaining resources needed.

- Let n be the number of processes and m be the number of resource types.
- For a matrix, we will use subscript to refer to a row vector of it.

SAFETY ALGORITHM

 Part one, we want to check if a system is in a safe state.

```
#step 1
Work = Available
Finish = [False] * n
#step 2
i = index such that Finish[i] = False and
                    Need i ≤ Work
while i valid:
    #step 3
    Work = Work + Allocation i
    Finish[i] = True
    #step 2
    i = index such that Finish[i] = False and
                        Need i ≤ Work
#step 4
if forall i, Finish[i] = True:
  system is in safe state
```

RESOURCE REQUEST ALGORITHM

- Next, we want to check if a request can be safely granted by the system.
 - $Request_i = a_0$... a_m
- We need to represent which resources are being requested by each process, call it *i*, to complete.

```
validate_request (Request_i):
   if Request_i \leq Need_i:
        if Request_i \leq Available:
            Available = Available-Request_i
            Allocation_i = Allocation_i + Request_i
            Need_i = Need_i-Request_i
            if resulting state is safe: #safety algorithm
                 finalize resource allocation
        else:
            #P_i must wait for Request_i
                 restore old resource allocation state
```

SAFETY ALGORITHM EXAMPLE 1

	Allocation	Request
	ABC	ABC
P0	010	753
Pl	200	322
P2	302	902
P3	211	222
P4	002	433

	Need	
	ABC	
P0		
P1		
P2		
P3		
P4		

Available ABC 332

SAFETY ALGORITHM EXAMPLE 2

	Allocation	Request
	ABC	ABC
P0	010	753
Pl	200	322
P2	302	902
P3	211	222
P4	002	433

	Need	
	ABC	
P0	743	
Pl	122	
P2	600	
P3	011	
P4	431	

Available ABC 032

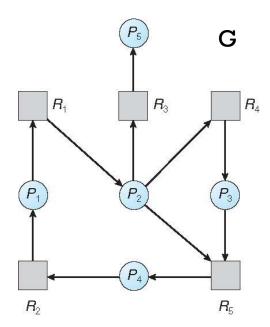
DEADLOCK DETECTION (7.6)

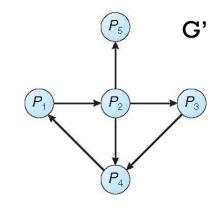
DETECTION

- In some systems, avoiding deadlocks may be expensive, in which case we could instead try to address them after they have occurred. This has two parts:
 - Detection
 - We'll discuss this for single and multiple resource instance systems.
 - Recovery
- Need to think about how to use a detection-algorithm. They
 have some cost so we want to minimize how often it is run.
 - How often should we look for deadlocks?

DETECTION WITH SINGLE RESOURCES

- We now introduce the idea of a wait-for graph.
- Previously we defined resource allocation graphs as the digraph: $G = (V, E) = (P \cup R \cup W, P \times R \cup W \times P)$.
- For some G, the wait-for graph is: G' = (P, E'), where $E' = (P_i, P_j) | (P_i, R_k) \in E \lor (R_k, P_j) \in E$).
- What is the advantage of using this over a resource allocation graph?
- What about disadvantages?





DETECTION WITH RESOURCE INSTANCES

else

system is not deadlocked

- Let n be the number of processes and m be the number of resource types.
- For a matrix, we will use subscript to refer to a row vector of it.
- We need to represent available resources, resources currently allocated to processes, and which resources are being request by each process to complete.

Available = a_0 ... a_m

```
#step 1
Work = Available
Finish = [False] * n
for each Allocation i = 0:
    Finish[i] = True
#step 2
i = index such that Finish[i] = False and
                    Request i ≤ Work
while i valid:
    #step 3
    Work = Work + Allocation i
    Finish[i] = True
    #step 2
    i = index such that Finish[i] = False and
                        Request i ≤ Work
#step 4
if for some i, Finish[i] = False:
  system is deadlocked on process i
```

DEADLOCKS WITH INSTANCES: EXAMPLE 1

```
#step 1
Work = Available
Finish = [False] * n
for each Allocation i = 0:
    Finish[i] = True
#step 2
i = index such that Finish[i] = False and
                    Request i ≤ Work
while i valid:
    #step 3
    Work = Work + Allocation i
    Finish[i] = True
    #step 2
    i = index such that Finish[i] = False
and
                        Request i ≤ Work
#step 4
if for some i, Finish[i] = False:
  system is deadlocked on process i
else
  system is not deadlocked
```

	Allocation	Request
	AB	AB
P0	10	01
Pl	01	10

Available
AB
00

DEADLOCKS WITH INSTANCES: EXAMPLE 2

```
#step 1
Work = Available
Finish = [False] * n
for each Allocation i = 0:
    Finish[i] = True
#step 2
i = index such that Finish[i] = False and
                    Request i ≤ Work
while i valid:
    #step 3
    Work = Work + Allocation i
    Finish[i] = True
    #step 2
    i = index such that Finish[i] = False
and
                        Request i ≤ Work
#step 4
if for some i, Finish[i] = False:
  system is deadlocked on process i
else
  system is not deadlocked
```

	Allocation	Request
	ABC	ABC
P0	010	000
Pl	200	202
P2	303	000
P3	211	100
P4	002	002

Available ABC 000

DEADLOCKS WITH INSTANCES: EXAMPLE 3

```
#step 1
Work = Available
Finish = [False] * n
for each Allocation i = 0:
    Finish[i] = True
#step 2
i = index such that Finish[i] = False and
                    Request i ≤ Work
while i valid:
    #step 3
    Work = Work + Allocation i
    Finish[i] = True
    #step 2
    i = index such that Finish[i] = False
and
                        Request i ≤ Work
#step 4
if for some i, Finish[i] = False:
  system is deadlocked on process i
else
  system is not deadlocked
```

	Allocation	Request
	ABC	ABC
P0	010	000
Pl	200	202
P2	303	001
P3	211	100
P4	002	002

Available ABC 000

RECOVERY FROM DEADLOCK (7.7)

RECOVERY

- Once we've found a deadlock, we need to deal with it. We can either try to fix it by killing process(es) or preempting resources.
 - Process Termination approaches:
 - Abort all deadlocked processes
 - Abort just one process
 - Which process should we abort?
 - Resource preemption considerations:
 - Selecting a victim
 - Rollback
 - Starvation