

(十四) HMM 隐马尔可夫模型



$\lambda = (\pi, A, B)$ 状态转移
 初始 prob dist 发射矩阵

观测变量: $o_1, o_2, \dots, o_T \rightarrow V = \{v_1, v_2, \dots, v_m\}$ (观测值的值域)

隐状态变量: $i_1, i_2, \dots, i_T \rightarrow Q = \{q_1, q_2, \dots, q_n\}$ (隐状态的值域)

$A = [a_{ij}]$, $a_{ij} = P(i_{t+1} = q_j | i_t = q_i)$ 状态转移矩阵

$B = [b_j^k]$ $b_j^k = P(o_t = v_k | i_t = q_j)$ 发射矩阵, 状态到观测
 两个假设: ① 齐次 Markov 假设, ② 观察独立

$$P(i_{t+1} = i_{t+1}, i_t = i_t, o_t = o_t, o_{t+1} = o_{t+1} | i_t = i_t) = P(o_{t+1} | i_t)$$

$$P(o_t | i_t, i_{t-1}, \dots, i_1, o_{t-1}, \dots, o_1) = P(o_t | i_t)$$

三个问题:

① Evaluation $\rightarrow P(O|I, \lambda)$ 前向反向

② Learning $\rightarrow EM$

③ Decoding $I = \arg \max P(I|O)$

预测 $\rightarrow P(i_{t+1} | o_1, o_2, \dots, o_t)$

Evaluation 问题: Given O, λ 求 $P(O|\lambda)$



$$P(O|\lambda) = \sum_I P(I, O|\lambda) = \sum_I P(O, I|\lambda) \cdot P(I|\lambda)$$

$$P(O|\lambda) = P(i_1, i_2, \dots, i_T|\lambda) = P(i_1 | i_1, i_2, \dots, i_{T-1}, \lambda) \cdot P(i_2, i_3, \dots, i_T | i_1, \lambda)$$

$$= \pi(a_{i1}) \prod_{t=2}^T a_{i_{t-1}, i_t} \cdot P(i_T | i_1, \lambda)$$

$$P(O|I, \lambda) = \prod_{t=1}^T b_{i_t}(o_t)$$

$$P(O|\lambda) = \sum_I \pi(a_{i1}) \prod_{t=2}^T a_{i_{t-1}, i_t} \prod_{t=1}^T b_{i_t}(o_t)$$

三 I 的可能种类为 $\sum_{i_1} \sum_{i_2} \dots \sum_{i_T}$

$$= \sum_{i_1} \sum_{i_2} \dots \sum_{i_T} \pi(a_{i1}) \prod_{t=2}^T a_{i_{t-1}, i_t} \prod_{t=1}^T b_{i_t}(o_t)$$

Forward Algorithm

