Jannik **Zürn**

University of Freiburg, Georges-Koehler-Allee 80, 79110 Freiburg im Breisgau, Germany

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Education

University of Freiburg, Germany — *Freiburg, Germany*
Ph.D. Robotics — *Dec. 2018 – Now*
- Advisor: Prof. Dr. Wolfram Burgard
- Research Focus: Self-Supervised Robot Learning, Perception for Autonomous Robots

Karlsruhe Institute of Technology (KIT), Germany — *Karlsruhe, Germany*
M.S. Theoretical Mechanical Engineering (GPA: 3.7/4.0) — *Aug. 2015 – Aug. 2018*
- Thesis topic: Neural Networks for Steady-State Fluid Flow Prediction
- Advisors: Dr. S. Suwelack, Dr. Christof Megnin. Grade: 1.0

Karlsruhe Institute of Technology (KIT), Germany — *Karlsruhe, Germany*
B.S. Mechanical Engineering (GPA: 3.1/4.0) — *Oct. 2011 – Aug. 2015*
- Thesis topic: Numerical Solution of the Chemical Master Equation
- Advisor: M.Sc. A. Koksharov. Grade: 1.0

Academic & Industry Experience

Graduate Research Assistant — *Karlsruhe, Germany*
Renumics GmbH — *Jun. 2018 – Aug. 2018*

Summer Internship, Robotics Software Engineering — *Redwood City, CA, USA*
Mayfield Robotics — *Jul. 2017 – Oct. 2017*

Graduate Research Assistant — *Karlsruhe, Germany*
FZI Research Center for Information Technology — *Sep. 2016 – Apr. 2018*

Graduate Research Assistant — *Karlsruhe, Germany*
Institute for Biomedical Engineering, KIT — *Jan. 2016 – Aug. 2018*

Summer Internship, Software Engineering — *San Diego, CA, USA*
ANSYS, Inc. — *May 2015 – Sep. 2015*

Undergraduate Research Assistant — *Karlsruhe, Germany*
Institute for Technical Thermodynamics, KIT — *Oct. 2014 – Apr. 2015*

Undergraduate Research Assistant — *Karlsruhe, Germany*
Institute for Applied Computer Science, KIT — *Jun. 2013 – Jun. 2014*

Research Projects

Autonomous Street Crossing with Navigational Robots in Cities — *2018 – Now*
Research Scientist

Open Deep Learning Toolkit for Robotics (OpenDR) *2021 – 2021*

Research Scientist

Selected Publications

Zürn, Jannik, and Wolfram Burgard. "Self-Supervised Moving Vehicle Detection from Audio-Visual Cues." arXiv preprint arXiv:2201.12771 (2022), *under review*.

Zürn, Jannik*, Johan Vertens*, and Wolfram Burgard. "Lane Graph Estimation for Scene Understanding in Urban Driving." IEEE Robotics and Automation Letters 6.4 (2021): 8615-8622.

Vertens, Johan*, Jannik Zürn*, and Wolfram Burgard. "Heatnet: Bridging the day-night domain gap in semantic segmentation with thermal images." 2020 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS). IEEE, 2020.

Zürn, Jannik, Wolfram Burgard, and Abhinav Valada. "Self-supervised visual terrain classification from unsupervised acoustic feature learning." IEEE Transactions on Robotics 37.2 (2020): 466-481.

Megnin, C., Moradi, B., Zürn, J., Ossmer, H., Gueltig, M., and Kohl, M. (2020). Shape memory alloy based controllable multiport microvalve. Microsystem Technologies, 26(3), 793-800.

Reviewing Activites

- **Journals**: IEEE Transactions on Robotics (T-RO), IEEE Robotics and Automation Letters (RA-L)
- **Conferences**: IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), IEEE International Conference on Multisensor Fusion and Integration (MFI)

Software & Datasets

Self-Supervised Visual Terrain Classification *http://deepterrain.cs.uni-freiburg.de/*

A Self-Supervised Terrain Classification Framework using Sound and Vision

Semantic Segmentation of Thermal Images *http://thermal.cs.uni-freiburg.de/*

Bridging the Day-Night Domain Gap in Semantic Segmentation with Thermal Images

LaneGraphNet *http://lanegraph.cs.uni-freiburg.de/*

Lane Graph Estimation for Scene Understanding in Urban Driving

Teaching

SS 2021 **FreiCar: Practical Autonomous Driving**, Co-Organizer, Lecturer
WS 2020/21 **FreiCar: Practical Autonomous Driving**, Co-Organizer, Lecturer
SS 2019 **Deep Learning Lab**, Teaching Assistant

Mentoring

2021-2022 **S. Weber**, Self-Supervised Drivable Surface Segmentation for Pedestrian Robots, MS Thesis
2020-2021 **S. Al-Rawi**, Sound Event Localization and Detection, MS Thesis
2020 **G. Stief**, Optical Flow based Window Detection, BS Thesis
2019 **T. Krautschneider**, Multimodal Object Tracking with Deep Learning, BS Thesis
2019 **Y. Satyawan**, Semantic Segmentation of Curb and Curb Cuts in Street Imagery, BS Thesis