# **GPU MODE Lecture 15: CUTLASS**

NOTES CUDA

Lecture #15 provides an in-depth conceptual explanation of NVIDIA's Cutlass library's tensor layout algebra system, focusing on how it handles shapes, strides, and tiling operations for efficient GPU tensor computations.

AUTHOR PUBLISHED

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This post is part of the following series:

- **GPU MODE Lecture Notes**: My notes from the **GPU MODE** reading group lectures run by **Andreas Kopf** and **Mark Saroufim**.
- Introduction
- Notation Clarifications
- Tensors in Cutlass
- Layout and Coordinate Systems
- Sub-Tiles and Memory Organization
- Tiling
- CuTe Framework
- Practical Implementation and Usage

#### Resource Links:

YouTube Recording: Lecture 15: CUTLASS

# Introduction

#### Talk Overview

- Speaker: Eric Auld
- Topic: Cutlass NVIDIA's CUDA Templates for Linear Algebra Subroutines
  - Focuses on the conceptual understanding of Cutlass rather than the API specifics.
  - Aims to help attendees loosen the lid and get started with learning Cutlass.

#### What is Cutlass

- Cutlass is a CUDA Templates for Linear Algebra Subroutines library developed by NVIDIA.
  - GitHub Repository: NVIDIA/cutlass

- Authors: https://github.com/NVIDIA/cutlass/blob/main/CITATION.cff
- It provides low-level control over GPU computations, particularly for tensor core operations.
- Used for writing high-performance kernels for machine learning and linear algebra applications.

## Why Learn Cutlass

- Cutlass allows developers to spec out new machine learning models and test their performance.
- It provides tools to make models **performant** by leveraging GPU capabilities directly.
- Useful for exploring performance-oriented machine learning models that incorporate extensive linear algebra.
- Understanding Cutlass is essential for working on performance-critical components like Flash Attention.
  - GitHub Repository: Dao-AlLab/flash-attention
    - cutlass code: flash-attention/csrc

# **Recognizing Cutlass Code**

#### **Indexing Conventions**

- Cutlass uses **round parentheses** () for indexing tensors, unlike the typical square brackets [].
- Uses underscores \_ in indexing:
  - The underscore acts like the **colon**: in Python for slicing.
  - Example: some\_tensor(\_, 2) selects all elements in the first dimension and the third element in the second dimension.

#### Common Functions

- **Greatest Hits Functions** frequently seen in Cutlass code:
  - local\_tile
  - local\_partition
  - o partition\_D
  - o partition\_S
- Underscore 3 3:
  - Represents a static integer 3.
  - The value is embodied in the type rather than the variable's value.
  - Used for compile-time constants.

### **Library Purpose and Context**

### Comparison with Other NVIDIA Libraries

- User-Friendly Libraries (Called from host):
  - o cuBLAS
  - o cuDNN
  - Features:
    - No kernel code writing required
    - Automatic Tensor core inference

- Some kernel fusion capabilities
- Host-to-device communication overhead
- Device-Level Libraries:
  - Cutlass
  - Thrust
  - o CUB
  - Features:
    - Low-level control
    - Direct tensor core operation exposure
    - Greater flexibility for new implementations

#### When to Use Cutlass

- Primary Use Cases:
  - For new ML models requiring performance optimization
  - When exploring performance-oriented machine learning models with extensive linear algebra
  - When requiring lower-level control than what CUDA BLAS (cuBLAS) provides
  - For implementing and testing new model architectures

### **Notation Clarifications**

#### Interval Notation

- Uses the following notation for intervals:
  - $\circ$  [i...j) represents the half-open interval from i to j, including i but excluding j.
  - Example: [0..n) includes integers from 0 up to but not including n.

#### **Definition of Modes**

- Mode:
  - An element of a nested tuple.
  - In a nested tuple of integers, each element (which could be a tuple itself) is called a mode.
  - Important in the context of **nested layouts** in Cutlass.

# Cutlass 3.0 (CuTe)

- CuTe refers to Cutlass 3.0, which introduced new tensor notation.
- Emphasizes nested structures and layouts for tensors.

# **Tensors in Cutlass**

# **Engine (Pointer)**

- The **engine** of a tensor represents the **underlying memory pointer**.
- It could be a pointer to global memory, shared memory, or other memory types.

# Layout (Shape and Stride)

- A tensor's layout consists of:
  - **Shape**: Specifies the allowable input coordinates.
    - Represented as nested integer tuples.
    - Defines the **dimensions** of the tensor.
  - Stride: Defines how to map coordinates to linear memory offsets.
    - Also represented as nested integer tuples.
    - Used in calculating the memory address for a given tensor coordinate.

# **Layout and Coordinate Systems**

# **Mapping Coordinates to Linear Offsets**

- In **C-style indexing**, linear offsets are calculated using strides:
  - For a coordinate (i, j), the offset is i + j \* M.
  - $\circ$  For (i, j, k), the offset is i + j \* M + k \* M \* N.
- This can be represented as a **dot product**:
  - Offset = (i, j, k) (1, M, M\*N).
- The **stride vector** (1, M, M\*N) is used to map multi-dimensional indices to linear memory.

### **Shape and Stride Concepts**

### **Shape Definition**

- Specifies allowable input coordinates
- Uses upper bounds notation
- Example: Shape (M, N, K) means:
  - i coordinates: [0, M)
  - j coordinates: [0, N)
  - k coordinates: [0, K)

### **Layout Notation**

```
• Format: shape:stride
```

Example: (M,N,K): (1,M,MN)

Shape component: (M,N,K)

Stride component: (1,M,MN)

# **Layout Concatenation**

#### **Basic Concatenation**

- Can combine one-dimensional layouts
- Example: (3:1,2:3) = (3,2):(1,3)
- Benefits:

- More convenient representation
- Keeps corresponding shape and stride values closer together

# **Nested Layouts**

#### Structure

- Flat Lavout:
  - o All dimensions are at the same level.
  - Coordinates are simple tuples.
  - Example: Shape (3, 4, 2), Stride (1, 3, 40).
    - Accepts coordinates like (1,2,1)
- Nested Layout:
  - Dimensions are grouped into nested tuples.
  - Coordinates are nested tuples.
  - Example:
    - Shape ((3,4),2).
    - Stride (1,3),40).
  - The first mode is (3,4), and the second mode is 2.
  - Accepts coordinates like ((1,2),1)

#### Congruence Concept

- Congruent: Having the same nesting structure
- Requirements:
  - Shape and stride must be congruent
  - Coordinates must match the nesting structure
- Example:
  - Nested layout accepts coordinate like (1,2),1
  - Flat layout accepts coordinate like 1,2,1

# **Layout Visualization**

### Purpose

- Drawing layouts helps in **visualizing** and **reasoning** about tensor layouts.
- Not meant to provide rigorous definitions but to aid understanding.

### **Drawing Conventions**

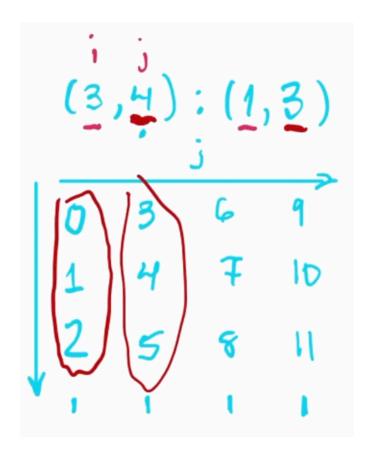
- Positive i direction: downward
- Positive j direction: rightward
- Starting point: always zero
- Compositional approach:
  - 1. Draw elements in first direction
  - 2. Replicate pattern for second direction
  - 3. Continue for additional dimensions

# Example: Simple 2D Layout

• Layout:

```
o shape = (3, 4)
o stride = (1, 3)
```

• Visualization:



- Along the i (row) direction:
  - Elements at offsets 0, 1, 2
- Along the j (column) direction:
  - Each step increases the offset by 3 (due to stride 3).
- $\circ~$  The overall offsets for each element can be calculated and plotted.

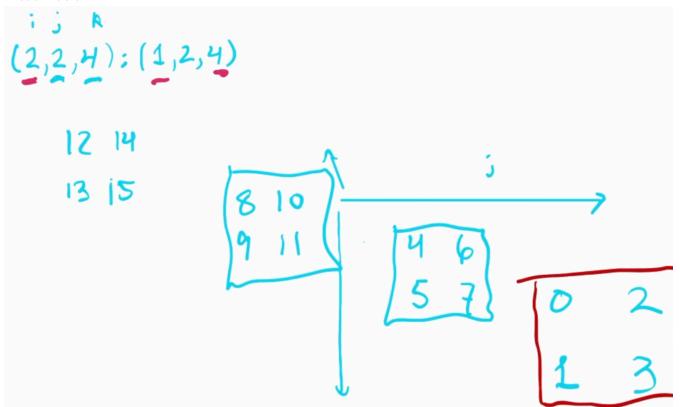
# Example: 3D Layout

• Layout:

```
o shape = (2, 2, 4)
```

o stride = 
$$(1, 2, 4)$$

Visualization:



- ∘ Three dimensions: i, j, k.
- Elements are offset according to strides in each dimension.
- Helps in understanding complex memory layouts.

# **Special Stride Types**

### Layout Left

- Generalized column-major ordering
- Stride calculation: Running prefix product from left
- Example for shape (A,B,C,D):
  - Resulting stride: (1, A, AB, ABC)

### Layout Right

- Generalized row-major ordering
- Stride calculation: Running prefix product from right
- Example for shape (A,B,C,D):
  - Resulting stride: (BCD,CD,D,1)

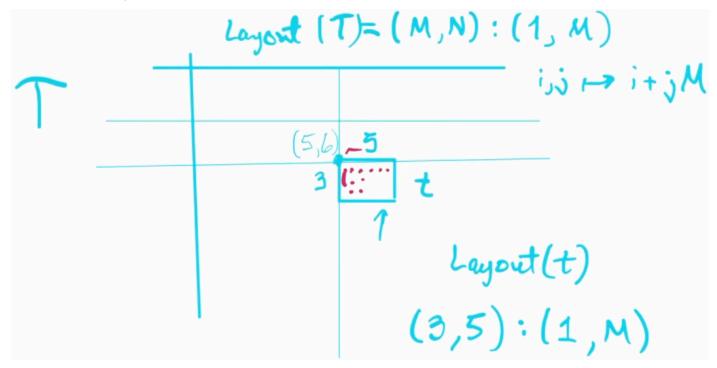
# **Sub-Tiles and Memory Organization**

# **Sub-Tile Concepts**

#### **Basic Properties of Sub-Tiles**

- Shape: Different (smaller) than parent tensor
- Stride: Identical to parent tensor
- Base Pointer: Offset from parent tensor's base

### Sub-Tile Example



- Parent Tensor: T with shape (M, N) and layout layout\_left (1,M) stride.
- Sub-Tile: t with shape (3, 5) at position (5,6).
- Maintains parent stride (1,M)
- Base pointer offset calculation: 5\*1 + 6\*M

# **Understanding Nestedness**

- **Question**: "Are you going to explain on an example what nestedness means?"
- Answer:
  - Eric elaborated:
    - Nested Tuples: Tuples where elements can themselves be tuples, forming a hierarchical or treelike structure.
    - Example:
      - A nested layout: ((3, 4), 2):((1,3),12)
        - Coordinates accepted: ((i, j), k)
      - Flat layout: (3,4,2):(1,3,12)
    - Usage in Cutlass:
      - Nested modes allow for logical subdivisions of tensors, which can represent different aspects like thread arrangements and value assignments.
      - Helps in assigning threads to multi-dimensional data efficiently.
  - Clarification:

- The nesting structure must be consistent across shape, stride, and the coordinates used.
- Nestedness facilitates operations where dimensions need to be grouped logically.

# Q&A

#### Specifying Sub-Tiles in Tensors

- **Question**: "How do you tile a tensor in this example? How do you specify that capital T is broken down into lowercase t s?"
- Answer:
  - Eric explained that tiling can be achieved using specific methods in Cutlass:
    - Methods for Tiling:
      - with\_shape: Adjusts the shape of a tensor while keeping the same stride, effectively creating a sub-tile.
      - local\_tile: Partitions a tensor into tiles for local computation.
      - local\_partition: Divides a tensor among threads or warps.
      - Composition:
        - Using the compose function to combine layouts, treating them as functions.
        - Allows creating sub-tiles by composing the parent tensor's layout with the desired subtile layout.
  - Key Point:
    - Sub-tiles share the same stride as the parent tensor but have different shapes and base pointers.
    - The base pointer of a sub-tile is offset based on its position within the parent tensor.

#### Composition at Compile Time vs. Runtime

- **Question**: "Is adding composition of layouts adding some hardware overhead, or is it all at runtime or compile time?"
- Answer:
  - Eric explained that it could be either, depending on the situation:
    - **Compile-Time Composition:** 
      - If layouts are entirely static and composed of static integers (e.g., \_3 representing a static
         3), composition can occur at compile time.
      - Benefits include potential performance optimizations and early error detection.
    - Runtime Composition:
      - If layouts involve dynamic components (e.g., dimensions not known until runtime), composition must occur at runtime.
      - Examples include large memory allocations where sizes aren't predetermined.
  - Implications:
    - Compile-time composition can reduce overhead, but flexibility may require runtime handling.
    - Developers can balance between performance and flexibility based on their needs.

# Support for Negative Strides in Cutlass

- **Question**: "Is it allowed in Cutlass to use negative strides?"
- Answer:

- Eric confirmed that negative strides are allowed and elaborated:
  - Usage:
    - Negative strides enable traversal of tensors in reverse order along a dimension.
    - Useful for operations like flipping tensors or accessing data in a non-standard sequence.
  - Considerations:
    - While powerful, using negative strides can be complex and requires careful handling to avoid errors.
  - Example:
    - A tensor with a negative stride in one dimension will decrement the memory offset when indexing along that dimension.

# **Non-Contiguous Layouts**

- Definition:
  - Layouts where elements are not stored in contiguous memory locations.
- Example:
  - Stride with Gaps:
    - $\blacksquare$  shape = (3)
    - stride = (2)
    - Offsets: 0, 2, 4 (skipping memory locations).

# **Multiple Sub-Tiles**

## Common Properties

- All sub-tiles of same size have:
  - Identical shape
  - Identical stride
  - Different base pointers

# Distinguishing Features

- Only differ in base pointer offset
- Each maintains parent tensor's memory layout pattern
- Base pointer calculation uses parent tensor's layout

### **Memory Management**

### **Tensor Components Review**

- 1. Engine (pointer/memory):
  - Base pointer location
  - Memory type (shared, global, etc.)
- 2. Layout:
  - Shape (dimensions)
  - Stride (memory pattern)

#### **Bounds Checking**

- Cutlass performs bounds checking
- Many checks possible at compile time due to static integers
- Type system encodes layout information

# **Tiling**

# **Tiling Operations**

#### **Basic Tiling Structure**

- Division of larger tensor into smaller parts
- Two components:
  - 1. Outer Part: Which tile we're examining
  - 2. Inner Part: Which element within the tile

#### Mathematical Representation

```
For tensor size A×B×C tiled by a×b×c: - Outer dimensions: (A/a) \times (B/b) \times (C/c) - Inner dimensions: a × b × c
```

# **Partial Tiling**

## Mode-Specific Tiling

- Can tile specific dimensions while leaving others untouched
- Example tiling modes A and C:

```
\circ Outer part: (A/a) \times B \times (C/c)
```

Inner part: a × 1 × c

### **Compute Resource Tiling**

#### Purpose

- Maps both data and compute resources
- Common in accelerator operations
- Example: Tensor core operations requiring specific thread counts

## Components to Tile

- 1. Compute Resources:
  - Thread arrangements
  - Warp-level operations

#### 2. Data Structures:

- Memory layouts
- Access patterns

# **Layout Division and Composition**

#### **Shape Division Concepts**

- Notation:
  - Uses circle-slash symbol (∅) to represent division-like operation
  - ∘ Format: BigShape ⊘ SmallShape
- Convention Rules:
  - 1. First Mode (Inner):
    - Represents elements within a tile
    - Answers "which element in the tile?"
    - 2. **Second Mode** (Outer):
      - Represents tile identification
      - Answers "which tile?"
  - 2. Leftover Modes:
    - Placed in outer part
    - Represents untiled dimensions

#### **Layout Division Implementation**

- Example with Layout Left:
  - Original Shape: (ABC)
  - Original Stride: (1, A, AB)
  - Dividing Shape: (a, b, c)
- Results in Two Parts:
  - 1. Inner Part (Subtile):
    - Shape: a, b, c
    - Stride: Same as original (1, A, AB)
  - 2. Outer Part (Tile Selection):
    - Shape: A/a, B/b, C/c
    - Stride: Original stride × small shape size
    - Calculation: (1×a, A×b, AB×c)

# **Example of Tiling**

- Original Shape: (M, N)
- Tile Shape: (m, n)
- Outer Shape: (M/m, N/n)
- Inner Shape: (m, n)
- Inner Stride: Same as original stride.
- Outer Stride:
  - Calculated as:
    - $\blacksquare$  (1 \* m, M \* n)

# **CuTe Framework**

#### **Overview and Context**

### Timeline and Integration

- Introduced with Cutlass 3.0.
- Released: Late 2022
- Integrated with Hopper architecture features

#### Framework Components

- Layout algebra
- Tensor operations
- Shape manipulation
- Memory management

# **Layout Algebra Concepts**

### **Core Operations**

- 1. Composition:
  - Combines two layouts
  - Used for creating subtiles
- 2. Product Types:
  - Different flavors of layout multiplication
  - Includes "ranked product"
- 3. Division Operations:
  - Various forms of layout division
  - Used in tiling operations

# **Implementation Details**

## Memory Types

- **SMEM Pointer**: Shared memory reference
- **GMEM Pointer**: Global memory reference

### Static vs Dynamic Elements

- Static Elements:
  - Known at compile time
  - Uses underscore notation (e.g., \_3)
  - o Enables compile-time optimizations
- Dynamic Elements:
  - Determined at runtime
  - Example: Input tensor dimensions

# **Library Architecture**

#### **Directory Structure**

#### 1. Include Directory:

- Core library components
- Header-only implementation

#### 2. Arch and Atom Directories:

- arch Directory:
  - Contains architecture-specific implementations.
  - Includes tensor core operations using inline assembly.
- atom Directory:
  - Contains abstractions over the architecture-specific implementations.
  - Provides templated structures for different operations.

#### 3. Architecture-Specific Code:

- Organized by compute capability
- Examples:
  - SM80 (Ampere)
  - SM90 (Hopper)

#### 4. Operations Categories:

- Copy operations
- Matrix Multiply Accumulate (MMA)
- Additional linear algebra operations
- Inline Assembly:
  - Low-level code directly interacts with GPU tensor cores.
  - Example operation: SM80\_16x8x4\_F32TF32TF32F32\_TN for matrix multiplication.

```
// MMA 16x8x4 TN
struct SM80_16x8x4_F32TF32TF32F32_TN
{
  using DRegisters = float[4];
  using ARegisters = uint32_t[2];
  using BRegisters = uint32 t[1];
  using CRegisters = float[4];
  CUTE HOST DEVICE static void
  fma(float
                  & d0, float
                                     & d1, float & d2, float
     uint32_t const& a0, uint32_t const& a1,
     uint32 t const& b0,
     float const & c0, float const & c1, float const & c2, float const
  {
#if defined(CUTE_ARCH_MMA_SM80_ENABLED)
    asm volatile(
     "mma.sync.aligned.m16n8k4.row.col.f32.tf32.tf32.f32"
     "{%0, %1, %2, %3},"
     "{%4, %5},"
     "{%6},"
     "{%7, %8, %9, %10};\n"
      : "=f"(d0), "=f"(d1), "=f"(d2), "=f"(d3)
      : "r"(a0), "r"(a1),
```

```
"r"(b0),
    "f"(c0), "f"(c1), "f"(c2), "f"(c3));
#else
    CUTE_INVALID_CONTROL_PATH("Attempting to use SM80_16x8x4_F32TF32TF32F32_TN
#endif
    }
};
```

- Template Specializations:
  - Operations are templated based on data types and compute capabilities.
  - Allows for compile-time dispatch to appropriate implementations.

#### Q&A

#### Availability Across Different GPUs

- Question: "Is this only available for Hopper, or can it also be used for other GPUs? The architectures look as if older GPUs would also be supported."
- Answer:
  - Eric confirmed that Cutlass supports multiple GPU architectures:
    - Supported Architectures:
      - While Cutlass provides extensive support for newer architectures like Hopper (SM90), it also supports older GPUs such as Ampere (SM80) and Volta (SM70).
    - Extent of Support:
      - Newer architectures have more features and optimizations available.
      - Some functionalities may have limited support or performance on older GPUs.
    - Implications for Developers:
      - Developers can use Cutlass across different GPU generations but should be aware of the available features and potential limitations on older hardware.

### Operations Beyond Matrix Multiplication

- **Question**: "Is Cutlass mostly about copy and matrix multiplications, or are there other linear algebra operations, like inversion of a matrix?"
- Answer:
  - Eric explained that while Cutlass focuses on fundamental operations, it is not limited to matrix multiplication:
    - Available Operations:
      - Cutlass supports a variety of tensor operations, including convolutions and reductions.
      - It provides the building blocks for more complex algorithms.
    - Advanced Linear Algebra:
      - For higher-level operations like matrix inversion or solving linear systems, libraries like cuBLAS or cuSOLVER might be more appropriate.
    - Use Cases:
      - Cutlass is ideal for developers needing low-level control to implement custom algorithms or optimize specific operations not covered by higher-level libraries.

# **Practical Implementation and Usage**

# **Matrix Multiplication Implementation**

SGEMM (Single Precision General Matrix Multiply)

- Source Code: examples/cute/tutorial/sgemm\_1.cu
- Name Convention Origin:
  - o S: Single precision
  - GE: General (dense matrices, no special structure)
  - MM: Matrix Multiplication

#### **Function Parameters**

```
// Common parameters
trans_a // Matrix A transpose flag
trans_b // Matrix B transpose flag
lda // Leading dimension of matrix A
alpha // Scalar multiplier
beta // Scalar multiplier for accumulation
```

General Operation Form: D = alpha \* (A \* B) + beta \* C

# **Memory Management Features**

Memory Types and Tags

- Shared Memory:
  - Tag: smem\_ptr
  - Used for thread block local storage
- Global Memory:
  - Tag: gmem\_ptr
  - Used for device-wide storage

## **Example Code Structure**

Basic Include Pattern

```
#include <cute/tensor.hpp>
```

#### **Tensor Creation**

```
// Creating tensors
make_tensor()
make_layout()
make_coord()
```

#### About Me:

I'm Christian Mills, a deep learning consultant specializing in practical AI implementations. I help clients leverage cutting-edge AI technologies to solve real-world problems.

Interested in working together? Fill out my Quick AI Project Assessment form or learn more about me.

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