Dynamic Design



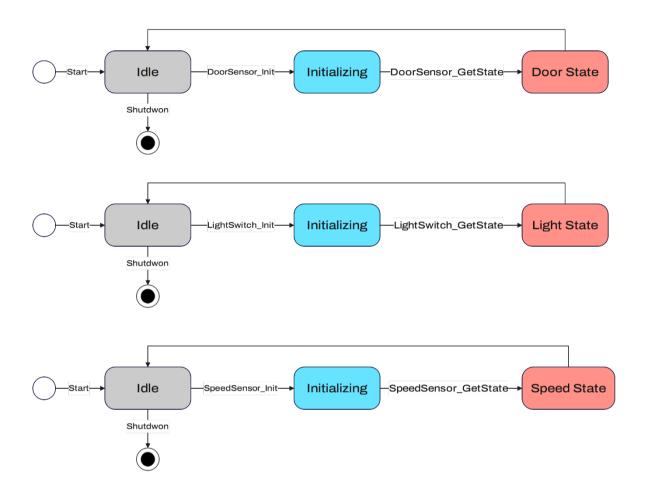
FEBRUARY 9

Automotive Door Control System Design Khaled Ibrahim Abdulaziz

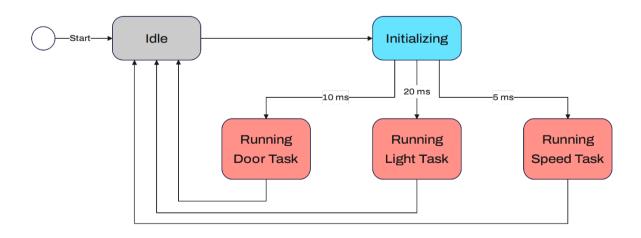


1.ECU1

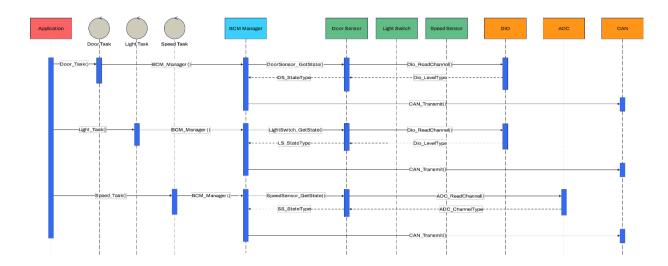
1.1 State Machine for Components



1.2 State Machine for Operation



1.3 Sequence Diagram



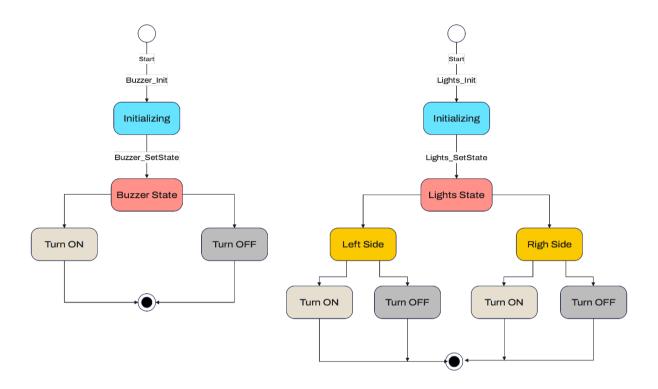
1.4 CPU Load

Assume that execution time of each time = 1 ms

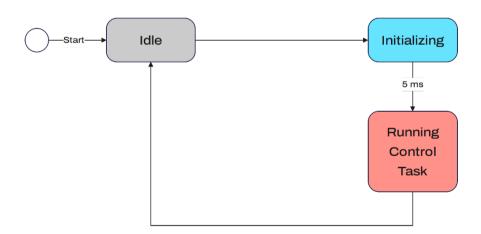
Task Name	Periodicity (ms)	Execution Time (ms)	Occurrence
Door Task	10	1	2
Light Task	20	1	1
Speed Task	5	1	4

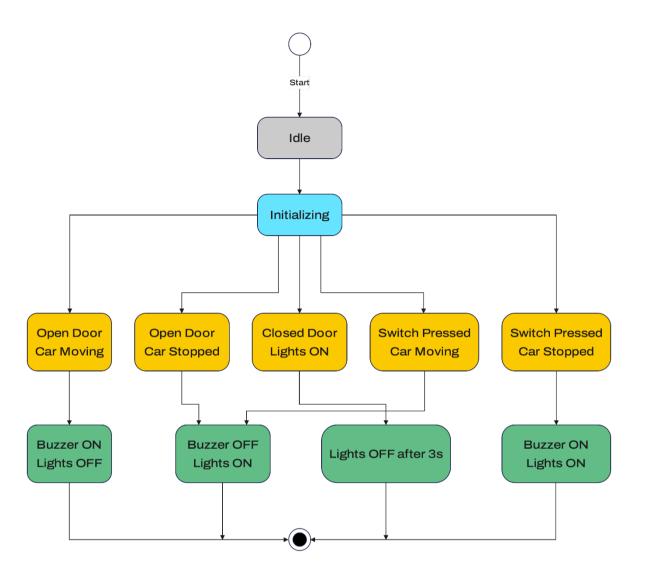
2.ECU2

2.1 State Machine for Components

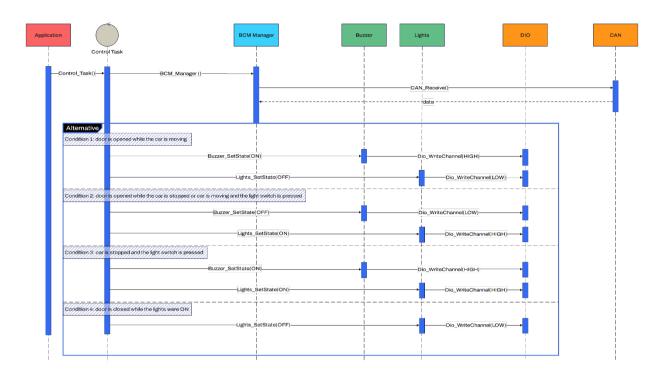


2.2 State Machine for Operation





2.3 Sequence Diagram



2.4 CPU Load

Assume that execution time of each time = 1 ms

Task Name	Periodicity (ms)	Execution Time (ms)	Occurrence
Control Task	5	1	1

Hyper period (H) = LCM = 5 ms
CPU Load = Sum(E) / H =
$$(1 \times 1) / 5 = 0.2$$

3. BUS Load

CAN frame has about 125 bits, assuming we're using 500 kbit/s.

Time to transfer 1 bit Time = 1/bitrate = $(1/500*1000) = 2 \mu s$

Time to transfer 1 frame = 2 * 125 = 250 μ s

1 frame / 20 ms -> 50 frames every 1000 ms, 1 frame / 10 ms -> 100 frames every 1000 ms, 1 frame / 5 ms -> 200 frames every 1000 ms

Total of frames per 1 second = 350 frames

Total time on Bus = total frames * time for frame = 350 * 0.25 = 87.5 ms

Bus Load = (87.5 / 1000) * 100= 8.75%