

# 1 $k$ -forms (July 24)

## 1.1 Multilinear Algebra

**Definition 1.** An  $(\ell, k)$ -tensor on a real vector space  $V$  is a multilinear map

$$T : \underbrace{V^* \times \cdots \times V^*}_{\ell \text{ times}} \times \underbrace{V \times \cdots \times V}_{k \text{ times}} \rightarrow \mathbb{R}.$$

In this course we will mainly be concerned with  $(0, k)$ -tensors, and we'll mainly refer to them as  $k$ -tensors. Why are these important? We have some reasons:

1. The set of tensors have a rich algebraic structure. (They will form a "graded algebra.")
2. They give us the objects we can integrate over. (It turns that the multilinear algebraic properties of forms allow us to define their integrals in a coordinate independent way.)
3. They provide the framework needed to generalize vector calculus to manifolds.

**Definition 2.** A  $k$ -tensor (hereafter this refers to a  $(0, k)$ -tensor, as defined above) is alternating if

$$f(v_1, \dots, v_i, \dots, v_j, \dots, v_k) = -f(v_1, \dots, v_j, \dots, v_i, \dots, v_k)$$

for all  $v_1, \dots, v_k \in V$ .

We have multiple characterizations of algebraic tensors that will make working with them easier.

**Proposition 1.1.** Let  $f$  be a  $k$ -tensor on  $V$ . The following are equivalent:

1.  $f$  is alternating.
2.  $f(v_1, \dots, v_k) = 0$  whenever  $v_i = v_k$  for some  $i \neq j$ .
3.  $f(v_1, \dots, v_k) = 0$  whenever  $\{v_1, \dots, v_k\}$  is linearly independent.
4. For all  $\sigma \in S_k$ ,  $\sigma f = \text{sgn}(\sigma)f$ , where  $\sigma f$  is defined as the  $k$ -tensor  $(\sigma f)(v_1, \dots, v_k) = f(v_{\sigma(1)}, \dots, v_{\sigma(k)})$ .

Let us introduce some notation for the spaces of different kinds of tensors.

- $T_k(V)$  for the vector space of  $k$ -tensors.
- $A_k(V)$  for the vector space of alternating  $k$ -tensors.
- $S_k(V)$  for the vector space of symmetric  $k$ -tensors; those  $k$ -tensors  $f$  satisfying  $\sigma f = f$  for any  $\sigma \in S_k$ .

Now we define projection operators:

$$\begin{aligned}\text{Sym} : T_k(V) &\rightarrow S_k(V) \\ f &\mapsto \sum_{\sigma \in S_k} \sigma f\end{aligned}$$

and

$$\begin{aligned}\text{Alt} : T_k(V) &\rightarrow A_k(V) \\ f &\mapsto \frac{1}{k!} \sum_{\sigma} (\text{sgn}(\sigma)) \sigma f.\end{aligned}$$

The reason for the mysterious  $1/k!$  in the definition of the operator Alt is a technical one: it makes a lot of results come out nicer. In particular,

- $f$  is symmetric if and only if  $f = \text{Sym}(f)$ ,
- $f$  is alternating if and only if  $f = \text{Alt}(f)$ .

**Definition 3.** For  $f \in T_k(V)$  and  $g \in T_\ell(V)$ , define the tensor product  $f \otimes g \in T_{k+\ell}(V)$  by  $(f \otimes g)(v_1, \dots, v_k, v_{k+1}, \dots, v_{k+\ell}) := f(v_1, \dots, v_k)g(v_{k+1}, \dots, v_{k+\ell})$ .

We want a product operation of the form  $A_k(V) \times A_\ell(V) \rightarrow A_{k+\ell}(V)$ . The tensor product does not satisfy this property, unfortunately. Our projection operators will help us define it, however.

**Definition 4.** For  $f \in A_k(V)$  and  $g \in A_\ell(V)$ , define the wedge product  $f \wedge g \in A_{k+\ell}(V)$  by

$$f \wedge g = \frac{(k+\ell)!}{k!\ell!} \text{Alt}(f \otimes g).$$

The mysterious scalar multiple is, again, there for technical reasons. We also have

$$f \wedge g = \frac{1}{k!\ell!} \sum_{\sigma \in S_{k+\ell}} \text{sgn}(\sigma) \sigma(f \otimes g).$$

Here are some properties of the wedge product  $\wedge : A_k(V) \times A_\ell(V) \rightarrow A_{k+\ell}(V)$ :

1. Bilinearity.
2. Associativity.
3. Anticommutativity:  $f \wedge g = (-1)^{k\ell} g \wedge f$ . (This is the reason we always sum over increasing indices!)

4. Fix a basis  $e_1, \dots, e_n$  of  $V$  and let  $\alpha^1, \dots, \alpha^n$  be the dual basis for  $V^* = A_1(V)$ . For any increasing multi-index  $I \subseteq \{1, \dots, n\}$  of length  $k$ , define  $\alpha^I$  as the unique element of  $A_k(V)$  sending  $e_J = (e_{j_1}, \dots, e_{j_k})$  to  $\delta_J^I$ , where  $J$  is another increasing multi-index of length  $k$  from  $\{1, \dots, n\}$ .

Then

$$\{\alpha^I : I \text{ an increasing multi-index of length } k \text{ from } \{1, \dots, n\}\}$$

forms a basis of  $A_k(V)$ . In particular,  $\dim(A_k(V)) = \binom{n}{k}$ . Also,  $a^I = a^{i_1} \wedge \cdots \wedge a^{i_k}$ .

5. For any  $\omega^1, \dots, \omega^k \in V^*$  and  $v_1, \dots, v_k \in V$ ,  $\omega^1 \wedge \cdots \wedge \omega^k(v_1, \dots, v_k) = \det(\omega^i(v_j))$ .

6. The wedge product is actually characterized by the above properties.

Because of these properties, we will hereafter denote by  $\bigwedge^k(V)$  the space of alternating  $k$ -tensors on a vector space  $V$ .

**Definition 5.** An  $\mathbb{R}$ -algebra  $A$  is said to be graded if  $A = \bigoplus_{k=0}^{\infty} A^k$ , where each  $A^k$  is an  $\mathbb{R}$ -vector space, such that the multiplication  $A^k \times A^\ell$  maps into  $A^{k+\ell}$ . A graded algebra  $A$  is said to be anticommutative if  $ab = (-1)^{k\ell}ba$  for  $a \in A^k$  and  $b \in A^\ell$ .

Define  $\bigwedge(V^*) := \bigoplus_{k=0}^{\infty} \bigwedge^k(V^*) = \bigoplus_{k=0}^n \bigwedge^k(V^*)$ . The properties of the wedge product make  $\bigwedge(V^*)$  an associative anticommutative graded algebra over  $\mathbb{R}$  of dimension  $\sum_{k=0}^n \binom{n}{k} = 2^n$ .

## 1.2 $k$ -forms On Manifolds

We developed a notion of smoothness for 1-forms on manifolds. We defined a 1-form  $\omega$  on  $M$  to be smooth if it was smooth as a section of the cotangent bundle. We will follow a similar approach by giving the union of all of the spaces  $A_k(T_p M)$ , over  $p \in M$ , a smooth structure, which will allow us to talk about a smooth  $k$ -form. (Along the way, our notation will change a little.)

Let  $(U, x^1, \dots, x^n)$  be a coordinate chart on  $M$  containing  $p$ . Then we have a basis  $\{\frac{\partial}{\partial x^1}|_p, \dots, \frac{\partial}{\partial x^n}|_p\}$  of  $T_p M$  with the dual basis  $\{dx_p^1, \dots, dx_p^n\}$ . Therefore

$$\{dx_p^{i_1} \wedge \cdots \wedge dx_p^{i_k} : 1 \leq i_1 < \cdots < i_k \leq n\}$$

is a basis of  $\bigwedge^k(T_p^* M)$ .

Define  $\bigwedge^k(T^* M) := \bigcup_{p \in M} \bigwedge^k(T_p^* M)$ . We call  $\bigwedge^k(T^* M)$  the *bundle of alternating k-tensors*. This comes with a projection map

$$\begin{aligned} \pi : \bigwedge^k(T^* M) &\rightarrow M \\ \omega &\mapsto p \quad \text{whenever } \omega \in \bigwedge^k(T_p^* M) \end{aligned}$$

We can equip  $\bigwedge^k(T^*M)$  with a topology and smooth structure making it into a rank  $\binom{n}{k}$  vector bundle. In fact, there is a unique topology and smooth structure for which this is the case. The construction is very similar to that for  $TM$  and for  $T^*M$ . The idea is that for a chart  $(U, \phi)$ , define  $\tilde{\phi} : \bigwedge^k(T^*U) \rightarrow \phi(U) \times \mathbb{R}^n$  by

$$\tilde{\phi} : \omega \mapsto (\phi(p), \{c_I\}_I) \quad \text{whenever } \omega = \sum_I c_I dx^I \in \bigwedge^k(T_p^*M).$$

(The sum is over increasing multi-indices  $I$ .) A detailed proof that  $\bigwedge^k(T^*M)$  is a smooth rank- $\binom{n}{k}$  vector bundle is left as an exercise. We will sometimes call  $\bigwedge^k(T^*M)$  the *kth exterior power of the cotangent bundle*.

With a smooth structure on  $\bigwedge^k(T^*M)$ , we can begin to talk about smooth forms of higher degree.

**Definition 6.** A (differential) *k-form on  $M$*  is a section of the *kth exterior power of the cotangent bundle*  $\pi : \bigwedge^k(T^*M) \rightarrow M$ .

For example, if  $(U, x^1, \dots, x^n)$  is a chart on  $M$ , we can define  $dx^I : U \rightarrow \bigwedge^k(T^*M)$  by  $d^I = dx^{i_1} \wedge \dots \wedge dx^{i_k}$ , where the wedge product of two forms is defined pointwise. Thus  $dx^I$  is a *k-form* on  $U$ .

Just as 1-forms act on vector fields, *k*-forms act on *k*-tuples of vector fields. Let  $\omega$  be a *k*-form on  $M$ . For  $X_1, \dots, X_k \in \mathfrak{X}(M)$ , define  $\omega(X_1, \dots, X_k) : M \rightarrow \mathbb{R}$  pointwise:  $\omega(X_1, \dots, X_k)(p) := \omega_p(X_{1p}, \dots, X_{kp})$ . We note the following important property: if  $h : M \rightarrow \mathbb{R}$  is a function, then

$$\omega(X_1, \dots, hX_i, \dots, X_k) = h\omega(X_1, \dots, X_k).$$

We now begin to discuss smooth *k*-forms. The definition is exactly what one would expect.

**Definition 7.** A *k-form  $\omega$  on  $M$  is smooth* if it is smooth as a section of  $\bigwedge^k(T^*M)$ . The set of all smooth *k*-forms on  $M$  is denoted  $\Omega^k(M)$ . We have  $\Omega^k(M) = \Gamma(\bigwedge^k(T^*M))$ , using vector bundle notation. We also define  $\Omega^0(M) = C^\infty(M)$ .

The space  $\Omega^k(M)$  is an  $\mathbb{R}$ -vector space and a  $C^\infty(M)$ -module, as we should expect by now. We have some equivalent conditions for smoothness of a *k*-form. The proofs are left as easy exercises.

**Proposition 1.2.** Let  $\omega$  be a *k*-form on  $M$ . The following are equivalent:

1.  $\omega$  is smooth as a section of  $\bigwedge^k(T^*M)$ .
2. For any chart  $(U, x^1, \dots, x^n)$ ,  $\omega = \sum_I c_I dx^I$  for some  $c_I \in C^\infty(U)$ , where the sum is over all increasing multi-indices  $I$ .
3. By its action on vector fields,  $\omega : \mathfrak{X}(M) \times \dots \times \mathfrak{X}(M) \rightarrow C^\infty(M)$ , and is  $C^\infty(M)$ -multilinear.

The next proposition is a higher degree form of a surprising result that we saw for 1-forms. The proof is identical.

**Proposition 1.3.** *Every  $C^\infty(M)$ -multilinear map  $\omega : \mathfrak{X}(M) \times \cdots \times \mathfrak{X}(M) \rightarrow C^\infty(M)$  is a  $k$ -form.*

Let's see some examples. Let  $f^1, \dots, f^k \in C^\infty(M)$ . Then we have  $df^1, \dots, df^k \in \Omega^1(M)$ . If  $(U, x^1, \dots, x^n)$  is a chart, then  $df^1 \wedge \cdots \wedge df^k = \sum c_I dx^I$ , where the sum is over increasing multi-indices  $I$ . If  $p \in M$ , then evaluating at  $p$  gives

$$df_p^1 \wedge \cdots \wedge df_p^k = \sum c_I(p) dx_p^{i_1} \wedge \cdots \wedge dx_p^{i_k}.$$

Evaluation at  $\frac{\partial}{\partial x^I}|_p$  (which means exactly what you think it means) gives

$$c_I(p) = df_p^1 \wedge \cdots \wedge dx_p^k \left( \frac{\partial}{\partial x^I} \Big|_p \right) = \det \left( df_p^i \left( \frac{\partial}{\partial x^{i_j}} \Big|_p \right) \right) = \frac{\partial(f^1, \dots, f^k)}{\partial(x^{i_1}, \dots, x^{i_k})}(p),$$

which is the determinant of the Jacobian evaluated at  $p$ . Therefore

$$df^1 \wedge \cdots \wedge df^k = \sum_{1 \leq i_1 < \cdots < i_k \leq n} \frac{\partial(f^1, \dots, f^k)}{\partial(x^{i_1}, \dots, x^{i_k})} dx^{i_1} \wedge \cdots \wedge dx^{i_k}.$$

So  $df^1 \wedge \cdots \wedge df^k \in \Omega^k(M)$ . This leads us to ask the question: is it true in general that wedges of smooth forms on  $M$  are also smooth forms on  $M$ ? The answer is yes.

Suppose  $\omega \in \Omega^k(M)$  and  $\eta \in \Omega^\ell(M)$ . In local coordinates, we have

$$\omega \wedge \eta = \left( \sum_I c_I dx^I \right) \wedge \left( \sum_J b_J dx^J \right) = \sum_{I,J} c_I b_J dx^{IJ} \in \Omega^{k+\ell}(M),$$

where  $IJ$  is the multi-index  $\{i_1, \dots, i_k, j_1, \dots, j_\ell\}$ , and all sums are over increasing multi-indices. Therefore the wedge product gives us a map  $\wedge : \Omega^k(M) \times \Omega^\ell(M) \rightarrow \Omega^{k+\ell}(M)$ . (We are not being too careful here, but it doesn't really matter in the end.)

We extend the wedge product to 0-forms in the obvious way: since  $\Omega^0(M) = C^0(M)$ ,  $f \wedge \omega = f\omega$  for  $f \in \Omega^0(M)$  and  $\omega \in \Omega^k(M)$ .

### 1.3 Pullbacks of $k$ -forms

Let  $F : N \rightarrow M$  be a smooth map. We define

$$\begin{aligned} F^{*,p} : \bigwedge^k (T_{F(p)}^* M) &\rightarrow \bigwedge^k (T_p^* N) \\ \theta &\mapsto F^{*,p}(\theta) := \theta \circ (F_{*,p}, \dots, F_{*,p}). \end{aligned}$$

That is, if  $\theta \in \bigwedge^k(T_{F(p)}^*M)$  and  $v_1, \dots, v_k \in T_{F(p)}M$ , then  $F^{*,p}(\theta)(v_1, \dots, v_k) = \theta(F_{*,p}(v_1), \dots, F_{*,p}(v_k))$ .

With this, we define the pullback of a  $k$ -form as follows: if  $\omega$  is a  $k$ -form on  $M$ , define  $F^*\omega$  on  $N$  by

$$(F^*\omega)_p := F^{*,p}\omega_{F(p)} = \omega_{F(p)} \circ (F_{*,p}, \dots, F_{*,p}).$$

The pullback has the following properties:

**Proposition 1.4.** 1.  $F^*(a\omega + \eta) = aF^*\omega + F^*\eta$ .

2. For any  $k$ -form  $\omega$  and  $\ell$ -form  $\eta$ ,  $F^*(\omega \wedge \eta) = F^*\omega \wedge F^*\eta$ . (The pullback distributes over the wedge product.)

3.  $F^* : \Omega^k(M) \rightarrow \Omega^k(N)$ .

*Proof.* We will prove only (3). In local coordinates,

$$\begin{aligned} F^*\omega &= F^*\left(\sum c_I dx^I\right) \\ &= \sum (c_I \circ F) F^*(dx^{i_1} \wedge \cdots \wedge dx^{i_k}) \\ &= \sum (c_I \circ F) d(x^{i_1} \circ F) \wedge \cdots \wedge d(x^{i_k} \circ F) \end{aligned}$$

the sum, as always, ranging over increasing multi-indices. Since each  $d(x^{i_1} \circ F) \wedge \cdots \wedge d(x^{i_k} \circ F)$  is a smooth  $k$ -form,  $F^*\omega$  must be a smooth  $k$ -form.  $\square$

## 1.4 A Remark About Top Degree Forms

Let  $M, N$  be smooth manifolds of common dimension  $n$  with charts  $(V, y^1, \dots, y^n)$  and  $(U, x^1, \dots, x^n)$ , respectively, and let  $F : N \rightarrow M$  be a smooth map with  $F(U) \subseteq V$ , for simplicity. Then

$$\Omega^n(V) = \{f dy^1 \wedge \cdots \wedge dy^n : f \in C^\infty(V)\}$$

is a 1-dimensional  $C^\infty(V)$ -module. On  $U$ ,

$$F^*(dy^1 \wedge \cdots \wedge dy^n) = dF^1 \wedge \cdots \wedge dF^n = \det\left(\frac{\partial F^i}{\partial x^j}\right) dx^1 \wedge \cdots \wedge dx^n,$$

giving us the very important identity

$$F^*(fdy^1 \wedge \cdots \wedge dy^n) = (f \circ F) \det\left(\frac{\partial F^i}{\partial x^j}\right) dx^1 \wedge \cdots \wedge dx^n$$

that we will (likely) use extensively.

Define

$$\Omega^*(M) := \bigoplus_{k=0}^{\infty} \Omega^k(M) = \bigoplus_{k=0}^{\infty} k = 0^n \Omega^k(M).$$

Equipped with the wedge product,  $\Omega^*(M)$  is an associative anticommutative graded algebra over  $\mathbb{R}$ . This is what was meant in the first section of this lesson by "tensors have a very rich algebraic structure." As we can see, the algebraic structure of differential forms on a manifold is *extremely* rich. In particular,  $\Omega^*(M)$  is studied extensively in algebraic topology. (See, for example, de Rham cohomology.)

Next time, we will develop the exterior derivative

$$\begin{aligned} d : \Omega^k(M) &\rightarrow \Omega^{k+1}(M) \\ d : \Omega^*(M) &\rightarrow \Omega^*(M). \end{aligned}$$