

Daniel Patel

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EDUCATION

Massachusetts Institute of Technology

Bachelor of Science in Mechanical Engineering

Relevant Coursework: Thermodynamics, Fluid Mechanics, Robotics, Control Systems, Materials Science, CAD Design

GPA: 3.89/4.0

Cambridge, MA

Aug 2024 – May 2028

TECHNICAL SKILLS

Languages and Technologies: Python, MATLAB, C++, SolidWorks, ANSYS, LabVIEW, ROS

Tools and Frameworks: Git, Docker, AWS, Simulink, Arduino, Raspberry Pi, OpenCV

PROJECTS

Robotic Arm for Precision Assembly | Python, ROS, SolidWorks

- Designed and built a robotic arm for precision assembly tasks in manufacturing
- Implemented inverse kinematics algorithms for accurate movement control
- Conducted performance testing and optimization for industrial applications

Autonomous Vehicle Simulation | C++, ROS, Gazebo

- Built a simulation environment for autonomous vehicle navigation using ROS and Gazebo
- Implemented path planning and obstacle avoidance algorithms
- Conducted performance testing and optimization for real-world deployment

Energy-Efficient HVAC System | MATLAB, Simulink, ANSYS

- Designed an energy-efficient HVAC system for commercial buildings
- Optimized thermal performance using computational fluid dynamics (CFD)
- Developed a control system for real-time energy management

RESEARCH EXPERIENCE

Research Assistant - Robotics Lab

Massachusetts Institute of Technology

Jan 2023 – May 2024

Cambridge, MA

- Conducted research on swarm robotics and multi-agent systems
- Developed algorithms for collaborative task execution in robotic swarms
- Published findings in a leading robotics journal

WORK EXPERIENCE

Mechanical Engineering Intern

General Electric

Jun 2024 – Aug 2024

Boston, MA

- Designed and tested components for gas turbine engines
- Conducted thermal and structural analysis for engine components
- Collaborated with cross-functional teams to meet project deadlines

Software Development Intern

Boston Dynamics

May 2023 – Aug 2023

Waltham, MA

- Developed software for robotic control systems
- Implemented algorithms for motion planning and obstacle avoidance
- Optimized code for real-time performance in dynamic environments