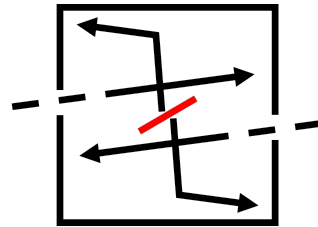
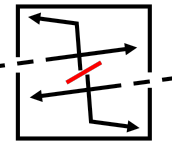


# STM32F407VET6 Digital Synthesizer with screen

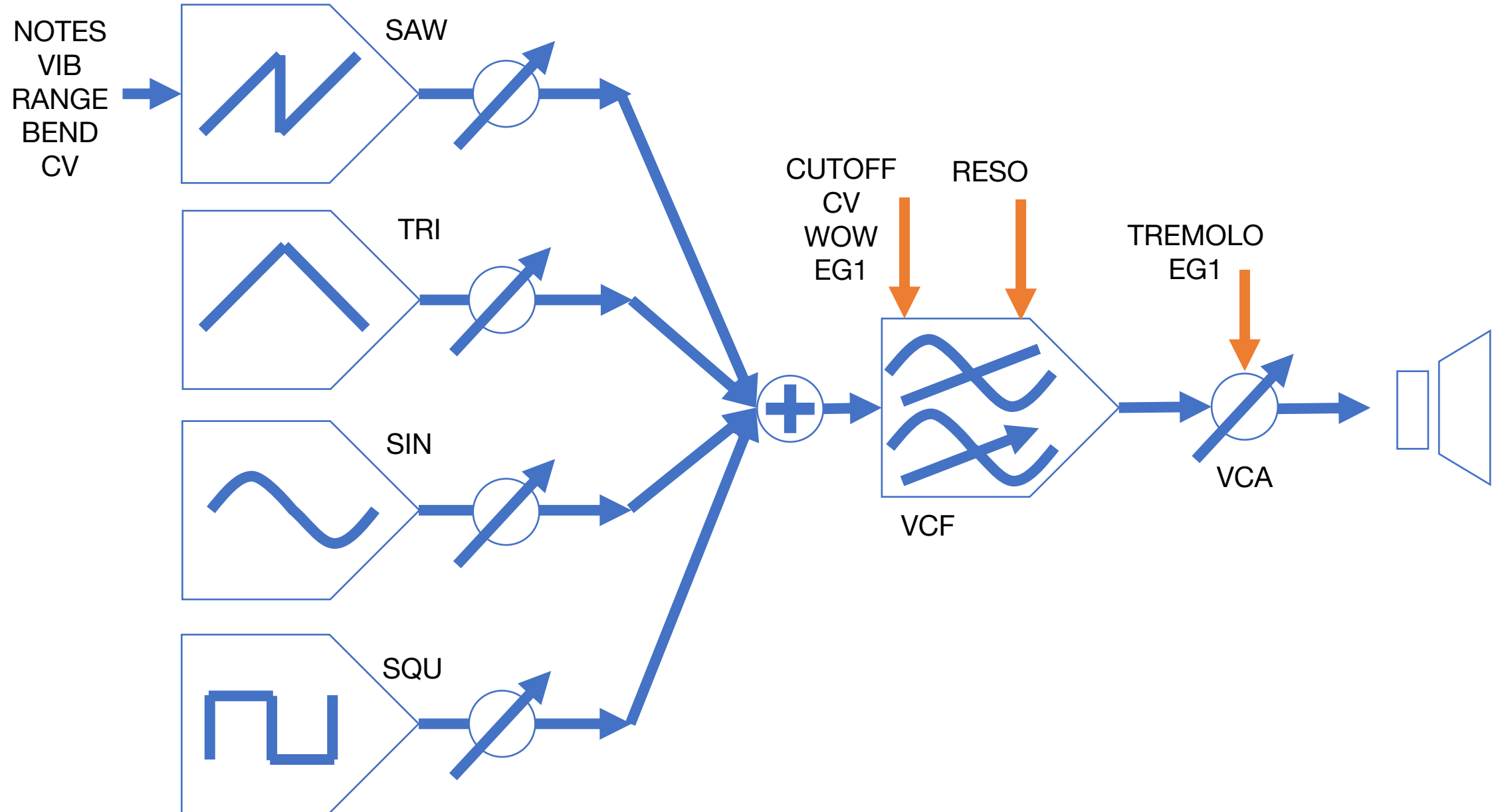
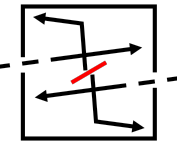
Update: 2020/12/29



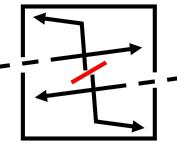


# Overview

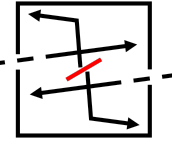
# Block diagram



# Parameter list (Will be expanded)

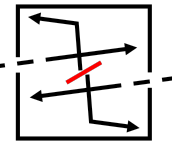


| Parameter | Description                            |
|-----------|--|
| T_1_FREQ  | First signal frequency                 |
| T_1_SIN   | Sine amplitude of the first signal     |
| T_1_SQU   | Square amplitude of the first signal   |
| T_1_SAW   | Saw amplitude of the first signal      |
| T_1_TRI   | Triangle amplitude of the first signal |
| F_CUTOFF  | Cutoff frequency of Low-Pass filter    |
| F_Q       | Q value of Low-Pass filter             |



# Design

# Sampling specifications

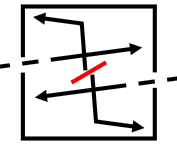


|                | Freq domain | Time domain |
|----------------|-------------|-------------|
| Sound max freq | 20kHz       | 50us        |
| Sound min freq | 20Hz        | 50ms        |
| Sampling freq  | 40kHz       | 25us        |

## Note

- Create a waveform by dividing into 1024 samples
- 12bit DAC → audio level 0 = 2048
- DAC Clock source 84MHz
  - ✓ Prescaler 100(840kHz, 1.19us), Period 21(21\*1.19us=25us)

# Sampling specifications



DMA Circular

Structure of DAC buffer

→ DAC position

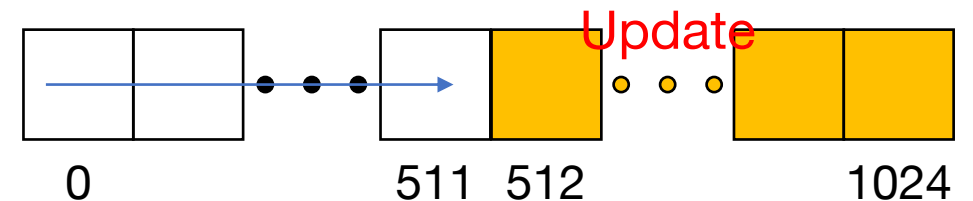
DAC start



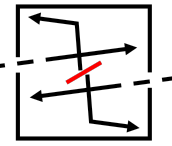
Half of the buffer is complete



All of the buffer is complete

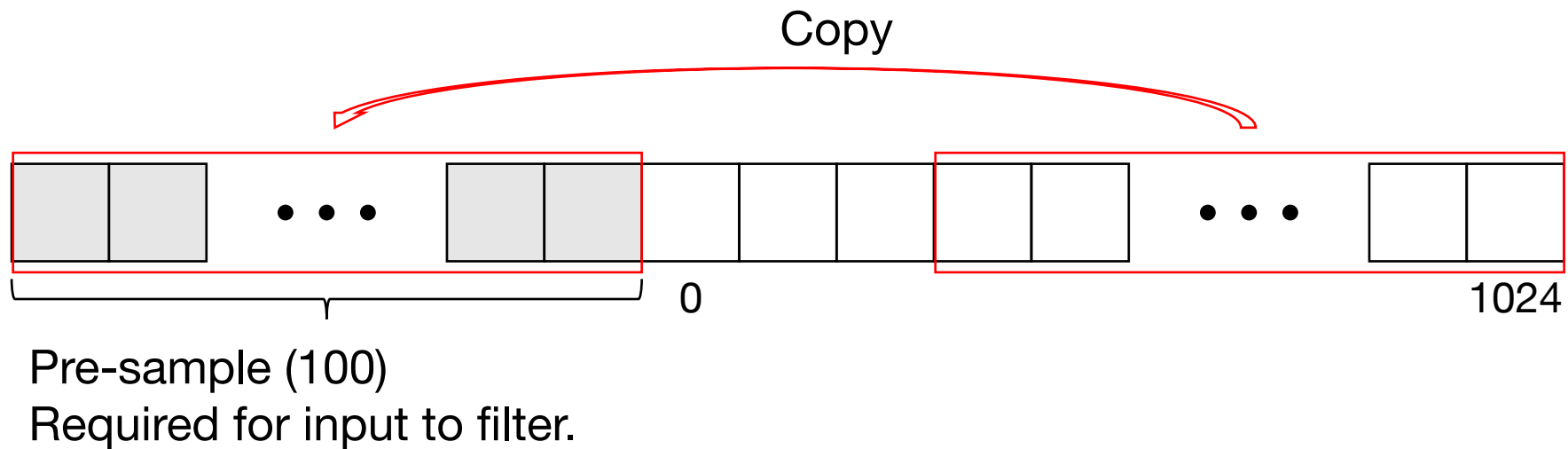


# Sampling specifications



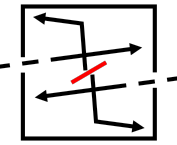
## Structure of sampling array

- Reserve a buffer of size  $100 + 1024$
- Only 1024 parts are used in DAC
- Add 100 samples at the beginning to obtain stationary filter output
- Copy the end of the previous buffer to the beginning





# Filter specifications



## Note

- biquad filter
- Normalize as  $a_0=1$

$$H(z) = \frac{b_0 + b_1 z^{-1} + b_2 z^{-2}}{a_0 + a_1 z^{-1} + a_2 z^{-2}} \quad \omega_c = \frac{2\pi f_c}{f_s} \quad \alpha = \frac{\sin \omega_c}{Q}$$

## LPF

### Time domain

$$b_0 = \frac{1 - \cos \omega_c}{2}$$

$$a_0 = 1 + \alpha$$

$$b_1 = 1 - \cos \omega_c$$

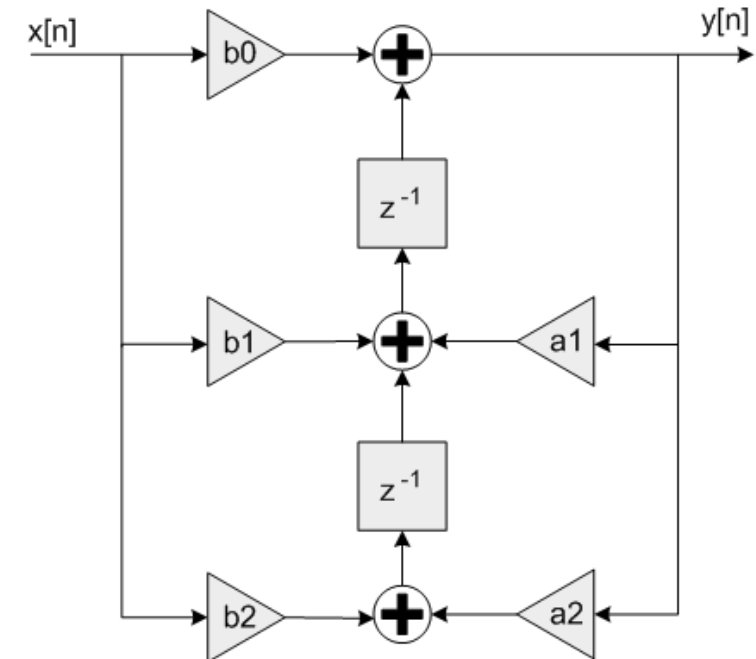
$$a_1 = 2 \cos \omega_c$$

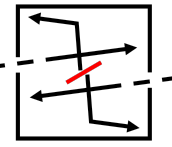
$$b_2 = \frac{1 - \cos \omega_c}{2}$$

$$a_2 = -(1 - \alpha)$$

### Freq domain

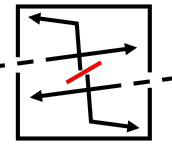
$$|H(\omega)| = \frac{\omega_c^2}{\sqrt{(\omega_c^2 - \omega^2)^2 + \left(\frac{\omega_c}{Q} \omega\right)^2}} = \frac{\frac{\omega_c}{\omega}}{\sqrt{\left(\frac{\omega_c}{\omega}\right)^2 + \left(\frac{\omega}{\omega_c}\right)^2 + \frac{1}{Q^2} - 2}}$$





# Communication

# Controller connection specifications



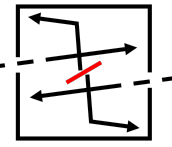
## SPI

- SPI3 as slave

## Data format

- Unsigned 4 byte

|            |             |           |
|------------|-------------|-----------|
| uint8_t[0] | Lower byte  | Parameter |
| uint8_t[1] | Higher byte |           |
| uint8_t[2] | Lower byte  | Value     |
| uint8_t[3] | Higher byte |           |



# Implementation

# Spectrum of DAC output at 100Hz(Sine)

