

# Heaps

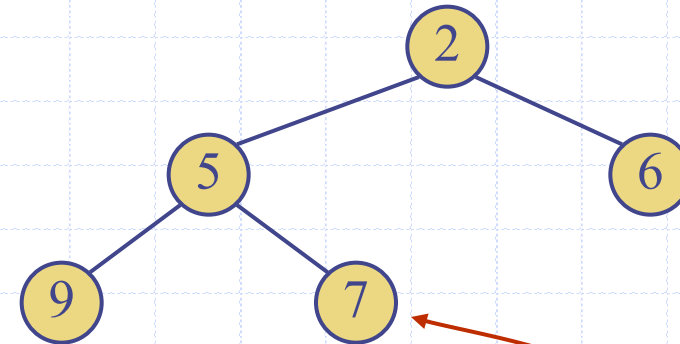
## Readings - Chapter 9



# Heaps

- A heap is a binary tree storing keys at its nodes and satisfying the following properties:
- **Heap-Order:** for every internal node  $v$  other than the root,  
 $key(v) \geq key(parent(v))$
- **Complete Binary Tree:** let  $h$  be the height of the heap
  - for  $i = 0, \dots, h - 1$ , there are  $2^i$  nodes of depth  $i$
  - at depth  $h - 1$ , the internal nodes are to the left of the external nodes
- The **last node** of a heap is the rightmost node of maximum depth

heap property

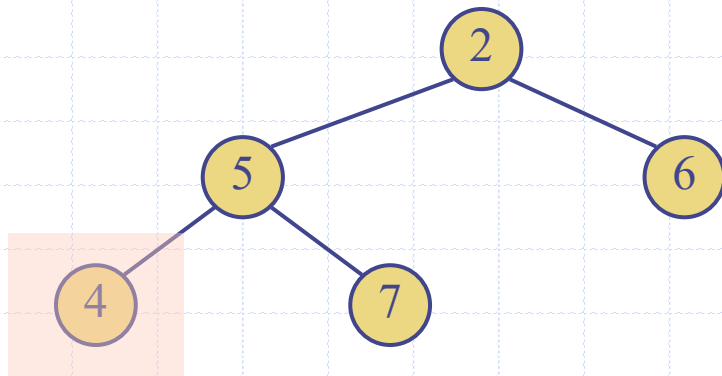


last node

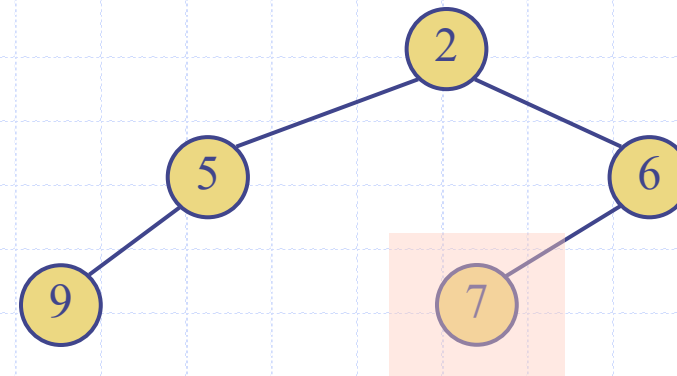
Structural property

# Example of non-Heaps

- Heap property violation



- Structural property violation



# Finding the minimum element

- The element with the smallest key value always sits at the root of the heap.
  - If it is elsewhere, it would have a parent with a larger key, thus violating the heap property.
  - hence finding the minimum can be done in  $O(1)$  time

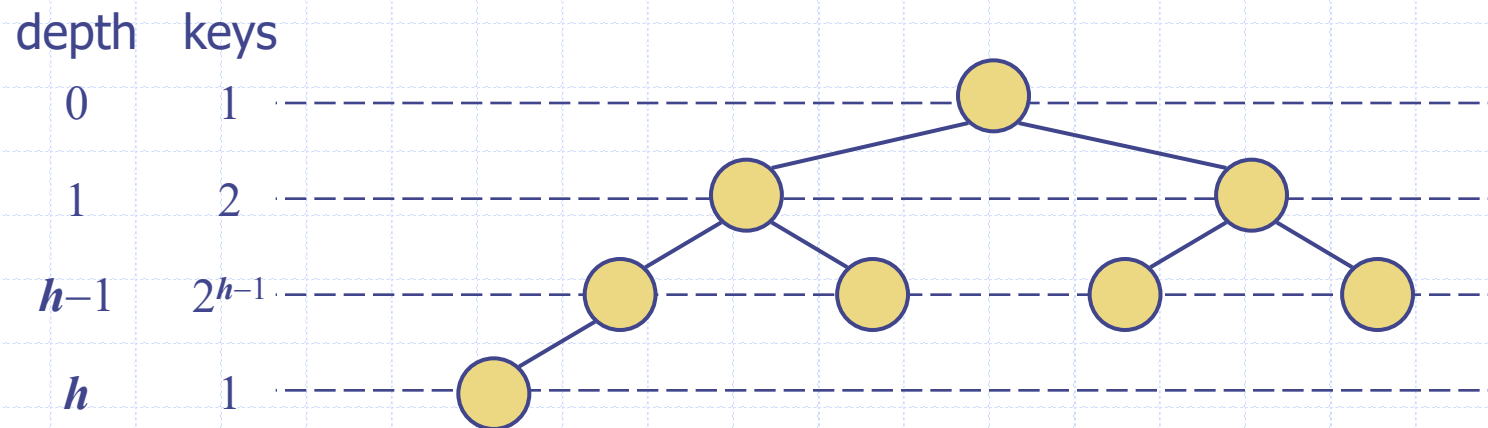
# Height of a Heap



- **Theorem:** A heap storing  $n$  keys has height  $O(\log n)$

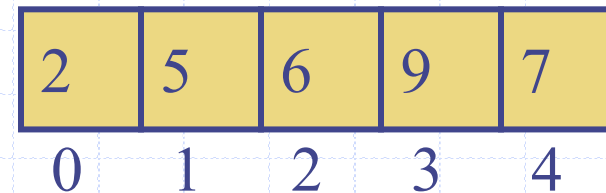
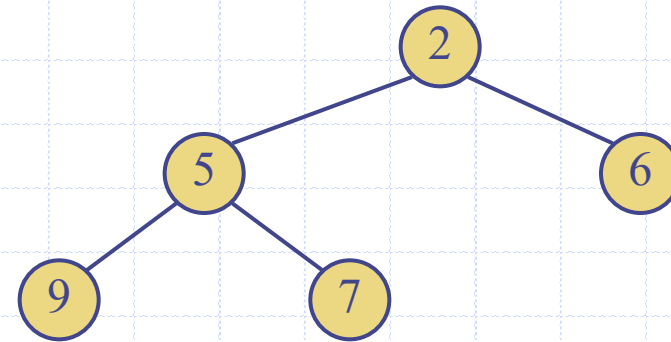
Proof: (we apply the complete binary tree property)

- Let  $h$  be the height of a heap storing  $n$  keys
- Since there are  $2^i$  keys at depth  $i = 0, \dots, h-1$  and at least one key at depth  $h$ , we have  $n \geq 1 + 2 + 4 + \dots + 2^{h-1} + 1$
- Thus,  $n \geq 2^h$ , i.e.,  $h \leq \log n$



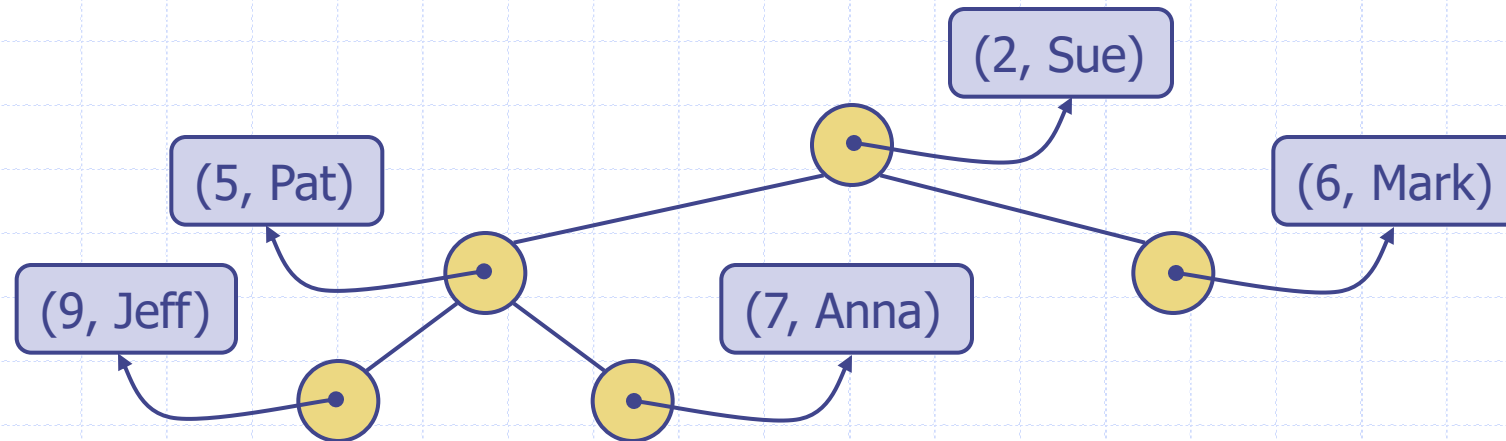
# Array-based Heap Implementation

- We can represent a heap with  $n$  keys by means of an array of length  $n$
- For the node at index  $i$ 
  - the left child is at index  $2i + 1$
  - the right child is at index  $2i + 2$
  - $\text{parent}(i)$  is  $\text{floor}((i-1)/2)$
- Operation **add** corresponds to inserting at index  $n + 1$
- Operation **remove\_min** corresponds to removing at index  $n$



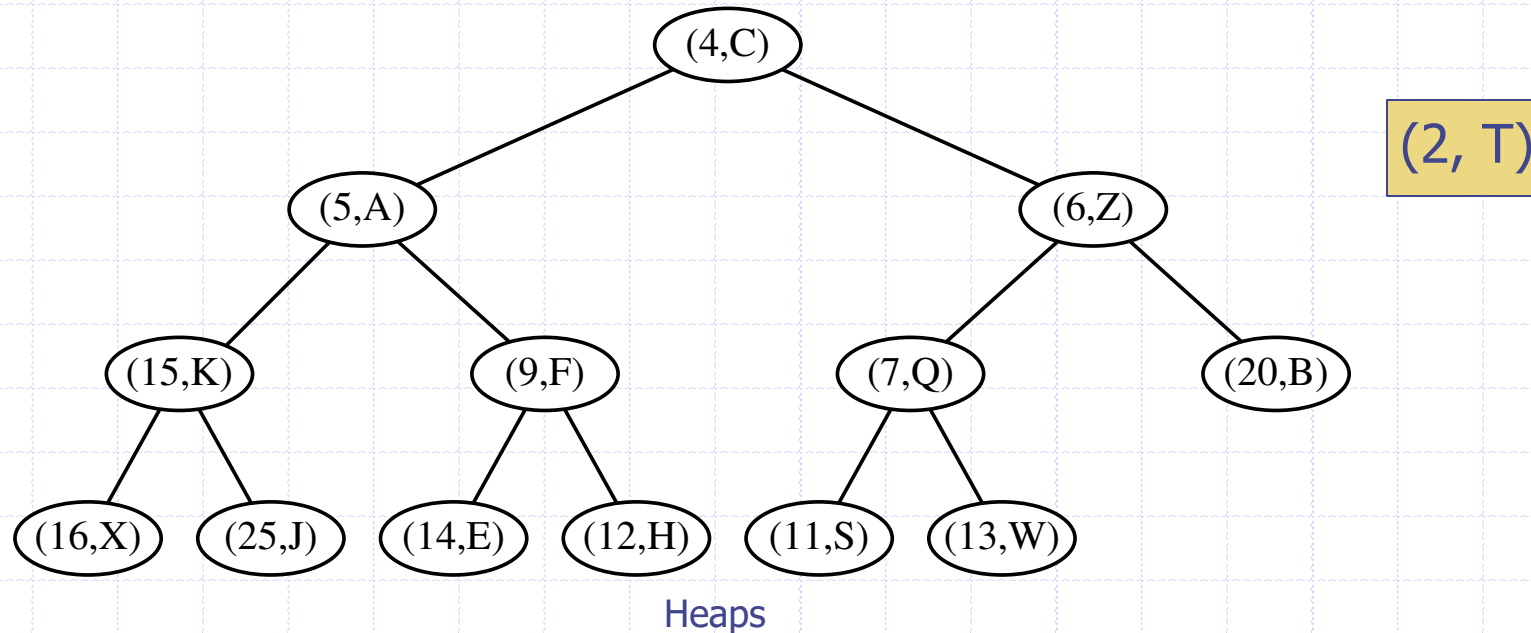
# Heaps and Priority Queues

- ❑ We can use a heap to implement a priority queue
- ❑ We store a (key, element) item at each internal node
- ❑ We keep track of the position of the last node



# Insertion into a Heap

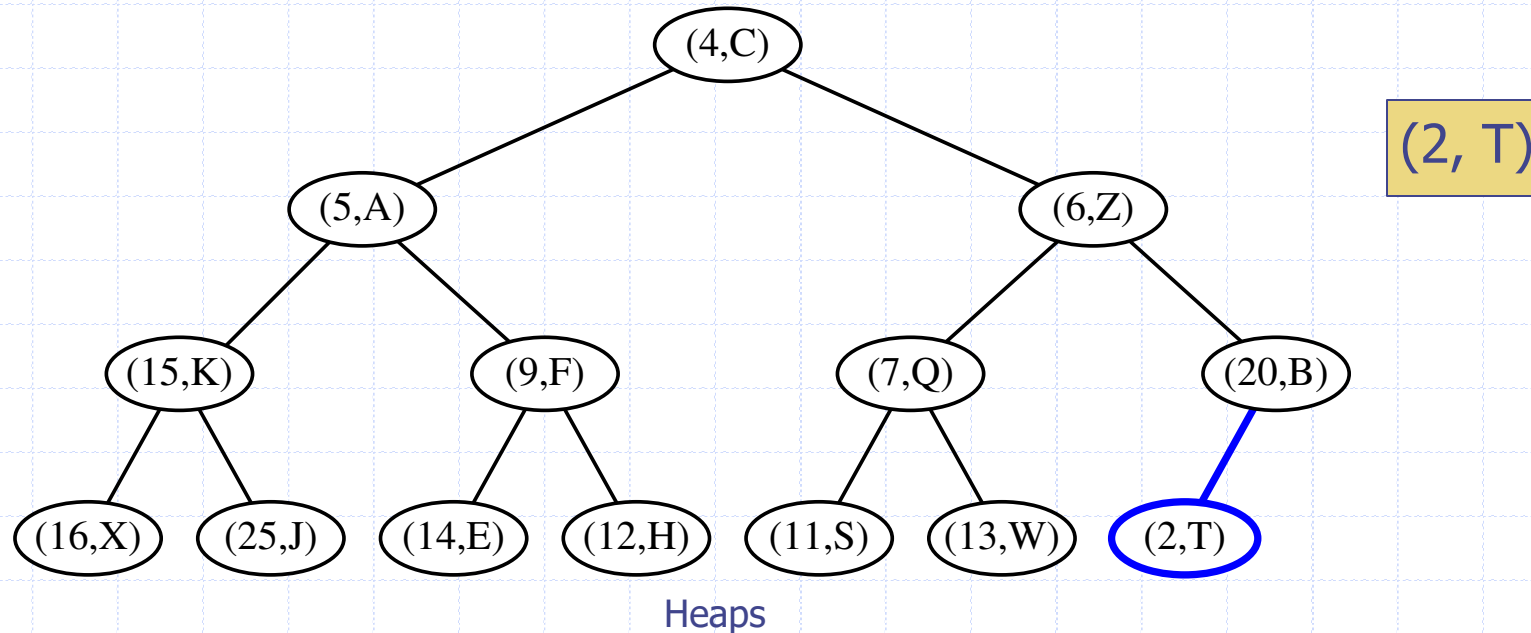
- ❑ Method `insertItem` of the priority queue ADT corresponds to the insertion of a key  $k$  to the heap
- ❑ The insertion algorithm consists of three steps
  - Find the insertion node  $z$  (the new last node)
  - Store  $k$  at  $z$
  - Restore the heap-order property (discussed next)





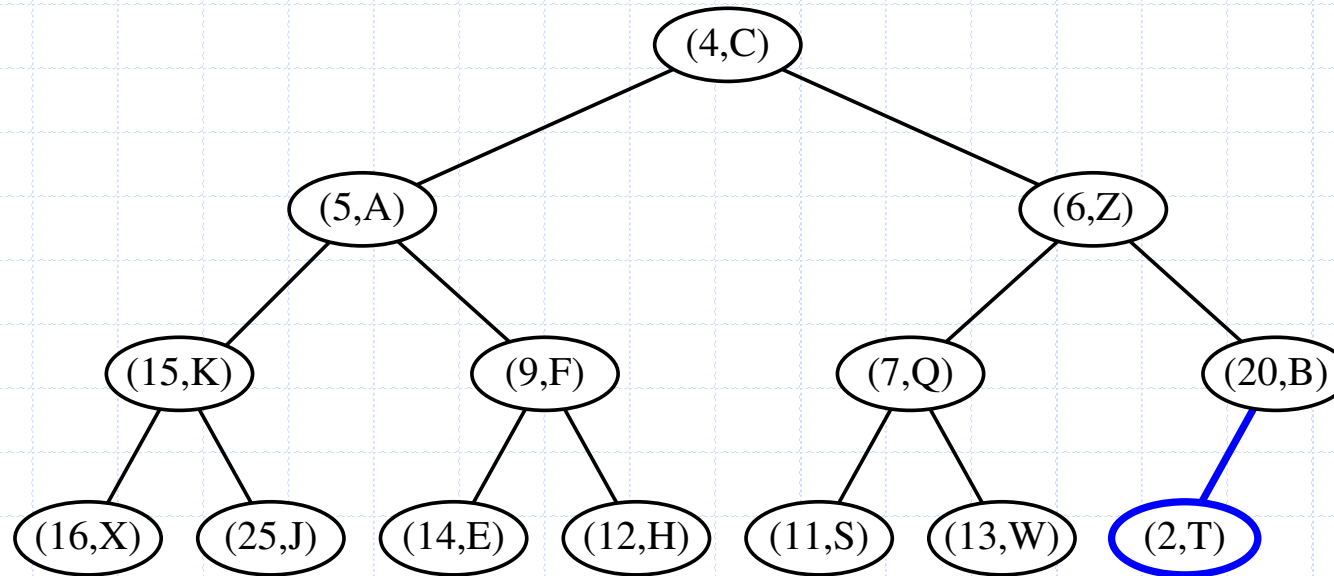
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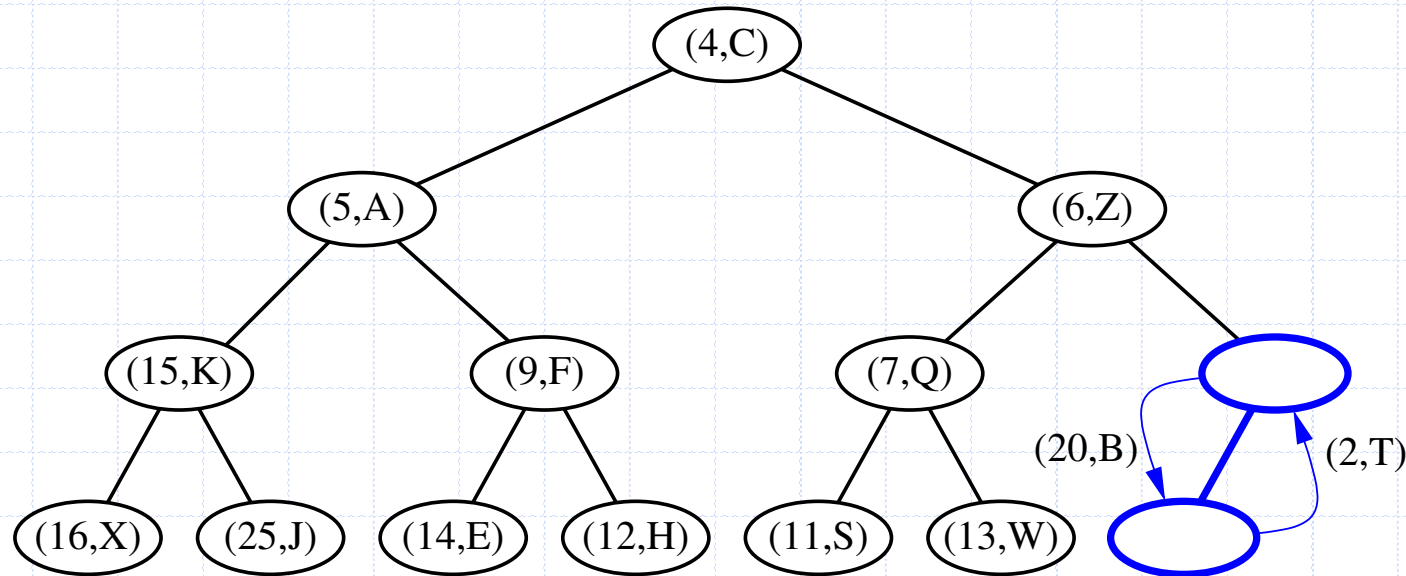
# Upheap

- ❑ After the insertion of a new key  $k$ , the heap-order property may be violated
- ❑ Algorithm upheap restores the heap-order property by swapping  $k$  along an upward path from the insertion node
- ❑ Upheap terminates when the key  $k$  reaches the root or a node whose parent has a key smaller than or equal to  $k$
- ❑ Since a heap has height  $O(\log n)$ , upheap runs in  $O(\log n)$  time



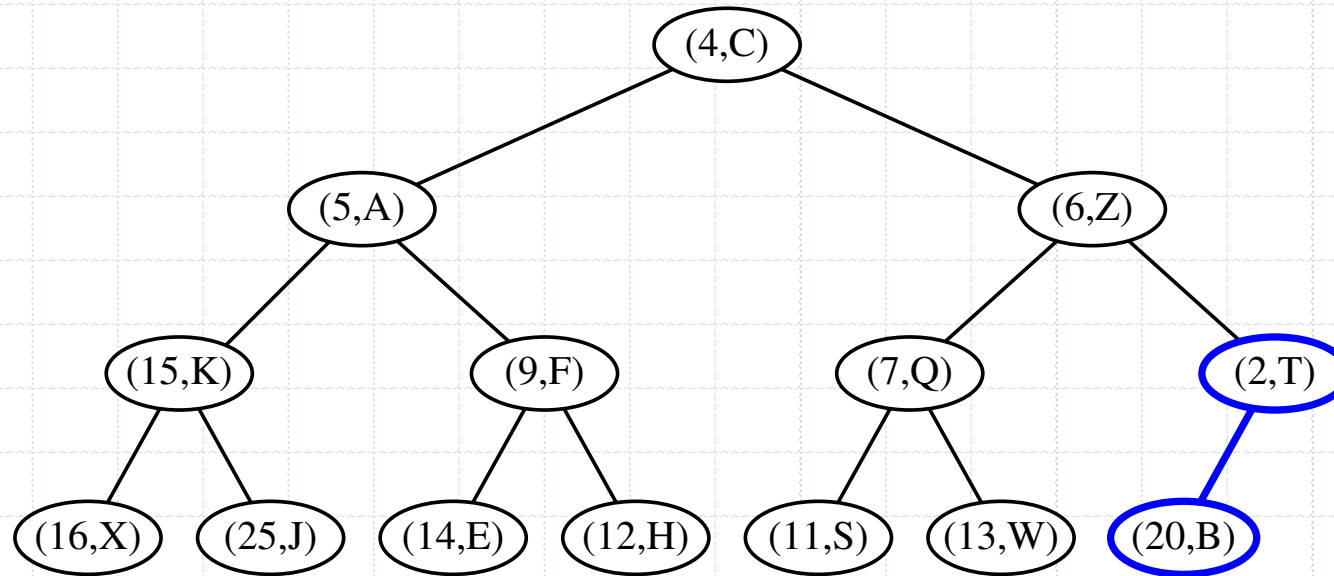
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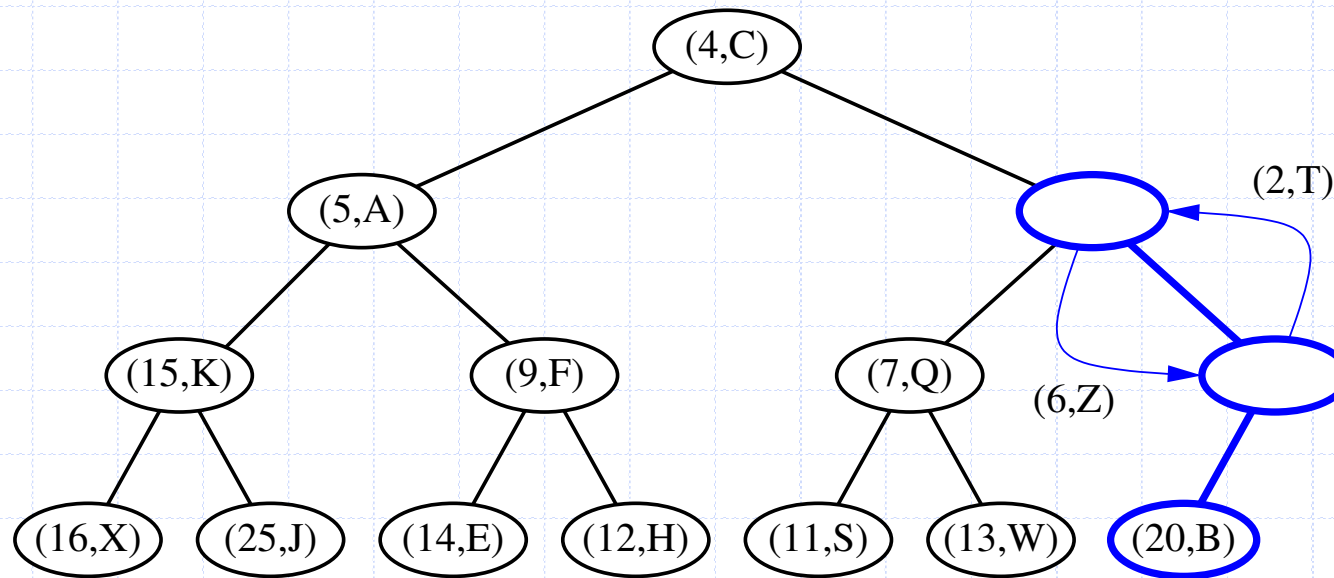
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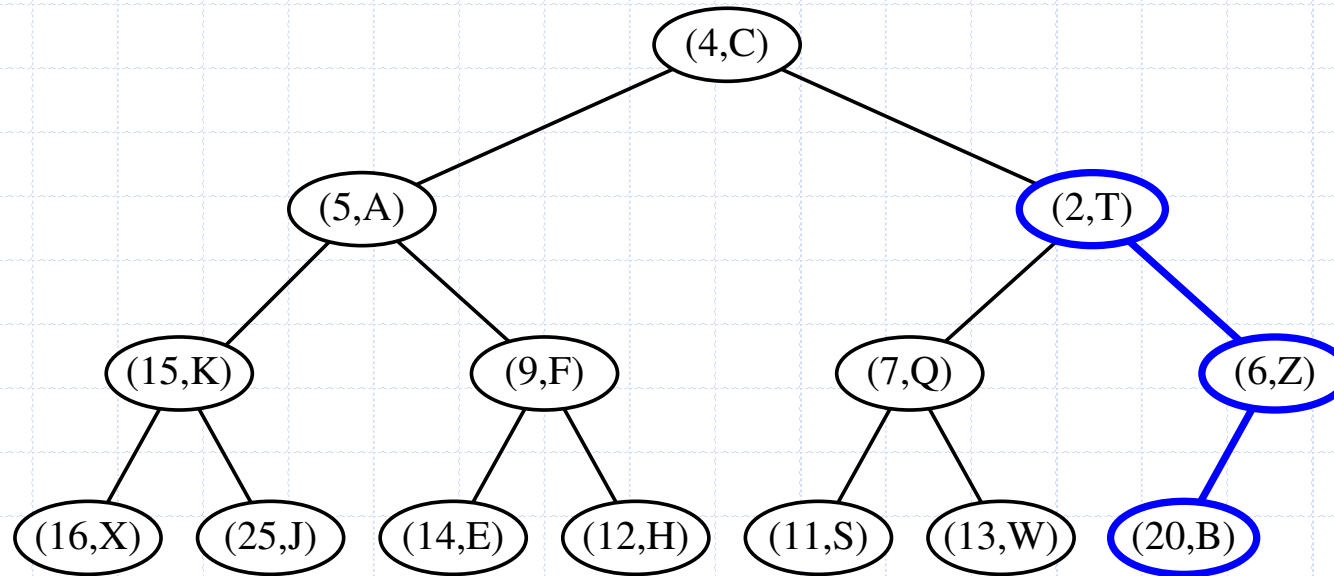
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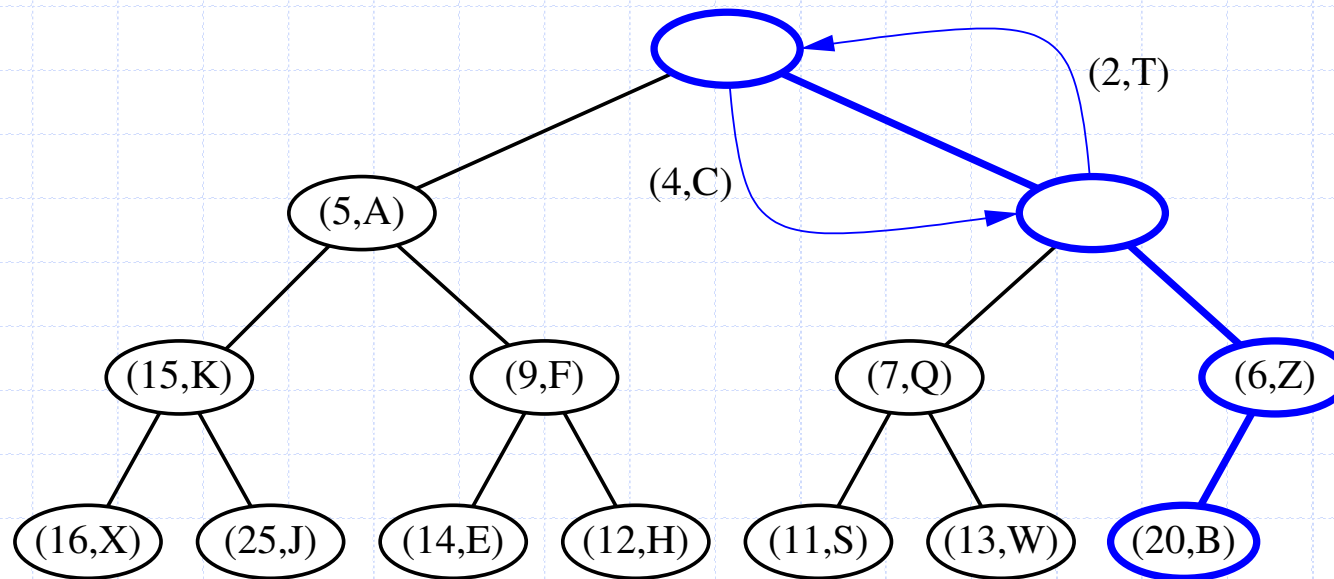
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# Upheap

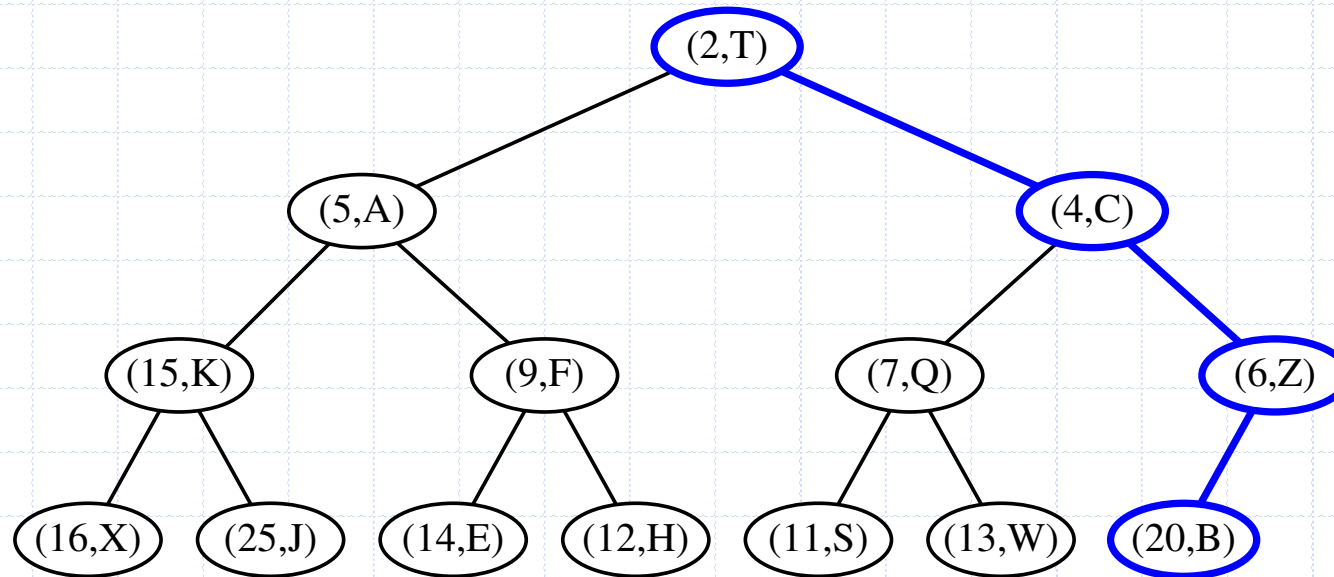
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Heaps

# Upheap

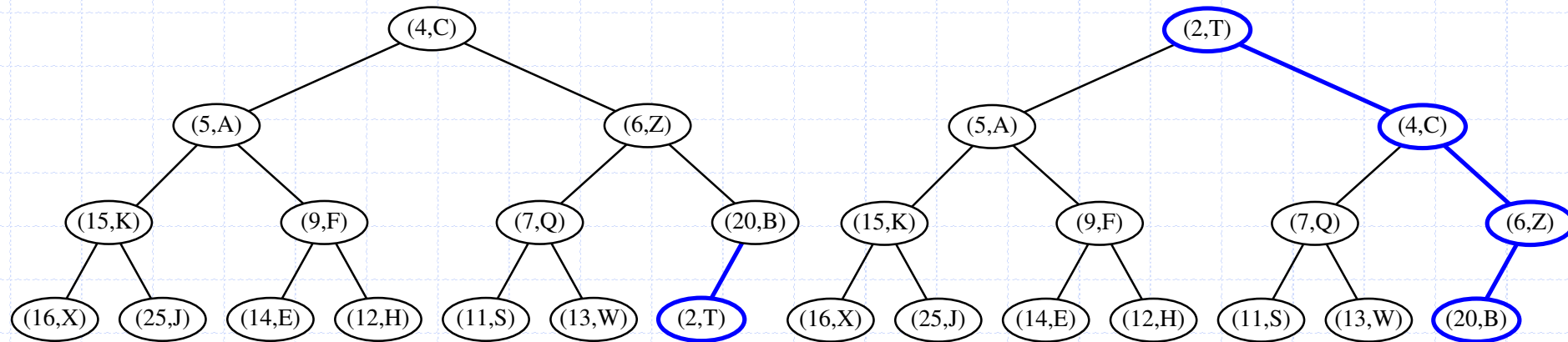
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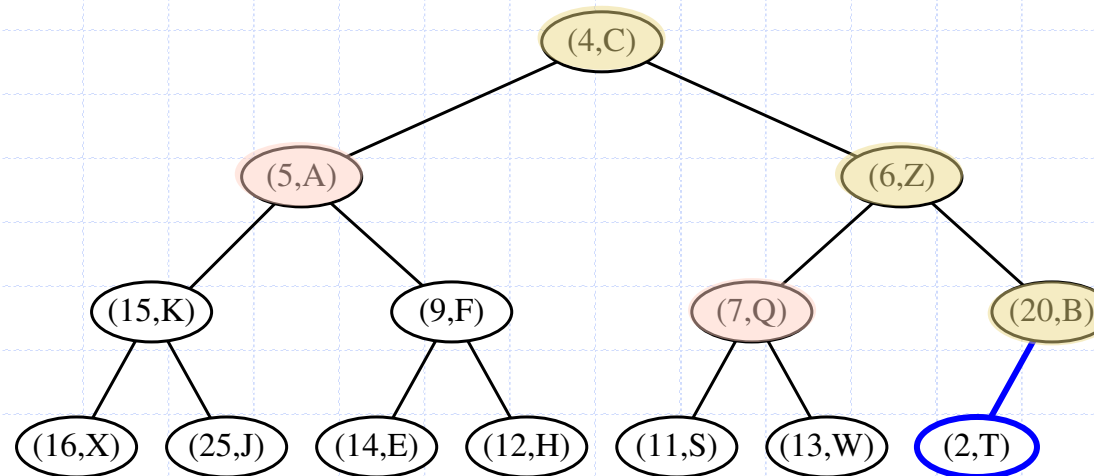
# Another View of Insertion

- ❑ Enlarge heap
- ❑ Consider path from root to inserted node
- ❑ Find topmost element on this path with higher priority than of inserted element
- ❑ Insert new element at this location by shifting down the other elements on the path



# Correctness of Upheap

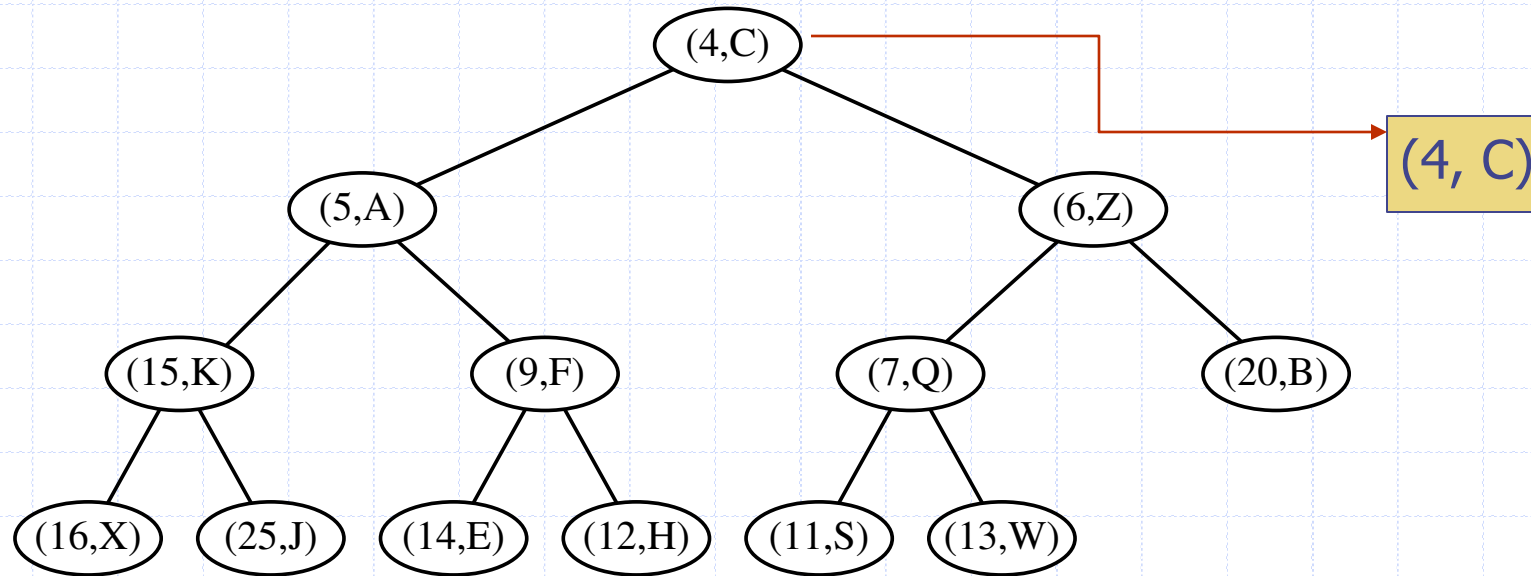
- ❑ The only nodes whose contents change are the ones on the path
- ❑ Heap property may be violated only for children on these nodes
- ❑ But new contents of these nodes only have lower priority
- ❑ So heap property is not violated



Heaps

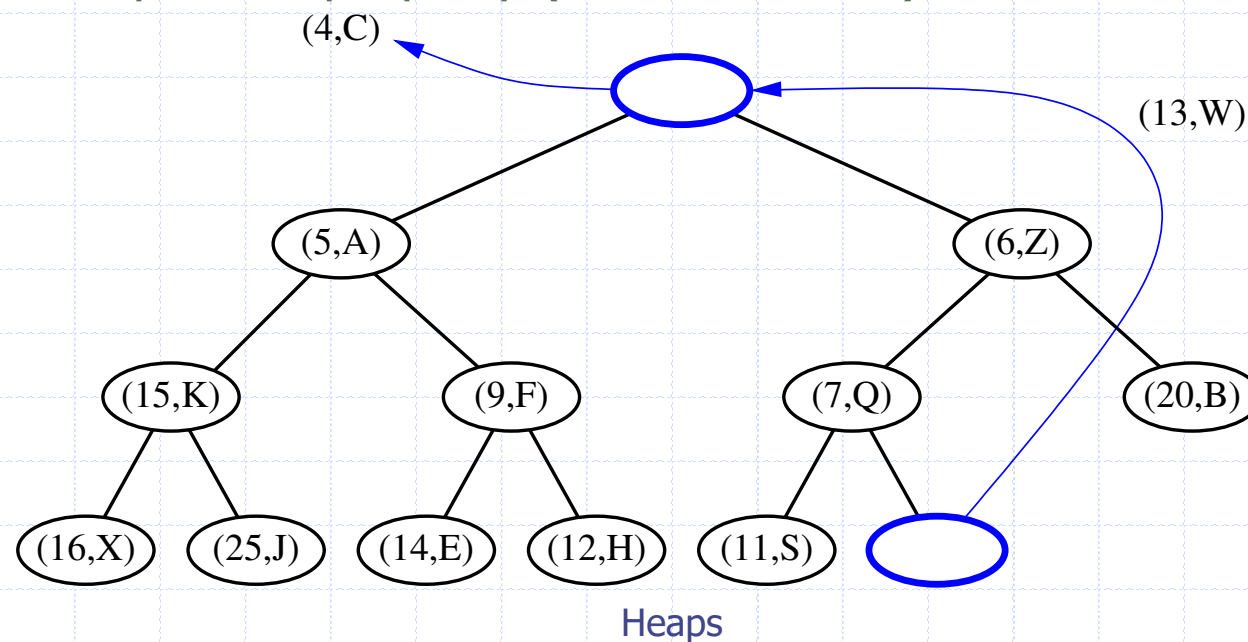
# Removal from a Heap

- ❑ Method removeMin of the priority queue ADT corresponds removing the root key from the heap
- ❑ The removal algorithm consists of three steps
  - Replace the root key with the key of the last node  $w$
  - Remove  $w$
  - Restore the heap-order property (discussed next)



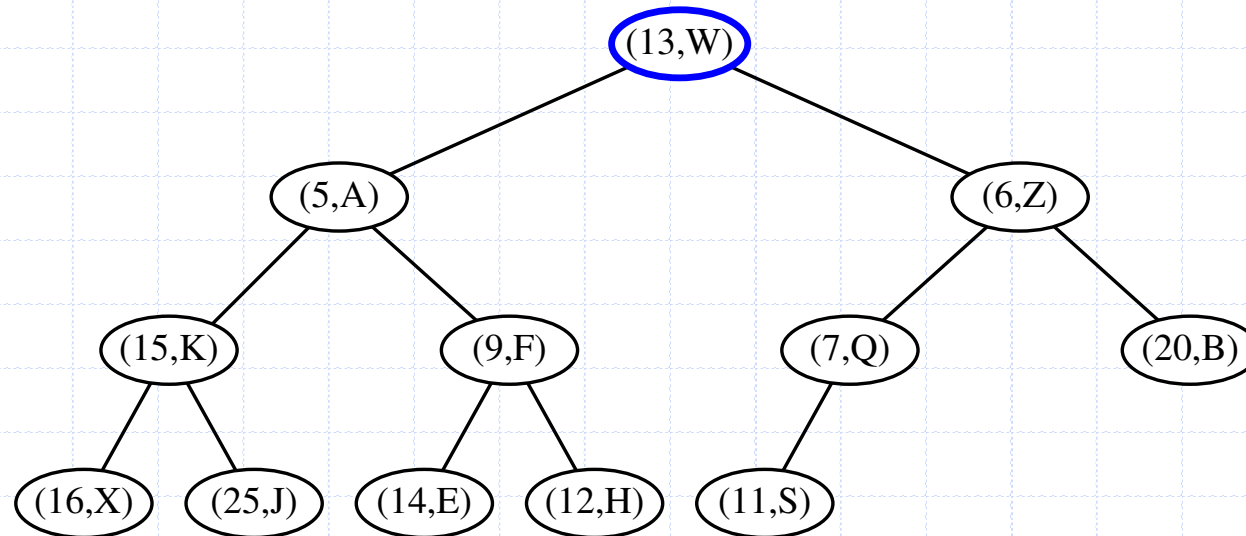
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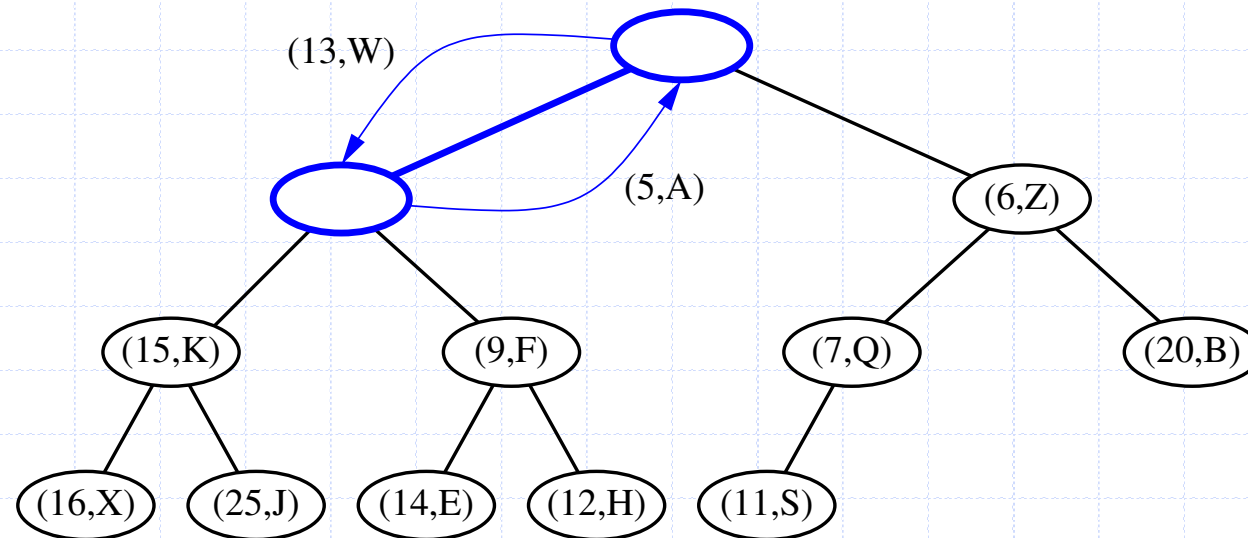
# Downheap

- ❑ After replacing the root key with the key  $k$  of the last node, the heap-order property may be violated
- ❑ Algorithm downheap restores the heap-order property by swapping key  $k$  along a downward path from the root
- ❑ Downheap terminates when key  $k$  reaches a leaf or a node whose children have keys greater than or equal to  $k$
- ❑ Since a heap has height  $O(\log n)$ , downheap runs in  $O(\log n)$  time



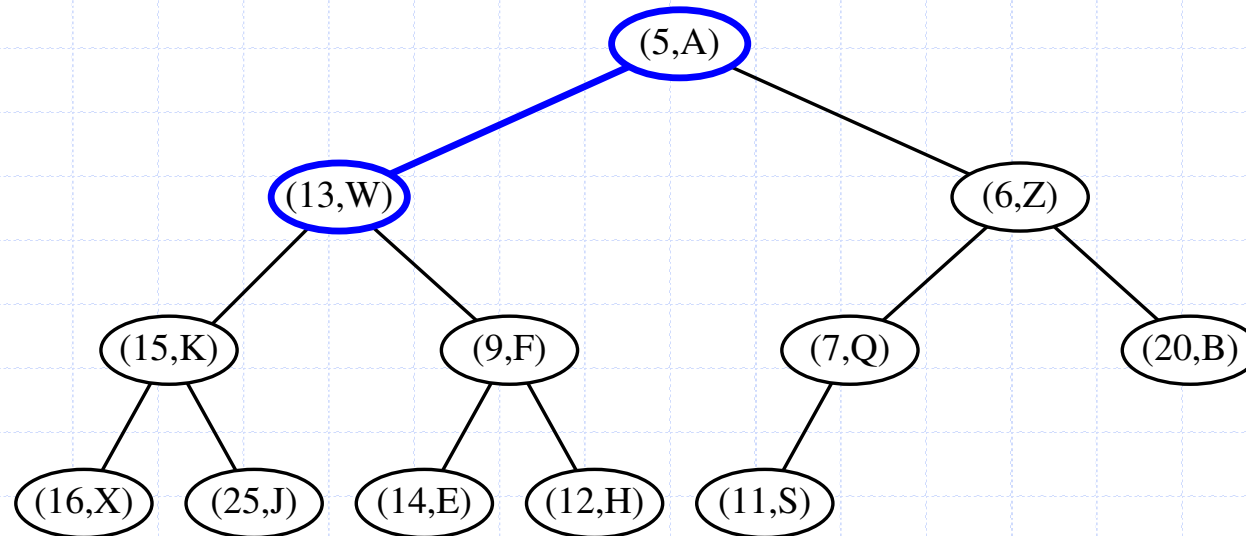
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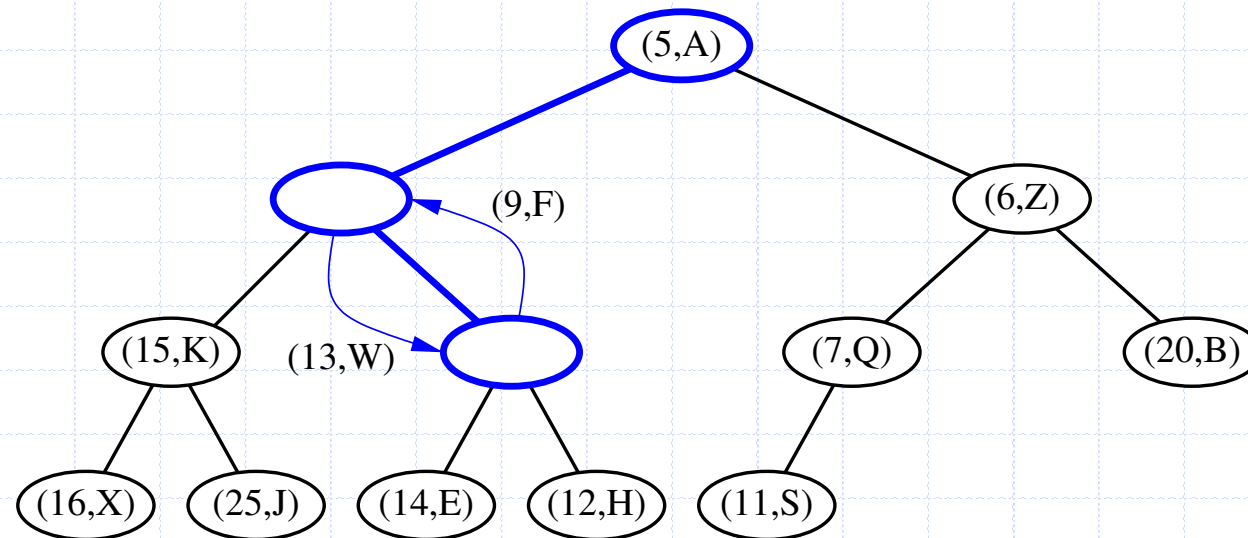
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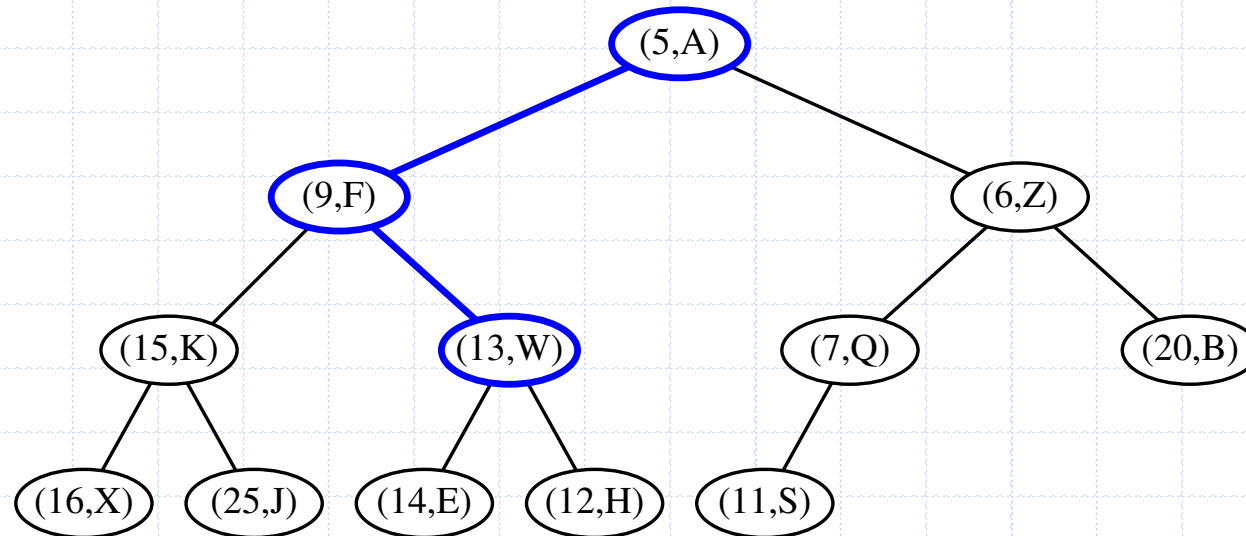
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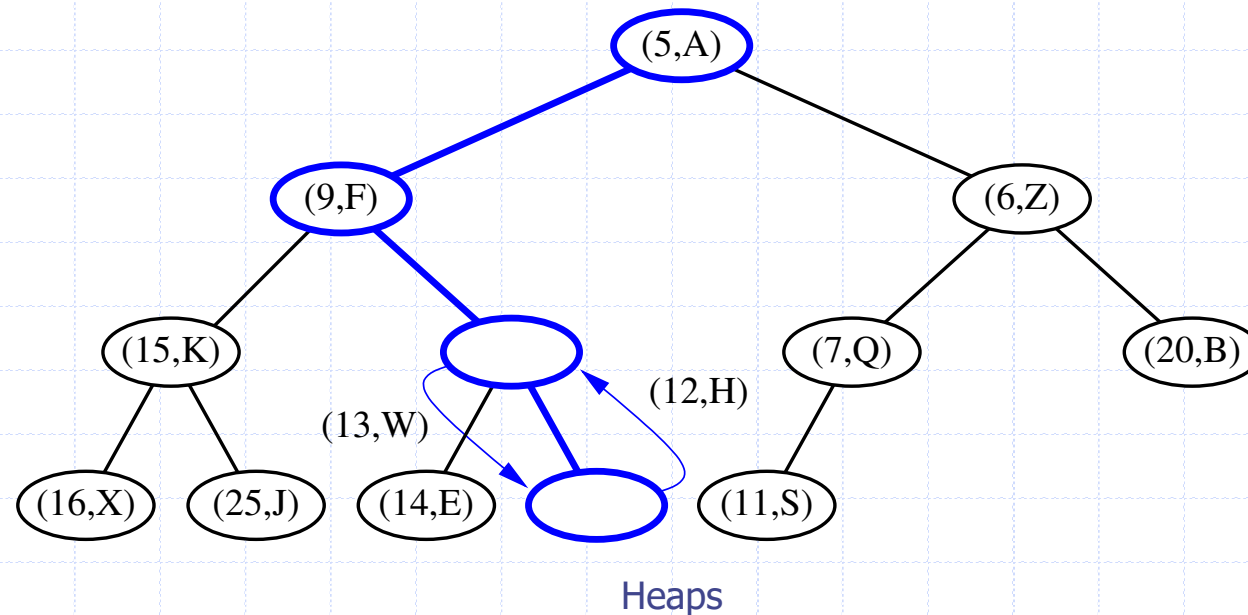
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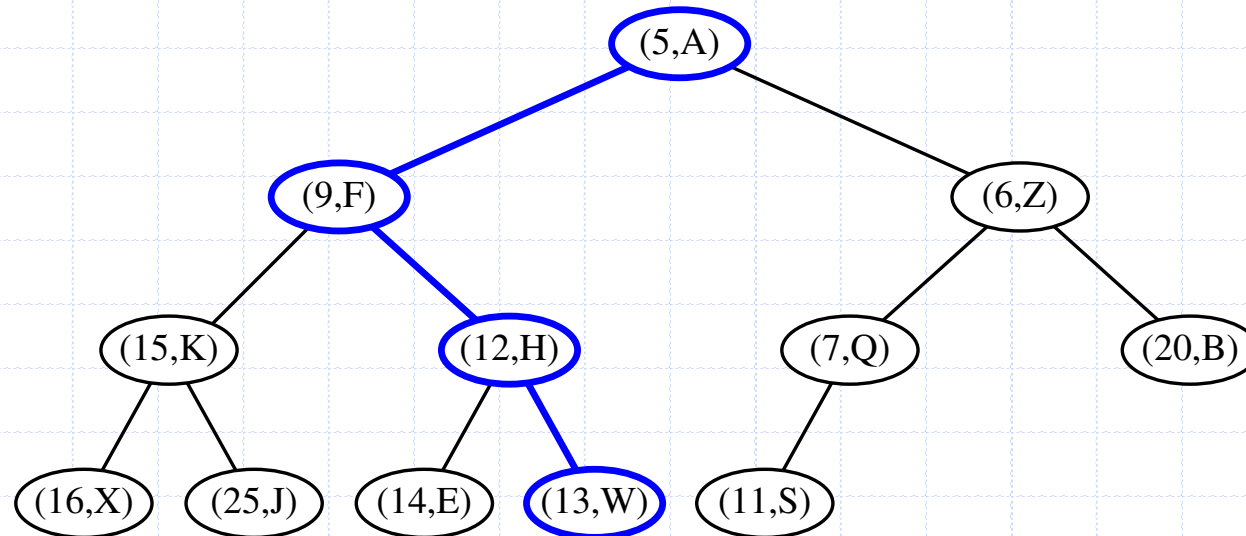
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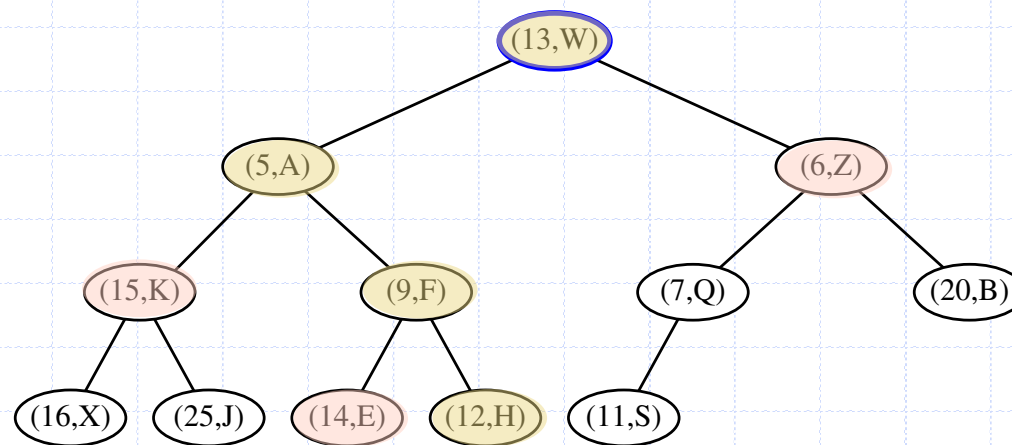
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# Correctness of Downheap

- ❑ Downheap traces a path down the tree
- ❑ For a node on the path (say  $j$ ) - both  $key(left(j))$  and  $key(right(j)) > key(j)$
- ❑ All elements on path have lower key values than their siblings
- ❑ All elements on this path are moved up.
- ❑ Hence the heap property is not violated.



# Run Time Analysis

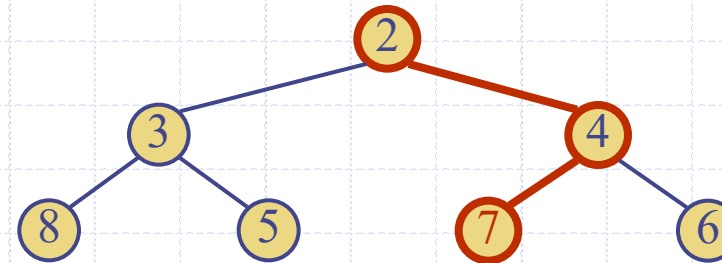
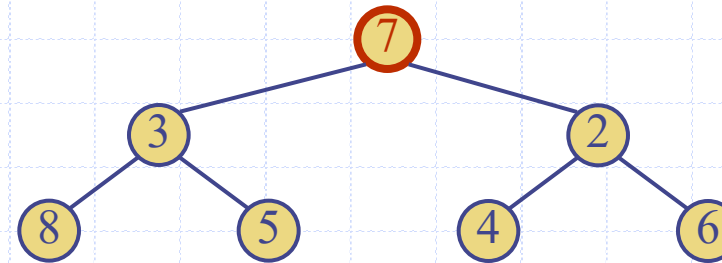
- heap of  $n$  nodes has height  $O(\log n)$
- insertion - Upheap – move the element all the way to the top
  - $O(\log n)$  steps in worst case
- removal – Downheap – move the root element all the way to a leaf
  - $O(\log n)$  steps in worst case

# Building a heap

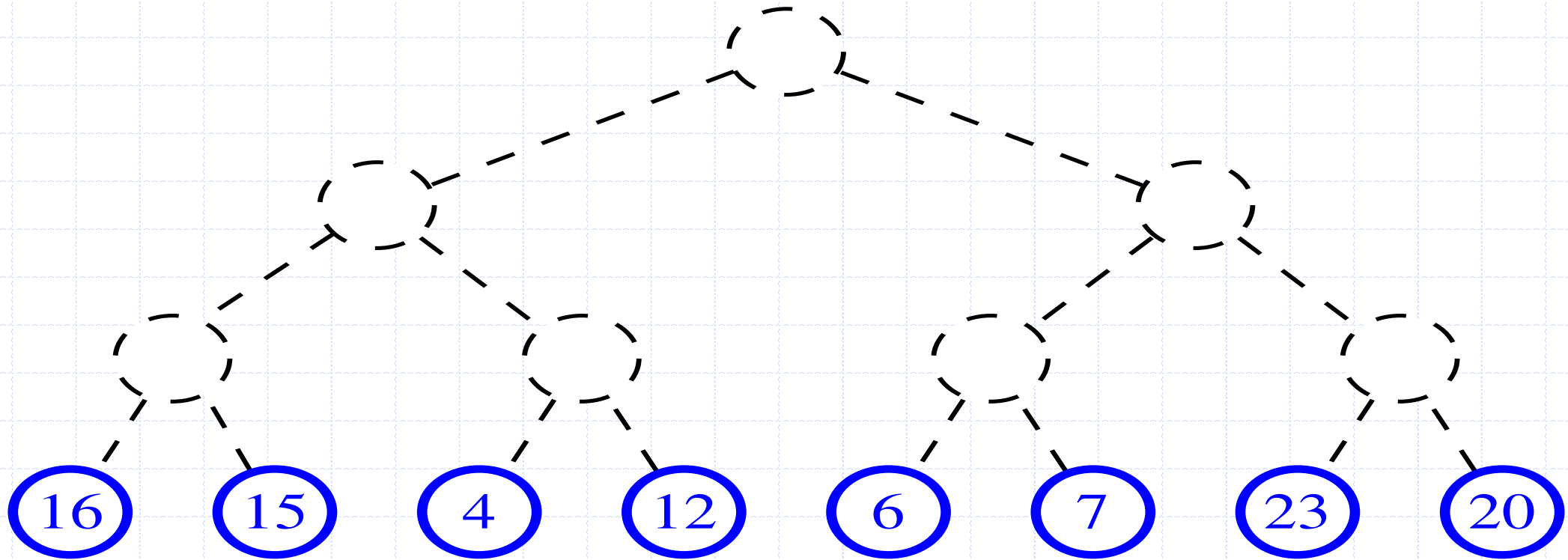
- Call Upheap procedure of the heap  $n$  times.
  - Upheap is  $O(\log n)$
  - inserting first element –  $O(\log 1)$
  - inserting second element –  $O(\log 2)$
  - ..
  - inserting the  $n$ th element –  $O(\log n)$
  - so for the  $n$  insertions –  $\log 1 + \log 2 + \dots + \log n = \log n! = O(n \log n)$

# Merging Two Heaps

- We are given two heaps and a key  $k$
- We create a new heap with the root node storing  $k$  and with the two heaps as subtrees
- We perform Downheap to restore the heap-order property

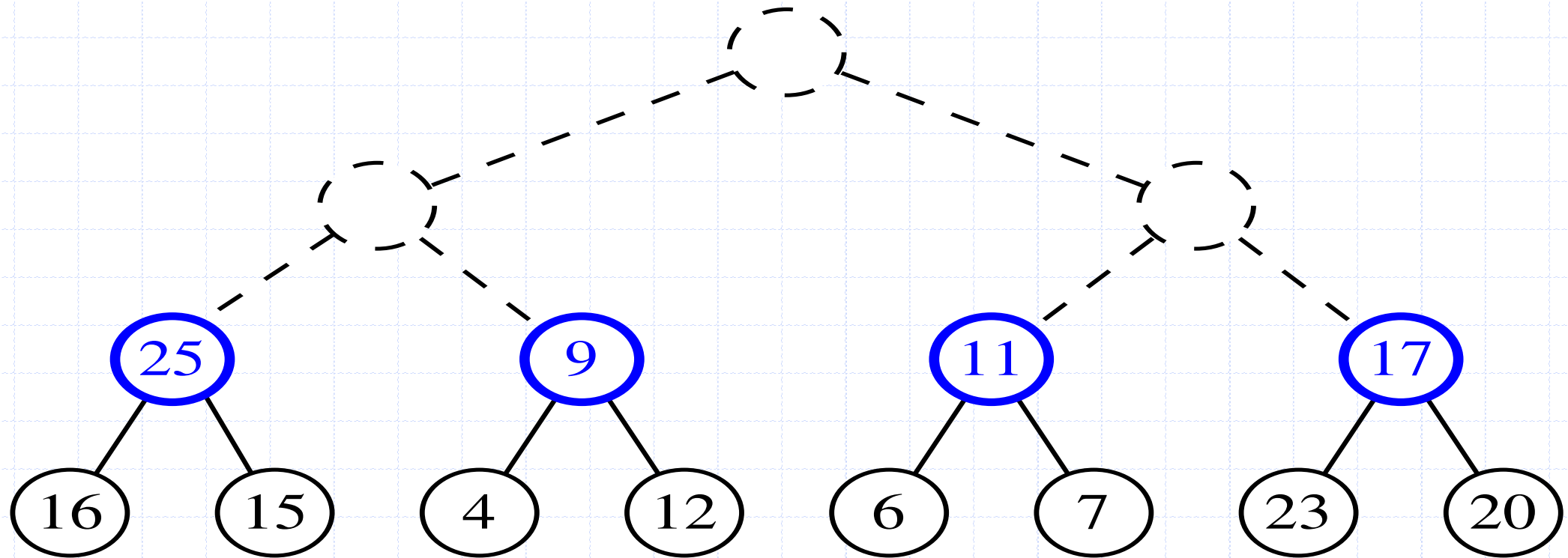


# Building a Heap – Bottomup

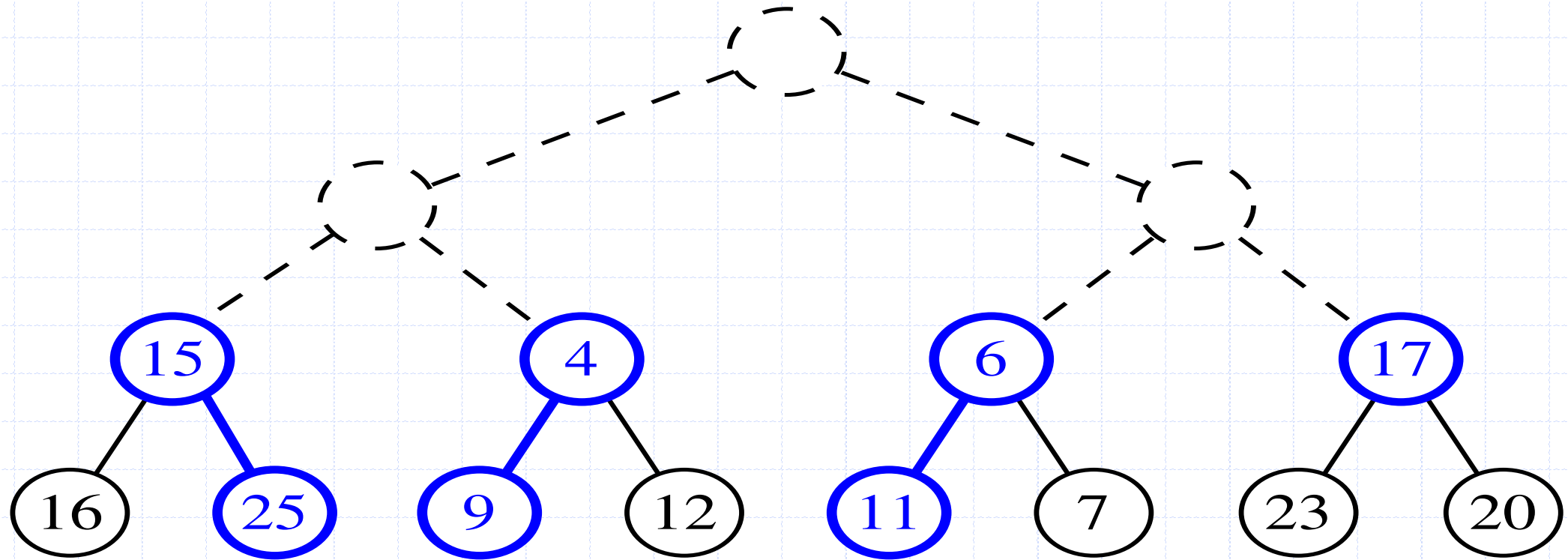




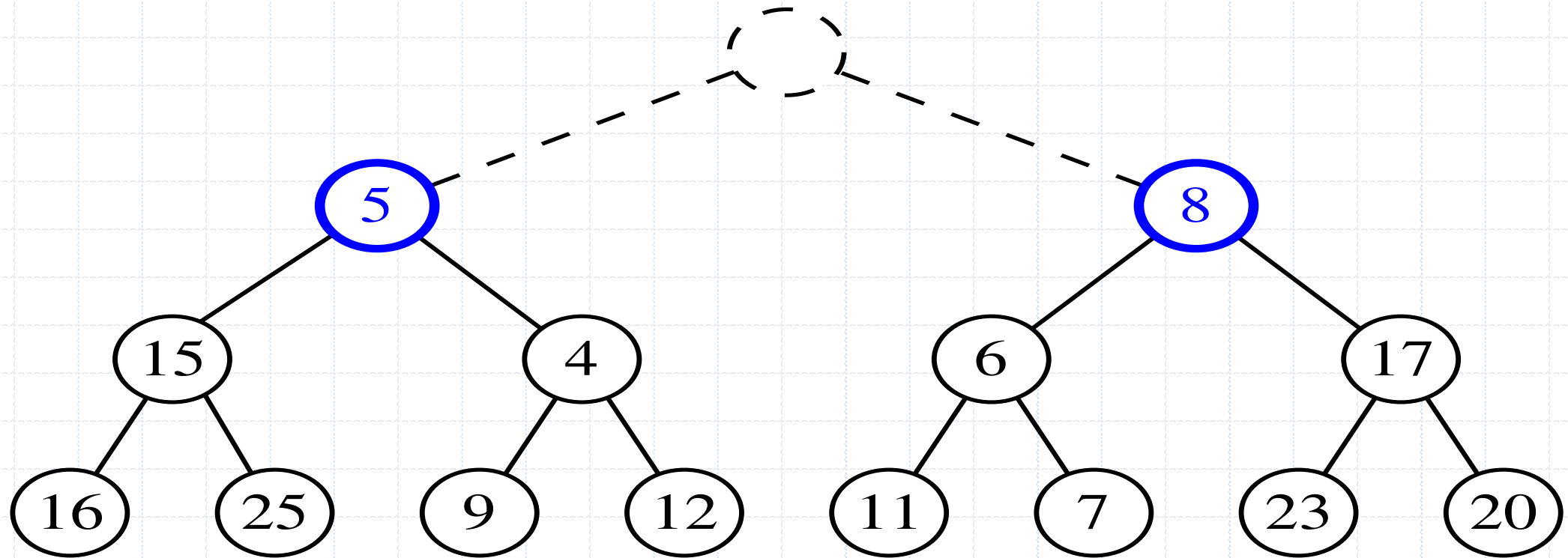
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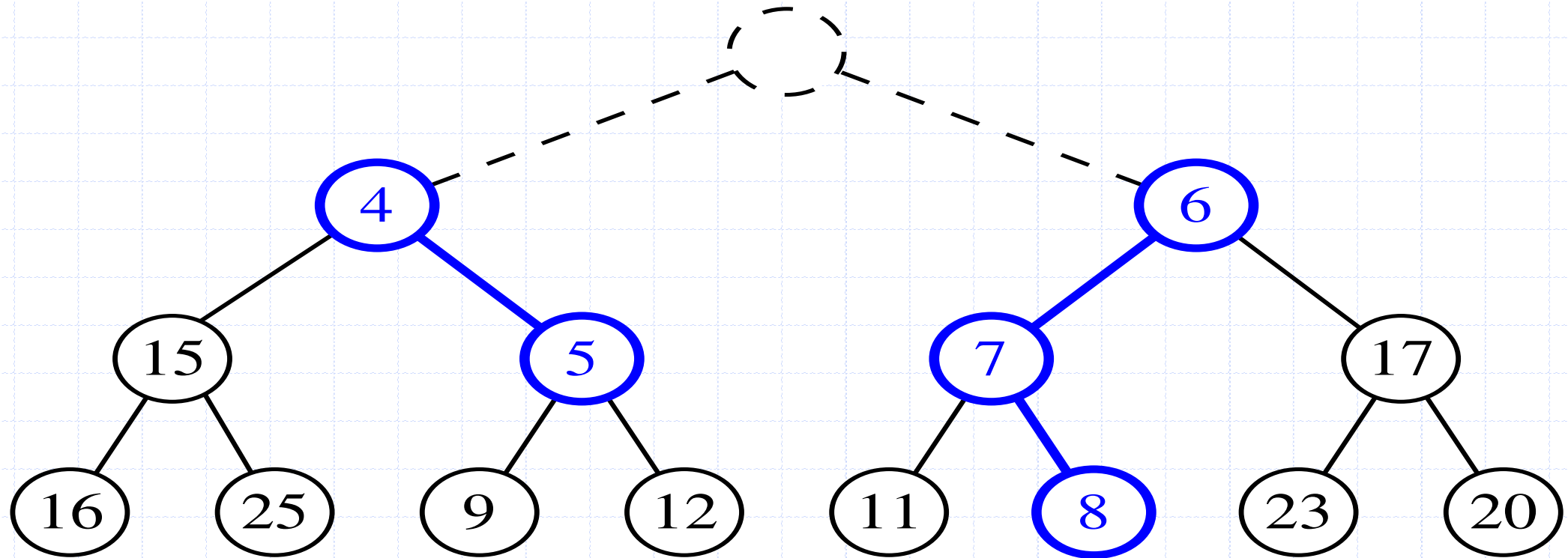
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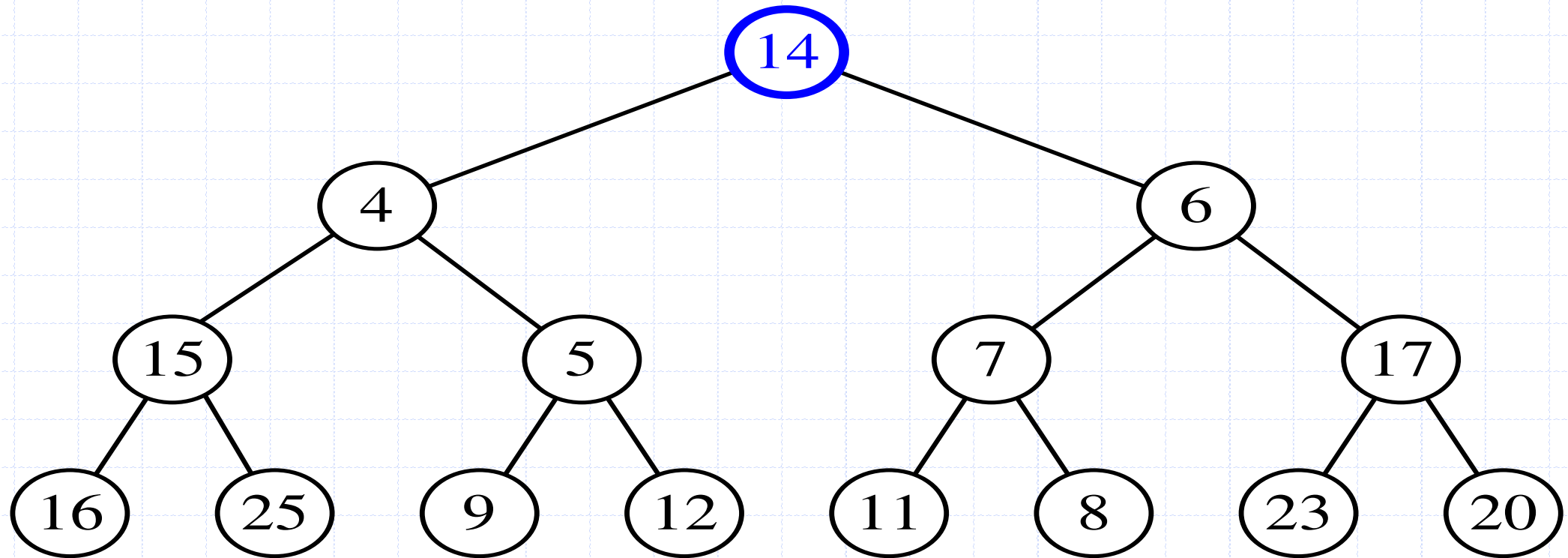
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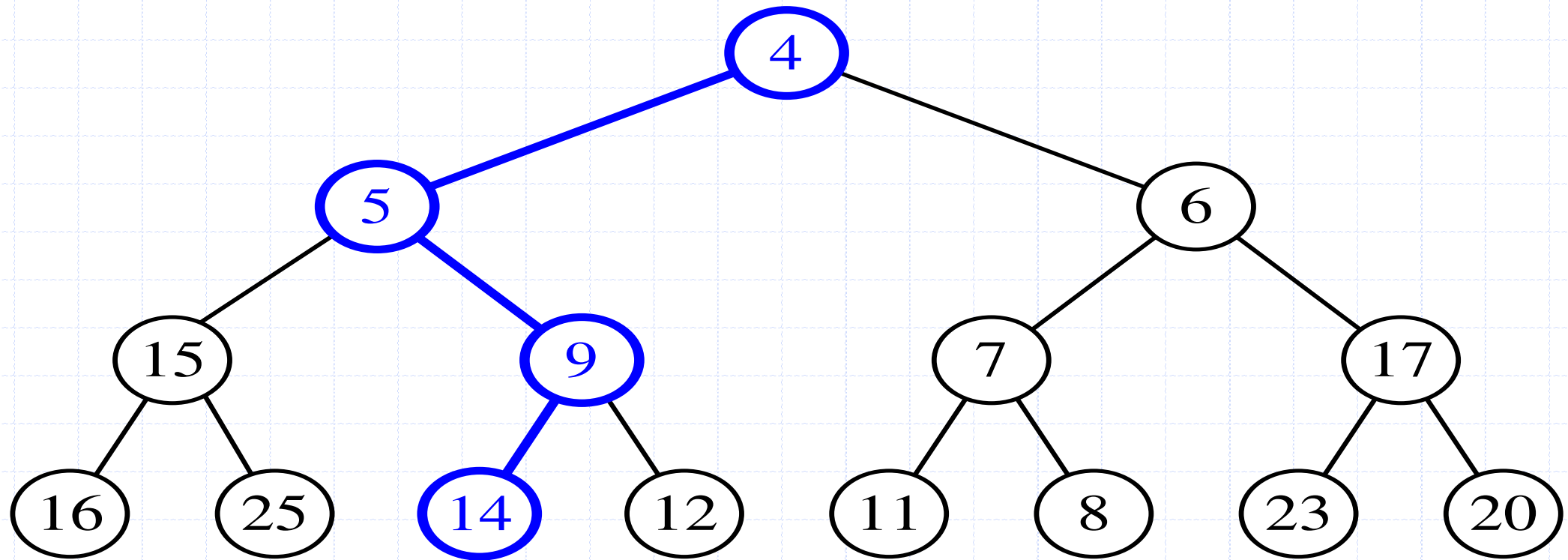
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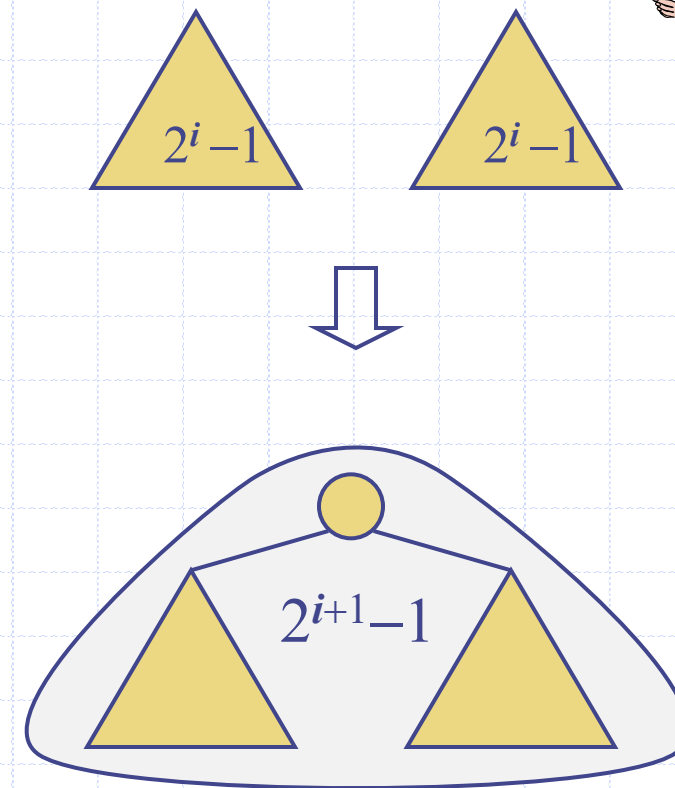


# Building a Heap – Bottomup



# Bottom-up Heap Construction

- We can construct a heap storing  $n$  given keys in using a bottom-up construction with  $\log n$  phases
- In phase  $i$ , pairs of heaps with  $2^i - 1$  keys are merged into heaps with  $2^{i+1} - 1$  keys



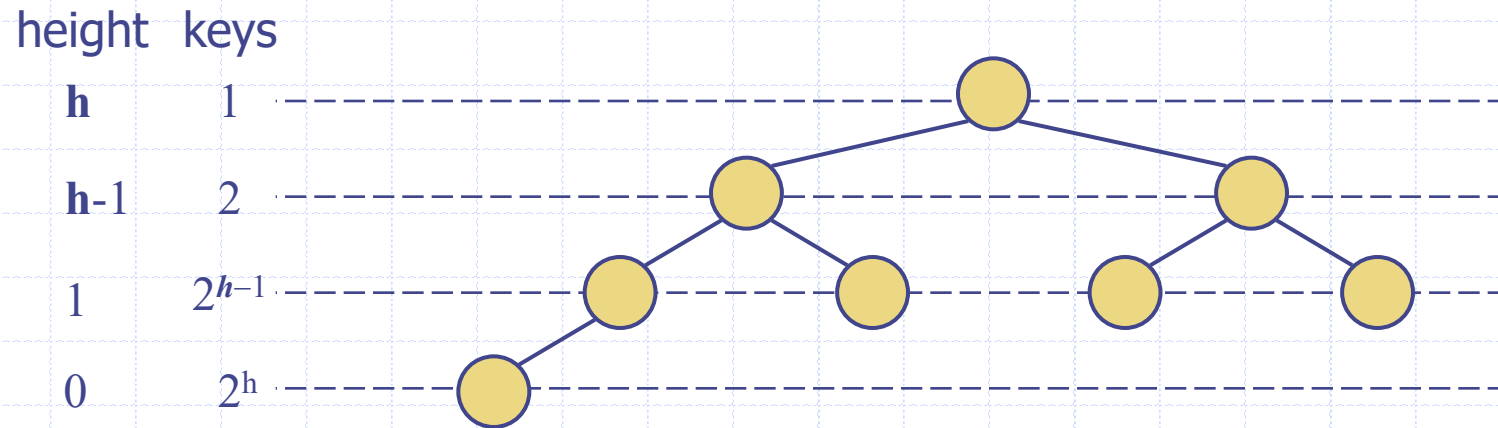
# Building a Heap – Bottomup Analysis

- Correctness: induction on  $i$ , all trees rooted at  $m > i$  are heaps
- Running time:  $n$  calls to Downheap
  - Downheap –  $O(\log n)$
  - so total running time  $O(n \log n)$
- We can provide a better bound –  $O(n)$ 
  - Idea – for most of the time, Downheap works on smaller than  $n$  element heaps



# Building a Heap – Bottomup Analysis (2)

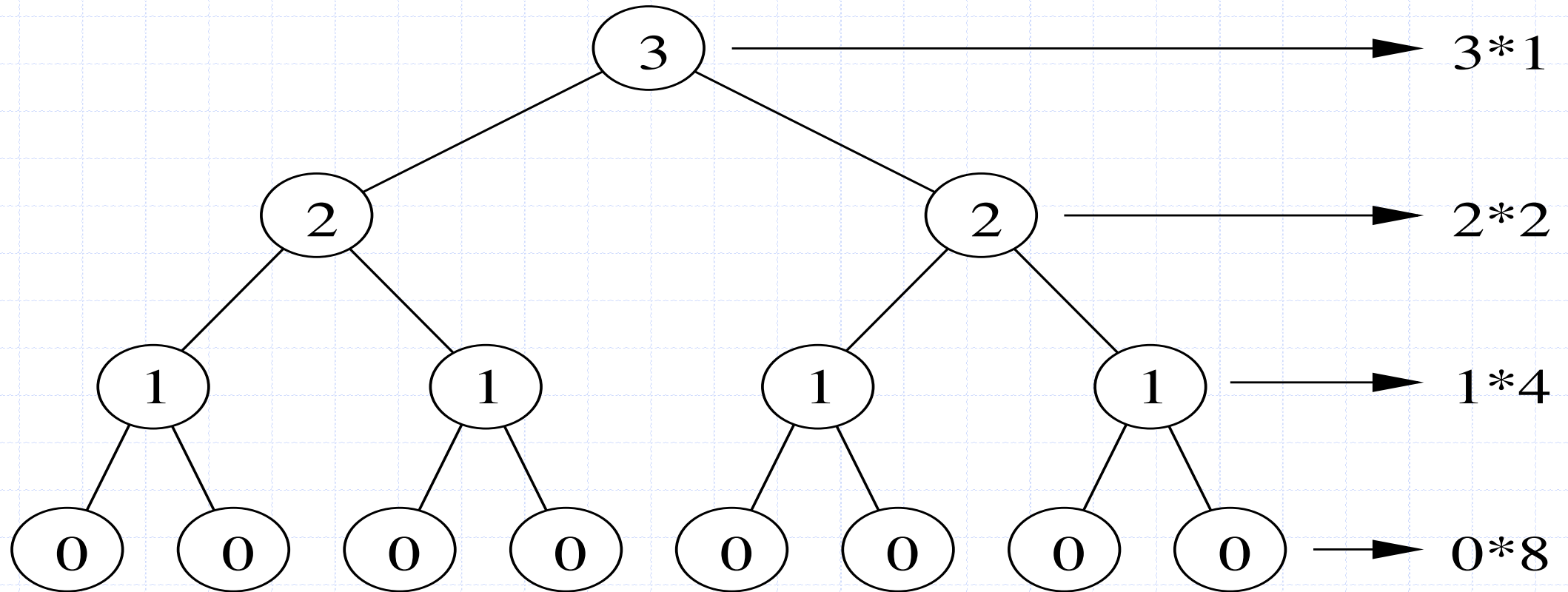
- height of node: length of longest path from node to leaf
- height of tree: height of root



# Building a Heap – Bottomup Analysis (3)

- height of node: length of longest path from node to leaf
- height of tree: height of root
- time for Downheap(i) =  $O(\text{height of subtree rooted at } i)$
- Let us assume a complete binary tree
  - $n = 2^{h+1} - 1$

# Building a Heap – Bottomup Analysis (4)



# Building a Heap – Bottomup Analysis (5)

- 0<sup>th</sup> level -  $2^h$  nodes, no need to call Downheap
- 1<sup>st</sup> level -  $2^{h-1}$  nodes, Downheap - 1 swap
- 2<sup>nd</sup> level -  $2^{h-2}$  nodes, Downheap - 2 swaps
- j<sup>th</sup> level -  $2^{h-j}$  nodes, Downheap - j swaps
- h<sup>th</sup> level – 1 node, Downheap – h swaps
- So total number of swaps is

$$\sum_{j=0}^h j 2^{h-j} = \sum_{j=0}^h j \frac{2^h}{2^j} = 2^h \sum_{j=0}^h \frac{j}{2^j}$$

- It can be shown that, this is bound by  $2^{(h+1)}$
- $2^{(h+1)} = n-1$
- Therefore  $O(n)$

# Selection-Sort

- Selection-sort is the variation of PQ-sort where the priority queue is implemented with an unsorted sequence
- Running time of Selection-sort:
  1. Inserting the elements into the priority queue with  $n$  **insert** operations takes  $O(n)$  time
  2. Removing the elements in sorted order from the priority queue with  $n$  **removeMin** operations takes time proportional to
$$n + n-1 + \dots + 2 + 1$$
- Selection-sort runs in  $O(n^2)$  time

# Selection-Sort Example

|         | Sequence S      | Priority Queue P |
|---------|-----------------|------------------|
| Input:  | (7,4,8,2,5,3,9) | ()               |
| Phase 1 |                 |                  |
| (a)     | (4,8,2,5,3,9)   | (7)              |
| (b)     | (8,2,5,3,9)     | (7,4)            |
| ..      | .. ..           |                  |
| (g)     | ()              | (7,4,8,2,5,3,9)  |
| Phase 2 |                 |                  |
| (a)     | (2)             | (7,4,8,5,3,9)    |
| (b)     | (2,3)           | (7,4,8,5,9)      |
| (c)     | (2,3,4)         | (7,8,5,9)        |
| (d)     | (2,3,4,5)       | (7,8,9)          |
| (e)     | (2,3,4,5,7)     | (8,9)            |
| (f)     | (2,3,4,5,7,8)   | (9)              |
| (g)     | (2,3,4,5,7,8,9) | ()               |

# Insertion-Sort

- Insertion-sort is the variation of PQ-sort where the priority queue is implemented with a sorted sequence
- Running time of Insertion-sort:
  - Inserting the elements into the priority queue with  $n$  insert operations takes time proportional to
$$1 + 2 + \dots + n$$
  - Removing the elements in sorted order from the priority queue with a series of  $n$  removeMin operations takes  $O(n)$  time
- Insertion-sort runs in  $O(n^2)$  time

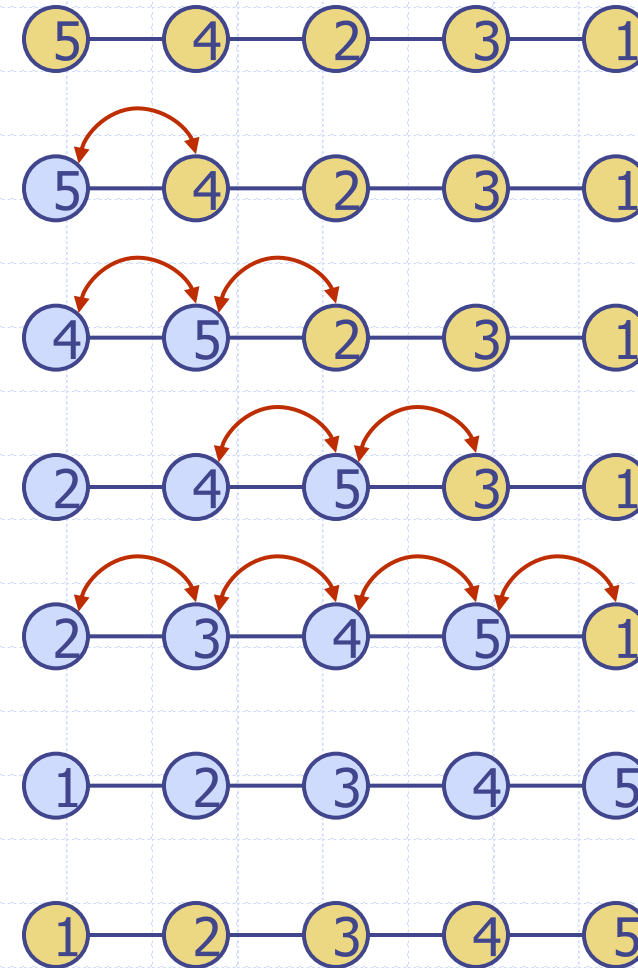
# Insertion-Sort Example

|         | Sequence S      | Priority queue P |
|---------|-----------------|------------------|
| Input:  | (7,4,8,2,5,3,9) | ()               |
| Phase 1 |                 |                  |
| (a)     | (4,8,2,5,3,9)   | (7)              |
| (b)     | (8,2,5,3,9)     | (4,7)            |
| (c)     | (2,5,3,9)       | (4,7,8)          |
| (d)     | (5,3,9)         | (2,4,7,8)        |
| (e)     | (3,9)           | (2,4,5,7,8)      |
| (f)     | (9)             | (2,3,4,5,7,8)    |
| (g)     | ()              | (2,3,4,5,7,8,9)  |
| Phase 2 |                 |                  |
| (a)     | (2)             | (3,4,5,7,8,9)    |
| (b)     | (2,3)           | (4,5,7,8,9)      |
| ⋮       | ⋮               | ⋮                |
| (g)     | (2,3,4,5,7,8,9) | ()               |

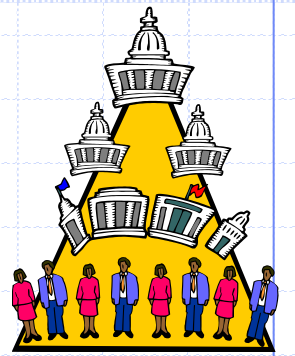


# In-place Insertion-Sort

- Instead of using an external data structure, we can implement selection-sort and insertion-sort in-place
- A portion of the input sequence itself serves as the priority queue
- For in-place insertion-sort
  - We keep sorted the initial portion of the sequence
  - We can use **swaps** instead of modifying the sequence



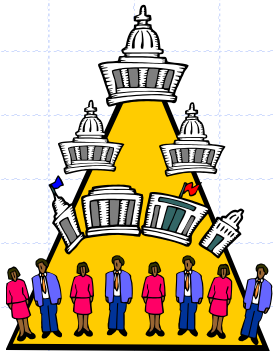
# Heap-Sort



- Consider a priority queue with  $n$  items implemented by means of a heap
  - the space used is  $O(n)$
  - methods **insert** and **removeMin** take  $O(\log n)$  time
  - methods **size**, **isEmpty**, and **min** take time  $O(1)$  time
- Using a heap-based priority queue, we can sort a sequence of  $n$  elements in  $O(n \log n)$  time
- The resulting algorithm is called heap-sort
- Heap-sort is much faster than quadratic sorting algorithms, such as insertion-sort and selection-sort

# Heap Sort

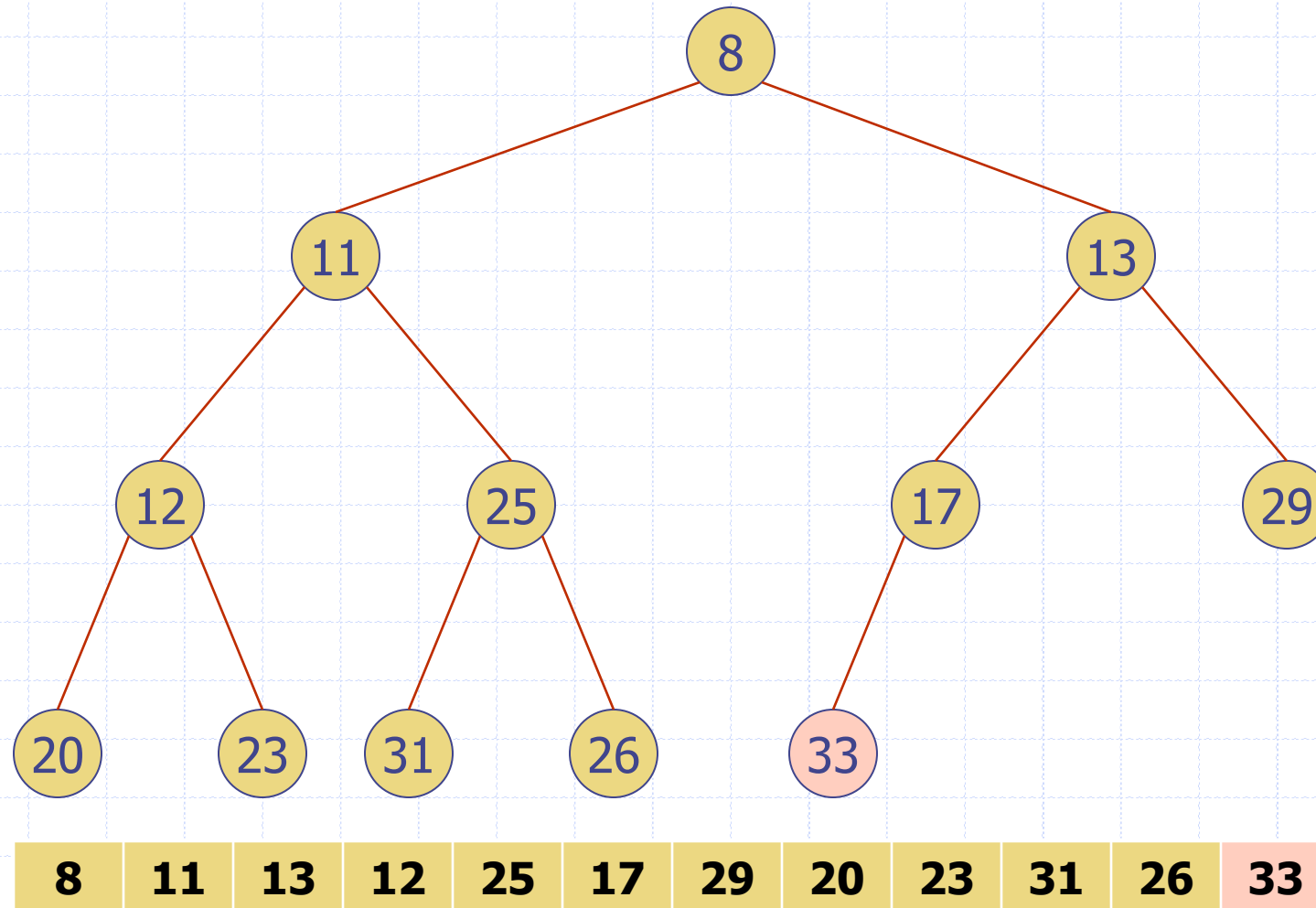
- Consider a priority queue with  $n$  items implemented by means of a heap
  - the space used is  $O(n)$
  - methods **insert** and **removeMin** take  $O(\log n)$  time
  - methods **size**, **isEmpty**, and **min** take time  $O(1)$  time
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- The resulting algorithm is called heap-sort
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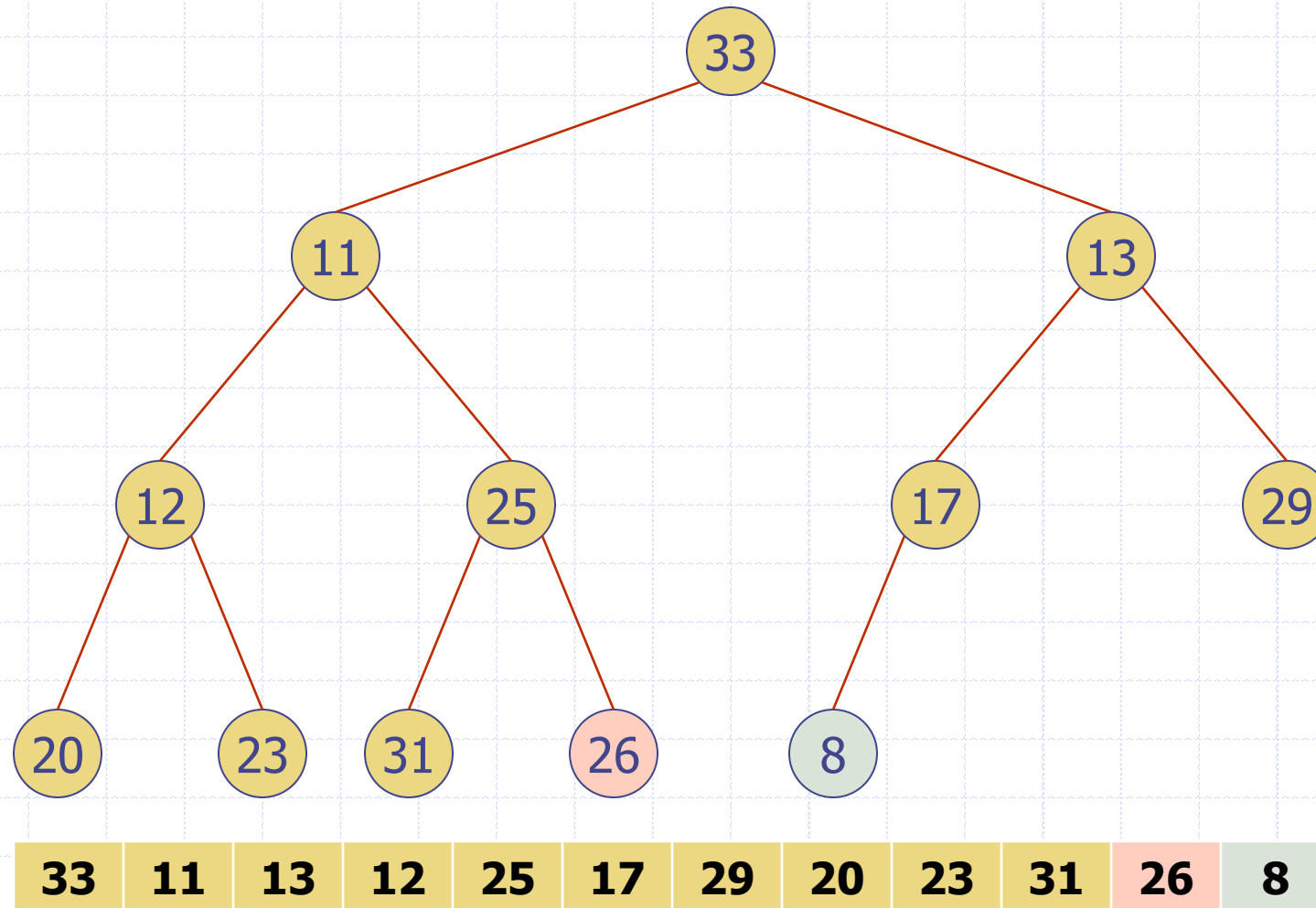
# Heap Sort

- ❑ Create a heap
- ❑ Do removeMin repeatedly till heap becomes empty
- ❑ To do an in place sort, we move deleted element to end of heap

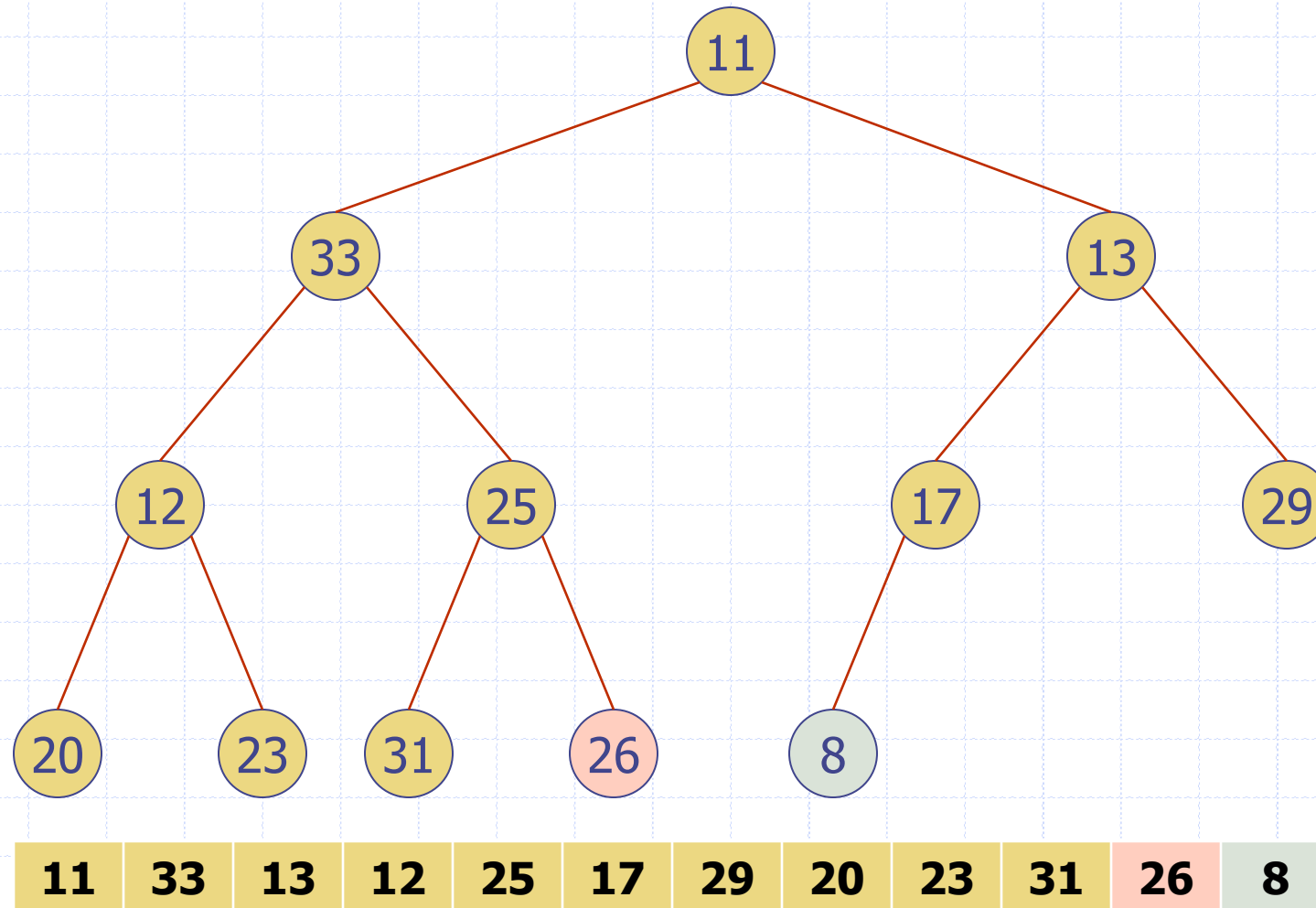
# Heap Sort



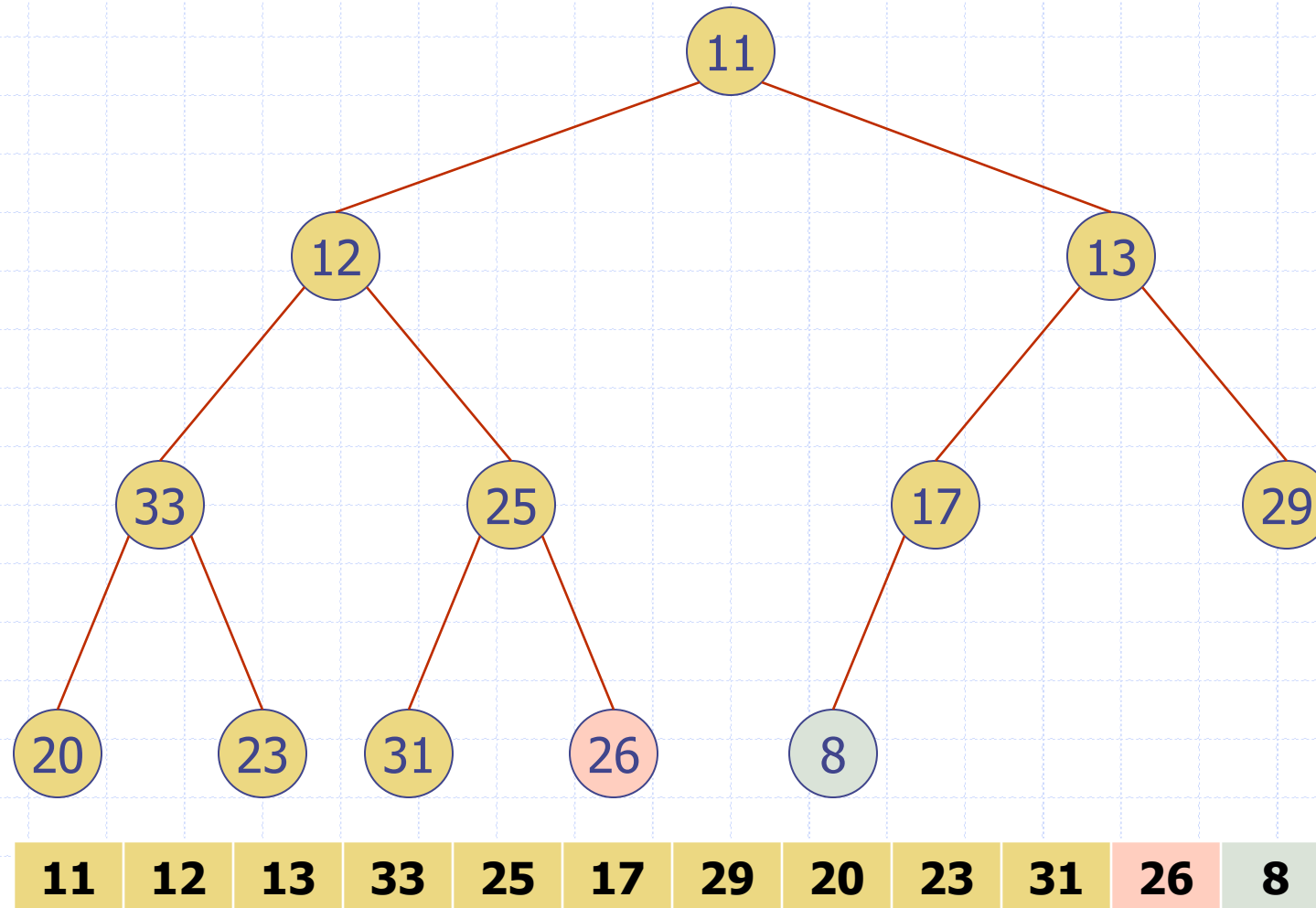
# Heap Sort



# Heap Sort

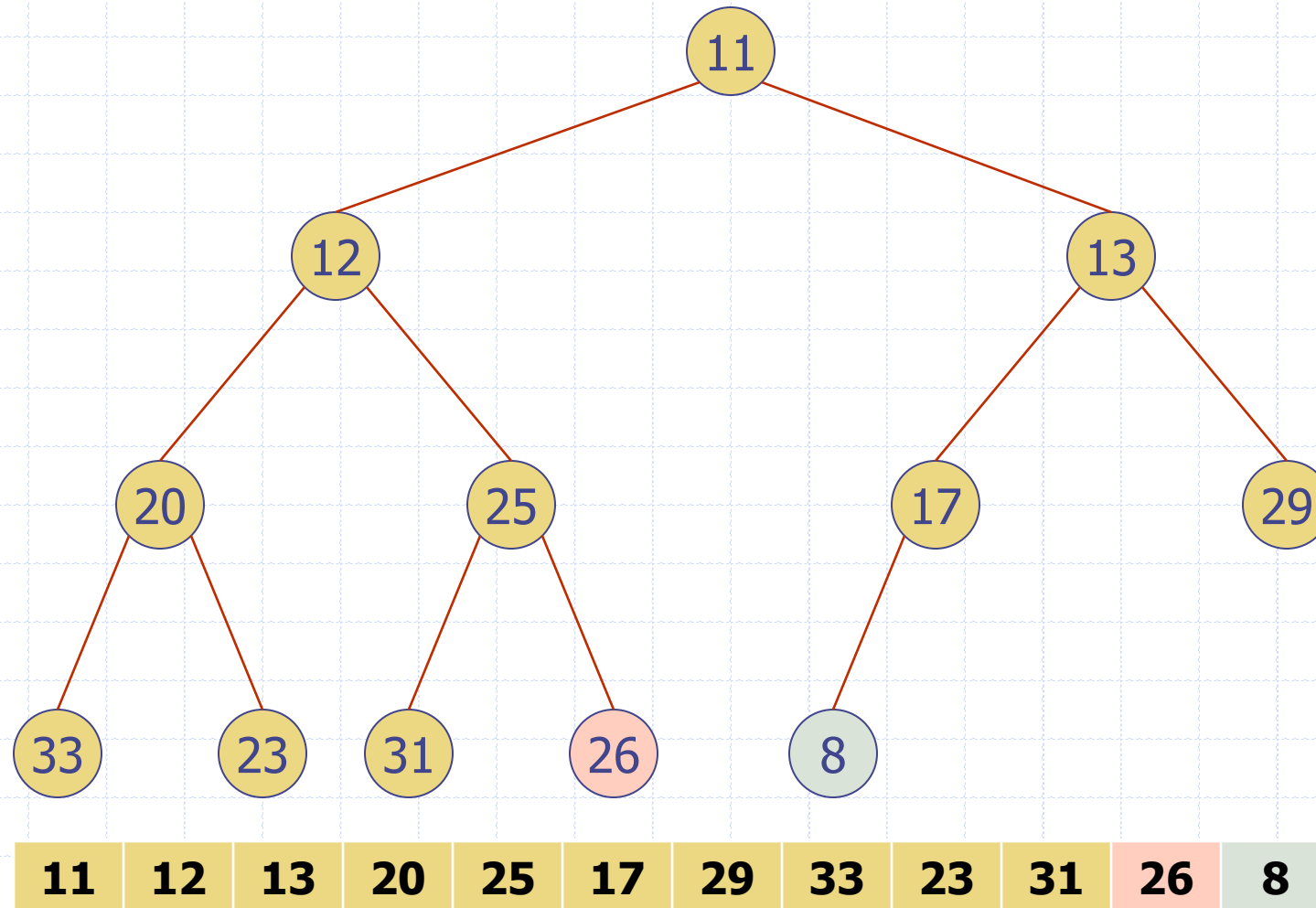


# Heap Sort

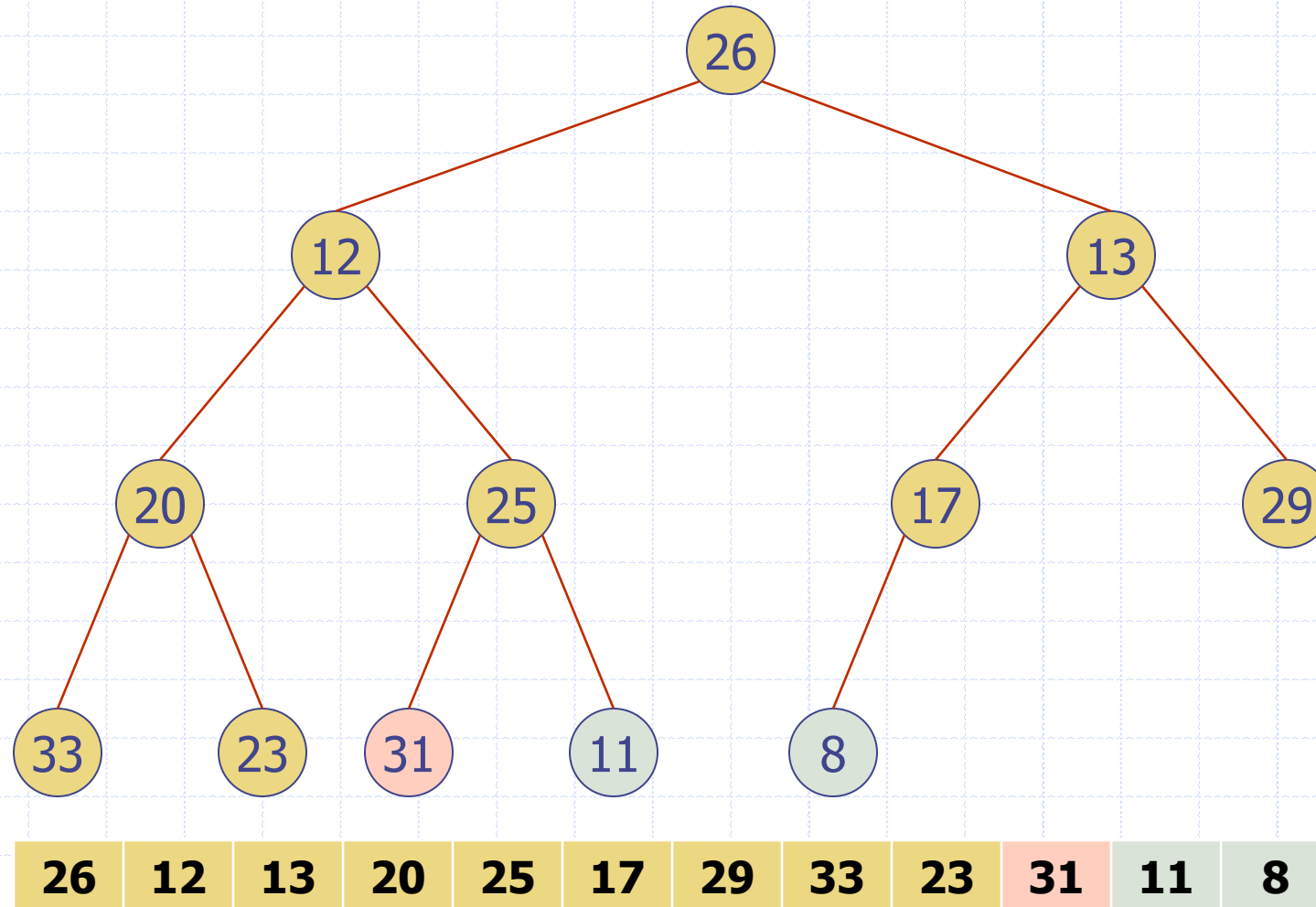




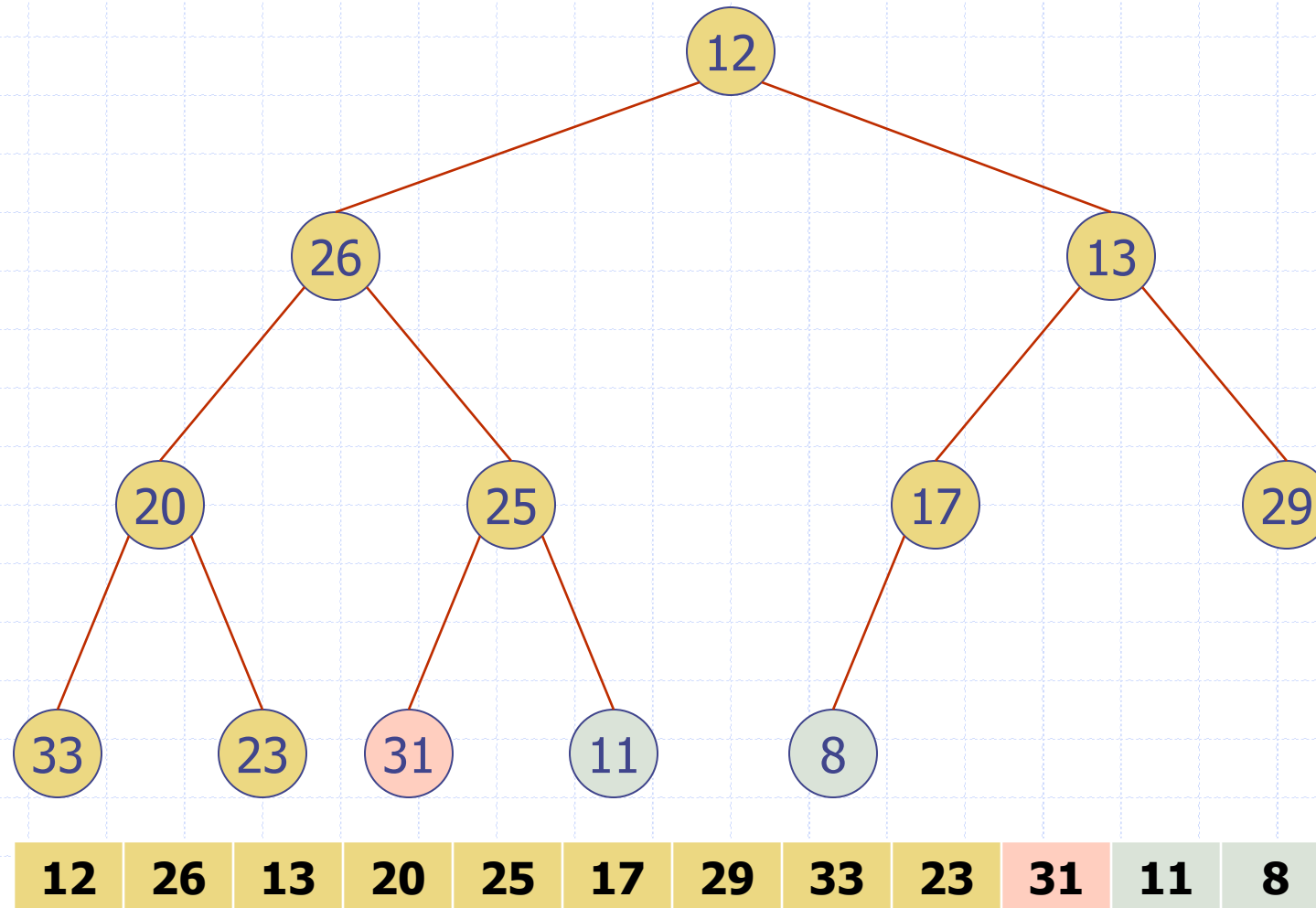
# Heap Sort



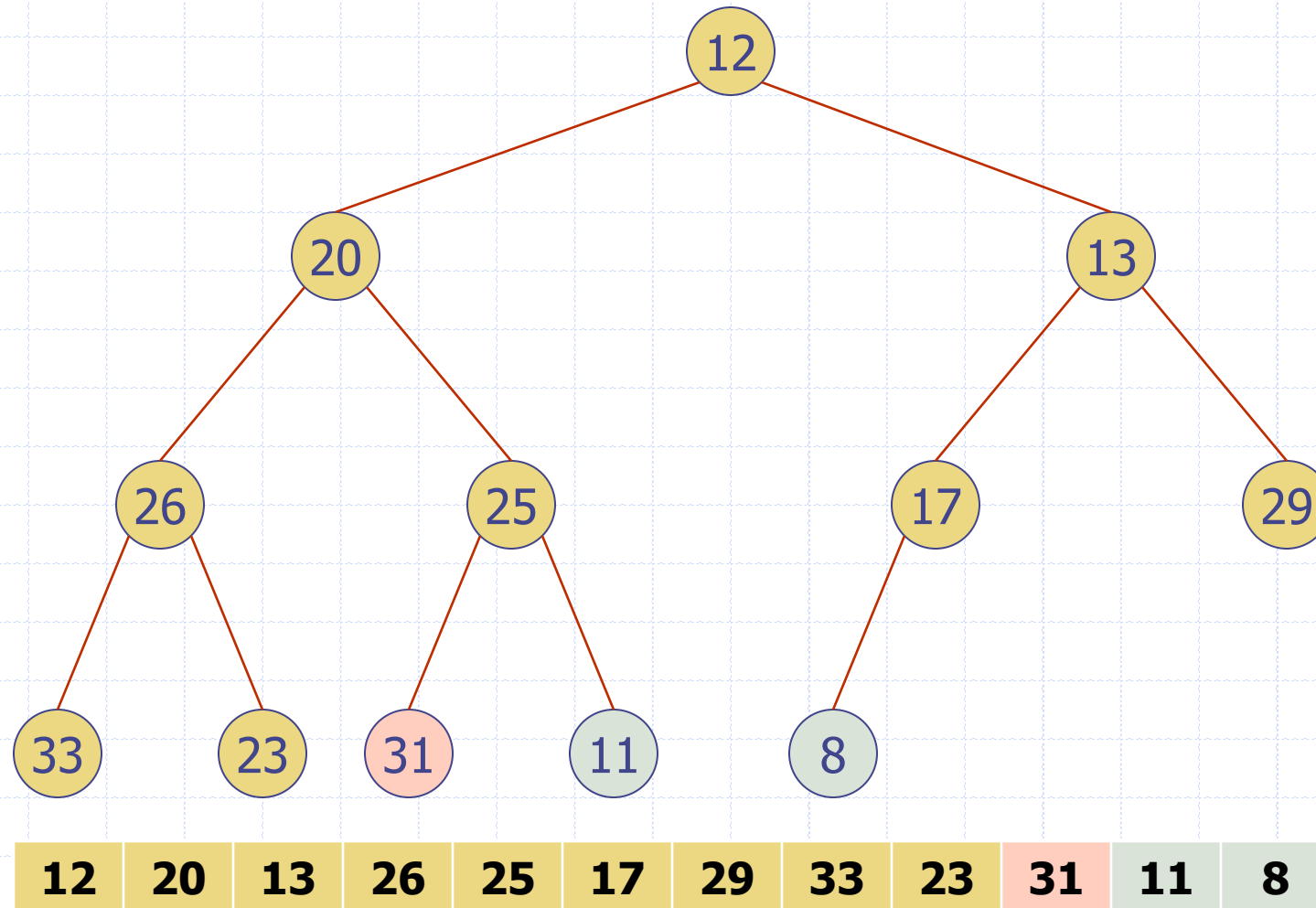
# Heap Sort



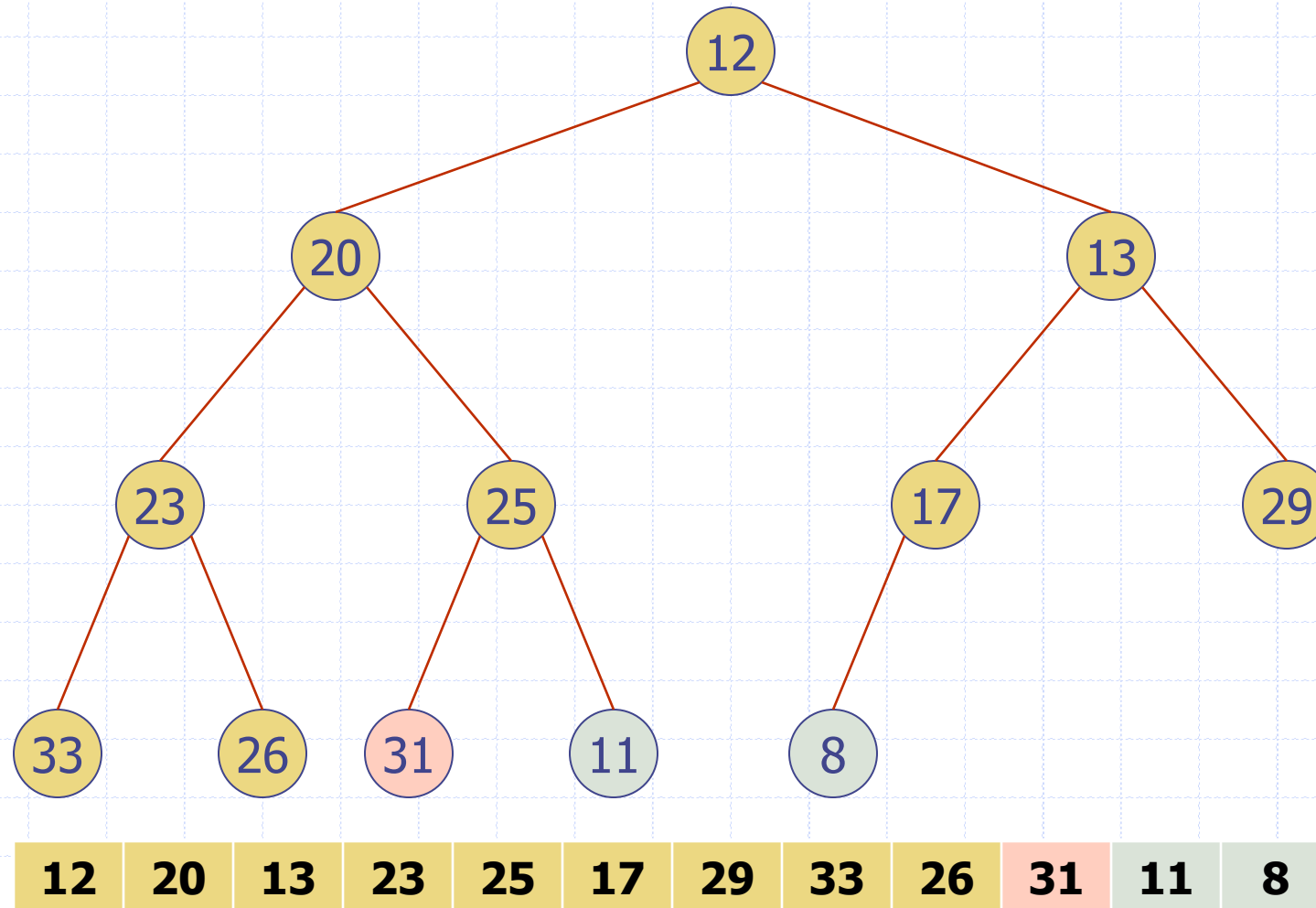
# Heap Sort



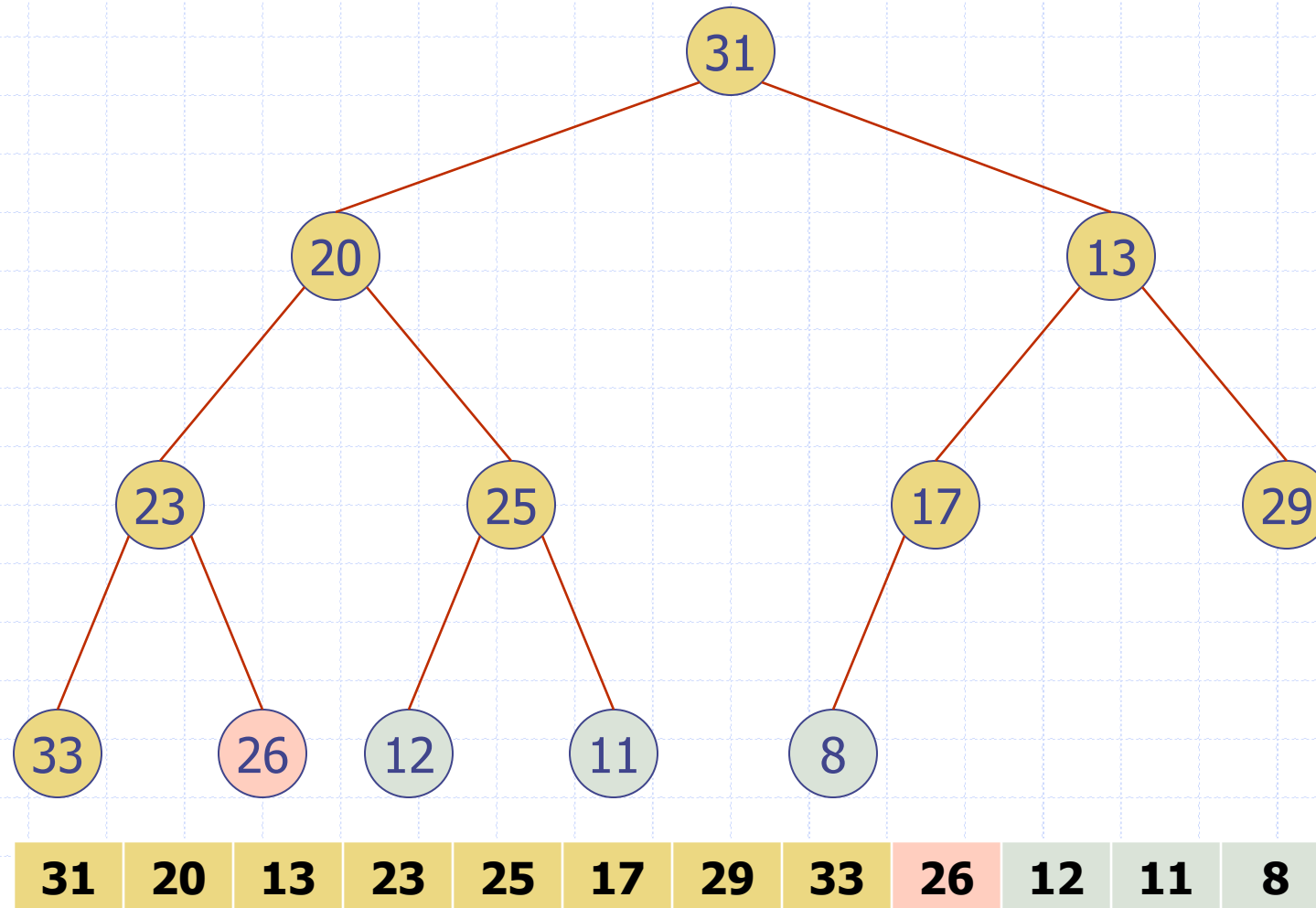
# Heap Sort



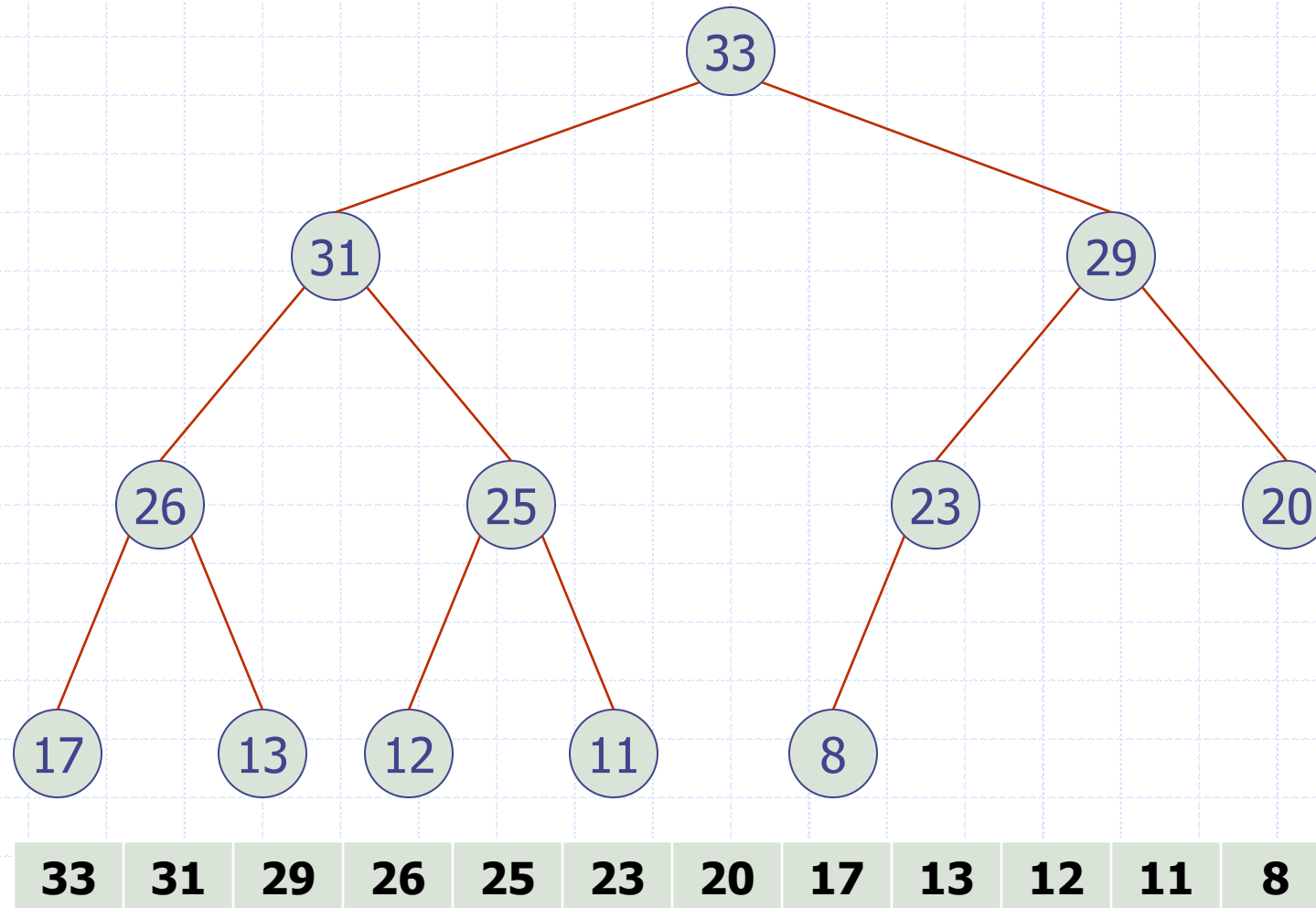
# Heap Sort



# Heap Sort



# Heap Sort



# Heapsort - Analysis

- Create a heap -  $O(n)$
- Do removeMin repeatedly till heap becomes empty
  - $O(\log n) + O(\log n-1) + O(\log n-2) + \dots O(1) = O(n \log n)$
- To do an in place sort, we move deleted element to end of heap