Algorithm 1: Insert(e)

```
Input: Flow e
Preprocess: Compute ID_e by concatenating IPs of e
Compute the hash FP_e = h(ID_e)
Select the bucket m = h(e) \mod X
for each entry n in bucket BK[m] do
  if BK[m].Et[n].FP == FP_e then
    return Update(BK[m].Et[n], ID_E)
  end if
end for
for each entry n in bucket BK[m] do
  if BK[m].Et[n].FP == 0 then
    BK[m].Et[n] = < FP_e, 1, 1, b > `00`
    return SUCCESS
  end if
end for
return Contend(BK[m], ID_e)
```

Algorithm 2 : Update(e,mode)

```
Input: Flow e, Location BK[m].Et[n], mode='f','p'
if BK[m].Et[n].f \ge BK[m].Et[n].p > 0 then
  if BK[m].Et[n].flag[W] == 0 then
    BK[m].Et[n].p+=1
    BK[m].Et[n].flag[W] = 1
  end if
  BK[m].Et[n].f+=1
  if f or p overflows then
    if BK[m].Et[n].flag[OF] == 0 and p overflows then
      BK[m].Et[n].flag[OF] = 1
      BK[m].Et[n].p = 0
      Report(e)
    else if OF = 1 then
      BK[m].Et[n].mode = 0
      Report(e, mode)
    end if
  end if
else
  Clear the entry BK[m].Et[n]
end if
```

Algorithm 3: Report(e,mode)

```
Input: Flow e, mode='f','p'
if mode == c' then
  Search for empty entry or e in Prt[k]
  if empty entry found then
     Prt[k] = \langle ID_e, 0, 1 \rangle
  else
     Calculate d_e = f_e/p_e for e
    Find the highest density flow in Prt[h]
     if f_e/p_e > Prt[h].f/Prt[h].p then
       return FAIL
     else
       Prt[h] = \langle ID_e, 0, 1 \rangle
       return KICK, Clear kicked flow in CLayer.
     end if
  end if
else
  Prt[k].mode + = 1
end if
return SUCCESS
```

Algorithm 4: Contend

```
Identify flow e_k in BK[m] with the minimum persistence p_k Generate random number r \in (0, 1) if r < P_kANDBM[m].Et[k].flag['OF'] == 0 then BM[m].Et[k] =< FP_e, 1, 1, b'10'> return SUCCESS else return FAIL end if
```