第4回演習プログラム

新領域創成科学研究科 人間環境学専攻 橋本 学

第4回演習資料のプログラムを以下に示します.

第3節のプログラム: モジュール mod elemstiffmat3d, mod elemexforcevec3d の作成

1. 要素剛性マトリックスモジュール mod_elemstiffmat3d.f90

1:	MODULE mod_elemstiffmat3d
2:!####	***************************************
3:	
4:	USE mod_nodes3d
5:	USE mod_localelement3d
6:	USE mod_elements3d
7:	
8:!	
9:	
10:	IMPLICIT NONE
11:	
12:!	
13:	
14:	TYPE :: struct_elemstiffmat3d
15:	
16:	!
17:	
18:	PRIVATE
19:	
20:	!

```
21:
22:
         TYPE(struct\_nodes3d), POINTER :: ns3d => NULL()
23:
         TYPE(struct_localelement3d), POINTER :: le3d => NULL()
24:
         TYPE(struct_elements3d), POINTER :: es3d => NULL()
25:
26:
27:
28:
          ! k(:, :, :)
29:
          ! Element stiffness matrix
30:
31:
32:
33:
         ! e(:)
         ! Young's modulus
34:
35:
         !
36:
          ! nu(:)
37:
          ! Poisson's ratio
38:
39:
40:
          ! evec(:, :)
41:
42:
         ! Infinitesimal strain
          !
43:
         ! svec(:, :)
44:
45:
         ! Stress
46:
          !
47:
         ! s_mises(:)
          ! Mises stress
48:
49:
50:
51:
52:
         REAL(8), ALLOCATABLE :: k(:, :, :)
         REAL(8), ALLOCATABLE :: e(:)
53:
         REAL(8), ALLOCATABLE :: nu(:)
54:
55:
         REAL(8), ALLOCATABLE :: evec(:, :)
         REAL(8), ALLOCATABLE :: svec(:, :)
56:
```

```
57:
     REAL(8), ALLOCATABLE :: s_mises(:)
58:
59:
60:
61:
     END TYPE
62:
63:!--
64:
65:
     CONTAINS
66:
67:
     ! Get element stiffness matrix
SUBROUTINE get_elemstiffmat3d_k(esm3d, k)
70:
72:
73:
     TYPE(struct_elemstiffmat3d), INTENT(IN) :: esm3d
74:
75:
     REAL(8), INTENT(OUT) :: k(:, :, :)
76:
77:!--
78:
79:
     k = esm3d%k
80:
81:!--
82:
83:
     RETURN
84:
86:
     END SUBROUTINE get_elemstiffmat3d_k
88:
89:
     ! Set Young's modulus and Poisson's ratio
92:
     SUBROUTINE set_elemstiffmat3d_e_nu(esm3d, e, nu)
```

```
94:
95:
      {\tt TYPE} ({\tt struct\_elemstiffmat3d}) \,, \quad {\tt INTENT} \, ({\tt INOUT}) \; :: \; {\tt esm3d} \\
96:
97:
      REAL(8), INTENT(IN) :: e(:)
98:
      REAL(8), INTENT(IN) :: nu(:)
99:
100:!-
101:
102:
      esm3d\%e = e
103:
      esm3d\%nu = nu
104:
105:!-
106:
107:
      RETURN
108:
110:
      END SUBROUTINE set_elemstiffmat3d_e_nu
112:
113:
114:
      ! Get Young's modulus and Poisson's ratio
116:
      SUBROUTINE get_elemstiffmat3d_e(esm3d, e, nu)
118:
119:
      TYPE(struct_elemstiffmat3d), INTENT(IN) :: esm3d
120:
      REAL(8), INTENT(OUT) :: e(:)
121:
122:
      REAL(8), INTENT(OUT) :: nu(:)
123:
124:!--
125:
126:
      e = esm3d\%e
127:
      nu = esm3d%nu
128:
```

```
129: !---
130:
     RETURN
131:
132:
END SUBROUTINE get_elemstiffmat3d_e
136:
137:
138:
     ! Get infinitesimal strain and stress
140:
     SUBROUTINE get_elemstiffmat3d_evec_svec &
141:
            (esm3d, evec, svec, s_mises)
143:
144:
     TYPE(struct_elemstiffmat3d), INTENT(IN) :: esm3d
145:
     REAL(8), INTENT(OUT) :: evec(:, :)
146:
     REAL(8), INTENT(OUT) :: svec(:, :)
147:
148:
     REAL(8), INTENT(OUT) :: s_mises(:)
149:
150:!---
151:
152: evec = esm3d%evec
153:
    svec = esm3d%svec
154:
155:
     s_mises = esm3d%s_mises
156:
157:!--
158:
159:
     RETURN
160:
162:
     END SUBROUTINE get_elemstiffmat3d_evec_svec
164:
```

```
165:
167:
         SUBROUTINE init_elemstiffmat3d(esm3d, ns3d, le3d, es3d)
169:
170:
         {\tt TYPE} ({\tt struct\_elemstiffmat3d}) \,, \quad {\tt INTENT} \, ({\tt INOUT}) \; :: \; {\tt esm3d} \\
171:
         TYPE(struct_nodes3d), TARGET, INTENT(IN)
172:
                                                    ∷ ns3d
173:
         TYPE(struct_localelement3d), TARGET, INTENT(IN) :: le3d
174:
         TYPE(struct_elements3d), TARGET, INTENT(IN)
                                                     ∷ es3d
175:
176:!--
177:
178:
         INTEGER :: le3d_nnodes
179:
         INTEGER :: es3d_n
180:
181: !---
182:
183:
         esm3d\%ns3d \Rightarrow ns3d
184:
         esm3d\%le3d \Rightarrow le3d
185:
         esm3d\%es3d \Rightarrow es3d
186:
187: !--
188:
189:
         CALL get_localelement3d_nnodes(esm3d%le3d, le3d_nnodes)
190:
191:
         CALL get_elements3d_n(esm3d%es3d, es3d_n)
192:
193:!--
194:
195:
         ALLOCATE ( esm3d%k (3*le3d_nnodes, 3*le3d_nnodes, es3d_n) )
196:
197:
         esm3d\%k = 0.0D0
198:
199:
200:
```

```
201:
      ALLOCATE( esm3d%e(es3d_n) )
202:
      ALLOCATE( esm3d%nu(es3d_n) )
203:
204:
      esm3d\%e = 0.0D0
205:
      esm3d\%nu = 0.0D0
206:
207:
208:
209:
      ALLOCATE ( esm3d%evec(6, es3d_n) )
210:
211:
      esm3d\%evec = 0.0D0
212:
213:
      ALLOCATE( esm3d\%svec(6, es3d_n) )
214:
215:
      esm3d\%svec = 0.0D0
216:
217:
      ALLOCATE( esm3d%s_mises(es3d_n) )
218:
219:
      esm3d\%s_mises = 0.000
220:
221:!--
222:
223:
      RETURN
224:
END SUBROUTINE init_elemstiffmat3d
228:
229:
SUBROUTINE cal_elemstiffmat3d(esm3d)
233:
      TYPE(struct_elemstiffmat3d), INTENT(INOUT) :: esm3d
234:
235:
```

```
237:
238:
          INTEGER :: ns3d_n
239:
          INTEGER :: le3d_nnodes
240:
          INTEGER :: le3d_nqps
241:
          INTEGER \ :: \ es3d\_n
242:
          INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
243:
          INTEGER :: nqps_tot
244:
          INTEGER ∷ i, j, k
245:
          INTEGER :: id
246:
          INTEGER :: na, nb
247:
          INTEGER :: ie
248:
          INTEGER :: idof
249:
          INTEGER :: isize, jsize
250:
          INTEGER :: jsize1, jsize2, jsize3
251:
          INTEGER :: ijk
252:
253:
          REAL(8), ALLOCATABLE :: ns3d_x(:, :)
254:
          REAL(8), ALLOCATABLE :: ns3d_u(:)
255:
          REAL(8), ALLOCATABLE :: le3d_xi_qp(:, :)
256:
          REAL(8), ALLOCATABLE :: le3d_w_qp(:, :)
257:
          REAL(8), ALLOCATABLE :: le3d_n_qp(:, :)
258:
          REAL(8), ALLOCATABLE :: le3d_dndxi_qp(:, :, :)
259:
          REAL(8), ALLOCATABLE :: x_local(:, :)
          REAL(8), ALLOCATABLE :: u_local(:)
260:
261:
          REAL(8) :: nqps_tot_inv
262:
          REAL(8) :: g1(3), g2(3), g3(3)
263:
          REAL(8) :: det_j, det_j_inv
264:
          REAL(8) :: w_w_w_det_j
265:
          REAL(8) :: cg1(3), cg2(3), cg3(3)
266:
          REAL(8), ALLOCATABLE :: dndx(:, :)
          REAL(8), ALLOCATABLE :: bmat(:, :)
267:
          REAL (8) :: evec (6)
268:
269:
          REAL(8) :: lambda, mu
270:
          REAL(8) :: dmat(6, 6)
271:
          {\sf REAL}\,(8)\,,\ {\sf ALLOCATABLE}\ ::\ {\sf cmat}\,(:,\ :)
272:
          REAL(8) :: svec(6)
```

```
273:
274:!
275:
276:
          CALL get_nodes3d_n (esm3d%ns3d, ns3d_n)
277:
          ALLOCATE(ns3d_x(3, ns3d_n))
278:
          CALL get_nodes3d_x (esm3d%ns3d, ns3d_x)
279:
          ALLOCATE( ns3d_u(3*ns3d_n) )
280:
          CALL get_nodes3d_u (esm3d%ns3d, ns3d_u)
281:
282:
          CALL get_localelement3d_nnodes(esm3d%le3d, le3d_nnodes)
283:
          CALL get_localelement3d_nqps(esm3d%le3d, le3d_nqps)
284:
          nqps_tot = le3d_nqps*le3d_nqps*le3d_nqps
285:
          nqps_tot_inv = 1.0D0/DFL0AT( nqps_tot )
286:
          ALLOCATE ( le3d_xi_qp(3, nqps_tot) )
287:
          ALLOCATE ( le3d_w_qp(3, nqps_tot) )
288:
          CALL get_localelement3d_xi_w_qp
289:
               (esm3d%le3d, le3d_xi_qp, le3d_w_qp)
290:
          ALLOCATE( le3d_n_qp(le3d_nnodes, nqps_tot) )
291:
          ALLOCATE( le3d_dndxi_qp(3, le3d_nnodes, nqps_tot) )
292:
                                                        &
          CALL get_localelement3d_n_qp
293:
               (esm3d%le3d, le3d_n_qp, le3d_dndxi_qp)
294:
295:
          CALL get_elements3d_n(esm3d%es3d, es3d_n)
296:
          ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
297:
          CALL get_elements3d_connectivity(esm3d%es3d, es3d_connectivity)
298:
299:
          ALLOCATE( x_local(3, le3d_nnodes) )
300:
          ALLOCATE( u_local(3*le3d_nnodes) )
301:
          ALLOCATE ( dndx (3, le3d_nnodes) )
302:
          ALLOCATE( bmat(6, 3*le3d_nnodes) )
303:
          ALLOCATE( cmat(6, 3*le3d_nnodes) )
304:
305: !-
306:
307:
          esm3d\%k = 0.0D0
308:
```

```
309:
          DO ie = 1, es3d_n
310:
311:
312:
           DO na = 1, le3d_nnodes
313:
314:
315:
            id = es3d_connectivity(na, ie)
316:
317:
            D0 i = 1, 3
318:
319:
             idof = 3*(id-1)+i
320:
             isize = 3*(na-1)+i
321:
322:
             x_{local(i, na)} = ns3d_x(i, id)
323:
             u_local(isize) = ns3d_u(idof)
324:
325:
            END DO
326:
327:
           END DO
328:
329:
330:
331:
           DO ijk = 1, nqps_tot
332:
333:
334:
335:
            ! Covariant basis vector
            D0 i = 1, 3
336:
337:
338:
             g1(i) = 0.000
339:
             g2(i) = 0.000
340:
             g3(i) = 0.000
341:
             D0 na = 1, le3d_nnodes
342:
343:
344:
              g1(i) = g1(i) + le3d_dndxi_qp(1, na, ijk)*x_local(i, na)
```

```
345:
              g2(i) = g2(i)+le3d_dndxi_qp(2, na, ijk)*x_local(i, na)
346:
              g3(i) = g3(i)+le3d_dndxi_qp(3, na, ijk)*x_local(i, na)
347:
348:
             END DO
349:
350:
            END DO
351:
352:
353:
354:
            ! Jacobian
355:
            \det_{j} = g1(1)*(g2(2)*g3(3)-g2(3)*g3(2)) &
356:
                  +g1(2)*(g2(3)*g3(1)-g2(1)*g3(3)) &
357:
                  +g1(3)*(g2(1)*g3(2)-g2(2)*g3(1))
358:
359:
            det_j_inv = 1.0D0/det_j
360:
361:
            w_w_w_det_j
            = le3d_w_qp(1, ijk)*le3d_w_qp(2, ijk)*le3d_w_qp(3, ijk) &
362:
363:
             *det_j
364:
365:
366:
367:
            ! Contravariant basis vector
368:
            cg1(1) = det_j_inv
369:
                     *(g2(2)*g3(3)-g2(3)*g3(2))
370:
            cg1(2) = det_j_inv
371:
                     *(g2(3)*g3(1)-g2(1)*g3(3))
372:
            cg1(3) = det_j_inv
373:
                     *(g2(1)*g3(2)-g2(2)*g3(1))
374:
            cg2(1) = det_j_inv
375:
                     *(g3(2)*g1(3)-g3(3)*g1(2))
376:
            cg2(2) = det_j_inv
377:
                     *(g3(3)*g1(1)-g3(1)*g1(3))
378:
            cg2(3) = det_j_inv
379:
                     *(g3(1)*g1(2)-g3(2)*g1(1))
380:
            cg3(1) = det_j_inv
```

```
381:
                      *(g1(2)*g2(3)-g1(3)*g2(2))
382:
             cg3(2) = det_j_inv
383:
                      *( g1(3)*g2(1)-g1(1)*g2(3) )
384:
             cg3(3) = det_j_inv
385:
                      *(g1(1)*g2(2)-g1(2)*g2(1))
386:
387:
388:
389:
             D0 \text{ na} = 1, \text{ le}3d\_\text{nnodes}
390:
391:
              dndx (1, na)
                                                    &
392:
              = cg1(1)*le3d_dndxi_qp(1, na, ijk) &
393:
              +cg2(1)*le3d_dndxi_qp(2, na, ijk) &
394:
               +cg3(1)*le3d_dndxi_qp(3, na, ijk)
395:
              dndx (2, na)
                                                    &
396:
              = cg1(2)*le3d_dndxi_qp(1, na, ijk) &
397:
               +cg2(2)*le3d_dndxi_qp(2, na, ijk) &
398:
              +cg3(2)*le3d_dndxi_qp(3, na, ijk)
399:
              dndx (3, na)
                                                    &
400:
              = cg1(3)*le3d_dndxi_qp(1, na, ijk) &
401:
               +cg2(3)*le3d_dndxi_qp(2, na, ijk) &
402:
               +cg3(3)*le3d_dndxi_qp(3, na, ijk)
403:
             END DO
404:
405:
406:
407:
408:
             ! B matrix
409:
410:
             bmat = 0.000
411:
412:
             D0 \text{ nb} = 1, \text{ le}3d\_\text{nnodes}
413:
414:
              jsize1 = 3*(nb-1)+1
415:
              jsize2 = 3*(nb-1)+2
              jsize3 = 3*(nb-1)+3
416:
```

```
417:
418:
             bmat(1, jsize1) = dndx(1, nb)
419:
             bmat(4, jsize1) = dndx(2, nb)
420:
             bmat(6, jsize1) = dndx(3, nb)
421:
             bmat(2, jsize2) = dndx(2, nb)
422:
             bmat(4, jsize2) = dndx(1, nb)
423:
             bmat(5, jsize2) = dndx(3, nb)
424:
             bmat(3, jsize3) = dndx(3, nb)
             bmat(5, jsize3) = dndx(2, nb)
425:
426:
             bmat(6, jsize3) = dndx(1, nb)
427:
428:
            END DO
429:
430:
431:
432:
            evec = 0.000
433:
            D0 i = 1, 6
434:
435:
436:
             DO jsize = 1, 3*le3d_nnodes
437:
438:
              evec(i) = evec(i)+bmat(i, jsize)*u_local(jsize)
439:
440:
             END DO
441:
442:
            END DO
443:
444:
445:
446:
            lambda
                                                                         &
447:
            = (esm3d\%e(ie)*esm3d\%nu(ie))
              /( ( 1.0D0+esm3d%nu(ie) )*( 1.0D0-2.0D0*esm3d%nu(ie) ) )
448:
            mu = esm3d\%e(ie)/(2.0D0*(1.0D0+esm3d\%nu(ie)))
449:
450:
451:
452:
```

```
453:
            ! D matrix
454:
455:
            dmat = 0.000
456:
457:
            dmat(1, 1) = lambda+2.0D0*mu
458:
            dmat(2, 2) = lambda+2.0D0*mu
459:
            dmat(3, 3) = lambda+2.000*mu
460:
            dmat(1, 2) = lambda
461:
            dmat(1, 3) = lambda
462:
            dmat(2, 1) = lambda
463:
            dmat(2, 3) = lambda
464:
            dmat(3, 1) = lambda
465:
            dmat(3, 2) = lambda
            dmat(4, 4) = mu
466:
467:
            dmat(5, 5) = mu
468:
            dmat(6, 6) = mu
469:
470:
471:
472:
            D0 i = 1, 6
473:
474:
             D0 jsize = 1, 3*le3d_nnodes
475:
476:
              cmat(i, jsize) = 0.000
477:
478:
              D0 k = 1, 6
479:
480:
               cmat(i, jsize) = cmat(i, jsize)+dmat(i, k)*bmat(k, jsize)
481:
482:
              END DO
483:
             END DO
484:
485:
486:
            END DO
487:
488:
            D0 isize = 1, 3*le3d_nnodes
```

```
489:
490:
             D0 jsize = 1, 3*le3d_nnodes
491:
492:
              D0 k = 1, 6
493:
494:
               esm3d%k(isize, jsize, ie)
495:
               = esm3d%k(isize, jsize, ie)
496:
               +w_w_w_det_j*bmat(k, isize)*cmat(k, jsize)
497:
              END DO
498:
499:
500:
             END DO
501:
502:
            END DO
503:
504:
505:
506:
            svec = 0.000
507:
508:
            D0 i = 1, 6
509:
510:
             D0 j = 1, 6
511:
              svec(i) = svec(i) + dmat(i, j) * evec(j)
512:
513:
514:
             END DO
515:
516:
            END DO
517:
518:
519:
520:
            D0 i = 1, 6
521:
522:
             esm3d%evec(i, ie) = esm3d%evec(i, ie)+evec(i)
523:
             esm3d%svec(i, ie) = esm3d%svec(i, ie)+svec(i)
524:
```

```
525:
            END DO
526:
527:
528:
529:
           END DO
530:
531:
532:
533:
           D0 I = 1, 6
534:
535:
            esm3d%evec(i, ie) = nqps_tot_inv*esm3d%evec(i, ie)
536:
            esm3d%svec(i, ie) = nqps_tot_inv*esm3d%svec(i, ie)
537:
538:
           END DO
539:
540:
           esm3d%s_mises(ie)
541:
           = DSQRT( 0.5D0*( (esm3d%svec(1, ie)-esm3d%svec(2, ie) )**2 &
                           +( esm3d%svec(2, ie)-esm3d%svec(3, ie) )**2 &
542:
                           +( esm3d%svec(3, ie)-esm3d%svec(1, ie) )**2 &
543:
544:
                           +6. 0D0
                                                                         &
545:
                            *( esm3d%svec(4, ie)**2
                                                                         &
546:
                              +esm3d%svec(5, ie)**2
                                                                         &
                              +esm3d%svec(6, ie)**2)))
547:
548:
549:
550:
551:
          END DO
552:
553:!-
554:
555:
          DEALLOCATE( ns3d_x )
          DEALLOCATE( ns3d_u )
556:
557:
558:
          DEALLOCATE( le3d_xi_qp )
559:
          DEALLOCATE( le3d_w_qp )
          DEALLOCATE( le3d_n_qp )
560:
```

```
561:
      DEALLOCATE( le3d_dndxi_qp )
562:
563:
      DEALLOCATE( es3d_connectivity )
564:
565:
      DEALLOCATE( x_local )
566:
      DEALLOCATE( u_local )
      DEALLOCATE( dndx )
567:
568:
      DEALLOCATE( bmat )
      DEALLOCATE( cmat )
569:
570:
571:!--
572:
573:
      RETURN
574:
576:
      END SUBROUTINE cal_elemstiffmat3d
578:
579:
SUBROUTINE del_elemstiffmat3d(esm3d)
583:
      TYPE(struct_elemstiffmat3d), INTENT(INOUT) :: esm3d
584:
585:
586:!-
587:
      NULLIFY( esm3d%ns3d )
588:
589:
      NULLIFY( esm3d%le3d )
590:
      NULLIFY( esm3d%es3d )
591:
592: !--
593:
594:
      DEALLOCATE( esm3d%k )
595:
596:
```

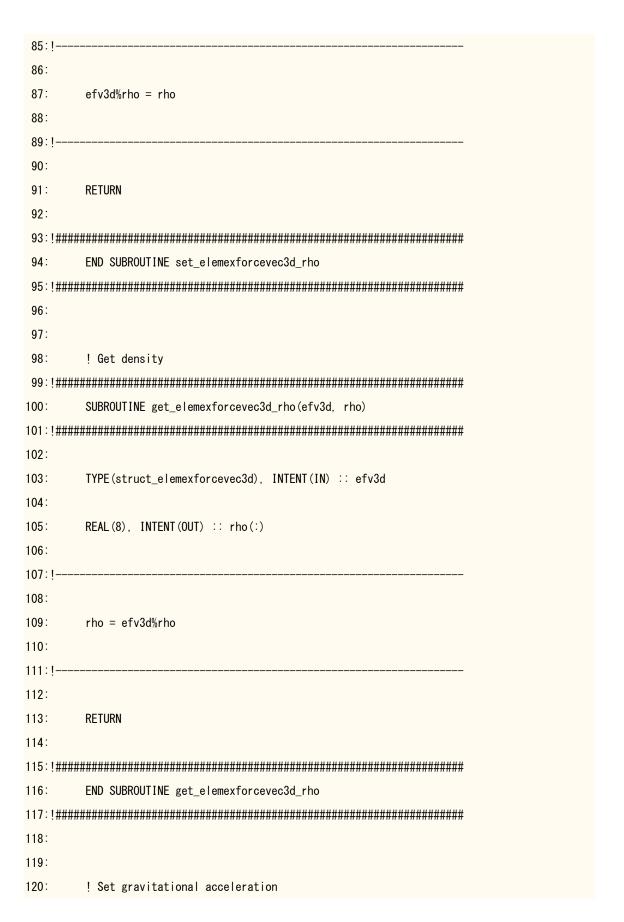
```
597:
598:
     DEALLOCATE( esm3d%e )
599:
     DEALLOCATE( esm3d%nu )
600:
601:
602:
603:
     DEALLOCATE( esm3d%evec )
604:
     DEALLOCATE( esm3d%svec )
605:
     DEALLOCATE( esm3d%s_mises )
606:
607:!--
608:
609:
     RETURN
610:
END SUBROUTINE del_elemstiffmat3d
614:
615:
617:
     END MODULE mod_elemstiffmat3d
```

2. 要素外力ベクトルモジュール mod_elemexforcevec3d.f90

1:	MODULE mod_elemexforcevec3d
2:!#	***************************************
3:	
4:	USE mod_nodes3d
5:	USE mod_localelement3d
6:	USE mod_elements3d
7:	
8:!-	
9:	
10:	IMPLICIT NONE
11:	
12:!-	

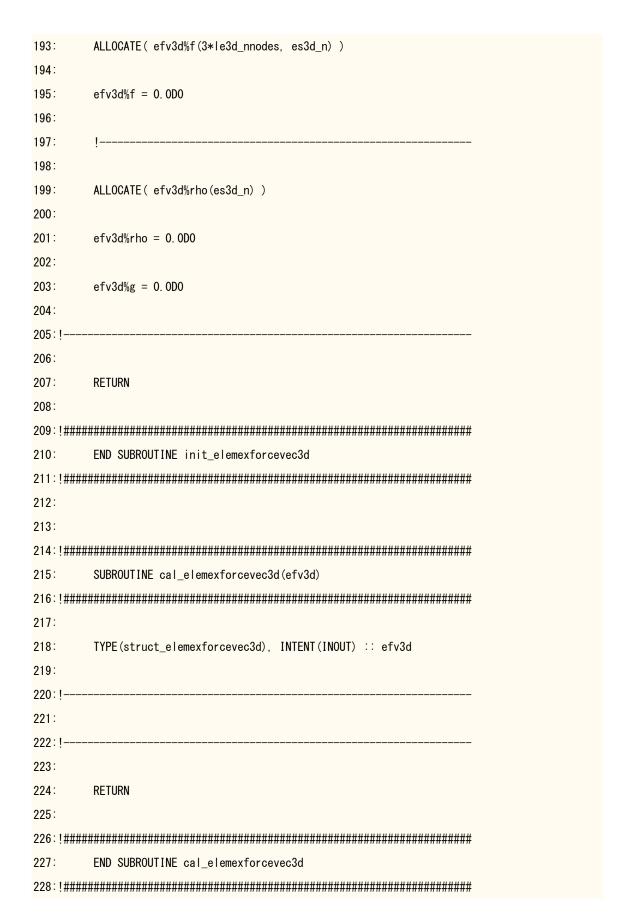
```
13:
14:
        TYPE :: struct_elemexforcevec3d
15:
16:
17:
         PRIVATE
18:
19:
20:
21:
         TYPE(struct\_nodes3d), POINTER :: ns3d => NULL()
22:
         TYPE(struct_localelement3d), POINTER :: le3d => NULL()
23:
         TYPE(struct_elements3d), POINTER :: es3d => NULL()
24:
25:
26:
27:
         ! f(:, :)
28:
29:
         ! Element external force vector
30:
31:
32:
33:
         ! rho(:)
34:
         ! Density
35:
         !
36:
         ! g
37:
         ! Gravitational acceleration
38:
39:
40:
         REAL(8), ALLOCATABLE :: f(:, :)
41:
         REAL(8), ALLOCATABLE :: rho(:)
42:
43:
         REAL(8) :: g
44:
45:
46:
47:
        END TYPE struct_elemexforcevec3d
48:
```

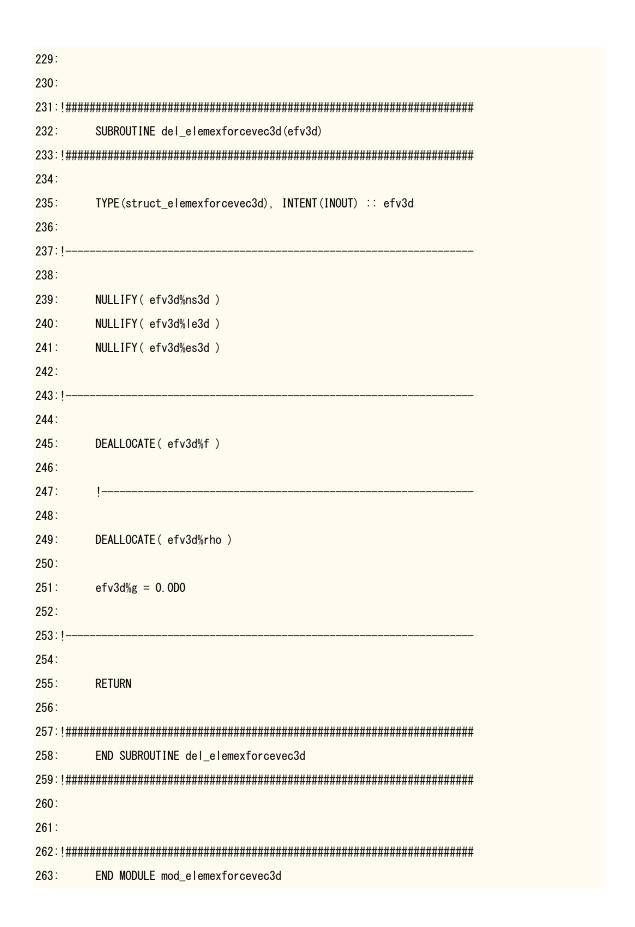
```
49:!---
50:
51:
    CONTAINS
52:
53:
54:
    ! Get element external force vector
56:
    SUBROUTINE get_elemexforcevec3d_f(efv3d, f)
58:
59:
    TYPE(struct_elemexforcevec3d), INTENT(IN) :: efv3d
60:
    REAL(8), INTENT(OUT) :: f(:, :)
61:
62:
63:!--
64:
65:
    f = efv3d\%f
66:
68:
69:
    RETURN
70:
72:
    END SUBROUTINE get_elemexforcevec3d_f
74:
75:
76:
    ! Set density
78:
    SUBROUTINE set_elemexforcevec3d_rho(efv3d, rho)
80:
    TYPE(struct_elemexforcevec3d), INTENT(INOUT) :: efv3d
81:
82:
83:
    REAL(8), INTENT(IN) :: rho(:)
84:
```



```
122:
     SUBROUTINE set_elemexforcevec3d_g(efv3d, g)
124:
125:
     TYPE(struct\_elemexforcevec3d), INTENT(INOUT) :: efv3d
126:
127:
     REAL(8), INTENT(IN) :: g
128:
129: !---
130:
131:
     efv3d\%g = g
132:
133: !--
134:
135:
     RETURN
136:
138:
     END SUBROUTINE set_elemexforcevec3d_g
140:
141:
142:
     ! Get gravitational acceleration
144:
     SUBROUTINE get_elemexforcevec3d_g(efv3d, g)
146:
147:
     TYPE(struct_elemexforcevec3d), INTENT(IN) :: efv3d
148:
     REAL(8), INTENT(OUT) :: g
149:
150:
151:!--
152:
153:
     g = efv3d%g
154:
155:!-
156:
```

```
157:
       RETURN
158:
160:
       END SUBROUTINE get_elemexforcevec3d_g
162:
163:
165:
       SUBROUTINE init_elemexforcevec3d(efv3d, ns3d, le3d, es3d)
167:
168:
       TYPE(struct_elemexforcevec3d), INTENT(INOUT) :: efv3d
169:
       TYPE(struct_nodes3d), TARGET, INTENT(IN) :: ns3d
170:
171:
       TYPE(struct\_localelement3d), TARGET, INTENT(IN) :: le3d
172:
       TYPE(struct_elements3d), TARGET, INTENT(IN)
                                        ∷ es3d
173:
174:!-
175:
176:
       INTEGER :: le3d_nnodes
177:
       INTEGER :: es3d_n
178:
179: !--
180:
181:
       efv3d%ns3d => ns3d
182:
       efv3d%le3d => le3d
183:
       efv3d\%es3d \Rightarrow es3d
184:
185:!--
186:
187:
       CALL get_localelement3d_nnodes(efv3d%le3d, le3d_nnodes)
188:
189:
       CALL get_elements3d_n(efv3d%es3d, es3d_n)
190:
191:!-
192:
```





<u>第4節のプログラム:モジュール mod fem3d の作成</u>

3. 有限要素法モジュール mod_fem3d.f90

1:	MODULE mod_fem3d
2:!	***************************************
3:	
4:	USE mod_nodes3d
5:	USE mod_localelement3d
6:	USE mod_elements3d
7:	USE mod_elemstiffmat3d
8:	USE mod_elemexforcevec3d
9:	
10:!	
11:	
12:	IMPLICIT NONE
13:	
14:!	
15:	
16:	TYPE :: struct_fem3d
17:	
18:	!
19:	
20:	PRIVATE
21:	
22:	!
23:	
24:	$TYPE (struct_nodes3d), POINTER :: ns3d => NULL()$
25:	<pre>TYPE(struct_localelement3d), POINTER :: le3d => NULL()</pre>
26:	$\label{type} \verb TYPE(struct_elements3d) , POINTER :: es3d => \verb NULL() \\$
27:	<pre>TYPE(struct_elemstiffmat3d), POINTER :: esm3d => NULL()</pre>
28:	$\label{eq:type} \textit{TYPE} (\texttt{struct_elemexforcevec3d}) , \;\; \textit{POINTER} \; :: \;\; \texttt{efv3d} \; \Rightarrow \; \textit{NULL} ()$
29:	
30:	!
31:	!

```
32:
          ! ndofs
33:
          ! The total number of DOFs
34:
35:
          ! k(:, :)
36:
          ! Stiffness matrix
37:
38:
          ! f(:)
39:
          ! External force vector
40:
41:
42:
43:
          ! nnodes_loaded
44:
          ! The total number of nodes with an equivalent nodal force
45:
          !
46:
          ! id_loaded(:)
          ! Node no. with an equivalent nodal force
47:
48:
49:
          ! f_loaded(:, :)
          ! Equivalent nodal force
50:
51:
          !
52:
53:
54:
          {\tt INTEGER} \ :: \ {\tt ndofs}
55:
          INTEGER :: nnodes_loaded
56:
          INTEGER, ALLOCATABLE :: id_loaded(:)
57:
58:
          REAL(8), ALLOCATABLE :: k(:, :)
          REAL(8), ALLOCATABLE :: f(:)
59:
          REAL(8), ALLOCATABLE :: f_loaded(:, :)
60:
61:
62:
63:
         END TYPE struct_fem3d
64:
65:
66:!-
67:
```

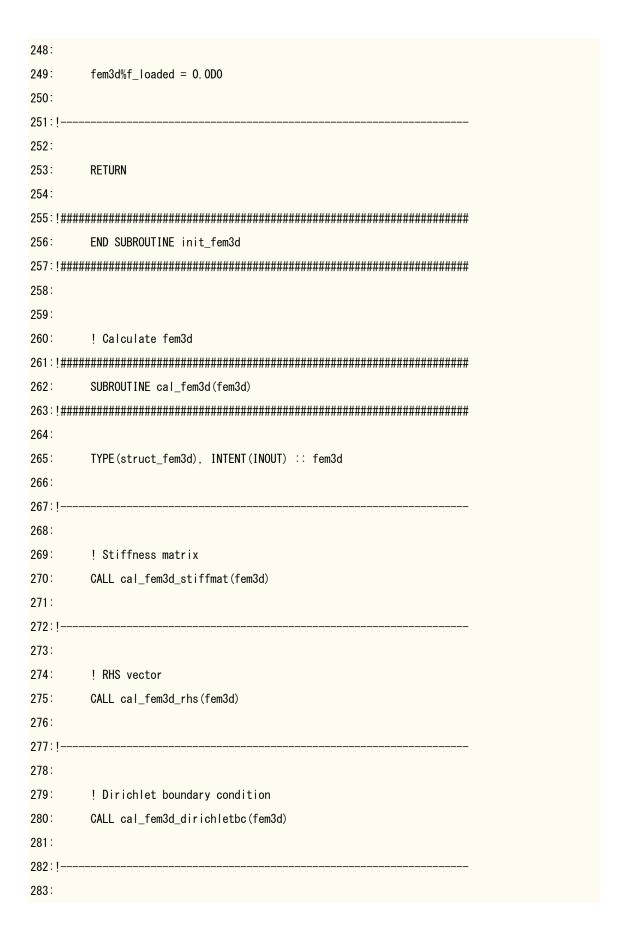
```
68:
     PRIVATE :: cal_fem3d_stiffmat
69:
     PRIVATE :: cal_fem3d_rhs
     PRIVATE :: cal_fem3d_dirichletbc
70:
71:
     PRIVATE :: cal_fem3d_linearsolver
72:
73:!---
74:
75:
     CONTAINS
76:
77:
78:
     ! Get the total number of DOFs
80:
     SUBROUTINE get_fem3d_ndofs(fem3d, ndofs)
82:
83:
     TYPE(struct_fem3d), INTENT(IN) :: fem3d
84:
     INTEGER, INTENT(OUT) :: ndofs
85:
86:
87:!--
88:
89:
     ndofs = fem3d%ndofs
90:
92:
93:
     RETURN
94:
96:
     END SUBROUTINE get_fem3d_ndofs
98:
99:
100:
     ! Get stiffness matrix
102:
     SUBROUTINE get_fem3d_k (fem3d, k)
```

```
104:
105:
     TYPE(struct_fem3d), INTENT(IN) :: fem3d
106:
107:
     INTEGER, INTENT(OUT) :: k(:, :)
108:
109: !---
110:
111: k = fem3d%k
112:
114:
115:
     RETURN
116:
118:
     END SUBROUTINE get_fem3d_k
120:
121:
122:
     ! Get external force vector
124:
     SUBROUTINE get_fem3d_f (fem3d, f)
126:
127:
    TYPE(struct_fem3d), INTENT(IN) :: fem3d
128:
129:
    INTEGER, INTENT(OUT) :: f(:)
130:
131: !-----
132:
133:
    f = fem3d\%f
134:
135:!---
136:
137:
     RETURN
138:
```

```
140:
     END SUBROUTINE get_fem3d_f
142:
143:
144:
     ! Set equivalent nodal force
SUBROUTINE set_fem3d_f_loaded(fem3d, id_loaded, f_loaded)
148:
149:
     TYPE(struct fem3d), INTENT(INOUT) :: fem3d
150:
151:
     INTEGER, INTENT(IN) :: id_loaded(:)
     REAL(8), INTENT(IN) :: f_loaded(:, :)
152:
153:
154:!--
155:
     fem3d%id_loaded = id_loaded
156:
     fem3d\%f_loaded = f_loaded
157:
158:
159:!--
160:
161:
     RETURN
162:
164:
     END SUBROUTINE set_fem3d_f_loaded
166:
167:
168:
     ! Get equivalent nodal force
SUBROUTINE get_fem3d_f_loaded(fem3d, id_loaded, f_loaded)
172:
173:
     TYPE(struct_fem3d), INTENT(IN) :: fem3d
174:
175:
     INTEGER, INTENT(OUT) :: id_loaded(:)
```

```
176:
       REAL(8), INTENT(OUT) :: f_loaded(:, :)
177:
178:!-
179:
180:
       id_loaded = fem3d%id_loaded
181:
       f_loaded = fem3d%f_loaded
182:
183: !--
184:
185:
       RETURN
186:
188:
       END SUBROUTINE get_fem3d_f_loaded
190:
191:
192:
       ! Initialize fem3d
194:
       SUBROUTINE init_fem3d
195:
               (fem3d, ns3d, le3d, es3d, esm3d, efv3d, &
196:
               nnodes_loaded)
198:
199:
       TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
200:
201:
       TYPE(struct_nodes3d), TARGET, INTENT(IN)
                                          ∷ ns3d
202:
       TYPE(struct_localelement3d), TARGET, INTENT(IN) :: le3d
       TYPE(struct_elements3d), TARGET, INTENT(IN)
203:
                                          ∷ es3d
204:
       TYPE(struct_elemstiffmat3d), TARGET, INTENT(IN) :: esm3d
205:
       TYPE(struct_elemexforcevec3d), TARGET, INTENT(IN) :: efv3d
206:
207:
       INTEGER, INTENT(IN) :: nnodes_loaded
208:
209: !--
210:
211:
       INTEGER :: ns3d_n
```

```
212:
213: !--
214:
215:
          fem3d\%ns3d \Rightarrow ns3d
216:
          fem3d\%le3d \Rightarrow le3d
217:
          fem3d\%es3d \Rightarrow es3d
218:
          fem3d\%esm3d \Rightarrow esm3d
219:
          fem3d\%efv3d \Rightarrow efv3d
220:
221:!--
222:
223:
          CALL get_nodes3d_n(fem3d%ns3d, ns3d_n)
224:
225:!--
226:
227:
          fem3d\%ndofs = 3*ns3d_n
228:
229:
230:
231:
          ALLOCATE ( fem3d%k (fem3d%ndofs, fem3d%ndofs) )
232:
233:
           fem3d\%k = 0.0D0
234:
235:
           ALLOCATE( fem3d%f(fem3d%ndofs) )
236:
237:
           fem3d\%f = 0.0D0
238:
239:
240:
241:
          fem3d%nnodes_loaded = nnodes_loaded
242:
243:
           ALLOCATE( fem3d%id_loaded(nnodes_loaded) )
244:
245:
           fem3d\%id_loaded = 0
246:
          ALLOCATE ( fem3d%f_loaded(3, nnodes_loaded) )
247:
```



```
284:
      ! Linear solver
      CALL cal_fem3d_linearsolver(fem3d)
285:
286:
287: !---
288:
289:
      ! Strain and stress
290:
      CALL cal elemstiffmat3d(fem3d%esm3d)
291:
292: !---
293:
294:
      RETURN
295:
297:
      END SUBROUTINE cal_fem3d
299:
300:
      ! Calculate fem3d (stiffness matrix)
301:
303:
      SUBROUTINE cal_fem3d_stiffmat(fem3d)
305:
      TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
306:
307:
308: !--
309:
310:
      INTEGER :: le3d_nnodes
311:
      INTEGER ∷ es3d_n
312:
      INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
313:
      INTEGER :: i, j
314:
      INTEGER ∷ id, jd
315:
      INTEGER :: na, nb
      INTEGER :: ie
316:
317:
      INTEGER :: idof, jdof
318:
      INTEGER :: isize, jsize
319:
```

```
320:
          REAL(8), ALLOCATABLE :: esm3d_k(:, :, :)
321:
          REAL(8), ALLOCATABLE :: efv3d_f(:, :)
322:
323: !--
324:
325:
          ! Element stiffness matrix
          CALL cal_elemstiffmat3d(fem3d%esm3d)
326:
327:
328: !--
329:
330:
          CALL get_localelement3d_nnodes(fem3d%le3d, le3d_nnodes)
331:
332:
          CALL get_elements3d_n(fem3d%es3d, es3d_n)
333:
          ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
334:
          CALL get_elements3d_connectivity(fem3d%es3d, es3d_connectivity)
335:
336:
          ALLOCATE( esm3d_k(3*le3d_nnodes, 3*le3d_nnodes, es3d_n) )
337:
          CALL get_elemstiffmat3d_k(fem3d%esm3d, esm3d_k)
338:
339:
          ! Stiffness matrix
340:
341:
          fem3d\%k = 0.0D0
342:
343:
          DO ie = 1, es3d_n
344:
345:
           D0 na = 1, le3d_nnodes
346:
347:
            id = es3d_connectivity(na, ie)
348:
349:
            D0 i = 1, 3
350:
351:
             idof = 3*(id-1)+i
352:
             isize = 3*(na-1)+i
353:
354:
             D0 \text{ nb} = 1, le3d\_nnodes
355:
```

```
356:
           jd = es3d_connectivity(nb, ie)
357:
358:
           D0 j = 1, 3
359:
360:
           jdof = 3*(jd-1)+j
361:
           jsize = 3*(nb-1)+j
362:
363:
           fem3d%k(idof, jdof)
                                                  &
           = fem3d%k(idof, jdof)+esm3d_k(isize, jsize, ie)
364:
365:
366:
           END DO
367:
          END DO
368:
369:
370:
         END DO
371:
372:
        END DO
373:
374:
       END DO
375:
376:!-
377:
378:
       DEALLOCATE( es3d_connectivity )
379:
380:
       DEALLOCATE (\ esm3d\_k\ )
381:
382: !--
383:
384:
       RETURN
385:
387:
       END SUBROUTINE cal_fem3d_stiffmat
389:
390:
391:
       ! Calculate fem3d (RHS vector)
```

```
393:
        SUBROUTINE cal_fem3d_rhs(fem3d)
395:
396:
        TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
397:
398: !--
399:
400:
        INTEGER :: le3d_nnodes
401:
        INTEGER :: es3d_n
402:
        INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
403:
        INTEGER :: i
        INTEGER :: id
404:
405:
        INTEGER :: id_l
406:
        INTEGER :: na
407:
        INTEGER :: ie
408:
        INTEGER :: idof
409:
        INTEGER :: isize
410:
411:
        REAL(8), ALLOCATABLE :: efv3d_f(:, :)
412:
413:!--
414:
415:
        ! Element external force vector
416:
        CALL cal_elemexforcevec3d(fem3d%efv3d)
417:
418: !--
419:
420:
        CALL get_localelement3d_nnodes(fem3d%le3d, le3d_nnodes)
421:
422:
        CALL get_elements3d_n(fem3d%es3d, es3d_n)
423:
        ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
424:
        CALL get_elements3d_connectivity(fem3d%es3d, es3d_connectivity)
425:
426:
        ALLOCATE( efv3d_f(3*le3d_nnodes, es3d_n) )
427:
        CALL get_elemexforcevec3d_f(fem3d%efv3d, efv3d_f)
```

```
428:
429:
430:
431:
          ! External force vector
432:
433:
          fem3d\%f = 0.0D0
434:
435:
          D0 id_I = 1, fem3d%nnodes_loaded
436:
437:
           id = fem3d%id_loaded(id_l)
438:
439:
           D0 i = 1, 3
440:
441:
           idof = 3*(id-1)+i
442:
443:
            fem3d%f(idof) = fem3d%f_loaded(i, id_l)
444:
           END DO
445:
446:
447:
          END DO
448:
449:
          DO ie = 1, es3d_n
450:
451:
           D0 na = 1, le3d_nnodes
452:
453:
            id = es3d_connectivity(na, ie)
454:
455:
            D0 i = 1, 3
456:
457:
             idof = 3*(id-1)+i
458:
             isize = 3*(na-1)+i
459:
460:
             fem3d%f(idof) = fem3d%f(idof)+efv3d_f(isize, ie)
461:
462:
            END DO
463:
```

```
464:
       END DO
465:
466:
      END DO
467:
468: !-
469:
470:
      DEALLOCATE( es3d_connectivity )
471:
472:
      DEALLOCATE( efv3d_f )
473:
474: !--
475:
476:
      RETURN
477:
479:
      END SUBROUTINE cal_fem3d_rhs
481:
482:
483:
      ! Calculate fem3d (Dirichlet boundary condition)
SUBROUTINE cal_fem3d_dirichletbc(fem3d)
487:
488:
      TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
489:
490:!--
491:
492:
      INTEGER :: ns3d_n
493:
      INTEGER, ALLOCATABLE :: ns3d_bc(:)
494:
      INTEGER ∷ idof, jdof
495:
      INTEGER :: idof_g
496:
      INTEGER :: ndofs_given
497:
      INTEGER, ALLOCATABLE :: idof_given(:)
498:
499:
      REAL(8), ALLOCATABLE :: ns3d_u(:)
```

```
500:
          REAL(8) :: u_given
501:
502:!-
503:
504:
          CALL get_nodes3d_n(fem3d%ns3d, ns3d_n)
505:
          ALLOCATE ( ns3d_u (fem3d%ndofs) )
506:
          CALL get_nodes3d_u(fem3d%ns3d, ns3d_u)
507:
          ALLOCATE( ns3d_bc(fem3d%ndofs) )
508:
          CALL get_nodes3d_bc(fem3d%ns3d, ns3d_bc)
509:
510:!--
511:
512:
          idof_g = 0
513:
514:
          D0 idof = 1, fem3d%ndofs
515:
516:
          IF( ns3d_bc(idof) .EQ. 1 ) THEN
517:
518:
          idof_g = idof_g+1
519:
           END IF
520:
521:
522:
          END DO
523:
524:
          ndofs_given = idof_g
525:
526:
527:
          ALLOCATE ( idof_given(ndofs_given) )
528:
529:
530:
531:
          idof_g = 0
532:
533:
534:
          D0 idof = 1, fem3d\%ndofs
535:
```

```
536:
           IF( ns3d\_bc(idof) . EQ. 1 ) THEN
537:
538:
            idof_g = idof_g+1
539:
540:
            idof_given(idof_g) = idof
541:
542:
           END IF
543:
544:
          END DO
545:
546:!-
547:
548:
          ! Dirichlet boundary conditions
549:
550:
          DO idof_g = 1, ndofs_given
551:
552:
           jdof = idof_given(idof_g)
553:
554:
           D0 idof = 1, fem3d%ndofs
555:
556:
            fem3d\%f(idof) = fem3d\%f(idof)-fem3d\%k(idof, jdof)*ns3d_u(jdof)
557:
           END DO
558:
559:
560:
          END DO
561:
562:
          DO idof_g = 1, ndofs_given
563:
564:
           idof = idof_given(idof_g)
565:
566:
           fem3d\%f(idof) = ns3d_u(idof)
567:
          END DO
568:
569:
570:
          DO idof_g = 1, ndofs_given
571:
```

```
572:
       jdof = idof_given(idof_g)
573:
574:
       D0 idof = 1, fem3d%ndofs
575:
576:
       fem3d\%k(idof, jdof) = 0.0D0
       fem3d\%k(jdof, idof) = 0.0D0
577:
578:
       END DO
579:
580:
581:
       fem3d\%k(jdof, jdof) = 1.0D0
582:
583:
      END DO
584:
585: !-
586:
587:
      DEALLOCATE( ns3d_u )
588:
      DEALLOCATE( ns3d_bc )
589:
590:
      DEALLOCATE( idof_given )
591:
592:!-
593:
594:
      RETURN
595:
END SUBROUTINE cal_fem3d_dirichletbc
599:
600:
601:
      ! Calculate fem3d (linear solver)
603:
      SUBROUTINE cal_fem3d_linearsolver(fem3d)
605:
606:
      TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
607:
```

```
608: !----
609:
610:
      INTEGER :: ipiv(fem3d%ndofs)
611:
      INTEGER ∷ info
612:
613: !---
614:
615:
     ! Linear solver
616:
617:
     ipiv = 0
618:
619:
      CALL DGESV
         (fem3d%ndofs, 1, fem3d%k, fem3d%ndofs, ipiv, &
620:
621:
          fem3d%f, fem3d%ndofs, info)
622:
623:
      CALL set_nodes3d_u (fem3d%ns3d, fem3d%f)
624:
625:!--
626:
627:
      RETURN
628:
630:
      END SUBROUTINE cal_fem3d_linearsolver
632:
633:
634:
      ! Delete fem3d
636:
      SUBROUTINE del_fem3d(fem3d)
638:
      TYPE(struct_fem3d), INTENT(INOUT) :: fem3d
639:
640:
641:!----
642:
643: IF ( fem3d%ndofs .EQ. 0 ) THEN
```

```
644:
645:
           RETURN
646:
647:
          END IF
648:
649:!-
650:
651:
          NULLIFY( fem3d%ns3d )
652:
          NULLIFY( fem3d%le3d )
653:
          NULLIFY( fem3d%es3d )
654:
          NULLIFY( fem3d%esm3d )
          NULLIFY( fem3d%efv3d )
655:
656:
657:!-
658:
659:
          fem3d\%ndofs = 0
660:
661:
662:
663:
          DEALLOCATE( fem3d%k )
664:
          DEALLOCATE( fem3d%f )
665:
666:!-
667:
668:
          IF( fem3d%nnodes_loaded .EQ. 0 ) THEN
669:
670:
           RETURN
671:
          END IF
672:
673:
674:!-
675:
676:
          fem3d\%nnodes_loaded = 0
677:
678:
679:
```

```
680:
    DEALLOCATE( fem3d%id_loaded )
    DEALLOCATE( fem3d%f_loaded )
681:
682:
683: !--
684:
685:
    RETURN
686:
688:
    END SUBROUTINE del_fem3d
690:
691:
693:
    END MODULE mod_fem3d
```

第 5 節のプログラム: メッシング用のアプリケーションモジュール mod_{appli} の修正

4. アプリケーションモジュール mod_appli.f90

```
MODULE mod_appli
3:
4:
      USE mod_nodes3d
5:
      USE mod_localelement3d
      USE mod_elements3d
6:
7:
      USE mod_elemstiffmat3d
      USE mod_elemexforcevec3d
9:
      USE mod_fem3d
10:
      USE mod_rectmesher3d
11:
12:!-
13:
14:
      IMPLICIT NONE
15:
```

```
16:!----
17:
       TYPE(struct_nodes3d), POINTER
18:
                                     ∷ ns3d
19:
       TYPE(struct_localelement3d), POINTER :: le3d
20:
       TYPE(struct_elements3d), POINTER
                                     ∷ es3d
21:
       TYPE(struct_elemstiffmat3d), POINTER :: esm3d
22:
       TYPE(struct_elemexforcevec3d), POINTER :: efv3d
23:
       TYPE(struct_fem3d), POINTER
                                     ∷ fem3d
       TYPE(struct_rectmesher3d), POINTER :: rm3d
24:
25:
26:
27:
       ! Problem number
28:
29:
       ! prob
30:
       Ţ
31:
32:
33:
       INTEGER ∷ prob
34:
35:!--
36:
37:
       CONTAINS
38:
39:
40:
      ! Start appli
SUBROUTINE start_appli()
44:
45:
       INTEGER :: ns3d_n
46:
       INTEGER :: le3d_nboundaries
       INTEGER :: le3d_nnodes
47:
48:
       INTEGER :: le3d_nqps
49:
       INTEGER :: es3d_n
50:
       INTEGER :: rm3d_n_x(3)
51:
```

```
52:
        REAL(8) :: rm3d_x_start(3)
53:
        REAL(8) :: rm3d_x_end(3)
54:
        REAL(8) ∷ e
55:
        REAL (8) :: nu
56:
        REAL(8) :: rho
57:
        REAL (8) :: g
58:
59:
        CHARACTER(1) :: dataname
60:
61:1--
62:
63:
        ALLOCATE ( ns3d )
64:
        ALLOCATE( le3d )
        ALLOCATE( es3d )
66:
        ALLOCATE( esm3d )
67:
        ALLOCATE( efv3d )
68:
        ALLOCATE( fem3d )
        ALLOCATE( rm3d )
69:
70:
71:!--
72:
73:
        OPEN(13, FILE = 'param_meshing.dat')
74:
75:
        READ(13, *) dataname
76:
        READ(13, *) rm3d_n_x(1), rm3d_n_x(2), rm3d_n_x(3)
77:
        READ(13, *) dataname
78:
        READ(13, *) rm3d_x_start(1), rm3d_x_start(2), rm3d_x_start(3)
79:
        READ(13, *) dataname
80:
        READ(13, *) rm3d_x_end(1), rm3d_x_end(2), rm3d_x_end(3)
81:
        READ(13, *) dataname
82:
        READ(13, *) prob
83:
        READ(13, *) dataname
        READ(13, *) e
84:
85:
        READ(13, *) dataname
86:
        READ (13, *) nu
87:
        READ(13, *) dataname
```

```
88:
          READ(13, *) rho
 89:
          READ(13, *) dataname
 90:
          READ (13, *) g
 91:
          READ(13, *) dataname
 92:
 93:
          CLOSE (13)
 94:
 95:!
 96:
 97:
          OPEN(13, FILE = 'param_fea.dat')
 98:
 99:
          WRITE(13, '(A)') '!ANALYSIS_TYPE'
100:
          WRITE(13, '(A)') 'STATIC_ANALYSIS'
101:
          WRITE(13, '(A)') "!YOUNG'S_MODULUS"
102:
          WRITE(13, '(E17.8)') e
          WRITE(13, '(A)') "!POISSON'S_RATIO"
103:
104:
          WRITE(13, '(E17.8)') nu
          WRITE(13, '(A)') '!DENSITY'
105:
106:
          WRITE(13, '(E17.8)') rho
107:
          WRITE (13, '(A)') '!GRAVITATIONAL_ACCELERATION'
108:
          WRITE(13, '(E17.8)') g
109:
110:!-
111:
112:
          CALL init_rectmesher3d
                                                     &
113:
               (rm3d, ns3d, le3d, es3d,
114:
                rm3d_n_x, rm3d_x_start, rm3d_x_end)
115:
116:!-
117:
118:
          CALL get_nodes3d_n(ns3d, ns3d_n)
119:
120:
          CALL get_localelement3d_nboundaries(le3d, le3d_nboundaries)
121:
          CALL get_localelement3d_nnodes(le3d, le3d_nnodes)
122:
          CALL get_localelement3d_nqps(le3d, le3d_nqps)
123:
```

```
124:
       CALL get_elements3d_n(es3d, es3d_n)
125:
126:
127:
128:
       CALL init_nodes3d(ns3d, ns3d_n)
129:
130:
       CALL init_localelement3d
131:
           (le3d, le3d_nboundaries, le3d_nnodes, le3d_nqps)
132:
133:
       CALL init_elements3d(es3d, ns3d, le3d, es3d_n)
134:
135:!-
136:
137:
       RETURN
138:
END SUBROUTINE start_appli
142:
143:
144:
       ! Run appli
146:
       SUBROUTINE run_appli()
148:
149:
       INTEGER :: ns3d_n
       INTEGER, ALLOCATABLE :: ns3d_bc(:)
150:
       INTEGER :: le3d_nboundaries
151:
152:
       INTEGER :: le3d_nnodes
153:
       INTEGER :: le3d_nnodes_boundary
154:
       INTEGER, ALLOCATABLE :: le3d_table_na(:, :)
155:
       INTEGER :: es3d_n
156:
       INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
157:
       INTEGER :: es3d_ie_max_volume
158:
       INTEGER :: es3d_ie_min_volume
159:
       INTEGER :: fem3d_ndofs
```

```
160:
          INTEGER :: fem3d_nnodes_loaded
161:
          INTEGER, ALLOCATABLE :: fem3d_id_loaded(:)
          INTEGER :: i
162:
163:
          INTEGER :: id
164:
          INTEGER :: id_I
165:
          INTEGER :: na
          INTEGER :: ie
166:
          INTEGER :: idof
167:
168:
169:
          REAL(8), ALLOCATABLE :: ns3d_x(:, :)
          REAL(8), ALLOCATABLE :: ns3d_u(:)
170:
171:
          REAL(8), ALLOCATABLE :: es3d_volume(:)
172:
          REAL(8) :: es3d_max_volume
173:
          REAL(8) :: es3d_min_volume
174:
          REAL(8) :: es3d_sum_volume
175:
          REAL(8), ALLOCATABLE :: fem3d_f_loaded(:, :)
176:
          REAL(8) :: rm3d_x_start(3)
177:
          REAL(8) :: rm3d_x_end(3)
178:
          REAL(8) :: rm3d_x_center(3)
179:
          REAL(8) :: rm3d\_length\_x(3)
180:
          REAL(8), ALLOCATABLE :: x_local(:, :)
181:
182: !-
183:
184:
          CALL cal_rectmesher3d(rm3d)
185:
186:
          CALL cal_elements3d(es3d)
187:
188: !-
189:
190:
          CALL get_nodes3d_n(ns3d, ns3d_n)
191:
192:
          ALLOCATE(ns3d_x(3, ns3d_n))
193:
          CALL get_nodes3d_x (ns3d, ns3d_x)
194:
          ALLOCATE( ns3d_u(3*ns3d_n) )
          ns3d_u = 0.000
195:
```

```
196:
          ALLOCATE( ns3d_bc(3*ns3d_n) )
197:
          ns3d_bc = 0
198:
199:
          CALL get_localelement3d_nboundaries(le3d, le3d_nboundaries)
200:
          CALL get_localelement3d_nnodes(le3d, le3d_nnodes)
201:
          CALL get_localelement3d_nnodes_boundary(le3d, le3d_nnodes_boundary)
202:
          ALLOCATE( le3d_table_na(le3d_nnodes_boundary, le3d_nboundaries) )
203:
          CALL get_localelement3d_table_na(le3d, le3d_table_na)
204:
205:
          CALL get_elements3d_n(es3d, es3d_n)
206:
          ALLOCATE( es3d_volume(es3d_n) )
207:
          CALL get_elements3d_volume
                                                      &
208:
               (es3d, es3d_volume,
209:
                es3d_max_volume, es3d_ie_max_volume, &
210:
                es3d_min_volume, es3d_ie_min_volume, &
211:
                es3d_sum_volume)
212:
          ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
213:
          CALL get_elements3d_connectivity(es3d, es3d_connectivity)
214:
          CALL get_rectmesher3d_x_start_x_end &
215:
               (rm3d, rm3d_x_start, rm3d_x_end, &
216:
                rm3d_x_center, rm3d_length_x)
217:
          ALLOCATE(x_local(3, le3d_nnodes_boundary))
218:
219:
220: !-
221:
222:
          ! Tensile deformation
223:
          IF (prob.EQ. 1) THEN
224:
225:
226:
227:
           id_I = 0
228:
229:
           D0 id = 1, ns3d_n
230:
231:
            IF ( DABS ( ns3d_x(1, id)-rm3d_x=nd(1) ) .LT. EPSILON(1.0D0) ) THEN
```

```
232:
233:
             id_l = id_l + 1
234:
235:
            END IF
236:
237:
           END DO
238:
239:
           fem3d_nnodes_loaded = id_l
240:
241:
242:
243:
          END IF
244:
245:
246:
247:
          CALL init_elemstiffmat3d(esm3d, ns3d, le3d, es3d)
248:
          CALL init_elemexforcevec3d(efv3d, ns3d, le3d, es3d)
249:
          CALL init_fem3d
250:
                (fem3d, ns3d, le3d, es3d, esm3d, efv3d, &
251:
                fem3d_nnodes_loaded)
252:
253:
          CALL get_fem3d_ndofs(fem3d, fem3d_ndofs)
254:
          ALLOCATE( fem3d_id_loaded(fem3d_nnodes_loaded) )
255:
          fem3d_id_loaded = 0
256:
          \label{locate} ALLOCATE (\ fem3d\_f\_loaded (3,\ fem3d\_nnodes\_loaded)\ )
257:
          fem3d_f_loaded = 0.000
258:
259:
260:
261:
          ! Tensile deformation
262:
          IF (prob.EQ. 1) THEN
263:
264:
265:
266:
           D0 id = 1, ns3d_n
267:
```

```
268:
            IF ( DABS ( ns3d_x(1, id)-rm3d_x_start(1) ) .LT. EPSILON(1.0D0) ) THEN
269:
270:
             idof = 3*(id-1)+1
271:
272:
             ns3d_u(idof) = 0.000
273:
             ns3d_bc(idof) = 1
274:
             IF ( DABS ( ns3d_x(2, id)-rm3d_x\_center(2) ) .LT. EPSILON(1.0D0) ) THEN
275:
276:
277:
              idof = 3*(id-1)+2
278:
279:
              ns3d_u(idof) = 0.000
280:
              ns3d_bc(idof) = 1
281:
282:
             END IF
283:
284:
             IF(\ DABS(\ ns3d\_x(3,\ id)-rm3d\_x\_center(3)\ )\ .LT.\ EPSILON(1.0D0)\ )\ THEN
285:
286:
              idof = 3*(id-1)+3
287:
288:
              ns3d_u(idof) = 0.000
289:
              ns3d_bc(idof) = 1
290:
291:
             END IF
292:
293:
            END IF
294:
295:
           END DO
296:
297:
298:
299:
          END IF
300:
301:
302:
303:
          id_l = 0
```

```
304:
305:
          ! Tensile deformation
306:
          IF(prob.EQ. 1) THEN
307:
308:
309:
310:
           D0 id = 1, ns3d_n
311:
312:
            IF ( DABS ( ns3d_x(1, id)-rm3d_x=nd(1) ) .LT. EPSILON(1.0D0) ) THEN
313:
314:
             id_l = id_l + 1
315:
316:
             fem3d_id_loaded(id_l) = id
317:
             fem3d_f_loaded(1, id_l) = 2.5D6
318:
319:
             IF ( DABS ( ns3d_x(2, id) - rm3d_x_center(2) ) .LT. EPSILON(1.0D0) ) THEN
320:
321:
              fem3d_f_loaded(1, id_l) = 5.0D6
322:
323:
             END IF
324:
325:
             IF ( DABS ( ns3d_x(3, id)-rm3d_x\_center(3) ) .LT. EPSILON(1.0D0) ) THEN
326:
327:
              fem3d_f_loaded(1, id_l) = 5.006
328:
329:
             END IF
330:
             IF ( DABS ( ns3d_x(2, id)-rm3d_x_center(2) ) .LT. EPSILON(1.0D0) ) THEN
331:
332:
333:
              IF ( DABS ( ns3d_x(3, id)-rm3d_x_center(3) ) .LT. EPSILON(1.0D0) ) THEN
334:
335:
               fem3d_f_loaded(1, id_l) = 1.0D7
336:
337:
              END IF
338:
             END IF
339:
```

```
340:
           END IF
341:
342:
343:
          END DO
344:
345:
346:
347:
         END IF
348:
349:
         {\tt CALL \ set\_fem3d\_f\_loaded}
350:
               (fem3d, fem3d_id_loaded, fem3d_f_loaded)
351:
352: !-
353:
354:
         OPEN(10, FILE = 'mesh.dat')
355:
356:
          WRITE(10, '(A)') '!NODE'
357:
358:
         D0 id = 1, ns3d_n
359:
          WRITE( 10, '( I8, 3(A, E17.8) )')
360:
361:
                 id, (',', ns3d_x(i, id), i = 1, 3)
362:
363:
          END DO
364:
365:
          WRITE( 10, '(A, 3(A, I3) )')
366:
                '!ELEMENT', ', ', le3d_nboundaries, &
                            ', ', le3d_nnodes, ', ', 2
367:
368:
369:
370:
          D0 ie = 1, es3d_n
371:
          WRITE( 10, '( I8, 27(A, I8) )')
372:
373:
                 ie, (',', es3d_connectivity(na, ie), &
374:
                       na = 1, le3d_nnodes)
375:
```

```
376:
         END DO
377:
378:
         WRITE(10, '(A)') '!END'
379:
380:
          CLOSE (10)
381:
382: !-
383:
384:
         OPEN(11, FILE = 'ic.dat')
385:
386:
         WRITE(11, '(A)') '!DISPLACEMENT'
387:
388:
         D0 id = 1, ns3d_n
389:
390:
          WRITE( 11, '(I8, 3(A, E17.8))')
391:
                 id, (', ', ns3d_u(3*(id-1)+i), i = 1, 3)
392:
393:
         END DO
394:
395:
         WRITE(11, '(A)') '!END'
396:
397:
         CLOSE (11)
398:
399: !-
400:
401:
         OPEN(12, FILE = 'bc.dat')
402:
         WRITE(12, '(A)') '!DISPLACEMENT'
403:
404:
405:
         D0 id = 1, ns3d_n
406:
407:
          WRITE( 12, '(18, 3(A, 18) )')
                 id, (', ', ns3d_bc(3*(id-1)+i), i = 1, 3)
408:
409:
410:
         END DO
411:
```

```
412:
         WRITE(12, '(A)') '!END'
413:
414:
         CLOSE (12)
415:
416:!-
417:
418:
         WRITE(13, '(A)') '!F_LOADED'
419:
420:
         DO id_I = 1, fem3d_nnodes_loaded
421:
422:
          WRITE( 13, '(18, 3(A, E17.8))')
423:
                 fem3d_id_loaded(id_l),
424:
                 (', ', fem3d_f_loaded(i, id_l), i = 1, 3)
425:
426:
         END DO
427:
428:
          WRITE(13, '(A)') '!END'
429:
430:
          CLOSE (13)
431:
432: !-
433:
434:
         OPEN(14, FILE = 'mesh.inp')
435:
436:
         WRITE(14, '(5(18, 1X))') ns3d_n, es3d_n, 3, 13, 0
437:
438:
         D0 id = 1, ns3d_n
439:
          WRITE( 14, '( (I8, 1X), 3(E17.8, 1X) )') &
440:
441:
                 id, (ns3d_x(i, id), i = 1, 3)
442:
443:
         END DO
444:
445:
         D0 ie = 1, es3d_n
446:
         WRITE(14, '(2(I8, 1X), (A5, 1X), 27(I8, 1X))') &
447:
```

```
ie, 1, ' hex',
448:
449:
                  ( es3d_connectivity(na, ie), na = 1, le3d_nnodes )
450:
451:
          END DO
452:
453:
          WRITE(14, '(4(I8, 1X))') 1, 3
454:
          WRITE(14, '(A)') 'DISPLACEMENT, m'
455:
456:
          D0 id = 1, ns3d_n
457:
458:
           WRITE( 14, '( (I8, 1X), 3(E17.8, 1X) )')
459:
                  id, (ns3d_u(3*(id-1)+i), i = 1, 3)
460:
461:
          END DO
462:
          WRITE(14, '( 14I8 )') 1, 1
463:
464:
          WRITE (14, \ \ '\ (\ (A,\ 1X)\ )\ '\ ) \ \ 'VOLUME, \ m3'
465:
466:
          DO ie = 1, es3d_n
467:
           WRITE( 14, '( (I8, 1X), (E17.8, 1X) )') &
468:
469:
                  ie, es3d_volume(ie)
470:
471:
          END DO
472:
473:
          CLOSE (14)
474:
475:!-
476:
477:
          DEALLOCATE( ns3d_x )
478:
          DEALLOCATE( ns3d_u )
479:
480:
          DEALLOCATE( le3d_table_na )
481:
482:
          DEALLOCATE( es3d_volume )
          DEALLOCATE( es3d_connectivity )
483:
```

```
484:
485:
       DEALLOCATE( fem3d_id_loaded )
       DEALLOCATE( fem3d_f_loaded )
486:
487:
488:
       DEALLOCATE( x_local )
489:
490: !-
491:
492:
       RETURN
493:
END SUBROUTINE run_appli
497:
498:
SUBROUTINE finish_appli()
502:
503:
      CALL del_nodes3d(ns3d)
504:
       CALL del_localelement3d(le3d)
505:
      CALL del_elements3d(es3d)
506:
       CALL del_elemstiffmat3d(esm3d)
507:
       CALL del_elemexforcevec3d(efv3d)
508:
      CALL del_fem3d(fem3d)
509:
       CALL del_rectmesher3d(rm3d)
510:
511:!-
512:
513:
      DEALLOCATE( ns3d )
514:
       DEALLOCATE( le3d )
515:
       DEALLOCATE( es3d )
516:
       DEALLOCATE( esm3d )
517:
       DEALLOCATE( efv3d )
518:
       DEALLOCATE( fem3d )
519:
       DEALLOCATE( rm3d )
```



<u>第6節のプログラム:有限要素解析用のアプリケーションモジュール mod_appli</u>の作成

5. アプリケーションモジュール mod_appli.f90

```
MODULE mod_appli
3:
4:
      USE mod_nodes3d
      USE mod_localelement3d
6:
      USE mod_elements3d
7:
      USE mod_elemstiffmat3d
      USE mod_elemexforcevec3d
8:
      USE mod_fem3d
9:
10:
11:!--
12:
13:
      IMPLICIT NONE
14:
15:!----
16:
                                 ∷ ns3d
     TYPE(struct_nodes3d), POINTER
```

```
18:
       TYPE(struct_localelement3d), POINTER :: le3d
19:
       TYPE(struct_elements3d), POINTER
                                        ∷ es3d
20:
       TYPE(struct_elemstiffmat3d), POINTER :: esm3d
21:
       TYPE(struct_elemexforcevec3d), POINTER :: efv3d
22:
       TYPE(struct_fem3d), POINTER
                                         :: fem3d
23:
24:!--
25:
26:
       CONTAINS
27:
28:
29:
       ! Start appli
31:
       SUBROUTINE start_appli()
33:
34:
       INTEGER :: ns3d_n
35:
       INTEGER, ALLOCATABLE :: ns3d_bc(:)
36:
       INTEGER :: le3d_nboundaries
37:
       INTEGER :: le3d_nnodes
38:
       INTEGER :: le3d_nqps
39:
       INTEGER :: es3d_n
40:
       INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
41:
       INTEGER :: fem3d_nnodes_loaded
42:
       INTEGER, ALLOCATABLE :: fem3d_id_loaded(:)
43:
       INTEGER :: fem3d_ndofs
44:
       INTEGER :: i
       INTEGER :: id
45:
46:
       INTEGER :: na
47:
       INTEGER ∷ ie
48:
       INTEGER :: ib
       INTEGER :: idof_g
49:
50:
       INTEGER :: idof_I
51:
       INTEGER :: number
52:
53:
       REAL(8), ALLOCATABLE :: ns3d_x(:, :)
```

```
54:
          REAL(8), ALLOCATABLE :: ns3d_u(:)
55:
          REAL(8), ALLOCATABLE :: esm3d_e(:)
56:
         REAL(8), ALLOCATABLE :: esm3d_nu(:)
57:
          REAL(8), ALLOCATABLE :: efv3d_rho(:)
          \label{eq:REAL} \textbf{REAL}\,(8)\,,\;\; \textbf{ALLOCATABLE}\; :: \; \text{fem3d\_f\_loaded}\,(:,\;\; :)
58:
59:
         REAL(8) ∷ e
60:
          REAL(8) ∷ nu
61:
          REAL(8) ∷ rho
62:
          REAL(8) :: g
63:
64:
          CHARACTER(1) :: dataname
65:
66:!-
67:
68:
         ALLOCATE( ns3d )
69:
          ALLOCATE ( le3d )
70:
          ALLOCATE( es3d )
71:
         ALLOCATE( esm3d )
72:
          ALLOCATE( efv3d )
73:
          ALLOCATE( fem3d )
74:
75:!--
76:
77:
          OPEN(10, FILE = 'mesh.dat')
78:
79:
         READ(10, *) dataname
80:
         ns3d_n = 0
81:
82:
83:
         D0
84:
85:
           READ(10, *) dataname
86:
87:
           ns3d_n = ns3d_n+1
88:
89:
           IF ( dataname . EQ. '!' ) THEN
```

```
90:
 91:
            EXIT
 92:
 93:
           END IF
 94:
 95:
          END DO
 96:
 97:
          ns3d_n = ns3d_n-1
 98:
 99:
          es3d_n = 0
100:
101:
          D0
102:
103:
           READ(10, *) dataname
104:
105:
           es3d_n = es3d_n+1
106:
           IF ( dataname .EQ. '!' ) THEN
107:
108:
109:
            EXIT
110:
111:
           END IF
112:
113:
          END DO
114:
115:
          es3d_n = es3d_n-1
116:
          CLOSE (10)
117:
118:
119:
120:
121:
          OPEN(13, FILE = 'param_fea.dat')
122:
123:
          READ(13, *) dataname
124:
          READ(13, *) dataname
125:
          READ(13, *) dataname
```

```
126:
          READ(13, *) dataname
127:
          READ(13, *) dataname
128:
          READ(13, *) dataname
129:
          READ(13, *) dataname
130:
          READ(13, *) dataname
131:
          READ(13, *) dataname
132:
          READ(13, *) dataname
133:
134:
          READ(13, *) dataname
135:
136:
          fem3d_nnodes_loaded = 0
137:
          D0
138:
139:
140:
           READ(13, *) dataname
141:
142:
           fem3d_nnodes_loaded = fem3d_nnodes_loaded+1
143:
144:
           IF ( dataname . EQ. '!' ) THEN
145:
146:
            EXIT
147:
           END IF
148:
149:
150:
          END DO
151:
152:
          fem3d_nnodes_loaded = fem3d_nnodes_loaded-1
153:
154:
          CLOSE (13)
155:
156: !-
157:
158:
          OPEN(10, FILE = 'mesh.dat')
159:
160:
          READ(10, *) dataname
161:
```

```
162:
          CALL init_nodes3d(ns3d, ns3d_n)
163:
164:
          ALLOCATE ( ns3d_x(3, ns3d_n) )
165:
166:
          D0 id = 1, ns3d_n
167:
168:
           READ(10, *) number, ( ns3d_x(i, id), i = 1, 3 )
169:
170:
          END DO
171:
172:
          CALL set_nodes3d_x (ns3d, ns3d_x)
173:
174:
          READ(10, *) dataname, le3d_nboundaries, le3d_nnodes, le3d_nqps
175:
176:
          CALL init_localelement3d
                                                                  &
177:
               (le3d, le3d_nboundaries, le3d_nnodes, le3d_nqps)
178:
          {\tt CALL\ init\_elements3d(es3d,\ ns3d,\ le3d,\ es3d\_n)}
179:
180:
          ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
181:
182:
          DO ie = 1, es3d_n
183:
           READ(10, *) number, (es3d_connectivity(na, ie), &
184:
185:
                                  na = 1, le3d_nnodes )
186:
187:
          END DO
188:
189:
          CALL set_elements3d_connectivity(es3d, es3d_connectivity)
190:
191:
          CLOSE (10)
192:
193:
194:
195:
          CALL init_elemstiffmat3d(esm3d, ns3d, le3d, es3d)
196:
          CALL init_elemexforcevec3d(efv3d, ns3d, le3d, es3d)
197:
          CALL init_fem3d
```

```
198:
               (fem3d, ns3d, le3d, es3d, esm3d, efv3d, 9)
199:
200:
          CALL get_fem3d_ndofs(fem3d, fem3d_ndofs)
201:
202:
203:
204:
          OPEN(11, FILE = 'ic.dat')
205:
206:
          READ(11, *) dataname
207:
208:
          ALLOCATE ( ns3d_u (3*ns3d_n) )
209:
210:
         D0 id = 1, ns3d_n
211:
212:
           READ(11, *) number, ( ns3d_u(3*(id-1)+i), i = 1, 3)
213:
214:
          END DO
215:
216:
          CALL set_nodes3d_u(ns3d, ns3d_u)
217:
218:
          READ(11, *) dataname
219:
220:
          CLOSE (11)
221:
222:
223:
224:
          OPEN(12, FILE = 'bc.dat')
225:
226:
          READ(12, *) dataname
227:
228:
          ALLOCATE( ns3d_bc(3*ns3d_n) )
229:
230:
          DO id = 1, ns3d_n
231:
232:
           READ(12, *) number, ( ns3d_bc(3*(id-1)+i), i = 1, 3)
233:
```

```
234:
          END DO
235:
236:
          CALL set_nodes3d_bc(ns3d, ns3d_bc)
237:
238:
          READ(12, *) dataname
239:
240:
          CLOSE (12)
241:
242:!-
243:
244:
          OPEN(13, FILE = 'param_fea.dat')
245:
246:
          READ(13, *) dataname
247:
          READ(13, *) dataname
248:
          READ(13, *) dataname
          READ(13, *) e
249:
250:
          READ(13, *) dataname
251:
          READ(13, *) nu
252:
          READ(13, *) dataname
253:
          READ(13, *) rho
254:
          READ(13, *) dataname
255:
          READ(13, *) g
256:
257:
258:
259:
          ALLOCATE( esm3d_e(es3d_n) )
260:
          ALLOCATE( esm3d_nu(es3d_n) )
261:
262:
          ALLOCATE( efv3d_rho(es3d_n) )
263:
264:
          D0 ie = 1, es3d_n
265:
266:
           esm3d_e(ie) = e
267:
           esm3d_nu(ie) = nu
268:
           efv3d_rho(ie) = rho
269:
```

```
270:
271:
          END DO
272:
273:
          CALL set_elemstiffmat3d_e_nu(esm3d, esm3d_e, esm3d_nu)
274:
275:
          CALL set_elemexforcevec3d_rho(efv3d, efv3d_rho)
276:
          CALL set_elemexforcevec3d_g(efv3d, g)
277:
278:
279:
280:
          READ(13, *) dataname
281:
282:
          ALLOCATE( fem3d_id_loaded(fem3d_nnodes_loaded) )
283:
          ALLOCATE ( fem3d_f_loaded(3, fem3d_nnodes_loaded) )
284:
285:
          DO idof_I = 1, fem3d_nnodes_loaded
286:
287:
           READ(13, *) fem3d_id_loaded(idof_l),
288:
                       (fem3d_f_loaded(i, idof_l), i = 1, 3)
289:
290:
          END DO
291:
292:
          CALL set_fem3d_f_loaded
293:
               (fem3d, fem3d_id_loaded, fem3d_f_loaded)
294:
295:
          READ(13, *) dataname
296:
297:
          CLOSE (13)
298:
299: !-
300:
301:
          DEALLOCATE( ns3d_x )
302:
          DEALLOCATE( ns3d_u )
303:
          DEALLOCATE( ns3d_bc )
304:
305:
          DEALLOCATE( es3d_connectivity )
```

```
306:
307:
       DEALLOCATE( esm3d_e )
308:
       DEALLOCATE( esm3d_nu )
309:
310:
       DEALLOCATE( efv3d_rho )
311:
312:
       DEALLOCATE( fem3d_id_loaded )
313:
       DEALLOCATE( fem3d_f_loaded )
314:
315: 1---
316:
317:
       RETURN
318:
320:
       END SUBROUTINE start_appli
322:
323:
324:
       ! Run appli
326:
       SUBROUTINE run_appli()
328:
329:
      INTEGER :: ns3d_n
330:
       INTEGER :: le3d_nnodes
331:
       INTEGER :: es3d_n
332:
       INTEGER, ALLOCATABLE :: es3d_connectivity(:, :)
333:
       INTEGER :: i
334:
       INTEGER :: id
335:
       INTEGER :: na
336:
       INTEGER :: ie
337:
338:
       REAL(8), ALLOCATABLE :: ns3d_x(:, :)
339:
       REAL(8), ALLOCATABLE :: ns3d_u(:)
340:
       REAL(8), ALLOCATABLE :: esm3d_evec(:, :)
341:
       REAL(8), ALLOCATABLE :: esm3d_svec(:, :), esm3d_s_mises(:)
```

```
342:
343: !-
344:
345:
          CALL cal_elements3d(es3d)
346:
347:
          CALL cal_fem3d(fem3d)
348:
349:!
350:
351:
          CALL get_nodes3d_n (ns3d, ns3d_n)
352:
          ALLOCATE( ns3d_x(3, ns3d_n) )
353:
          CALL get_nodes3d_x (ns3d, ns3d_x)
354:
          ALLOCATE( ns3d_u(3*ns3d_n) )
355:
          CALL get_nodes3d_u(ns3d, ns3d_u)
356:
357:
          CALL get_localelement3d_nnodes(le3d, le3d_nnodes)
358:
359:
          CALL get_elements3d_n(es3d, es3d_n)
          ALLOCATE( es3d_connectivity(le3d_nnodes, es3d_n) )
360:
361:
          CALL get_elements3d_connectivity(es3d, es3d_connectivity)
362:
363:
          ALLOCATE( esm3d_evec(6, es3d_n) )
364:
          ALLOCATE( esm3d_svec(6, es3d_n) )
365:
          ALLOCATE ( esm3d_s_mises (es3d_n) )
366:
          {\tt CALL \ get\_elemstiffmat3d\_evec\_svec}
367:
                (esm3d, esm3d_evec, esm3d_svec, esm3d_s_mises)
368:
369: !-
370:
371:
          OPEN(14, FILE = 'result.inp')
372:
373:
          WRITE(14, '(5(I8, 1X))') ns3d_n, es3d_n, 3, 13, 0
374:
375:
          D0 id = 1, ns3d_n
376:
           WRITE(14, '( (I8, 1X), 3(E17.8, 1X) )') &
377:
```

```
378:
                 id, (ns3d_x(i, id), i = 1, 3)
379:
380:
          END DO
381:
382:
          DO ie = 1, es3d_n
383:
384:
          WRITE(14, '( 2(18, 1X), (A5, 1X), 27(18, 1X))')
385:
                 ie, 1, 'hex',
                 ( es3d_connectivity(na, ie), na = 1, le3d_nnodes)
386:
387:
388:
          END DO
389:
390:
          WRITE(14, '(4(I8, 1X))') 1, 3
          WRITE(14, '(A)') 'DISPLACEMENT, m'
391:
392:
393:
          D0 id = 1, ns3d_n
394:
          WRITE(14, '( (I8, 1X), 3(E17.8, 1X) )')
395:
396:
                 id, (ns3d_u(3*(id-1)+i), i = 1, 3)
397:
398:
          END DO
399:
400:
          WRITE(14, '( 1418 )') 13, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
401:
          WRITE(14, '( (A, 1X) )') 'STRAIN_11, unit_unknown'
402:
          WRITE(14, '( (A, 1X) )') 'STRAIN_22, unit_unknown'
403:
          WRITE(14, '( (A, 1X) )') 'STRAIN_33, unit_unknown'
          WRITE(14, '( (A, 1X) )') 'STRAIN_12, unit_unknown'
404:
405:
          WRITE(14, '( (A, 1X) )') 'STRAIN_23, unit_unknown'
406:
          WRITE(14, '( (A, 1X) )') 'STRAIN_31, unit_unknown'
407:
          WRITE(14, '( (A, 1X) )') 'STRESS_11, Pa'
408:
          WRITE(14, '( (A, 1X) )') 'STRESS_22, Pa'
          WRITE(14, '( (A, 1X) )') 'STRESS_33, Pa'
409:
          WRITE(14, '( (A, 1X) )') 'STRESS_12, Pa'
410:
411:
          WRITE(14, '( (A, 1X) )') 'STRESS_23, Pa'
412:
          WRITE(14, '( (A, 1X) )') 'STRESS_31, Pa'
413:
          WRITE(14, '( (A, 1X) )') 'STRESS_MISES, Pa'
```

```
414:
415:
      DO ie = 1, es3d_n
416:
417:
       WRITE(14, '( (I8, 1X), 13(E17.8, 1X) )')
418:
           ie, (esm3d_evec(i, ie), i = 1, 6),
419:
              (esm3d\_svec(i, ie), i = 1, 6), esm3d\_s\_mises(ie)
420:
      END DO
421:
422:
423:
      CLOSE (14)
424:
425: !-
426:
427:
      DEALLOCATE( ns3d_x )
428:
      DEALLOCATE( ns3d_u )
429:
430:
      DEALLOCATE( es3d_connectivity )
431:
432:
      DEALLOCATE( esm3d_evec )
433:
      DEALLOCATE( esm3d_svec )
434:
      DEALLOCATE( esm3d_s_mises )
435:
436:!-
437:
438:
      RETURN
439:
441:
      END SUBROUTINE run_appli
443:
444:
445:
      ! Finish appli
447:
      SUBROUTINE finish_appli()
449:
```

```
450:
      CALL del_nodes3d(ns3d)
451:
      CALL del_localelement3d(le3d)
452:
      CALL del_elements3d(es3d)
453:
      CALL del_elemstiffmat3d(esm3d)
454:
      CALL del_elemexforcevec3d(efv3d)
455:
      CALL del_fem3d(fem3d)
456:
457:!-
458:
459:
      DEALLOCATE( ns3d )
460:
      DEALLOCATE( le3d )
461:
      DEALLOCATE( es3d )
      DEALLOCATE( esm3d )
462:
      DEALLOCATE( efv3d )
463:
464:
      DEALLOCATE( fem3d )
465:
466:!-
467:
468:
      RETURN
469:
END SUBROUTINE finish_appli
473:
474:
476:
      END MODULE mod_appli
```