Elementary Linear Algebra - MATH 2250 - Exam 2

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Please read	and sign	(papers without	printed name	and signature	will not	be graded)	
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"On my honor, I have neither given nor received unauthorized aid in doing this assignment."

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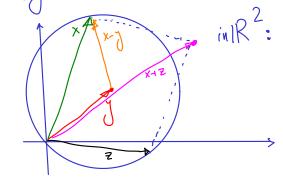
- 1. Which of the following (if any) are subspaces. For any that are **not** subspaces give an example of how they violate a property of subspaces.
 - (a) Given a 3×5 matrix with full row rank, the set of all solutions to $Ax = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$.
 - (b) All 3×5 matrices with $\begin{bmatrix} -3\\2\\1 \end{bmatrix}$ in their column space.
 - (c) All 5×3 matrices with (2,1,3) in their column space.
 - (d) All vectors x with ||x y|| = ||y||, for some given fixed vector $y \neq 0$.

(a) Is not a V.S. because it doesn't include zero: A 0 + [1]

(b) Is not a V.S. because it doesn't coop of operations of the operation o

(c) There is not such a matrix. So this space is empty. But a V.S. cannot be empty, since it has to include zero.

(d)



in IR?: The set of all such vectors x

is a circle centered at J,

passing through origin. (it includes

zero.)

But X+z is not on the circle,

for some X,z on the circle,

hence it's not a vector space.

2. (a) Find the matrix P that projects every vector \boldsymbol{b} in \mathbb{R}^3 onto the line in the direction of (1,2,3).

 $N = \begin{bmatrix} -2 & -3 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}$

PTP

(b) Describe the Four fundamental subspaces of P by providing a basis for each of them.

(a)
$$P = \frac{\alpha a^{T}}{\alpha^{T} a} = \frac{1}{14} \begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \\ 3 & 6 & 9 \end{bmatrix}$$
 $\longrightarrow \text{ref}(P) = \begin{bmatrix} \frac{1}{2} & \frac{3}{3} \\ \frac{3}{6} & \frac{3}{6} & \frac{3}{6} \end{bmatrix}$

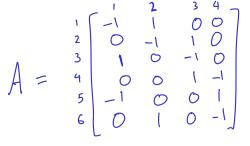
(b)
$$C(P) = \langle \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \rangle$$

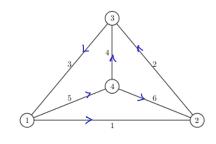
$$R(P) = \langle \begin{bmatrix} 1 & 2 & 3 \end{bmatrix} \rangle$$

$$N(P) = \left\langle \begin{bmatrix} -2\\1\\0 \end{bmatrix}, \begin{bmatrix} -3\\0\\1 \end{bmatrix} \right\rangle$$

$$E = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix} = Mef(A)$$

3. Write down the 6×4 incidence matrix A of this graph. What is the dimension of the column space C(A)? Describe the null space N(A).





rows 1,2,4 of A are lin. ind. 4-3
and [1111] is in the null space. 1
3+1=4

The space of A) = 3 = $\dim(\text{row space of A})$.

Inullify of A = 1 $N(A) = \lambda \begin{pmatrix} 1 \\ 1 \end{pmatrix} > 0$

4. (a) Consider the following data:

Year	US Population (million)		
1900	70		
1920	100		
1940	130		
1980	230		

Suppose the population growth is linear, and you want to fit the best line y = Cx + D to these values, where x = 0 represents the year 1900. What is the matrix A in the system $A \mid_D^C$ \hat{C}, \hat{D} , and the heights p_1, p_2, p_3, p_4 of that line $y = \hat{C}x + \hat{D}$ at years 1900, 1920, 1940, and 1980. What is the error vector e? Show by numbers that e is perpendicular to C(A).

5. Start with the two vectors (columns of A):

$$m{a}_1 = egin{bmatrix} \sin \theta \\ 0 \\ \cos \theta \end{bmatrix} \ ext{and} \ m{a}_2 = egin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}.$$

- (a) With $q_1 = a_1$ find an orthonormal basis q_1, q_2 for the space spanned by a_1 and a_2 (column space of A).
- (b) What shape is the matrix R in A = QR and why is $R = Q^T A$ (Here Q has columns q_1, q_2)? Compute

(c) Find the projection matrices P_A and P_Q onto the column spaces of A and Q.

(c) Find the projection matrices
$$P_A$$
 and P_Q onto the column spaces of A and Q .

(a) $Q = \begin{cases} \sin \theta \\ 0 \\ \cos \theta \end{cases}$, $b = a_2 - \frac{\partial^2 a_1}{\partial a_1^2} = a_2 - \frac{\partial^2 a_1}{\partial a_1^2} = a_1 = \begin{cases} \cos \theta \\ \cos \theta \end{cases} = \begin{cases} \sin \theta \\ \cos \theta \end{cases}$

$$||a|| = \int \sin^2 \theta \cos^2 \theta + \sin^2 \theta \cos^2 \theta = \int \cos^2 \theta \left(\sin^2 \theta + \cos^2 \theta \right) = \int \cos \theta$$

$$||b|| = \int \cos^2 \theta \cos^2 \theta \cos^2 \theta = \int \cos^2 \theta \left(\sin^2 \theta + \cos^2 \theta \right) = \int \cos \theta \cos^2 \theta \cos^2$$

(assuming O° < 0 < 900)

$$R = Q^{T}A, \qquad Q = \begin{bmatrix} \sin \theta & \cos \theta \\ 0 & 0 \\ \cos \theta & -\sin \theta \end{bmatrix}, \quad A = \begin{bmatrix} \sin \theta & 1 \\ 0 & 0 \\ \cos \theta & 0 \end{bmatrix}$$

$$R = Q^{T}A = \begin{bmatrix} \sin\theta & 0 & \cos\theta \\ \cos\theta & 0 & -\sin\theta \end{bmatrix} \begin{bmatrix} \sin\theta & 1 \\ 0 & 0 \\ \cos\theta & 0 \end{bmatrix} = \begin{bmatrix} 1 & \sin\theta \\ 0 & \cos\theta \\ \cos\theta & 0 \end{bmatrix}$$

(C)
$$P_A = A(ATA)^{-1}A^{T}$$
, and $ATA = \begin{pmatrix} 1 & \sin\theta \\ \sin\theta & 1 \end{pmatrix}$ and $(ATA)^{-1} = \begin{pmatrix} \sec^2\theta & -\sec\theta \\ -\sec\theta & 1 \end{pmatrix}$

(b)
$$R$$
 is alway upper triangular.

$$R = QTA, \qquad Q = \begin{bmatrix} sin\theta & cos\theta \\ 0 & 0 \\ cos\theta & -sin\theta \end{bmatrix}, A = \begin{bmatrix} sin\theta & 1 \\ 0 & 0 \\ cos\theta & 0 \end{bmatrix}$$

$$R = QTA = \begin{bmatrix} sin\theta & 0 & cos\theta \\ cos\theta & 0 & -sin\theta \end{bmatrix} \begin{bmatrix} sin\theta & 1 \\ 0 & 0 \\ cos\theta & 0 \end{bmatrix} = \begin{bmatrix} sin\theta & 0 & cos\theta \\ 0 & 0 & -sin\theta \end{bmatrix}$$

$$COS\theta = A(ATA)^{-1}A^{-1}, and ATA = \begin{bmatrix} 1 & sin\theta \\ sin\theta & 1 \end{bmatrix} \text{ and } (ATA)^{-1} = \begin{bmatrix} se^2\theta & -seeton\theta \\ -seeton\theta & se^2\theta \end{bmatrix}$$

$$R = QTA = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R = A(ATA)^{-1}A^{-1}, and ATA = \begin{bmatrix} 1 & sin\theta \\ sin\theta & 1 \end{bmatrix} \text{ and } (ATA)^{-1} = \begin{bmatrix} se^2\theta & -seeton\theta \\ -seeton\theta & se^2\theta \end{bmatrix}$$

$$R = Q(QTA)^{-1}Q^{-1} = QQ^{-1} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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$$P_{Q} = Q(Q^{T}Q) Q^{T} = QQ^{T} = \begin{bmatrix} 1 & 00 \\ 0 & 00 \\ 0 & 01 \end{bmatrix}$$