

SHIVAM

JAISWAL



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https://kaalraavan.github.io/

Objective

Want to work in the field of Robotics to use my knowledge for the welfare of the society and nature.

Education

School

High school Senior Secondary School

Mechatronics

Bachelor of Technology

Robotics

Master of Technology

Jagran Public School (2011-2014)

9.2/10 in year 2012 82.5 % in year 2014

Manipal University (2015-19)

8.45/10 in year 2019

Defence Institute of Advanced Technology-DRDO (2020-22)

8.37/10 in year 2022

Solidworks

C/C++

Skills

MSC Adams

AutoCAD

Creo

MATLAB

Simscape/

Simulink

Siemens NX

OpenSim

Python

Embedded System

GitHub

ROS



Robotic Arm

2017 (Ended)

3D Printer

2020 (Ended)

Path Planning

2021 (Ended)

Robotic Arm

2021 (Ended)

Exoskeleton

2022 (Ended)

Six Degree of Freedom arm Manipulator

To demonstrate forward kinematic for pick and place use using potentiometer.

Fused Filament Fabrication, 3D Printer.

3D printer for personal use, using Marlin1.1 code.

Path planning using D* Algorithm

Generating shortest path between two points with MATLAB.

Four Degree of Freedom arm Manipulator

Simulation and Analysis of 4-Dof Manipulator in Adams.

Cable-driven upper body exoskeleton

Simulation and control of cable-driven exoskeleton to provide assistance to elbow joint for weightlifting task.

Experience

CSIR-CSIO

2019 (Ended)

CAIR-DRDO

2021-22 (Ended)

Agnikul Cosmos

2022 (Ended)

Surgical Robotic Systems

6-month Project Trainee on 2R arm manipulator.

Simulation and control of Exoskeleton

10-months Project training on simulation and control of upper body exoskeleton for elbow assistance in weightlifting.

Space Silicon Engineer - Intern

2.5 month - Worked on **Ni-PXIe HIL system** and Embedded system with **POSIX- IPC** handling.

Languages

Hindi

English

SHIVAM

JAISWAL

Learning

Image Processing

Raspberry Pi

Cocurricular



Photography









Sports



Badminton



Swimming



Table Tennis

Strengths

Logics

Understandings

Creativity

Analysis

Strength to subdue weakness

Passionate to learn new things

Competitions

Microprocessor

2020-21 (Ended)

Toy hackathon 2021 (Ended)

AIM

2021 (Ended)

Innovator 1.0

2021 (Ended)

Robotic

2021 (Ended)

Swadeshi Microprocessor Challenge

To Use Made in India microprocessors for an application

Toy hackathon by Government of India

To design toys based on Indian culture and education

AIM by NITI Aayog, Government of India

Generating shortest path between two points with MATLAB.

Periyar U. Business Incubation Confederation

(Swachh Urija: A Piezoelectric Way) Light up and control streetlights using Piezoelectric Material.

ARTPARK Robotics Challenge by IISc

Building a Mobile Manipulator Robot to clean Bathroom, made it to as top 30 teams all over India.

Publications

Path Planning

Elsevier-ScienceDirect

IFAC-ACODS-2022

https://doi.org/10.1016/j.ifacol.2022.04.128

Exam Gate

Computer Science and Information Technology Qualified Gate exam in Computer science in 2019 and 2020.

NPTEL

Hardware Modelling using Verilog. Parallel programming using OpenMP.

NPTEL Topper 2017



Mechatronics design

Exoskeleton

Kinematic and Dynamic modelling

Multibody system design & simulation

Humanoid robotics

Control System

Robot Operating System

Cyber Physical System

Robotics

Mobile/ Aerial robotics

State Space Modelling and Control

Wearable robots

Rehabilitation robotics

Manipulator robots

Embedded system

CAD-Design