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# base script for virality example

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## create 2-D 10x10 lattice network

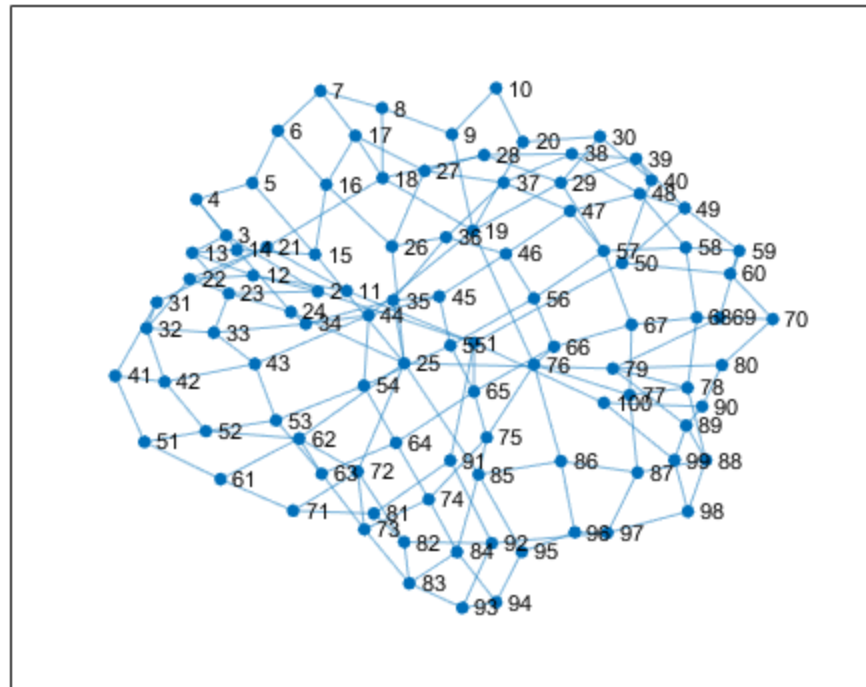
```
n = 12;
A = delsq(numgrid('S',n));
G = graph(A, 'omitselfloops');

% implement small-world topography, add some edges to G
% there is really good transportation, so many populations are
  connected.
G = addedge(G, 25, 79, 1);
G = addedge(G, 25, 62, 1);
G = addedge(G, 18, 21, 1);
G = addedge(G, 2, 23, 1);
G = addedge(G, 92, 97, 1);
G = addedge(G, 29, 57, 1);
G = addedge(G, 1, 65, 1);
G = addedge(G, 1, 91, 1);
G = addedge(G, 1, 50, 1);
G = addedge(G, 1, 100, 1);
G = addedge(G, 19, 76, 1);
G = addedge(G, 19, 44, 1);
G = addedge(G, 25, 85, 1);
G = addedge(G, 25, 72, 1);

figure();
plot(G);

% extract the adjacency matrix
ad = adjacency(G);

% establish the dimensions
n_dim = length(ad);
```



**now we create a state transition matrix for our linear dynamical model**

```
% set a self-decay factor
decayf = 0.9; % originally 0.5

% scale strength of nodal interactions
Aff = ad*0.20; % originally 0.16

% create the final dynamical matrix as sum of self-decay and nodal
% interactions
Aff = Aff + (eye(n_dim).*decayf);
```

**simulate the network**

```
% set the length of the simulation
Tf = 90;

% initialize an array to store the state of the network at each time
% point
x_out = zeros(n_dim,Tf);

% random positive initial conditions
% x_init = randn(n_dim,1).^2;
```

```
% zero initial condition
x_init = zeros(n_dim,1);

x_out(:,1) = x_init;

control_out = zeros(n_dim,Tf);
```

## model some disturbance.

In this example, we will consider two short bursts of excitation applied at  $t = 25$  (to node 25) and 50 (to node 45)

```
w_dist = zeros(n_dim, Tf);
w_dist(25,25) = 15;
w_dist(45,50) = 15;
```

## simulate

```
for ind = 2:Tf
    % we were originally inputting x_out(:,ind-1)
    % we changed it to x_out(:,1:ind-1)
    control_vector = find_cvec(x_out(:,1:ind-1));

    % without control
    % x_out(:,ind) = Aff*x_out(:,ind-1) + w_dist(:,ind);

    % with control
    x_out(:,ind) = Aff*x_out(:,ind-1) + w_dist(:,ind) +
    control_vector;
    control_out(:,ind) = control_vector;

    % keep x_out positive
    x_out = max(x_out, 0);

end

% anything over 10 is saturated
x_out = min(x_out,10);
```

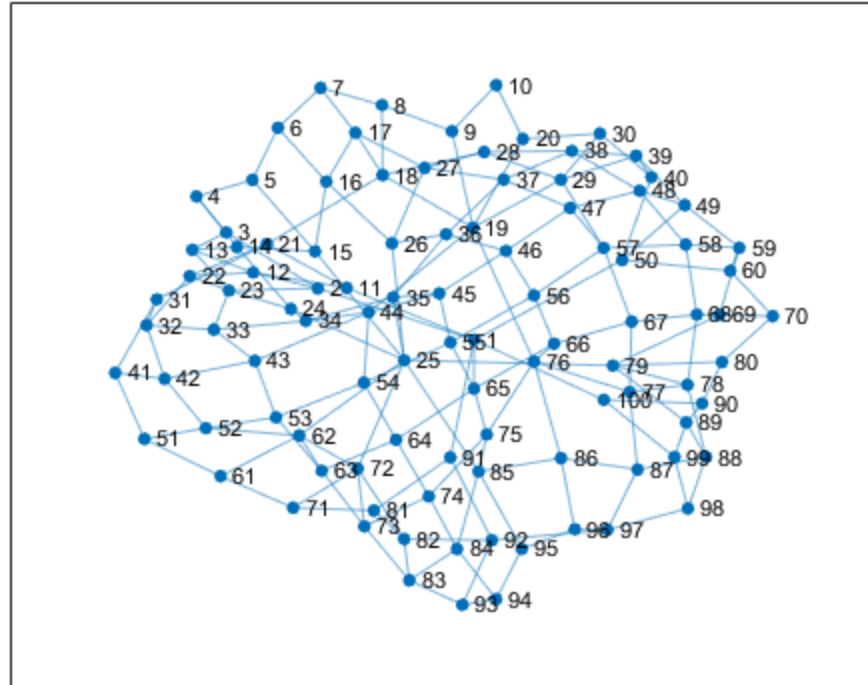
## plot a movie of the network state evolution

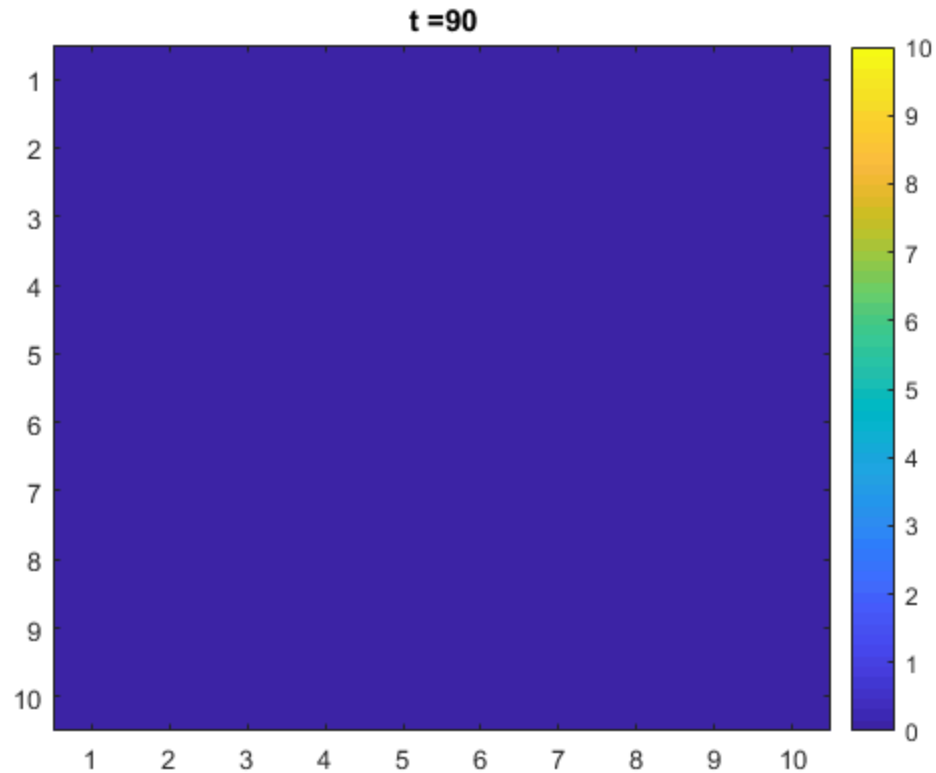
```
figure(2);
for ind = 1:Tf

    F = reshape(x_out(:,ind),[10 10]);
    F = min(F,10);
    figure(2);
    imagesc(F,[0 10]);
    title(strcat('t = ',num2str(ind)));
    colorbar;
```

```
pause(0.1);
```

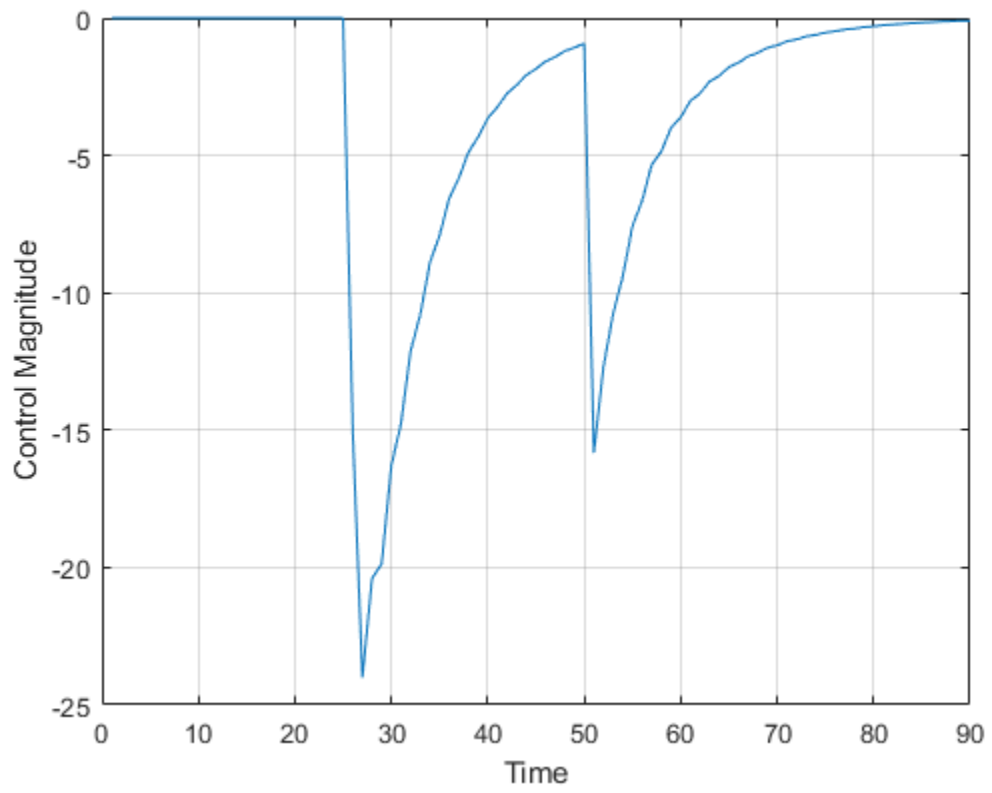
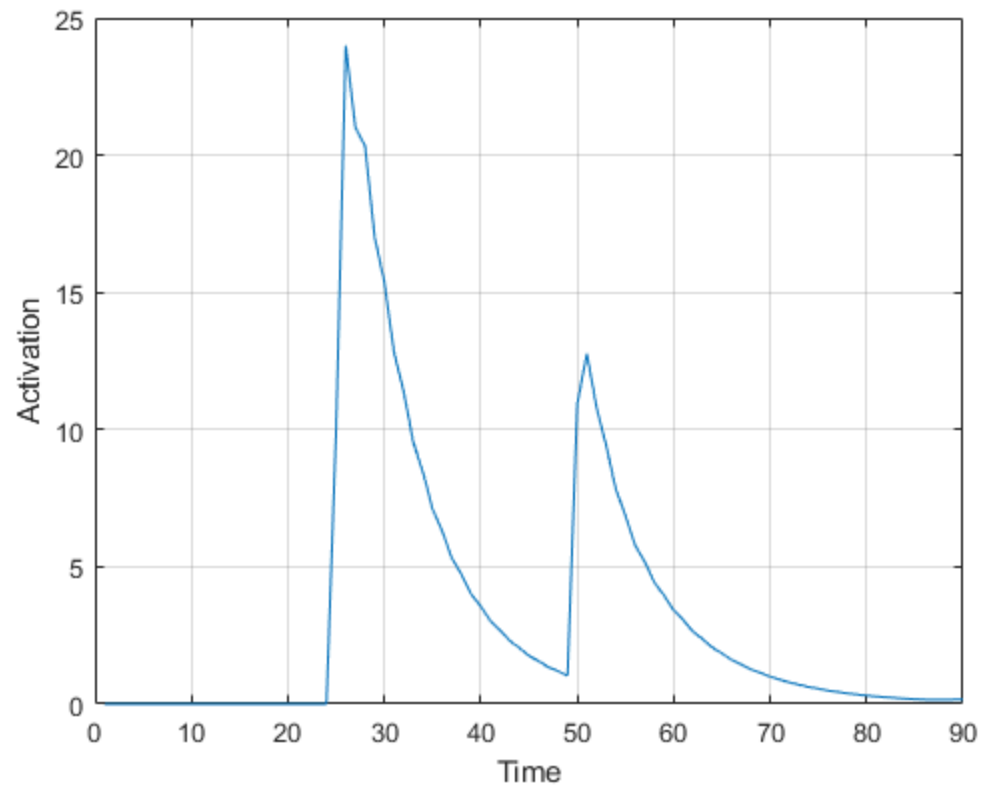
```
end
```





## Plot the total activation of the network as a function of time

```
figure(3);  
plot(sum(x_out));  
xlabel('Time');  
ylabel('Activation');  
grid on;  
  
figure(4);  
plot(sum(control_out));  
xlabel('Time');  
ylabel('Control Magnitude');  
grid on;
```



## prototype for function that returns a "control vector"

```
% parameter x_out is the column data for the current day, along with
the
% column data for every previous day that has happened so far
function control_vector = find_cvec(x_out);

% make control vector 100x1 vector
control_vector = zeros([length(x_out),1]);

% check if number of columns is only 1
cols = size(x_out, 2);
if(cols == 1)
    % do nothing, leave control_vector as all zeros
else
    for i = 1:100
        % check difference between each row of the
        % last column with the row in the previous column
        % i.e. each row of "cols" - each row of "cols-1"
        if(x_out(i,cols) - x_out(i,cols-1) > 0.001)
            control_vector(i) = -1*x_out(i, cols);
        end
    end
end
end
```

*Published with MATLAB® R2019a*