

PERSONAL DATA

Name KanishakKatahra
Address Bleichstraße 12, 89077 Ulm
Phone +49 177 8768378
E-mail kanishak14@gmail.com



WORK EXPERIENCE

- 08/2024 - Present **Embedded Software Developer, Scantinel Photonics GmbH, Ulm, Germany**
Aurix TriCore ■ Software Architecture ■ C ■ Python ■ FreeRTOS
- Contact point for next generation of the sample
 - Conception and implementation of software architecture
 - Programming laser control board, EEPROM, I2C sensor array
 - Interfacing DAC array using SPI for switching optical exits
 - Optimized communication signals through advanced PWM generation
 - Developed robust Ethernet-based communication between the device and GUI
 - Development of automated test scripts and simulation
 - Introduction and maintenance of Git repository including submodule management and CI/CD pipeline
 - Hardware debugging, oscilloscope measurement
- 04/2023 - 07/2024 **Embedded Software Developer, ALTEN GmbH, Coburg, Germany**
C ■ AUTOSAR ■ Functional Safety ■ ASPICE
- Software development for massage functionality in a car seat
 - Design software architect of Door Control Unit
 - Participation in ASPICE assessment
- 11/2021 – 03/2023 **Master Thesis and Intern, Blickfeld GmbH, Munich, Germany**
C ■ STM32 ■ C ■ MATLAB ■ SIMULINK ■ Python ■ Git ■ Docker
- Thesis: "Lissajous Curves as Scan Patterns in a 3D Scanning LiDAR" (Grade: 1.3)
 - Software development for massage functionality in a car seat
 - Control of the mirrors to deflect the laser beam with MCUs
 - Development of laser triggering algorithm on ARM Cortex-M MCU
 - Optimized the code on STM32 to make it 16% faster
 - Reduced power consumption by the ARM Cortex-M MCU by 9%
 - Developed a Python based tool for flashing firmware images on MCU
 - Developed Python based tool for profiling
- 06/2017 – 09/2018 **Embedded Software Developer, Corporate Designz, Delhi, India**
C ■ AVR ■ STM32 ■ Proteus
- Developed a controller for a motor driver
 - Developed a controller for eBike including system overcurrent protection and speed measurement

EDUCATION

- 10/2018 – 03/2023 **Master of Science, Embedded Systems, Technische Universität, Chemnitz, (Grade: 2.1)**
- 08/2013 – 05/2017 **Bachelor in Technology in Instrumentation and Control Engineering, Manipal Institute of Technology, Manipal, (Grade: 2.2)**

SKILLS

Languages	German (B2), English (Fluent C1)
Programming Lang.	C, C++, Python, Make, Bash
Software	MATLAB, SIMULINK, PyQt, CMake, Git, Docker, Altium, VS Code
Microcontrollers	STM32, Aurix TriCore
Miscellaneous	ARM-based Microcontrollers, Linux, FreeRTOS, ARM-GCC Toolchain, Debugger (JTAG, SWD), CodeBeamer, ASPICE, Requirements

Projects

Ground Contact Evaluation of a Walking Robot

C++ ■ CAN ■ I2C ■ SPI ■ USB

- Interfaced matrix of 48 pressure sensors with STM32
- Computed center of pressure
- Used IMU to measure orientation using Kalman filter
- Python based tool for visualizing data
- USB, CAN to forward data

Ground Contact Evaluation of a Walking Robot

C++ ■ CAN ■ I2C ■ SPI ■ USB

- Interfaced matrix of 48 pressure sensors with STM32
- Computed center of pressure
- Used IMU to measure orientation using Kalman filter
- Python based tool for visualizing data
- USB, CAN to forward data

Ground Contact Evaluation of a Walking Robot

C++ ■ CAN ■ I2C ■ SPI ■ USB

- Interfaced matrix of 48 pressure sensors with STM32
- Computed center of pressure
- Used IMU to measure orientation using Kalman filter
- Python based tool for visualizing data
- USB, CAN to forward data