



Universität St.Gallen



ML Mavericks

Machine Learning - Coding Challenge - Spring 2023

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Team Introduction

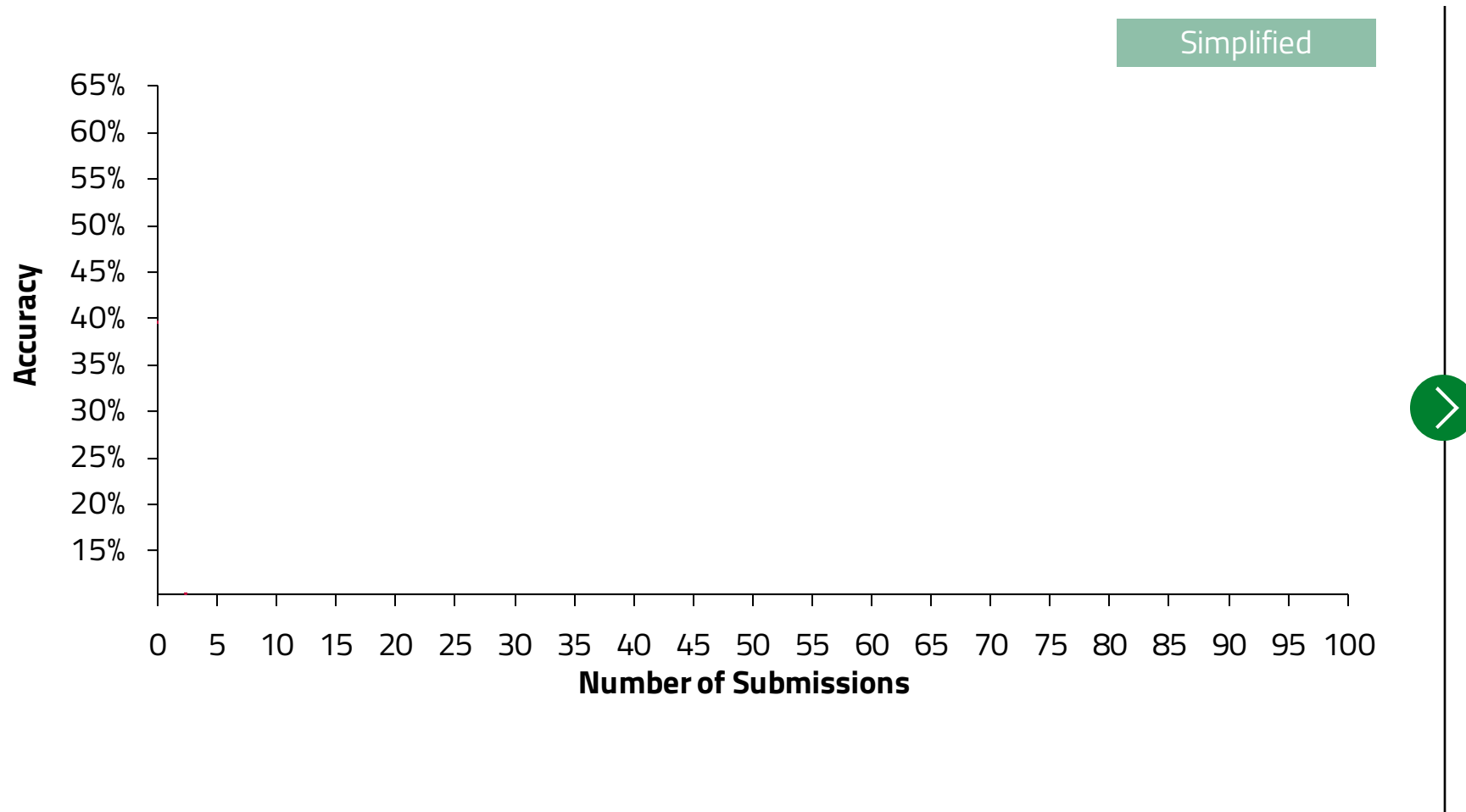


**Florence
Pfammatter**



**Kaan
Aydin**

Our Journey in the Coding Challenge



Models

ResNet50: default pretrained weights from PyTorch

ResNeXt: as above, architecture ResNeXt101_64X4D

Transformations

- Re-sizing to 92x92 pixels
- Random rotation of 5°
- Random crop to 112 pixels and padding of 10pixels
- Normalization ([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])

Experiments

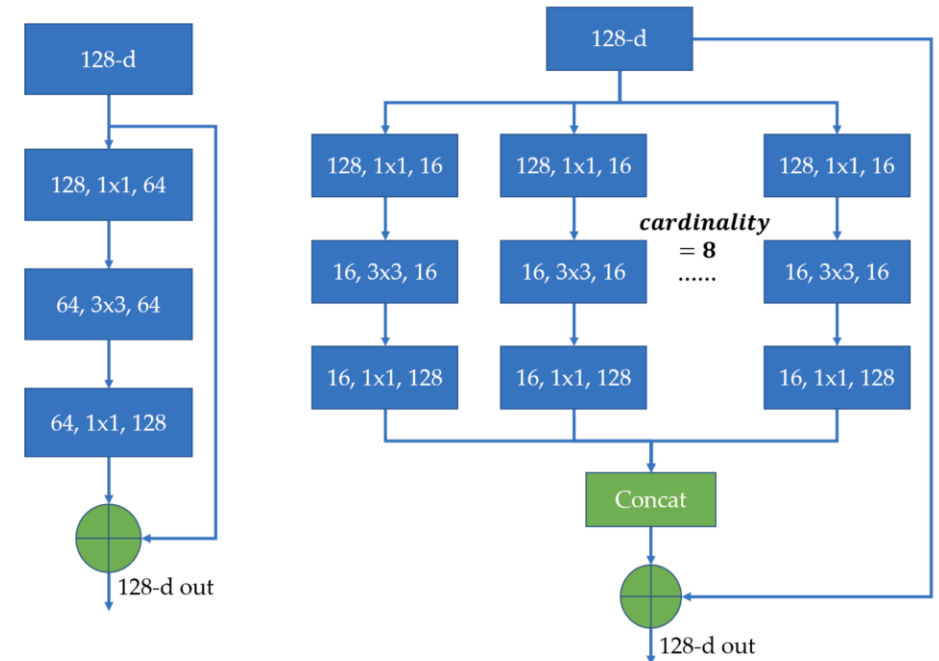
To reduce overfitting, we tried:

Regularization L1/L2, further transformations (Flipping, ColorJitter etc.), freezing layers of pretrained model, Dropout layer (with probability 0.2 and 0.5)

ResNeXt for better generalizability:

Increased capacity of network to capture broader feature variations through cardinality dimension.

Image from Wu et al. (2020)



Best Score: ResNet50 0.585

ResNeXt 0.617

Aggregated Residual Transformations for Deep Neural Network (Xie et al., 2017)

Models

Pretrained weights from PyTorch, ViT_B_16 (best performance on ImageNet1K with this image size)

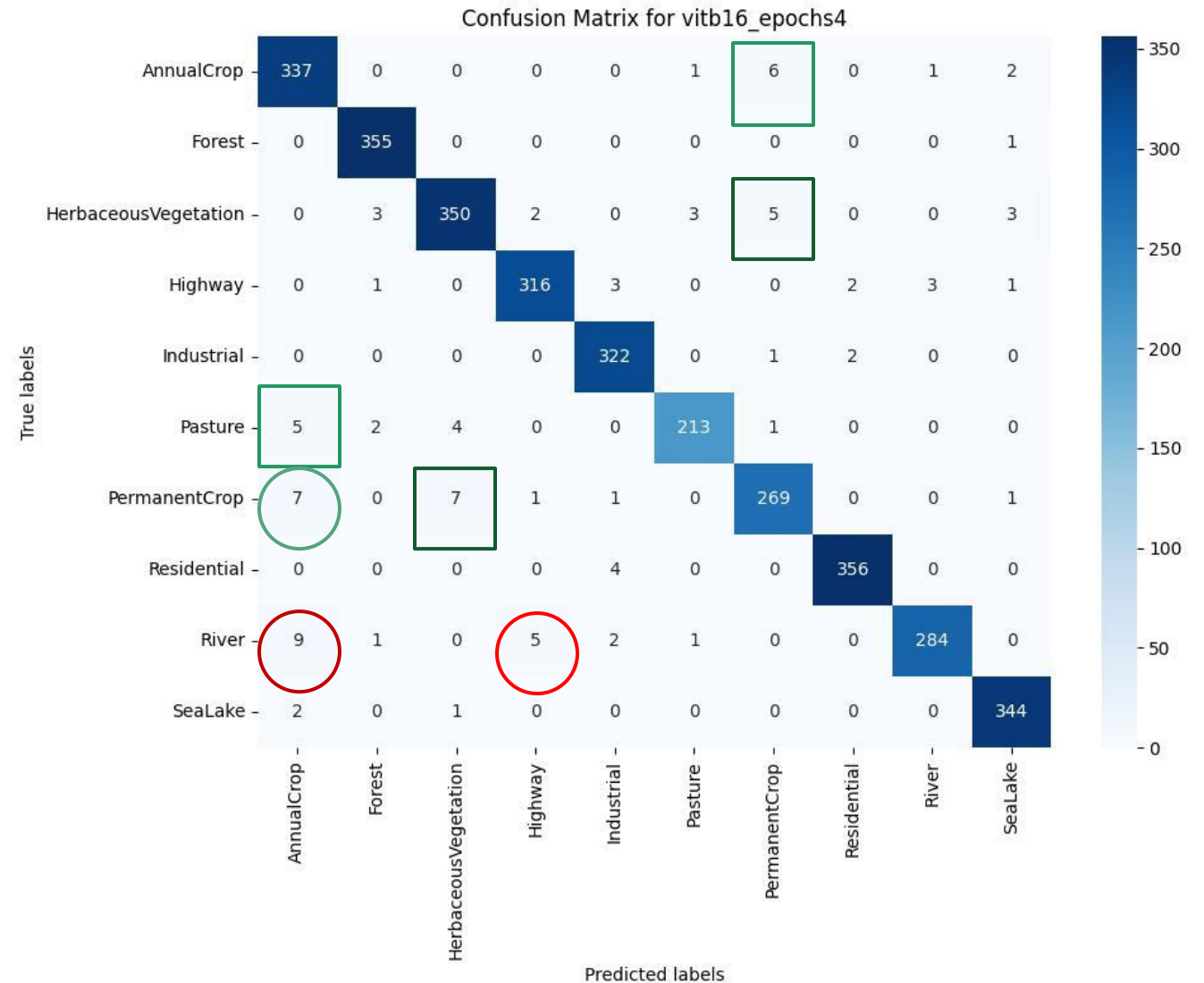
Transformations

- Re-sizing to 204x204 pixels
- Random rotation of 5°
- Random crop to 224 pixels and padding of 10pixels
- Normalization ([0.5, 0.5, 0.5], [0.5, 0.5, 0.5])

Experiments

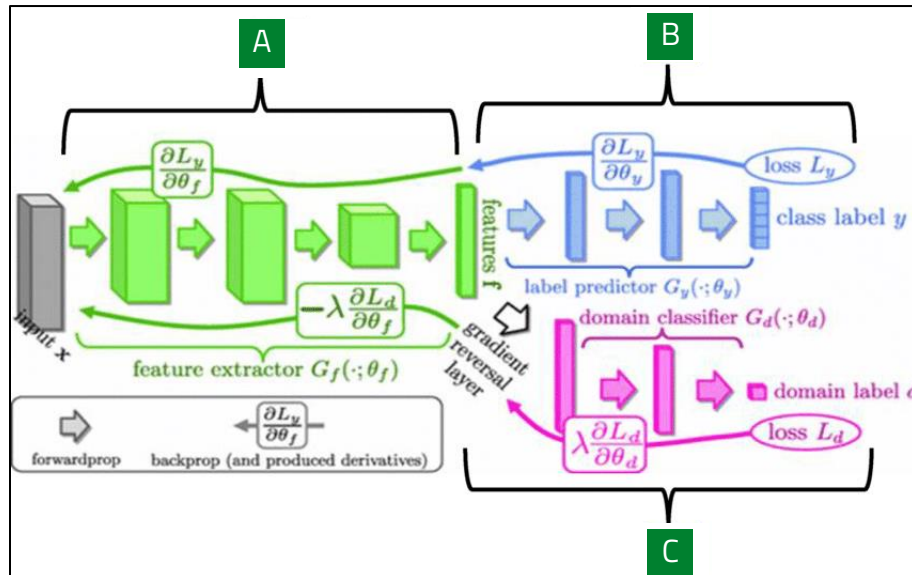
Image Resizing, DeiT model for low RAM consumption, Dropout Layer (with probability 0.3 and 0.5)

Best Score: 0.62564



Domain Adaptation (1/2) - Setup

Approach of DANN



- Based on the approach as outlined by Ganin et al., 2015
- Same feature extractor, two different heads: one for predicting label, the other for classifying domain
- Loss for classifying domain backpropagates through reversal layer to maximize loss of domain classifier
- Goal: Increase loss for domain & decrease for label classifier

Deep Neural Network details

A

Feature Extractor

- Based on the feature extractor layers from the ResNet architecture (i.e., ResNet18 and ResNet50)
- Using default pre-trained weights from PyTorch

B

Label classifier

- 4-layer head on top of feature extractor, consisting of: one linear transformation (to number of classes), batch norm, ReLU activation function & SoftMax

C

Domain classifier

- 8-layer head on top of feature extractor, consisting of various linear mapping and ReLU activation functions and a SoftMax at the end

Experimental details

- 20 epochs, with learning rate of 1e-3 & momentum of 0.9
- Standard transformation (i.e., rotation, padding)
- For every second epoch, we only trained the domain classifier to generate better domain invariant features
- Keeping the λ constant at 0.2 for every iteration & epoch

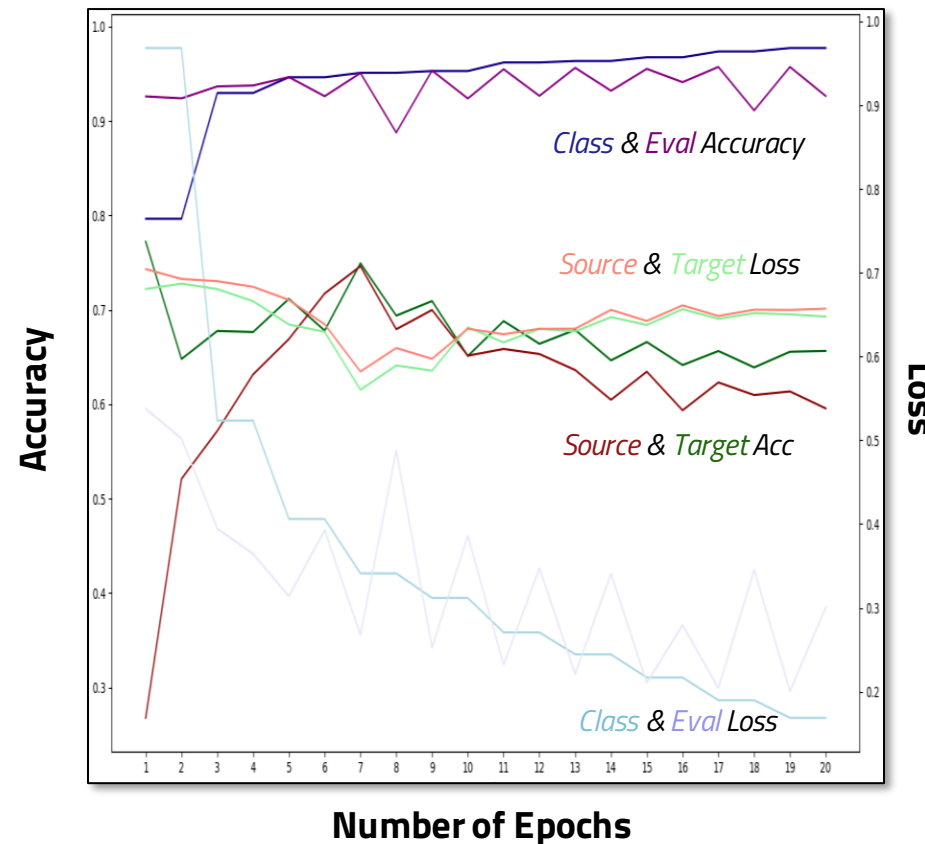
Domain Adaptation (2/2) - Result

High-level results

Feature Extractor	Result
ResNet50 (w/ DA)	50.4%
ResNet18 (w/ DA)	57.4%
ResNet18 (w/o DA)	52.6%

- All results are based on the same data transformations
- DA results are based on based on the same setup as previously shown
- For ResNet18, we show the epoch with the highest performance on eval

Accuracy & Loss curve



Best result achieved with ResNet18 (vs. ResNet50 despite same setup)

ResNet18 with DA performed better than without – indicating that DA has had some impact

Varying accuracy / loss of the domain classifier across epochs – little convergence

DA is promising given some initial results, but needs further deep-dive, e.g.:

- Implementing lower-layer feature extracors
- Adjusting the λ in the GRL

Learnings from the Challenge



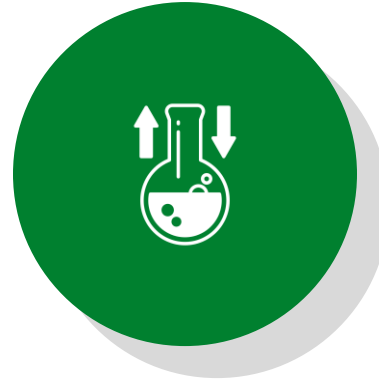
Overfitting as key issue

Overfitting is a key factor to be considered - even more so when dealing with different domains



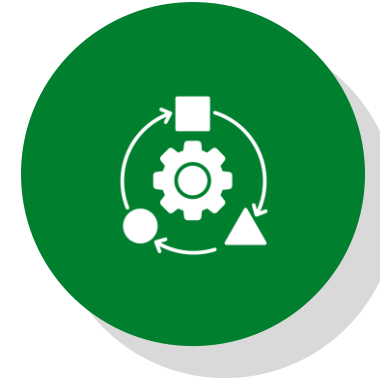
Target vs. Source domain

Little changes in augmentation can have a big impact on performance in target domain (vs. source)



Exploration vs. Exploitation

Good balance between trying new things out vs. pursuing existing approaches is important



Domain Adaptation

Domain Adaptation is difficult – has many considerations and factors to be tested



Development setup

A well-built development and model pipeline is key for speed, reproducibility and tracability



**Inclusion of
NDVI features
during training**



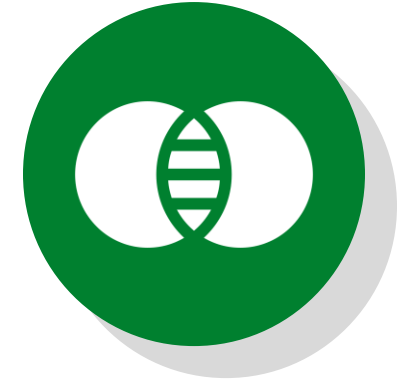
**Deep-dive
in Domain
Adaptation**



**Implementation of
Hyperparameter
Tuning**



**Training with
cross-validation to
reduce overfitting**



**Ensemble learning
by combining
various models**

- Wu, P., Cui, Z., Gan, Z., & Liu, F. (2020). Residual Group Channel and Space Attention Network for Hyperspectral Image Classification. *Remote Sensing*, 12(12), 2035. <https://doi.org/10.3390/rs12122035>
- Xie, S., Girshick, R., Dollár, P., Tu, Z. & He, K. (2017). Aggregated Residual Transformations for Deep Neural Networks. <https://doi.org/10.1109/cvpr.2017.634>
- Yaroslav Ganin, Evgeniya Ustinova, Hana Ajakan, Pascal Germain, Hugo Larochelle, François Laviolette, Mario Marchand, & Victor Lempitsky. (2016). Domain-Adversarial Training of Neural Networks.

A close-up photograph of four large, rusted metal letters spelling 'AIML' mounted on a dark, textured metal surface. The letters are heavily corroded, with bright orange and yellow rust visible around the edges and in the cutouts. The background metal is dark grey with some lighter, weathered patches.

THANK YOU! - ANY QUESTIONS?