Emergency Exit App incorporated with Arduino.

Final Report (semester 2)

Kacper Woloszyn

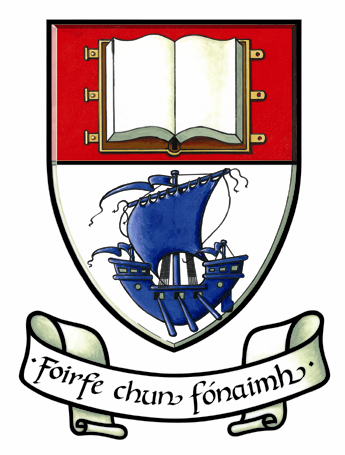
20071494

Supervisor: Caroline Cahill

Second Reader: Lucy White

BSc (Hons) in Applied Computing

Emergency Exit Mobile Application with Arduino



By Kacper Woloszyn, 20071494.

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# 

# Introduction

I have decided to go with a mobile application for my final year project. I have developed as a student educationally over the four years in Waterford Institute of Technology and at Universidad de Malaga, to finally be able to put my own project idea combining all the things that I have studied, and the things I would like to learn, not necessarily all the things that I had learned at WIT, but also individually.

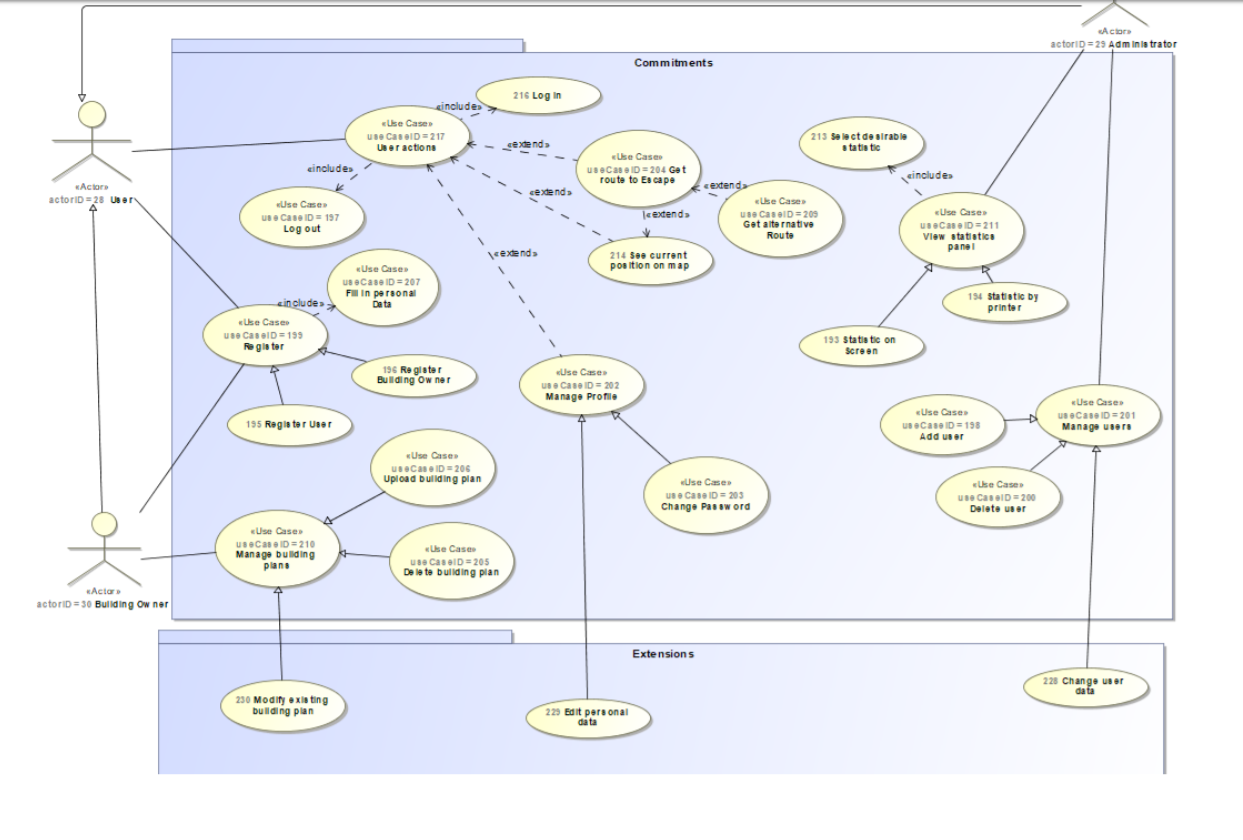
I feel the mobile application I am doing for my final year project may be very important for future generations as each of us nowadays does things on our phone more times than not. I feel there is a need in the market for an application that displays emergency exits to people in public areas and buildings in case of an emergency.

In the project I use an Arduino, the Arduino will be connected to my application and I programmed a buzzer and a sound sensor in Arduino. The buzzer will sound, and an emergency exit route is displayed on the screen, with some additional information, such as the path length or the time taken to find the route. The application is for android users, but as the projects developed in the future it could be brought to IOS devices. The application has a database of users that is stored in firebase so a connection to the internet would he a requirement. An algorithm is used in the background to find the quickest route out of the building. The algorithm used is called Dijstras. It works on having the start node, and the end node, and It picks the unvisited vertex with the lowest distance, calculates the distance through it to each unvisited neighbour, and updates the neighbour's distance if smaller. I used the knowledge from my Erasmus course in Intelligent Systems, where I learned how to programme route finding algorithms such as A\* Algorithms and Dijkstra algorithm or genetic algorithms and neural networks. I take specific measures to make sure the security of the user is not breached, and that the application works as desired, by allowing logins so that I can keep track of who is on the application, and the location is not saved, so just in case someone was trying to steal the data it would be hard.

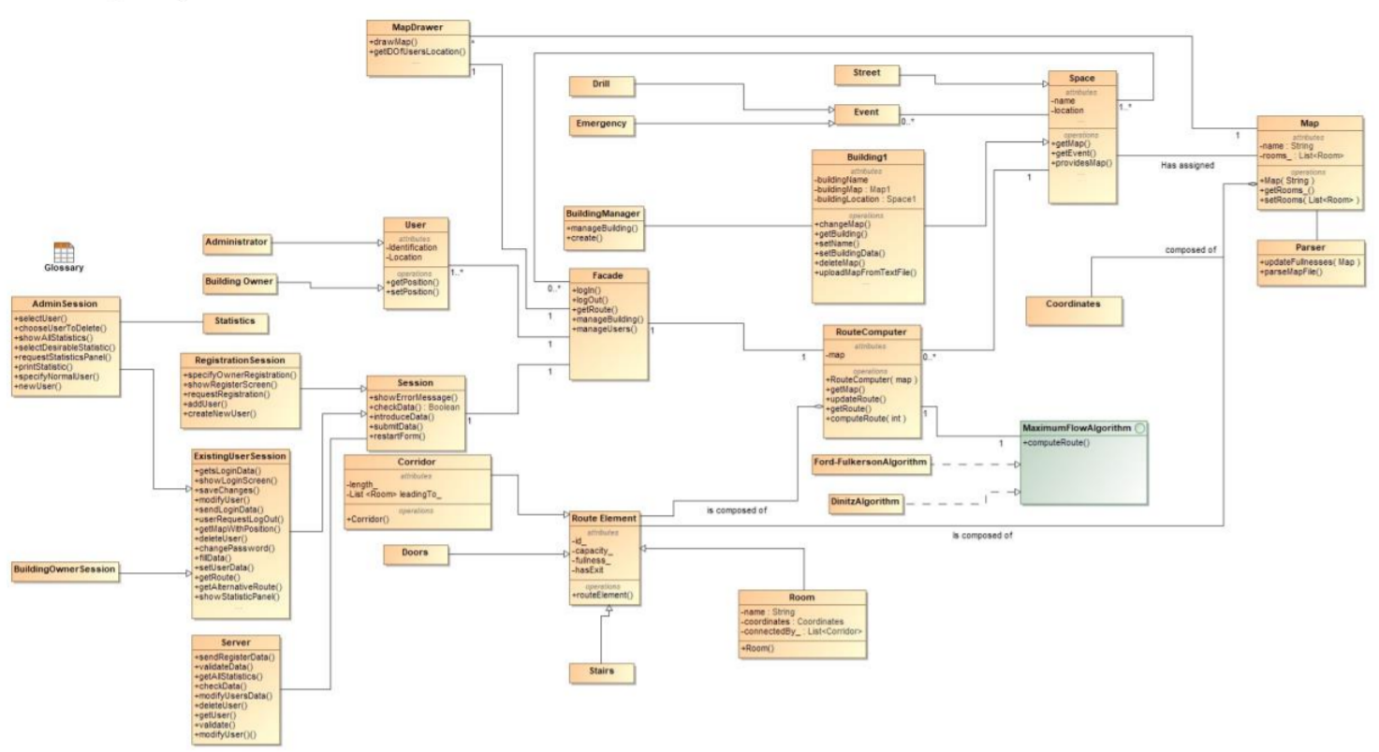
I have used a tool called magic draw to develop my diagrams which show the functioning of the application.

# Diagrams

## Use Case (Easier to Read Horizontally)

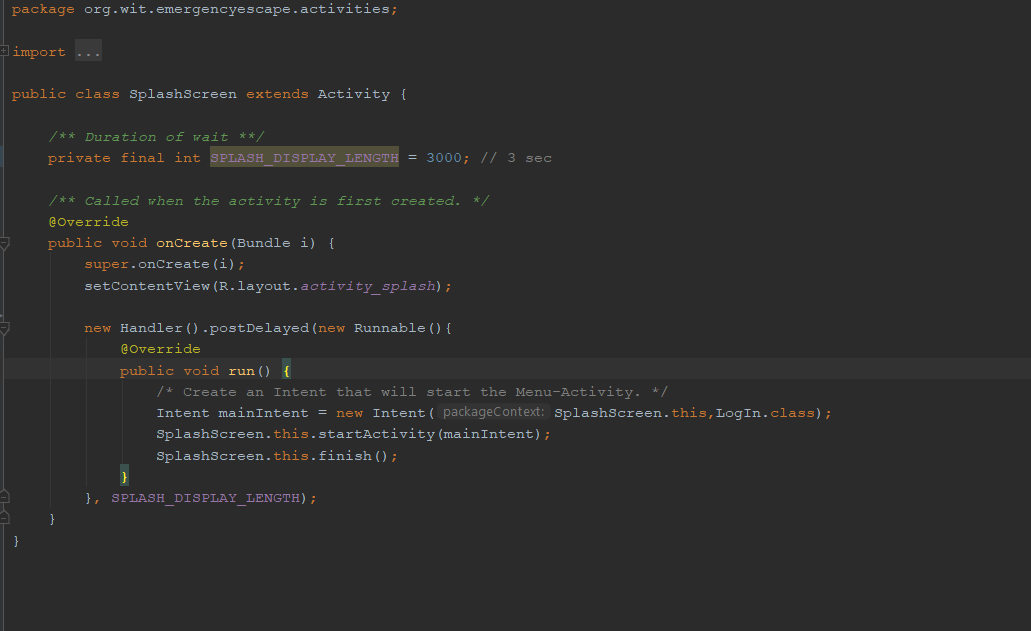


## Domain Model



## Splash Screen

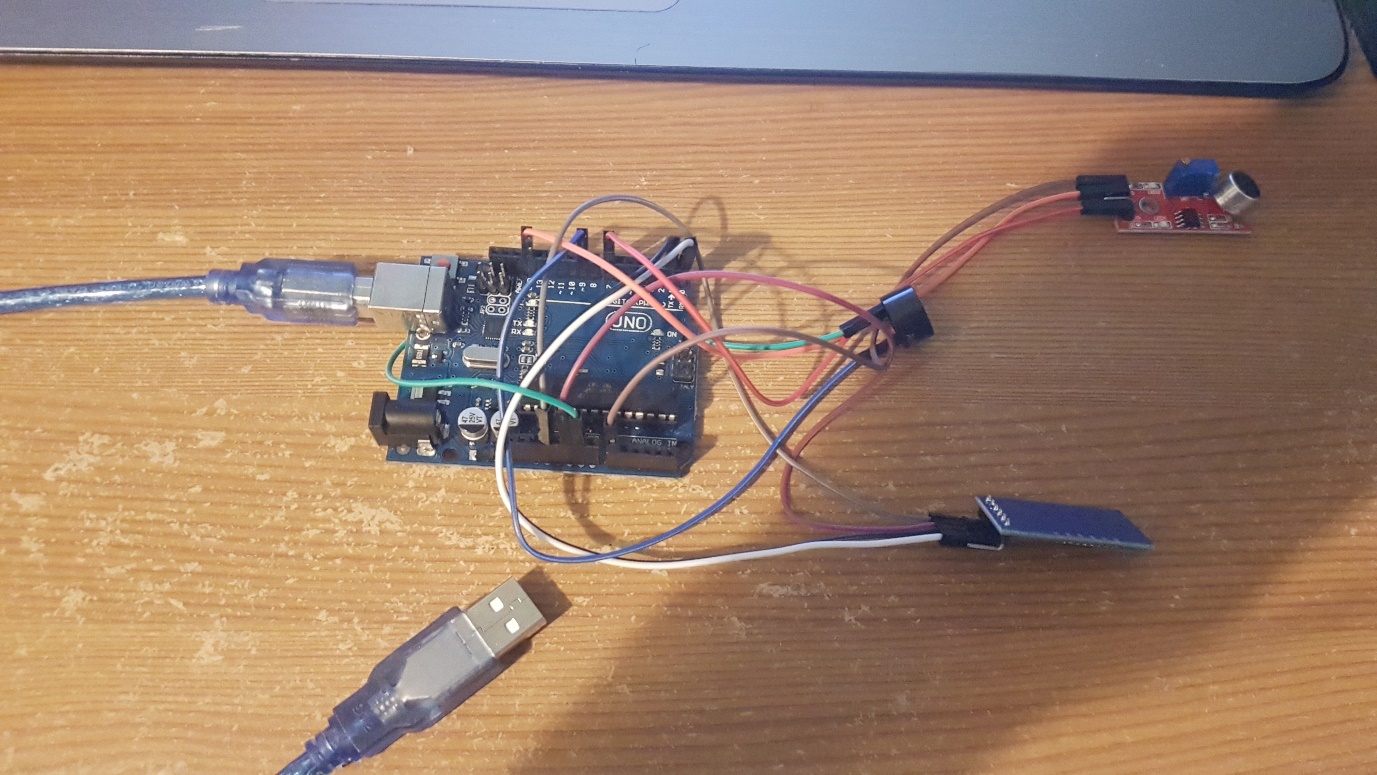
A splash screen is a graphical control element consisting of a window containing an image, a logo, and the current version of the software. Splash screens have their pros and cons, but since this is a personalised application, I’ve decided to design my own splash screen. If I were to place this app commercially on the Google play app store, or to develop it further, I would not include the splash screen as it steals valuable seconds from a user, to get the results he or she wants. I put in a splash screen, as many commercial applications have one, whilst the application is connecting to the internet. I had developed my own splash screen, and I’ve set its time to be 3 seconds just for visual purposes (Lifewire,2018).



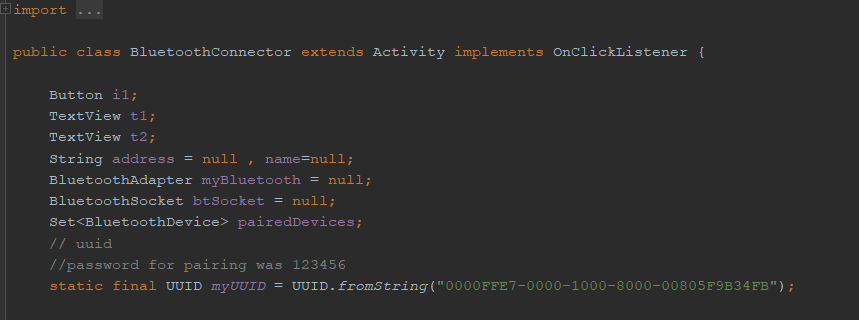


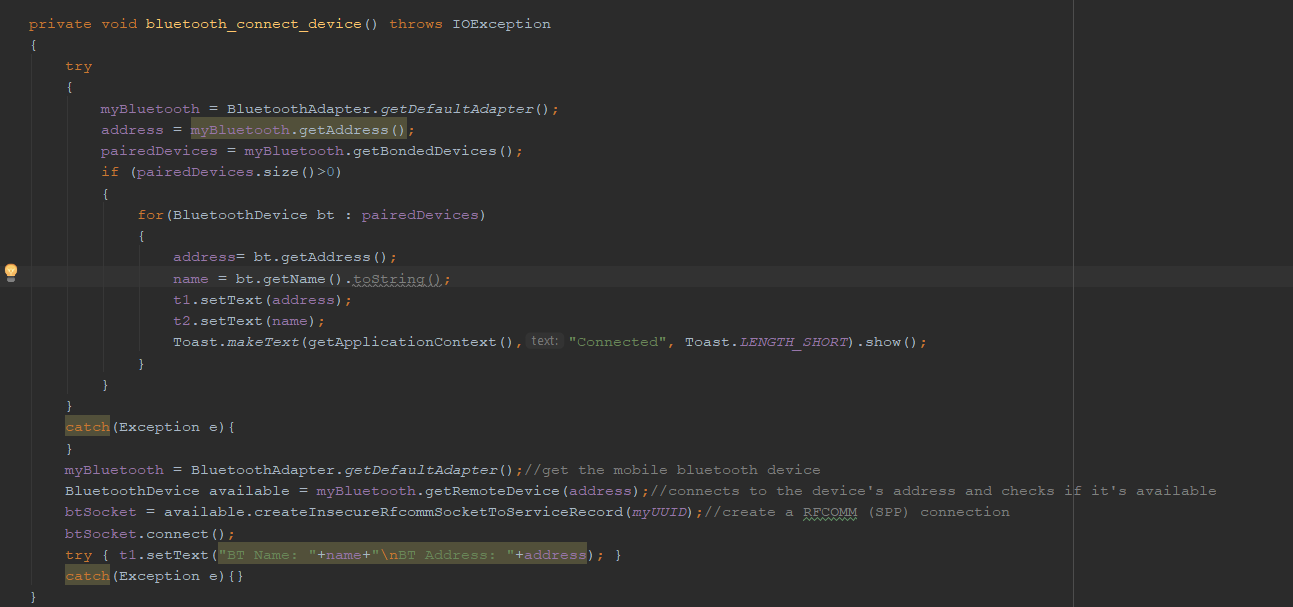
# Technology used in my assignment

## Arduino



I have an Arduino board with 3 modules I had to obtain separately along with the female-male wires, that did not come with the board. I have connected the Bluetooth module to the 3.5 V entry Ground, RX and TX as specified in a tutorial online on how to connect and wire up the module. The module I obtained was a cheap one, for this Project, and if I were to do this to a bigger scale, I would get more reliable and more documented hardware, as it was quite a challenge to know what to do with the module once obtained. The buzzer is connected to a digital pin 9, as specified also in the code below and ground. The sound sensor, which is the red item, is connected to ground, Analogue pin 0, as it has to pick up all of the sound ranges and not only 0 and 1’s like the buzzer on the digital pin. It also must be connected to a digital pin 7 as there could be a noise signal that was digital perfectly.





I have a method called Bluetooth\_connect\_device, that connects to a device, and creates a connection that’s stored in a variable. I then set the name and address fields of the application to be that of the device that has been connected. Arduino uses mostly C++ for programming, and I have programmed a connection program, that I flash the board with and a buzzer programme.

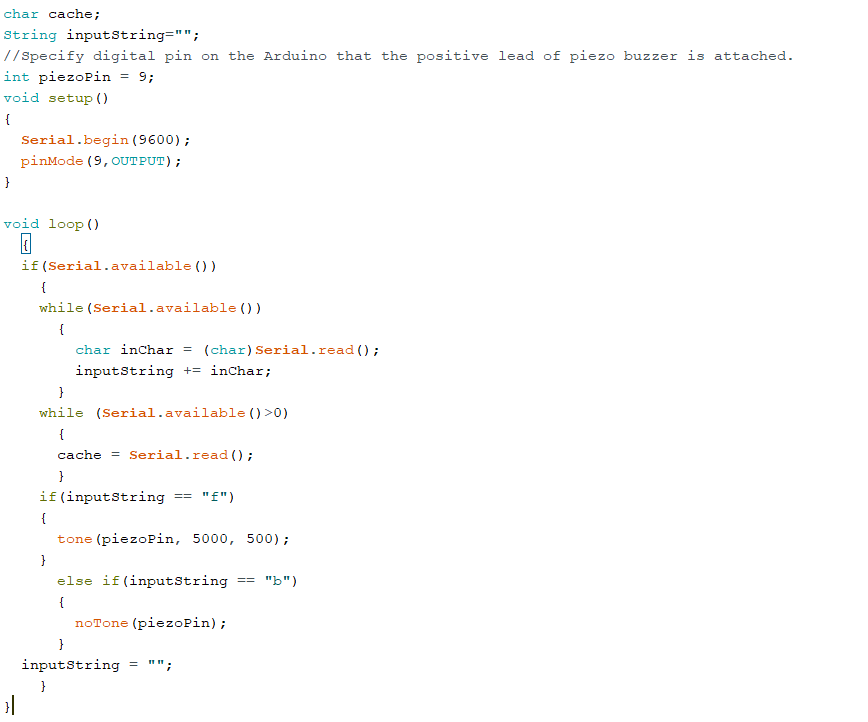


The programme above basically checks, what is connected to the pins on the Arduino board, and it flashes the board with a programme to allow for the Bluetooth module to work properly. It writes a set baud rate to make sure everything works properly and so that the Arduino board is not overheated and overclocked. To use Bluetooth features in my application, I had to declare two permissions. The first of these is BLUETOOTH. I need this permission to perform any Bluetooth communication, such as requesting a connection, accepting a connection, and transferring data. The other permission that I had to declare is ACCESS\_FINE\_LOCATION. A location permission is required because Bluetooth scans can be used to gather information about the location of the user.

I use a Bluetooth API, that scans for Bluetooth devices, query’s the local Bluetooth adapter and establish RFCOMM channels.

Arduino is an open-source hardware and software company that develops boards and kits for building digital devices and interactive objects that can sense and control from both the physical and digital worlds.

There are DIY kits that I use to make a buzzer sound whenever the application sends out a notification about an emergency. I could use that in the future iterations of the project so that whenever an alarm sounded the application would open, so build a sensor inside the application, but then security comes into play as the application would be listening over time.

A buzzer works like a drum, with a membrane that is stuck by a drum stick causing the device to vibrate and produce noise, but in the Arduino, the membrane is an electric current. To connect the device, firstly I connect the positive leg of the buzzer and connect it to a positive digital pin on the board. The negative leg was connected to ground on the Arduino. Tone command plays command, with two parameters, the digital pin, and the frequency of the noise. There is also a no tone command, which I would use in my assignment when there was no clear emergency. 

## Firebase – Log In / Register / Change Password / Deactivate

Databases for mobiles need to be:

* Lightweight as storage is limited on mobile devices.
* In a form of library with no or very limited dependency (embeddable) so that it can be used when needed
* Fast and secure.
* Easy to handle through code, and option to make it private or shared with other applications.
* Low memory and power consumption.

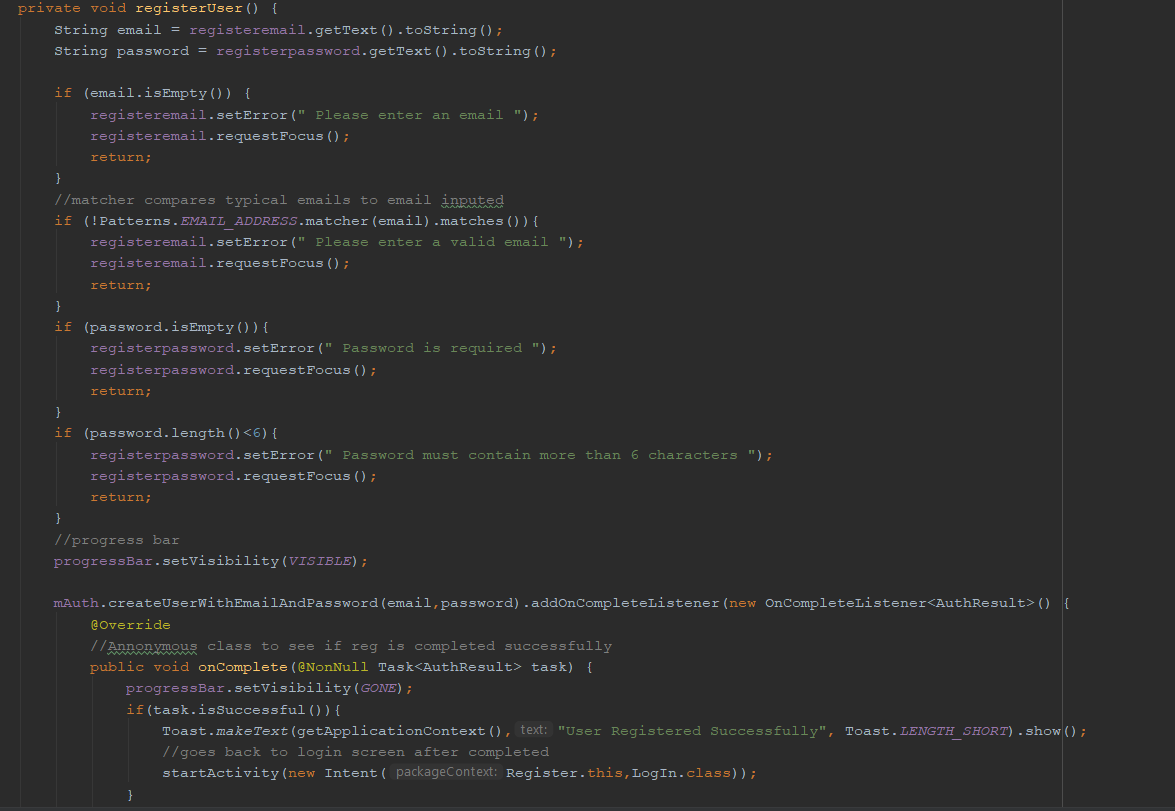
Firebase DB is a mobile app and web app development platform developed by Firebase in 2011, and it has been bought by Google in 2014. I would consider using it as it has been bought by google so it would have many advantages, such as easier accessibility to the google play store. Firebase is used by more than 1.5 million applications (Firebase.Inc, 2018).

Firebase is a free database, hence why it has a big advantage, as probably the application could be free. “Firebase Auth” is a service that can authenticate users using only client-side code, so it wouldn’t need internet to log the user in, just would need it to pull an emergency. The company provides client libraries that enable integration with Android / Java and Kotlin, hence why I would consider using it in my assignment.

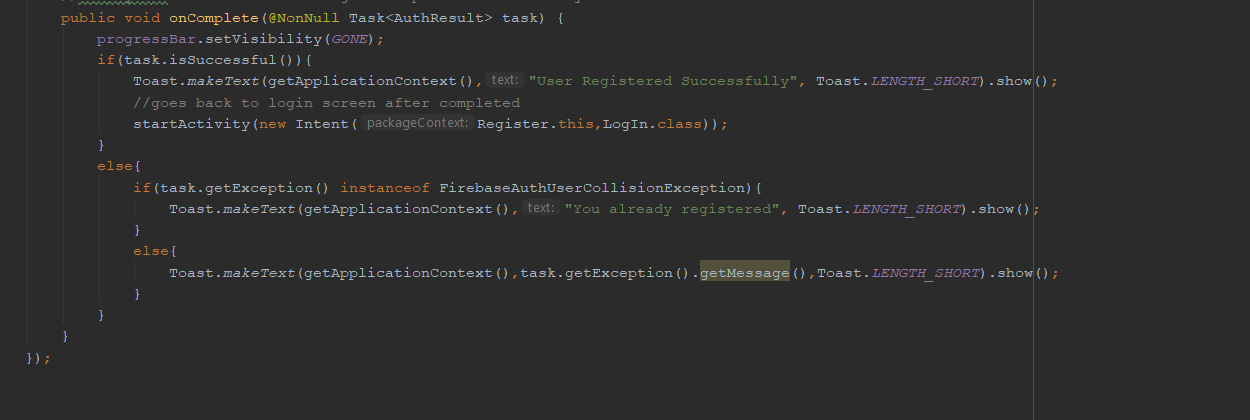
Firebase Storage provides secure file uploads and downloads for Firebase apps, regardless of network quality. The developer can use it to store images, audio, video, or other user-generated content, so if I were to store a Map of a building, it would be very secure, also takin in the fact that internet connection does not have to be amazing to access the service (FirebaseStorage, 2016).

Firebase Notifications is a service that enables targeted user notifications for mobile app developers at no cost, so the user would get notified about an emergency without having to have the app opened.

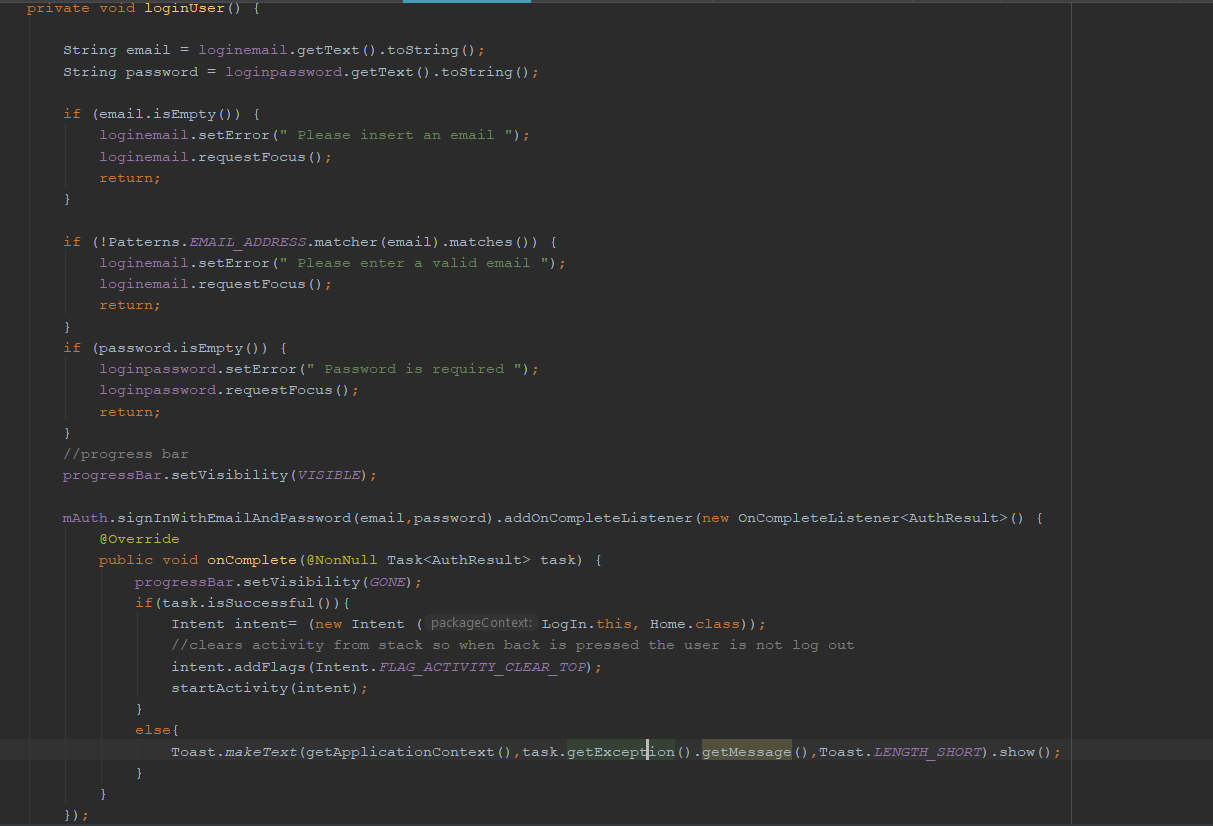
In my mobile application I use firebase auth mostly, as I do not want to store the user’s location, since it would be unnecessary and could lead to very dramatic consequences if someone would hack the application. Firebase auth, basically allows users to log in and register. I do this to make sure I, the administrator of the application, know who is currently using the mobile application to avoid security breaches. Firebase stores the passwords in a salted and hashed manner, so even I do not know what a user’s password is, which is good, as it would be hard for a security breach to happen. Firebase Auth makes my application very secure, so that I know who is using the application at most of the times.



This above is the register method, I check if the email is of correct format, and I check if the password is not empty and it has more than 6 characters, as specified by the firebase authentication.

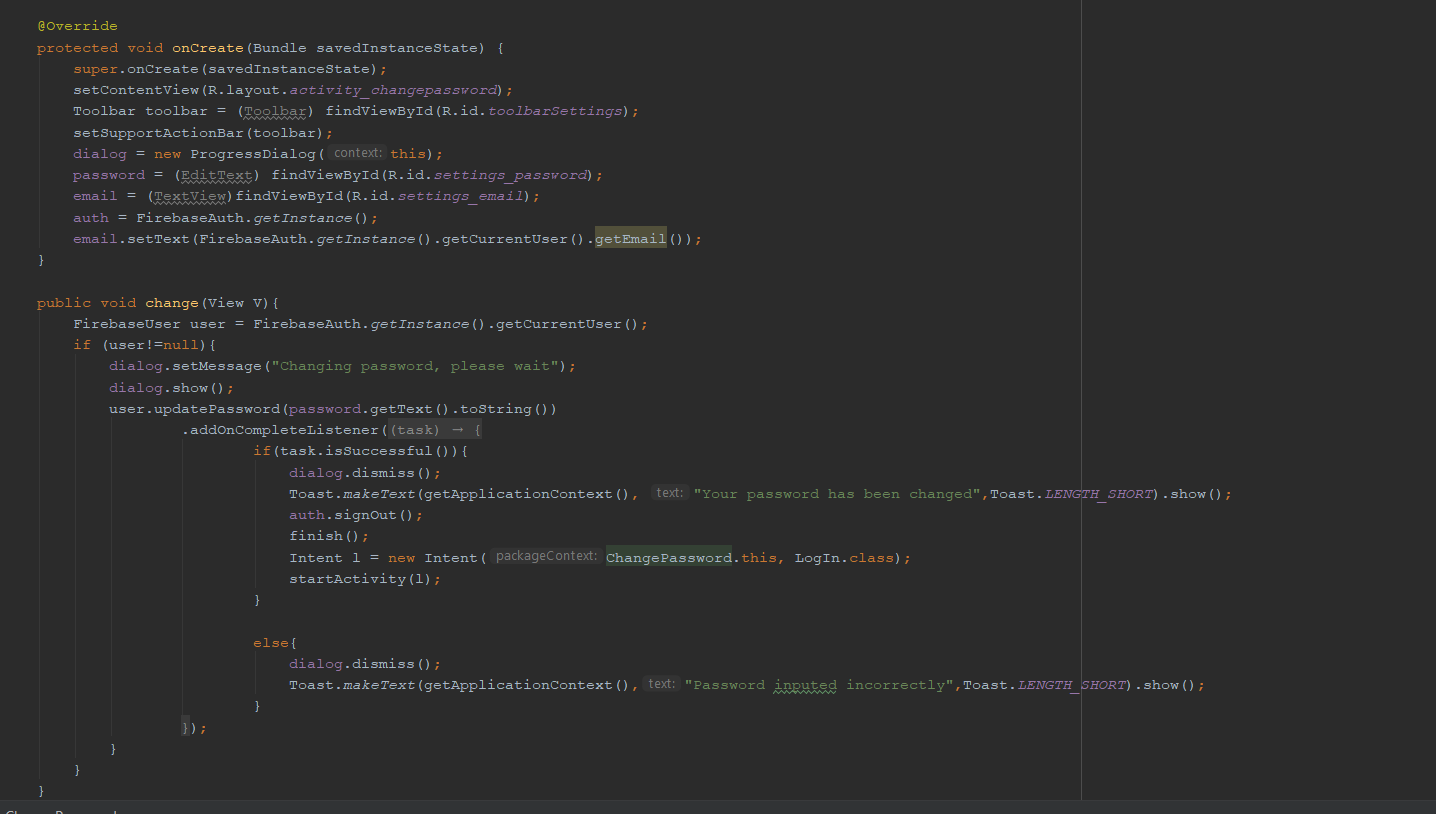


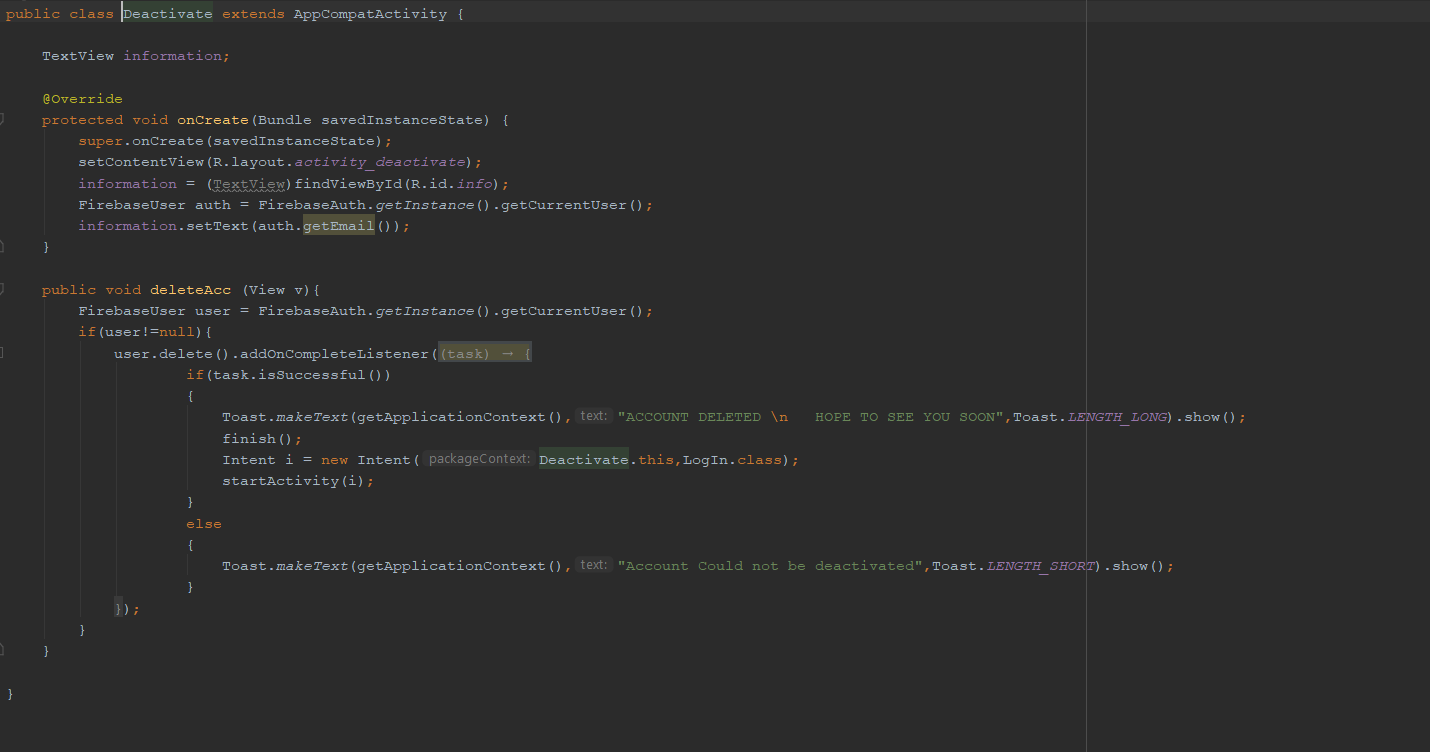
The on Complete is an anonymous class to see if the registration occurred without any errors, if no errors, the user goes to the login screen, if an error with the email already in use, the user gets a message to the screen specifying that he or she is already registered. If firebase error I display the exception.



This is the login method, it checks if the email is empty, also if the email is not valid and if the password is empty. The on Complete checks if the email is correct and if the password is correct, if so it brings the user to the home page, which contains the 3 buttons. If incorrect it gets the exception error from firebase.

As seen below, firebase allows users to also change the password. This is mainly completed in the backend. I let the user see his or her current email, and I’ve a textbox to allow for a new password to get inputted. The change method gets the current user, and if the password input is longer than 6 characters, i.e. it satisfies the constraints of firebase auth, then the user is logged out and brought back to the login screen with a message saying that his or her password is changed correctly, otherwise the password stays the same.

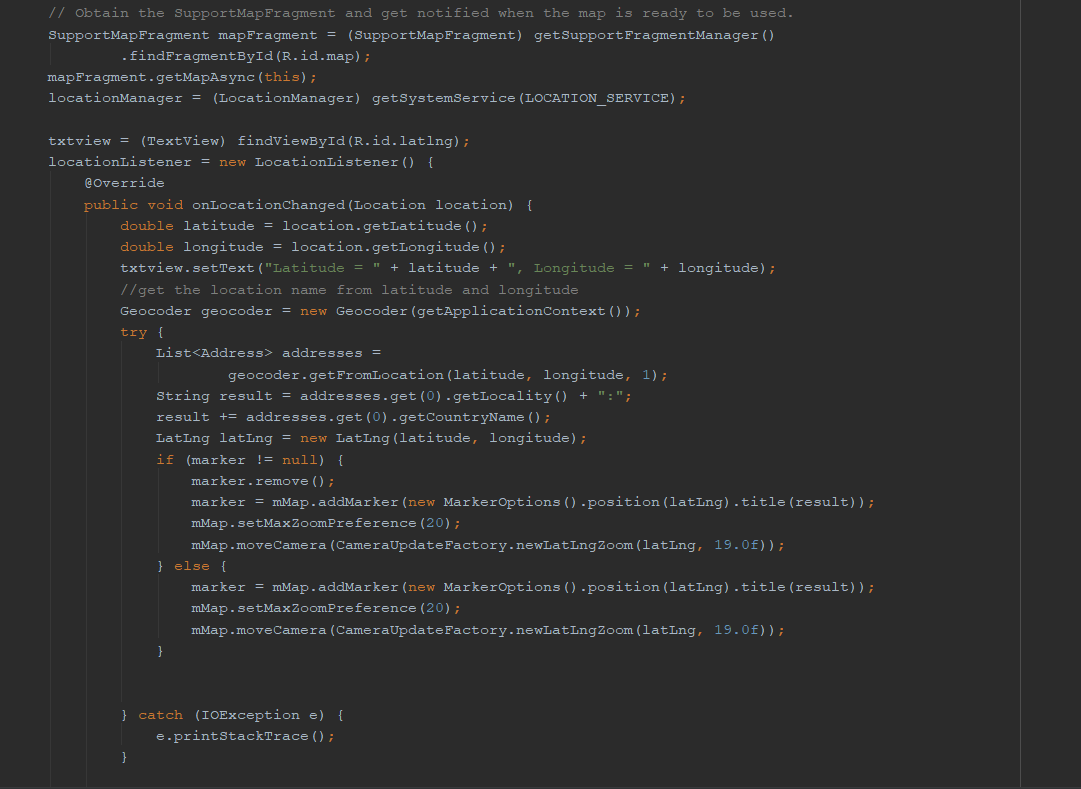


For a user to deactivate his or her account, they press a button, that has a delete Account method that is on Click. The current user is obtained, thanks to firebaseAuth.getInstance.getCurrentUser(). Firebase auth has a method that allows the users to be deleted easily by just calling user.delete() method, which deletes all the user’s entries in the authentication database, and there are no details left about the user.

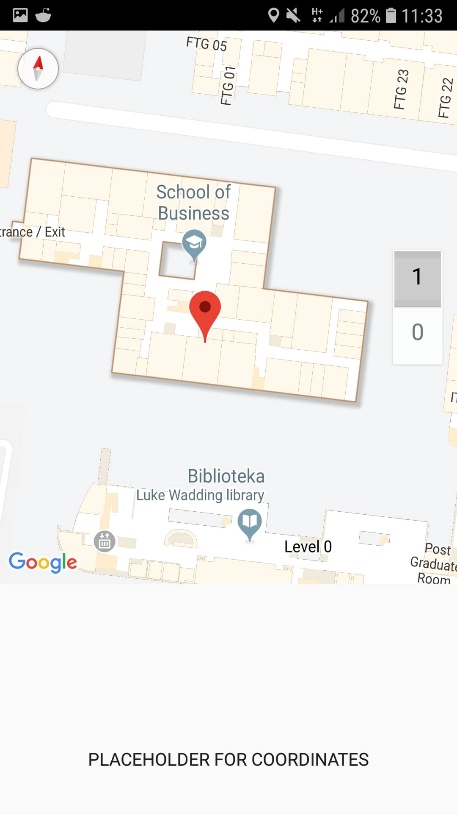
## Google Maps API

An API (application programming interface) is a framework that I can use to write a program. For example, web mapping APIs typically include classes for maps and layers so that I do not have to write all the low-level code for displaying an interactive map image and drawing a new layer on it.

The Google Maps API allow for the embedding of Google Maps onto web pages of outside developers, using a simple JavaScript interface or a Flash interface. It is designed to work on both mobile devices as well as traditional desktop browser applications. The API includes language localization for over 50 languages, region localization and geocoding, and has mechanisms for enterprise developers who want to utilize the Google Maps API within an intranet. The API HTTP services can be accessed over a secure (HTTPS) connection by Google Maps API Premier customers (programmableweb,2018).



I have a class called Maps Activity that contains and holds the map. The user of the application must give permissions for the application to get his or her current location. I get the location to be very accurate, as that is important for the user, to use when they want to escape from a specific room, to know exactly which room they are in. Thankfully google has a very accurate map, allowing the user to know which room he is at, when he or she specifies the floor they are at. I tried this feature in WIT and the results I obtained were very good. In the code, I get the location from the get System Service Location Service method. I have an On Location Changed method. This is to make sure that the map updates in real-time with the user. If a user moves, the application will know and present a new location. I have added a co-ordinate block too, in case the user had to specify where he currently is to emergency services, and to make the user more aware of the surroundings.



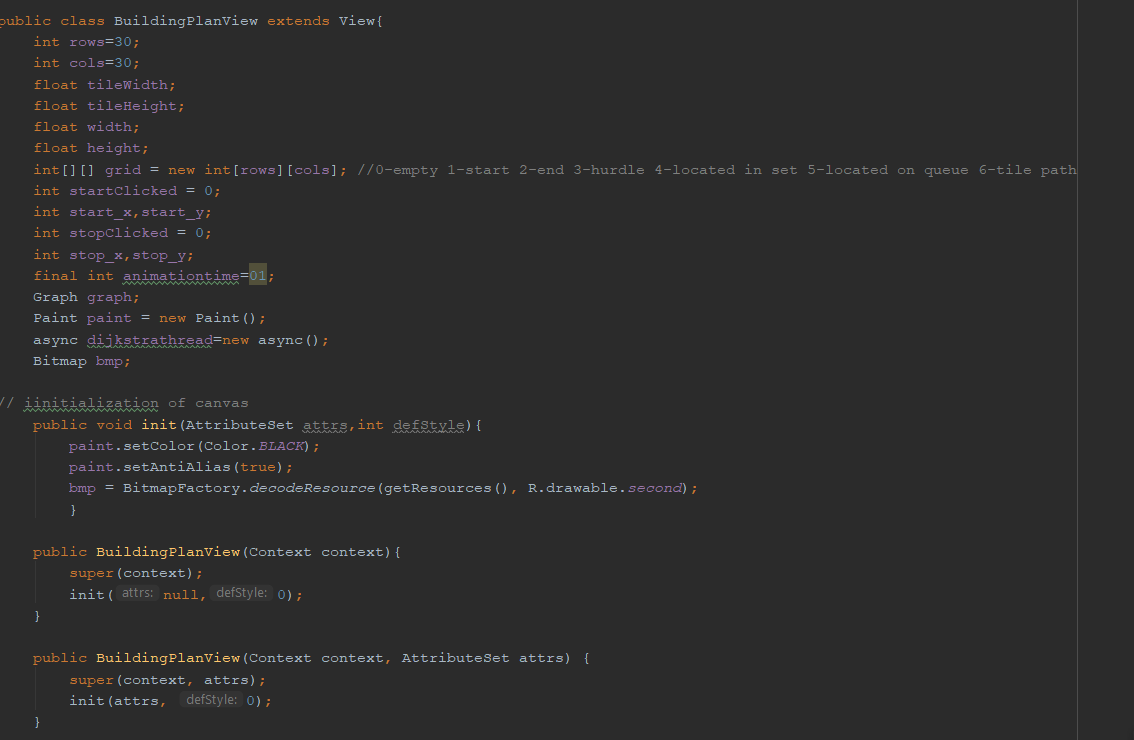
This screenshot was taken before I implemented the code, showing the correct co-ordinates, as I will show in the demo. The user would need this information to specify his/her location on the graph where they start and where they end. I decided not to store this information, as it would be taking security breach risks to a high level.

I had problems with API keys, as I’ve created a number of projects previously and had to contact google to get more keys available for my projects, this was a bit of a challenge and a pause in my application development as without the location the user would not know where they are and where to set the start points of the escape to be correctly. The keys were then working but I had to add a package on the google maps API website, as before that, I was just getting a blank map and it was not working correctly. After I completed the map, which was a vital part of my assignment, I decided to design and do out the algorithm, Dijkstra’s and started to look up ways of implementing it. I will talk about this in the next part of the report. Location was in the end obtained accurately and very precisely for the user to use. Not in the video, or the screenshot above, I’ve added a button to save the user from going back to the main screen to get building plan, and instead they are brought to the screen directly from the Maps Activity. This is a user experience addition, as the user would have fresh in his/her mind where they were last time.

## Route finding – Dijkstra’s algorithm implementation

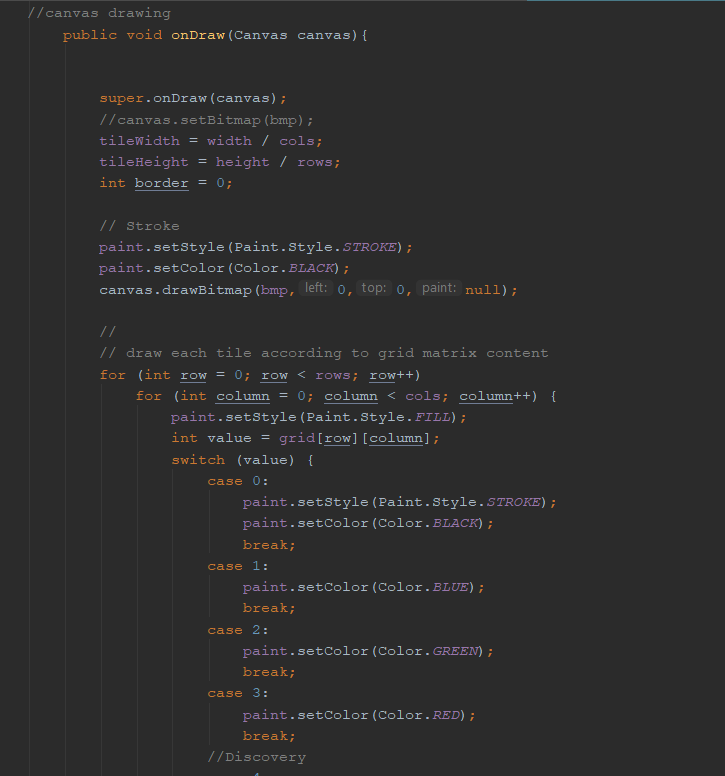
The user is given a route to escape, but how is the route computed. I use one of the algorithms that I learned during Erasmus called Dijkstra which works by starting at one vertex and exploring adjacent nodes until the destination node is reached. Dijkstra algorithm begins with a start node and an "open set" of candidate nodes. At each step, the node in the open set with the lowest distance from the start is examined. The node is marked "closed", and all nodes adjacent to it are added to the open set if they have not already been examined.

### Building View Class Explained – Dijkstra’s algorithm



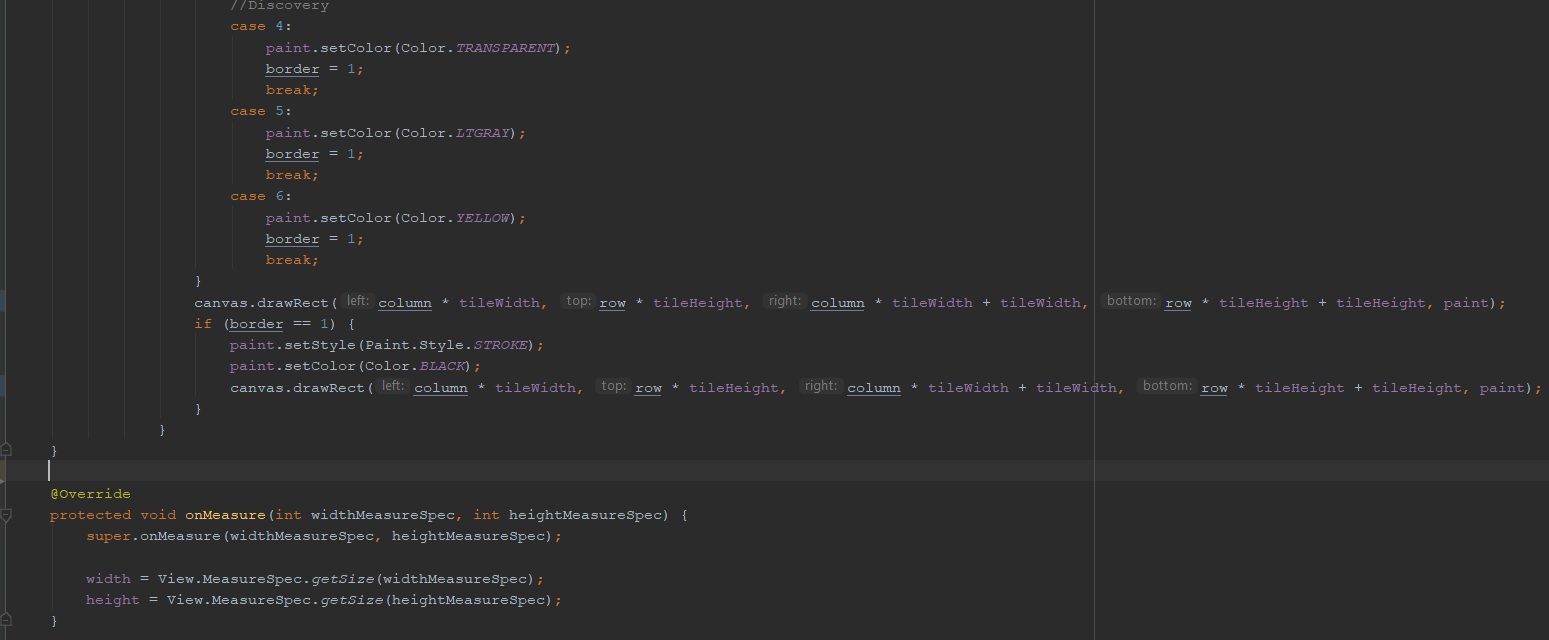
Above I state all the fields I will use, such as the rows and columns value, the higher the number, the smaller the grids get as more columns and rows are added decreasing the size. Tile Width and height are used to draw out the rows and columns on the canvas. Width and height are the width and height of the screen and that is to make sure no thing is created outside of the boundaries. Grid is an array of arrays, used to store rows and columns. Comment specifies the values of grid available. Start Clicked is 0 and 1, to specify where the user presses start, then when that happens, Grid start\_x and start\_y is set to be an empty grid. I then let grid[row][column] to be 1, and I let the start\_x to be column and start\_y is row. Stop Clicked is set to be 0 by default, stop\_x and stop\_y are variables for column and row when stop is clicked. Animation time is the time for the graph to be displayed, I have it as 01 as it is relatively quick, but could be set lower, this is purely for visuals during the demonstration. Graph is there to get the Vertex start and vertex destination in the async method. This gets the start\_x and start\_y, and the stop\_x and stop\_y and sets one as start and the other one as destination. Paint variable is calling a Paint() constructor, that creates a new paint with default settings. Later, in this project, I manipulate this method to make sure the Canvas paints what I want to paint, i.e. Start, Route, End. Async enables proper and easy use of the UI thread. This class allows me to perform background operations and publish results on the UI thread without having to manipulate threads and/or handlers. I use this to print out the results of the compilation of my algorithm. Bitmap is used to load the saved image if needed onto the canvas, which could be developed further if my assignment developed commercially.

The constructors init and BuildingPlanView are important so no exception occurs. The init initializes the application. The Building plan context is used when instantiating Views programmatically. The BuildingPlanView context attrs is used by the layout inflater to apply xml attributes.



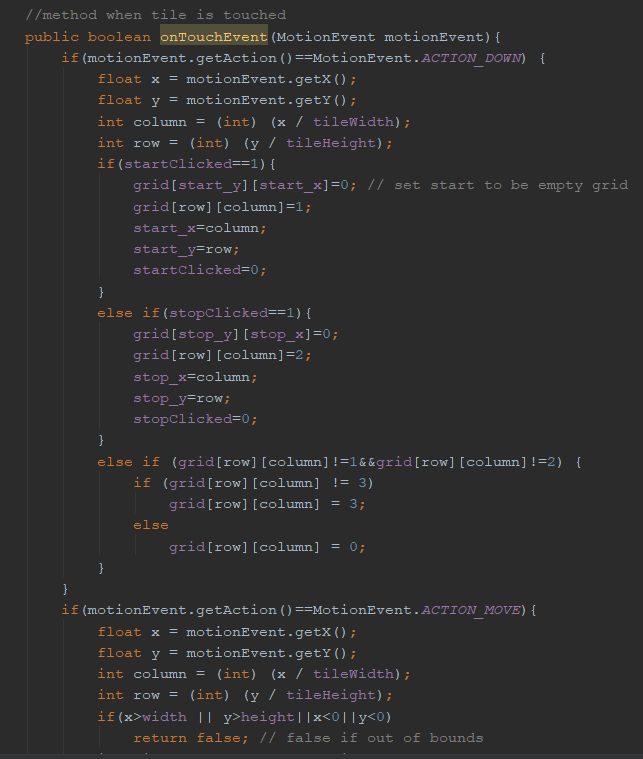
Having both Canvas and Paint objects will allow me to draw anything I need -> in my case rectangles in the grid

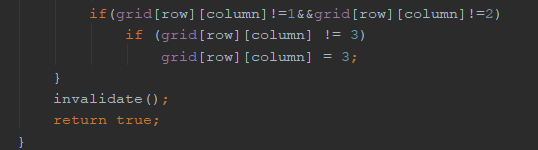
A Canvas instance comes as on Draw parameter, it basically responds for drawing a different shape, while Paint object defines that colour that shape will get. I get the tile width and height to be half of the width divided by columns and likewise with the height, being height divided by rows. The stroke and the colour are set to default values, and a bitmap is created. I have a nested for loop to draw and iterate through each row and column of the grid. The value is the grid[row][column], if it’s the start, set the colour to be blue. The end node is green, the Red is the fire and that’s case3, where a user paints onto the canvas where the fire currently is. This updates on a touch method which I will describe in a later part of this report.



The screenshot above is a continuation of the on-draw method. I set the colour to be transparent, in the poster I had a light blue colour set, for this option. This is basically all the discovered nodes that the algorithm has processed. The light grey, which is case 5, is the nodes that are currently being processed and case 6 is the final stage, which is the yellow path that is drawn.

For columns the draw rectangle method is called, with the grid values and the current paint depending on the case. If border is one, i.e. the discovery or discovered nodes then draw in black, this method is only used if an error occurs of some sort with the border value.





The OnTouchEvent method is used for when the user pressed down on a specific tile. The float values of x and y are the values of the screen x and y positions the user has pressed on. Column is x divided by Width and row is y divided by height.

When the start button is clicked, the y and x values are 0 in the array of arrays value and row and column values are 1, meaning that the user specifies a start node.

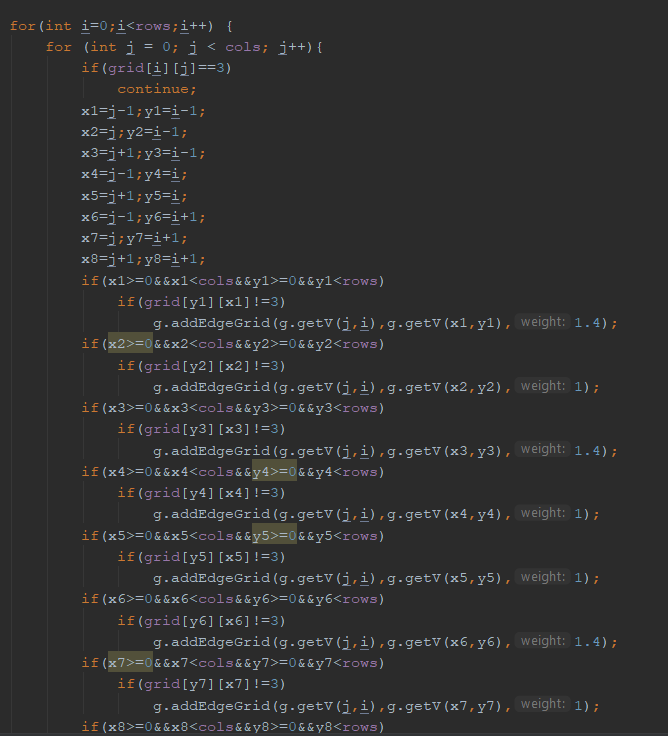
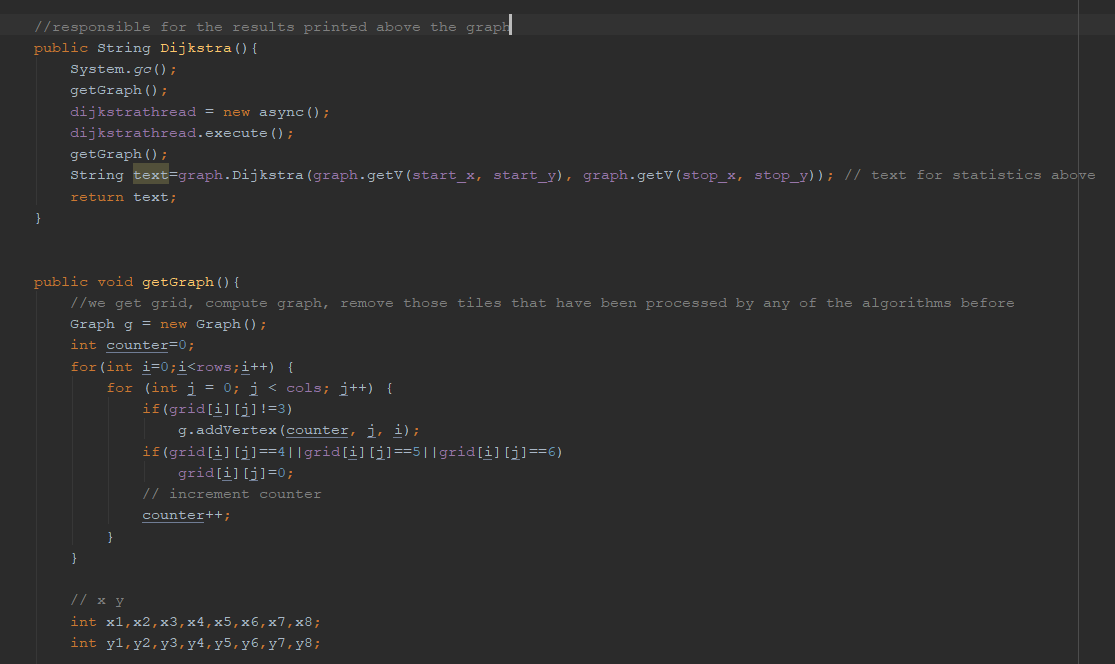
When the stop button is clicked, the y and x values are 0 in the array of arrays value and row and column values are 2, meaning that the user specifies an end node.

When the user did not press the button the row and column array of arrays value is 3, meaning that it is the red colour, of fire, or 0 meaning black, which is a default I set as an error checking value.

I also check that the width and height are in the bounds of the screen and aren’t pressed in a way I did not expect, so I make the on touch method very predictable to return a Boolean value of false, if the press was out of bounds, and then I check if the user pressed the start or the end node on the buttons and if not I set the colour to be 3.

I then call an invalidate method, this is an android method used because the system handles resizing, hiding, showing, but it sometimes has issues if the underlying buffer for drawn pixels or backing data has changed or is stale (I swap the image resource on a View or the raw dataset changes). This occurs because there is no way that the OS can know that the data changed in the specific manner that it did. Generally, invalidate() means 'redraw on screen' and results to a call of the view's onDraw() method, so if something changes and it needs to be reflected on screen, I need to call invalidate().

The return true is regarding the fact that the press, with the x and y coordinates was within the boundaries and is a correct press on the screen.



The Dijkstra is responsible for printing out the results above the graph. The first method is System.gc(); The System.gc() method runs the garbage collector. Calling this suggests that the Java Virtual Machine expend effort toward recycling unused objects to make the memory they currently occupy available for quick reuse. This is to make sure the application runs as quick as possible for a user to find the emergency escape. I then run the get Graph method, which is below, and I will explain in the next paragraph. I make the dijstrathread to execute asynchronously with the graph, this means that both the get graph and the text are executed at the same time and one doesn’t have to finish before the other one.

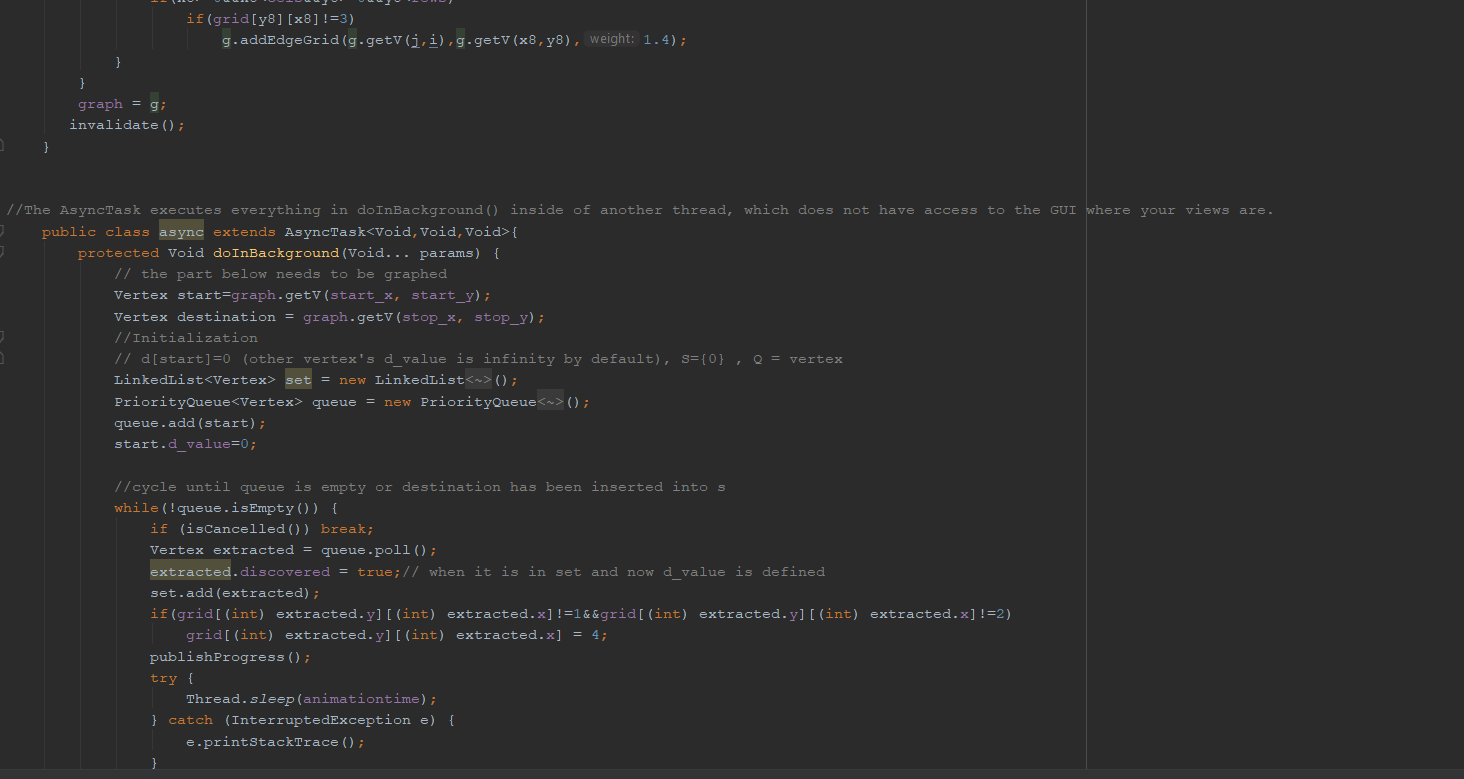
The get Graph is pressed when a user presses the Dijkstra button. This is the main feature and algorithm of my final year project. First, we let g be a new graph, I iterate through each row, and J iterates through each column. If grid I and j is not 3, which is when the user draws a fire, we add a vertex, which takes in a counter as id, j and I as the x and y values. If the grid I j value is 4 or 5 or 6, which means, its located, its on the located queue or the path is found, I let grid I j equal to 0 to reset. I then increment the counter id, as that would count as a second route finding.

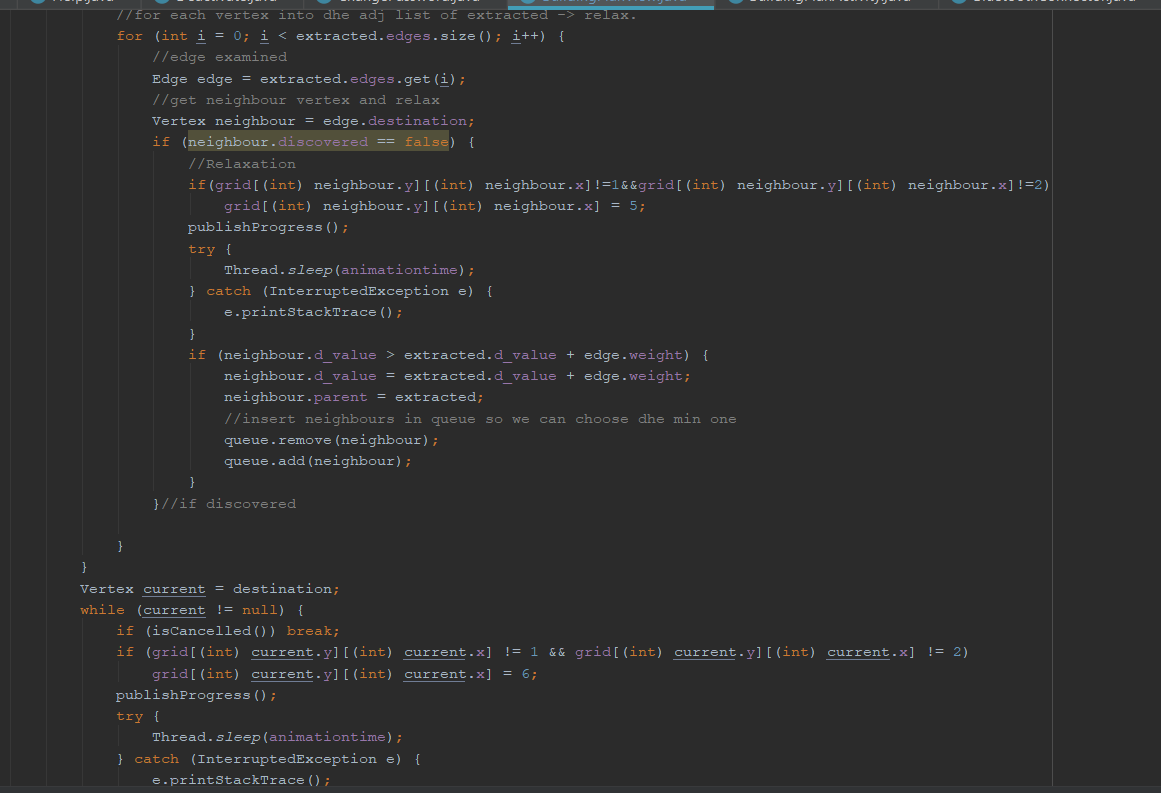
The nodes have 8 values of x and y around them, each of these must be iterated through, I subtract or add 1 as the values for them had to be in the for loop, so the values resemble the table I have below, except the one that is directly by the node and not Diagonal. The table below is how I implement the x1-x8 y1-y8 values and this is to make sure the algorithm works correctly. This is also to find the end node of the algorithm i.e. the destination and to instruct the algorithm which way to go

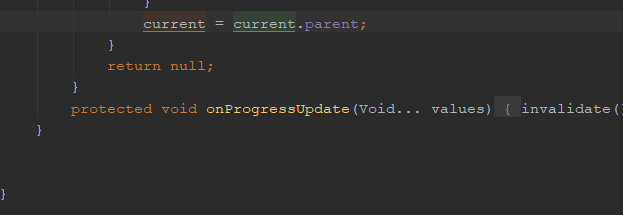
|  |  |  |
| --- | --- | --- |
| X1 j-1 i -1 Weight 1.4 | X4 j-1 i+0 Weight 1 | X6 j-1 i+1 Weight 1.4 |
| X2 j+0 i-1 Weight 1 | Node ( j 0 I 0) | X7 j+0 i+1 Weight 1 |
| X3 j+1 i-1 Weight 1.4 | X5 j-1 i+0 Weight 1 | X8 j+1 i+1 Weight 1.4 |

I then have if statements to see if x1>0 and x1 is greater than cols and y1 is greater than 0 and less than rows and if nothing is drawn there in red, we add edge grid with a source j and i, we add the destination from that edge x1 and y1 and we set the weight to be 1.4. The if statement is there to make sure that the node we add to the edge grid is not the node we are using as the end node. The weights on the diagonal is greater than on the straight lines. This algorithm tends to avoid the routes with the larger weights unless it is necessary to find the optimal escape route.

I then check in all the 8 if statements if the current x value is greater than 0, meaning it is not found, and it is less than cols, meaning that it is on the screen and if the y value is greater than 0, meaning it is not found and that it is less than rows, meaning its on the screen, I then add an edge grid, with the source, destination and a weight of either 1 or 1.4 depending on the position of the node that is been discovered currently. This goes on for each x and y value, and then I let the graph to be g, meaning the graph is updated and I invalidate, this is an android method used because the system handles resizing, hiding, showing, but it sometimes has issues if the underlying buffer for drawn pixels or backing data has changed.







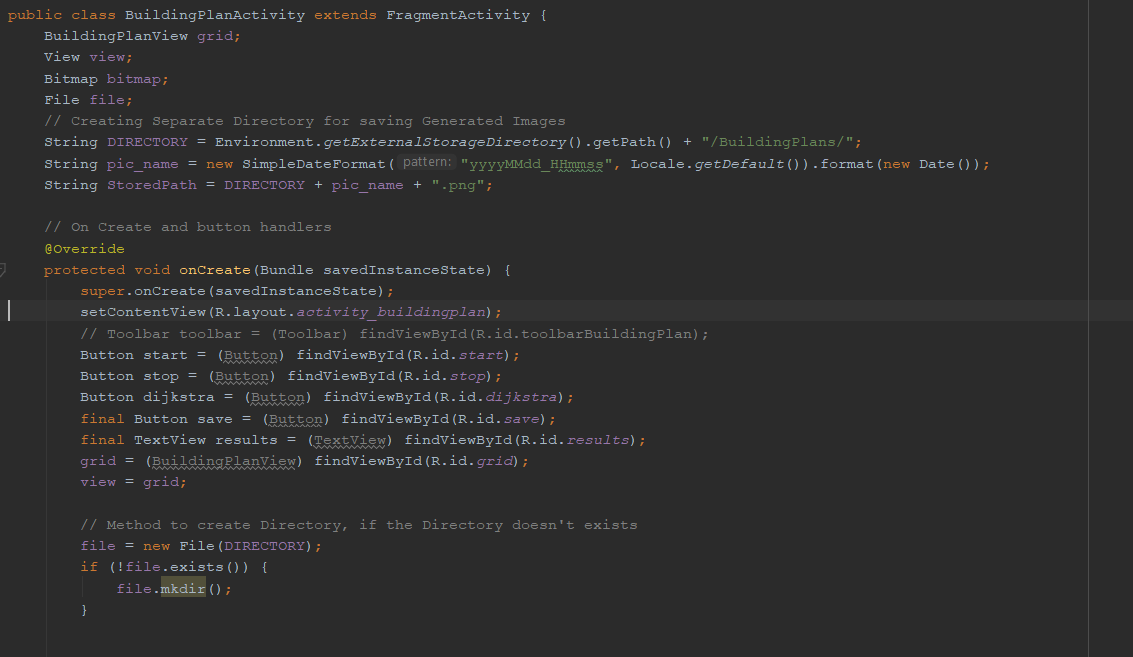
In the above screenshots I have the AsyncTask that executes everything in the background while the graph is drawn. First, I initialise the start and destination Vertex. I have a linked list called set and a priority queue called queue. Set basically stores all the nodes visited that are not part of the solution- transparent in the final demo, blue on the poster. Queue is the ones that are bound to be discover and are grey in colour. I add then the start to be on the queue and set the d\_value to be 0 , as this is the start and I will use this to draw out the yellow path from the start. I then cycle until queue is empty or the destination has been reached and inserted into the set. I have an extracted vertex value to be equal to the poll value of the queue. I then set the extracted discovered to be true, and then add it to the set.

If the grid value of the extracted is not the start i.e. !=1 and if the grid extracted is not the end !=2 then the grid must be of value 4 = Transparent i.e. discovered I publish the results. I then call a Java Async method called publishProgress() which pushes the information onto the UI. If the extracted is the destination I break from the animation and the route is drawn.

I then go through the size of the extracted edges and I check all edges and get the neighbour of each edge that was discovered. If the neighbour is not discovered and if it is not the start or the end, it is the future nodes to discovered which is 5, the grey colour on the poster app demo. I publish the progress. The d\_value for start is 0, but for any other node it is infinity. If the neighbours.d\_value is greater than the extracted.d\_value +weight I let the d\_value to be the weight and the parent to be extracted. I add the neighbour to the queue to be discovered. This step is to add the future nodes to be explored, excluding the ones marked by the user that indicate there is a fire there.

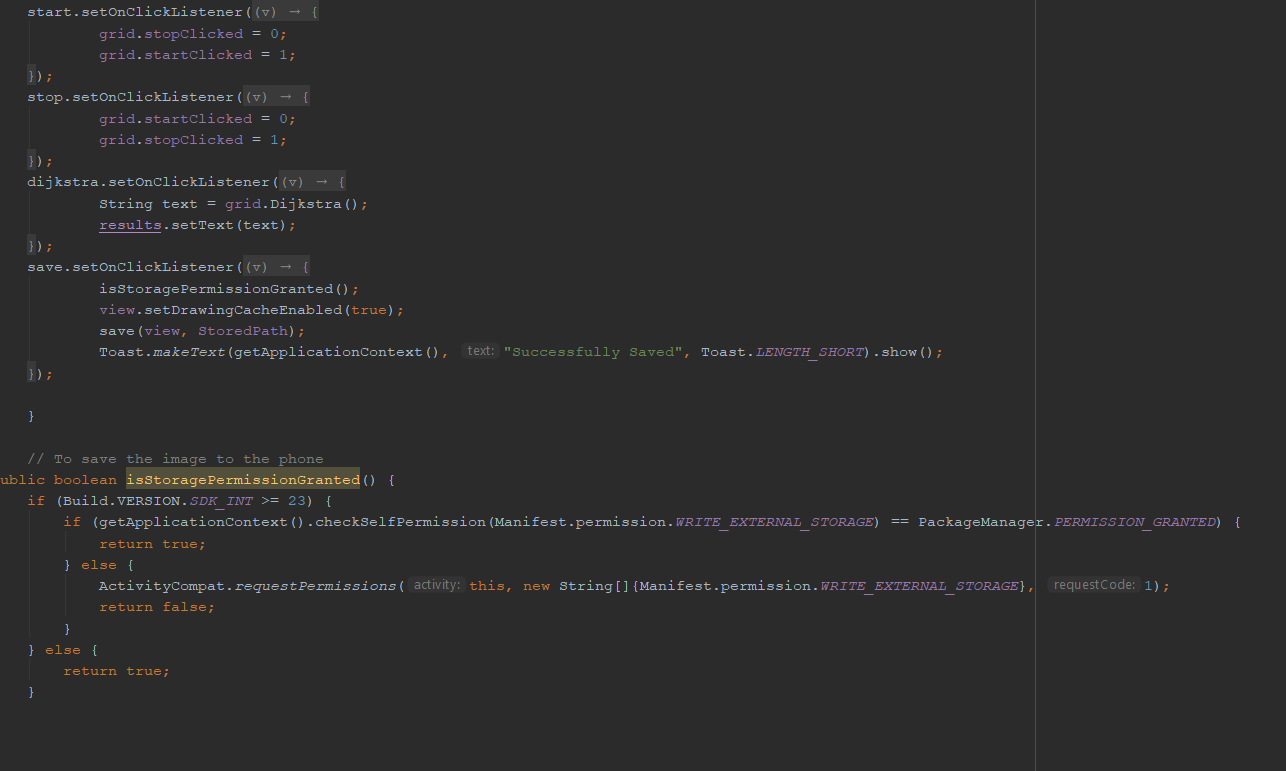
If the queue is empty, i.e. no more nodes to discover I set the current vertex to be destination. If the destination is not null, and not the start or the end node, I let the grid of current x and y to be 6, which is the yellow specifying the quickest path. I specify that the current node is the current parent so that there are no more nodes to be discovered. This method returns null, it just updates the UI with the publishProgress(); java method, and I try to sleep the thread for the animation time, just to make sure there are no errors.

### Building Activity Class Explained



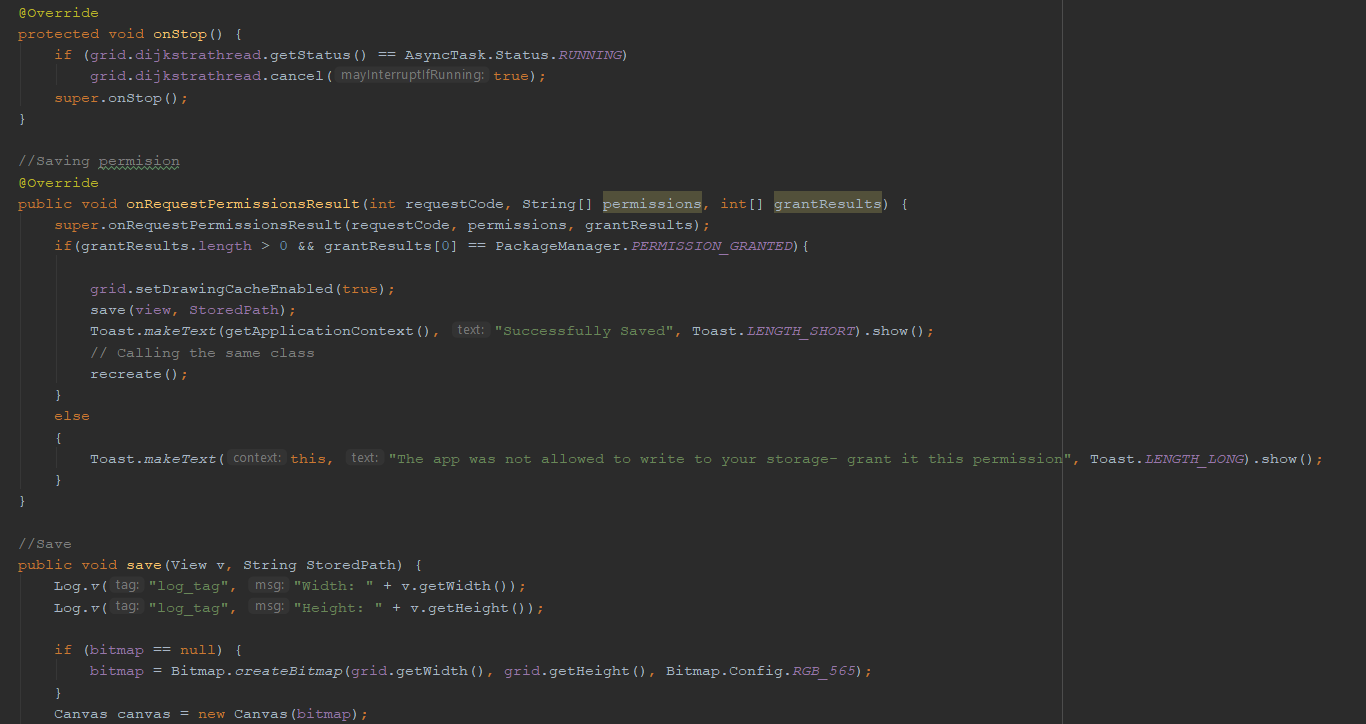
This class is responsible for the buttons that are pressed at the bottom of the screen and the links with the GUI. I also have a method to save the image to a bitmap, and possibly re-use the image as the application would develop. I create in the On Create method the buttons, the results tab, the grid and I let the view to be the grid.

I also create a directory of the format as seen in the String DIRECTORY prior the On Create method. I check if the directory to save the image exists and if it does not I create it.

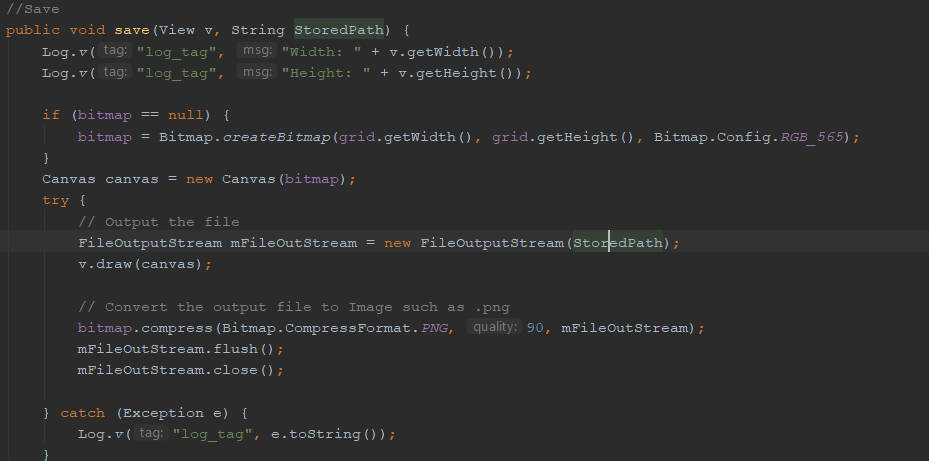


In the above I have a start button, stop button, dijsktra button and save button on click listeners. Each of these buttons have rolls. The start sets the start node, stop sets the end node, the dijstra button runs all of the methods in the view and also sets the results to be the text obtained from the Graph class. The save first checks if the storage permission is granted, then saves the view to the stored path and a toast message is then printed to confirm a save occurred.

I have a boolean method to check if the storage permission is given. This is a feature the user must implement from versions 23 or above. If the permision is given return true else false, and that will then save or not save the bitmap.

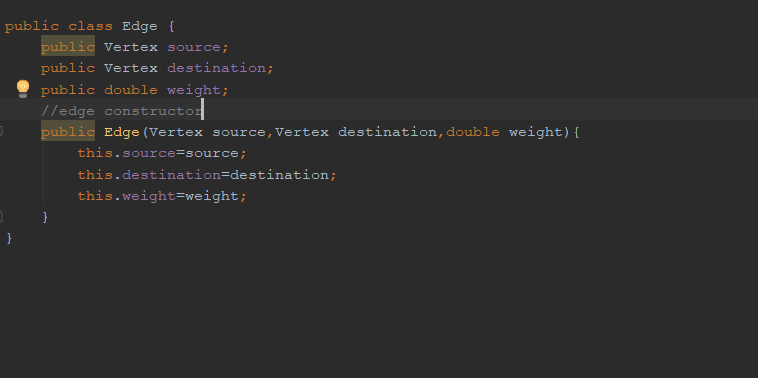


The On Stop method above checks if the Background task is running and cancels it. There is a method called onRequestPermisionResults which saves the picture.



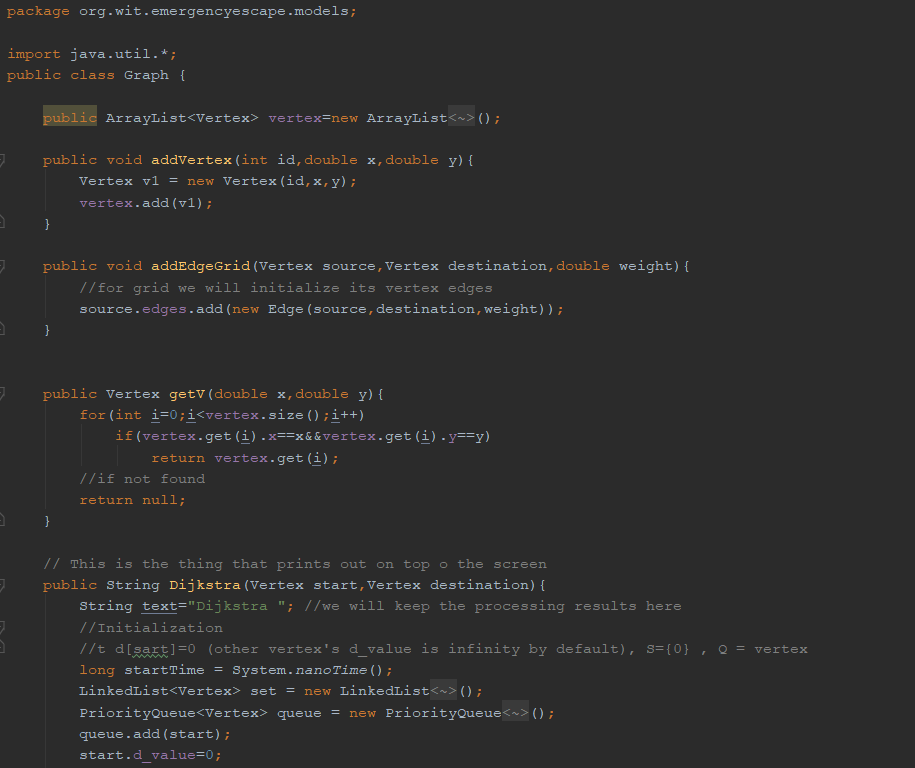
This method is run when the button is pressed, as it’s the OnClick Handler. It logs to the admin, could change that to user, but felt like it’s unnecesarry information, the image Width and Image height. If the bitmap is null it creates the bitmap with the grid width, height and the colours. It then stores the canvas and loads it back in. The bitmap is then converted to a png format, for the user to be able to view, even if the application fails to function after the path was given out, or to save battery due to the location of the user being check for.

### Edge Class Explained – Dijkstra’s algorithm

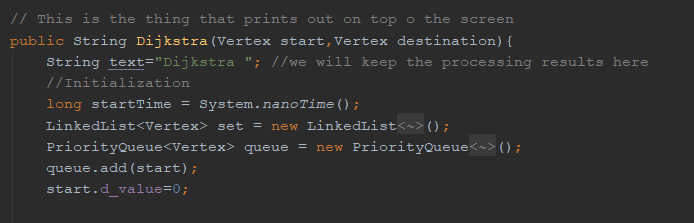


Each edge has a source, a destination and a weight. Weight can be 1 or 1.4. 1 means that the nodes adjacent are not diagonal and a weight value of 1.4 means that the node is on a diagonal. Vertex source and Vertex destination means the angular point of the source and destination, i.e. the first two nodes.

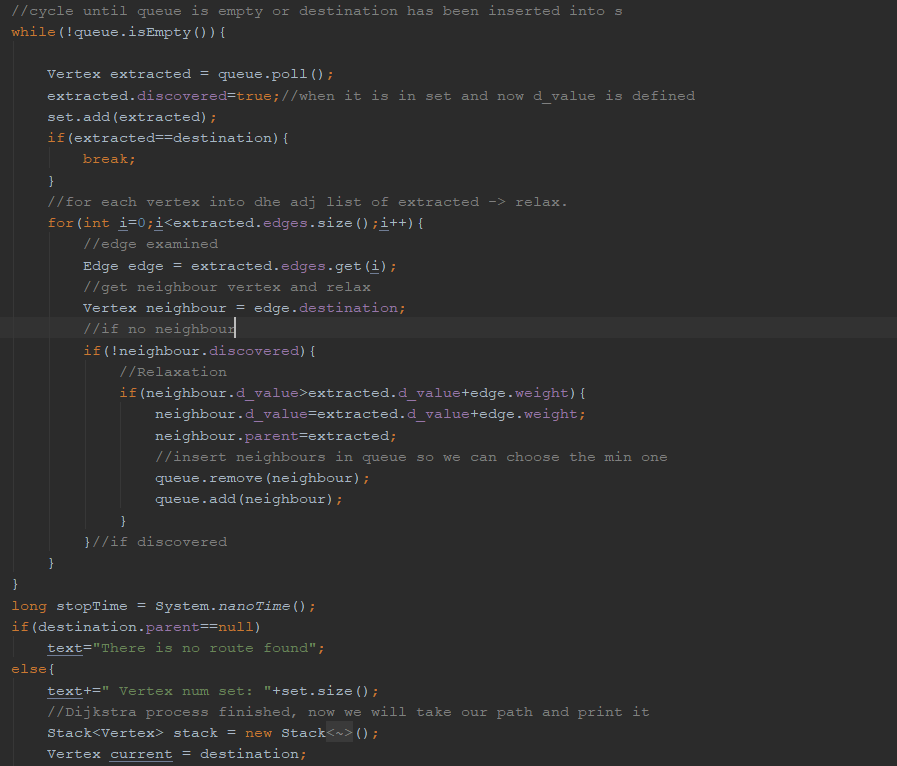
### Graph Class Explained – Dijkstra’s algorithm

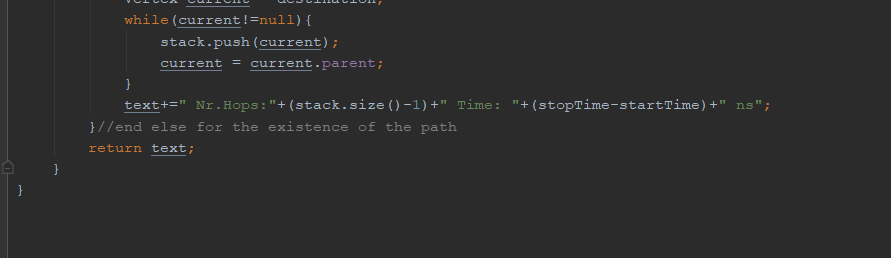


Add Vertex adds a vertex with an id, x and y value. AddEdgeGrid adds the source, destination and weight and it’s used in the BuildingPlanView class. The getV method gets the vertexes with a specific I value, when given the x co-ordinate and the y co-ordinate. Returns null when there is no vertex found.



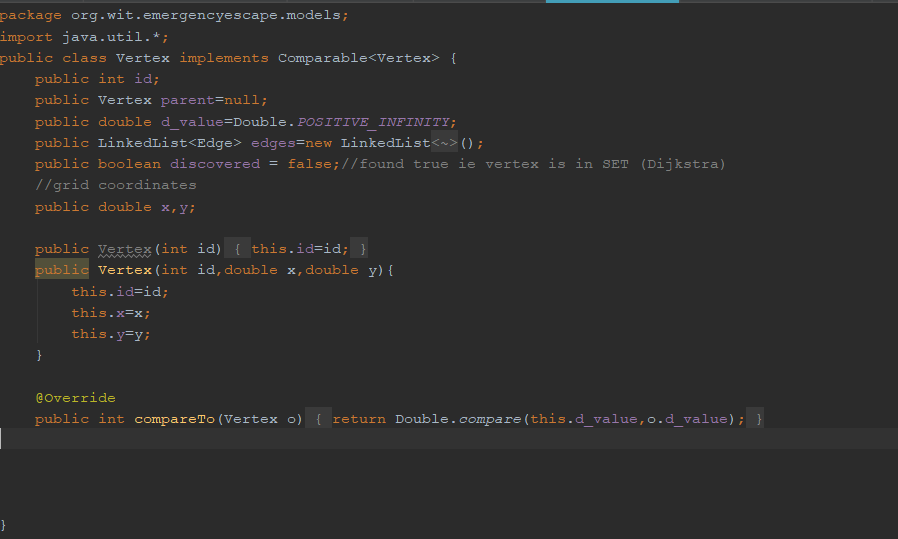
This is what pressing the Dijkstra button prints out. I initialise the start time. I have a linked list called set and a priority queue called queue. Set basically stores all the nodes visited that are not part of the solution- transparent in the final demo, blue on the poster. Queue is the ones that are bound to be discover and are grey in colour. I add then the start to be on the queue and set the d\_value to be 0 , as this is the start and I will use this to draw out the yellow path from the start.





I then cycle until queue is empty or the destination has been reached and inserted into the set. If the extracted is discovered I add it to the set. I then iterate through the extracted edges. I get the edge examined and get the neighbour verted. If no neighbour discovered I, then check the d\_value and I let the neighbour.parent value to be equal to the extracted and delete the neighbour. I then have a stop time, and if the destination parent is null I print out that there is no route found. Else I have the set size, meaning how many nodes were looked at, I will then check if the destination is not null and I will print out the number of hops, which is the stack size-1 since the stack starts with 1. I then also get the time in nanoseconds that it took for the route to be found. I then return the text

### Vertex Class Explained – Dijkstra’s algorithm



The Vertex implements a comparable as I had compared vertex to each other. It has an id, a parent that is set to Null by default. A random d\_value that is infinite, depending on the weight added in the programme, but at the start it’s infinite. I have a LinkedList of edges, and a Boolean whether the vertex is discovered, set to false by default. The Vertex has a double x and y value. I then have a constructor and a compareTo method, that compares the d\_values.

# How security is dealt with?

Security was an important for this project, as each person will be having to specify their own location. I will make sure the variables for latitude and longitude are not kept in any database, and that each user would have to log in, and when logged in they would only be able to see their own private location. No other person’s location could be given away, and personal information such as name and surname and other details given at the register stag are not stored, hence they can’t be given away. The log in/ register feature is there to provide security to avoid many people entering the system and trying to ddos the system. I will also know some details, like emails of the users using my app so that increases the security. Thanks to the use of firebase authentication I could allow users to log in securely.

## Language

I wrote the application in Java, as in second semester I learned java with android studio, but also, I had a backup language called Kotlin. Kotlin is a newer version of java, with many things just made easier for the developer to write code in. Java is used, as Kotlin is only a new language, and as much as it simplifies the creation of applications by making some of the methods easier, the language is based on Java. Java was my go to language due to the fact Java apps are more compact – in comparison to Kotlin, Java apps tend to be lighter, which is good for my final year project as I do not know what the phone of the user is going to be. A Kotlin app that includes complex computing processes in its code can turn out to work slowly on user devices with low technical specs. Java also allows top development speed, and faster build process than kotlin according to netguru (netguru, 2018). The build time for my assignment is vital as the quicker the user gets the route, and the quicker the application opens, the more chance the user would have to escape an emergency. According to Netguru Kotlin also has a small developer community, which means limited learning resources and difficulty in finding answers to questions. At looking only on stackoverflow there are only around 8000 questions tagged with Kotlin against 1.37 million questions about Java.

# Plan for the application after the final year project

Firstly, I plan for the application in the future to get the administrator and building owner rights in onto the system, administrators can add building owners, and building owners can add or delete maps. The building owners would have to verified manually, and therefore I did not implement this feature in this project now, but it could be part of future development. The user would not have any access to adding or deleting maps, or owners. The user will only have a map of the building, and when an emergency happens the user will be able to see the path. In building the application.

The application could be connected to the amazon web services to be deployed in the cloud for many users- but the Arduino boards would have to be more widespread and used by more building administrators and users. There would be a need to install fire alarms in all the buildings and connecting them through Bluetooth, but I see this step being viable in the future as the world becomes connected and IOT – internet of things begins to be a daily thing.

As my application would develop I could use neural networks to find the best route, if the number of users was enough, to test if the network would be enough. The users would be inputs to the neural network, and the neural network second layer could be different locations and based on the current location of the user the route would be shown. This would be an overkill for my final year project at this stage though as I do not have many users.

I would also take more time in developing the building plans and to match them correctly with specific buildings, as this is a draft application I just created a plan in a graphics programme called GIMP, but more professional image designs would be a nice feature.

# Draft user manual

The user would download the application from the app store. The user then would have to register for safety reasons and for the information to be used by the application regarding location, to keep a database of the user. The user would then log into the application where both a map would be displayed, showing the current location and a building plan. The user tries to get out of a fire. He or she must get the current location by pressing the get location button. Then he or she is going to get the route to the exit. If a fire develops that blocks the path, the user would draw the fire onto the canvas of the application, he or she would then press the button again, and a new route would be calculated and displayed. This image can be saved by the user to the phone device, in case the battery is low and the application that requires location is draining too much battery. The building administrator would press the button for the buzzer to notify all the users that there is an emergency taking place.

# Learning curve and challenges

This was the first time where I had to link things that I have learned throughout different subjects and combine them together to get a fully working effect. The things I learned at doing this final year project are vital for my future as an IT graduate. I had researched the things that I planned to for the application, and the things that I will do if things do not work out for me. I planned to continue this approach in different areas of my project, and I plan to use my problem-solving skills to the best of my ability. The project was a challenge to show my time keeping skills, my programming skills and my way of working around problems that will arise in the project. Connecting the Arduino with the different modules, pins and wires was also a challenge, since it was the first time I was doing it. I had also problems with the Google API keys, about which I had to contact Google. I would invest more money on the Bluetooth module, as the signal is sometimes very weak. I had small problems bringing all the libraries and API’s together and that took some time, also to fix all the gradle files where an error occurred due to a dependency being of a wrong version.

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# Minutes from meetings – Semester 1

|  |  |  |  |
| --- | --- | --- | --- |
| Meeting Date | Work Completed | Y/N | Work to Do |
| 18/Oct/18 | * Discussed grading scheme of project * Discussed project Idea | Y | * Project proposal start * Technologies that I will use |

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| --- | --- | --- | --- |
| Meeting Date | Work Completed | Y/N | Work to Do |
| 22/Oct/18 | * Discussed the diagrams of the project and what my project is about | Y | * Write up a report about the technologies that I will use |

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| --- | --- | --- | --- |
| Meeting Date | Work Completed | Y/N | Work to Do |
| 5/Nov/18 | * Basic report completed * Done over email due to meetings and me working | Y | * Fix the things highlighted by the supervisor * Make the report more aimed at my project |

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| --- | --- | --- | --- |
| Meeting Date | Work Completed | Y/N | Work to Do |
| 12/Nov/18 | * Report Fixed * Technologies changed and looked up * Fixed Harvard referencing. | Y | * Do minutes for all the reports? * Write about alternatives of the technologies I will use. |

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| --- | --- | --- | --- |
| Meeting Date | Work Completed | Y/N | Work to Do |
| 30/Nov/18 | * Minutes fixed * Alternatives written up | Y | * Presentation * Spelling fixes * Citation fixes |

# Minutes from meetings – Semester 2

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 1 | * Refactored login screen * Used proto.io to decide on the look of the application * Meeting time arrangements | Y | * Plan out timetable * UML diagrams * Start looking at W3C guidelines * Splash screen |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 2 | * Planned out timetables * UML Diagrams finalised * Develop a splash screen myself to avoid copy right infringements | Y | * Settings to allow users to see their location * Co-ordinates placeholder * Google Maps API |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 3 | * Settings to allow users to see their location * Co-ordinates placeholder * Google Maps API | Y | * Building plan tab * Drew out a building plan * Classes for coding the Dijkstra’s algorithm * Cognito form for the industry day |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 4 | * Building plan tab * Drew out a building plan * Classes for coding the Dijkstra’s algorithm * Cognito form for the industry day | Y | * Fix library imports * Arduino connection * Sensors and modules in Arduino code * Connecting Arduino with application |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 5 | * Fix library imports * Arduino connection * Sensors and modules in Arduino code * Connecting Arduino with application | Y | * Connectivity checks * GitHub documentation and converting all to Java, as has a few Kotlin classes- as that was my previous module and I had to learn the Java way of implementing something * Buzzer test * Coordinates need to be displayed in the placeholder. |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 6 | * Connectivity checks * GitHub documentation and converted all to Java, as has a few Kotlin classes- as that was my previous module and I had to learn the Java way of implementing something * Buzzer test * Coordinates displayed in the placeholder. | Y | * XML updates to make application look more appealing * Logo of the application will be developed in GIMP * Add help window that helps the users to use the application * Add info tab, for users to contact me the developer with any inquires |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 7 | * XML updates to make application look more appealing * Logo of the application developed in GIMP * Added help window that helps the users to use the application * Added info tab, for users to contact me the developer with any inquires | Y | * Add a Bluetooth file written in Arduino to connect to the application. * Display ip address of Bluetooth * Download nRF Connect on the phone as it gives a debugging tool on the Bluetooth signals from the Arduino. * Add an option to deactivate an account. * Updated Change Password method * Add Parser method, that parses the building plan and adds and creates rooms. * Connect buzzer and button works when I press to buzz. * Add consistent backgrounds in the app and consistent app bar names |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 8 | * Added a Bluetooth file written in Arduino to connect to the application. * The ip address now shows up on the application i.e. they are talking. * Needed to download nRF Connect on the phone as it gives a debugging tool on the Bluetooth signals from the Arduino, so I knew what was going on when I failed to connect. * Added an option to deactivate an account. * Updated Change Password method to keep the email of signed in user, instead of typing it out again * Added Parser method, that parses the building plan and adds and creates rooms. * Connected buzzer and button works when I press to buzz. * Added consistent backgrounds in the app and consistent app bar names | Y | * Dijkstra’s algorithm to obtain a correct graph to display and look at possibly older versions i.e. legacy items to display the thing I would like to display. * Create a poster * Update buttons for a better user experience |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 9 | * Coded Dijkstra’s algorithm gets a correct graph to display and look at possibly older versions i.e. legacy items to display the thing I would like to display. * Created a poster – draft model * Update buttons for a better user experience | Y | * Trying to figure out escape route still, the graph works but only if I specify the nodes statically and calculate the route myself. * Finish the poster * Start the report write up * Test the application |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 10 | * Finish the poster * Start the report write up * Test the application | Y | * Add a better UI * Allow users to save the escape route diagram onto the phone * Report * Video * Print Poster |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 11 | * Printed Poster * Added a better UI with diagrams * Added Save button for users to save the diagram * Report Started | Y | * Report * Further Application Improvements * Video |

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| --- | --- | --- | --- |
| Meeting | Work Completed | Y/N | Work to Do |
| Week 12 | * Tested the application * Report Started * Video Started | Y | * Report * Further Application Improvements * Video End |