CS171 | BM1

## Assignment 3

## **Full Code**

```
from random import random
from statistics import median, variance
from skimage import measure, io, img as ubyte
from matplotlib import pyplot as plt
from skimage.color import label2rgb, rgb2gray
import numpy as np
import cv2
import pandas as pd
# The input image
image = cv2.imread("images/image01/image01.jpg", 0)
# plt.imsave("images/image01/image01_gray.jpg", image, cmap = 'gray')
scale = 0.6 # microns/pixel
# display image measurements as histogram
# plt.hist(image.flat, bins=100, range=(0,255)) #.flat returns the flattened
numpy arra (1D)
from skimage.filters import threshold otsu # binarization of image
threshold = threshold_otsu(image)
# Generate thresholded image
thresholded img = image < threshold
plt.imshow(thresholded_img, cmap = 'gray')
# Command to save thresholded image
plt.imsave("images/image01/thresholded_gray_image01.jpg", thresholded_img, cmap =
'gray') # cmap = 'gray' may or may not be added
plt.imsave("images/image01/thresholded image01.jpg", thresholded img)
from skimage.segmentation import clear border
# Remove edge touching regions
edge_touching_removed = clear_border(thresholded_img)
plt.imshow(edge_touching_removed, cmap = 'gray')
# Command to save removed border image
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```
plt.imsave("images/image01/edge touching removed gray image01.jpg",
edge touching removed, cmap = 'gray') # cmap = 'gray' may or may not be added
plt.imsave("images/image01/edge_touching_removed_image01.jpg",
edge touching removed)
# Label connected regions of an integer array using measure.label
# Labels each connected entity as one object
# Connectivity = Maximum number of orthogonal hops to consider a pixel/voxel as a
neighbor.
# If none, a full connectivity of input.ndim is used, number of dimension of the
image
# For 2D image it would be 2
label image = measure.label(edge touching removed, connectivity=image.ndim)
plt.imshow(label image)
plt.imsave("images/image01/labeled image01 without rgb.jpg", label image, cmap =
plt.imsave("images/image01/labeled image01 with rgb.jpg", label image)
# Return an RGB image where color-coded labels are painted over the image.
# Using label2rgb
image_label_overlay = label2rgb(label_image, image=image)
plt.imshow(image label overlay)
# Commands to save the labeled image
plt.imsave("images/image01/labeled_image01.jpg", image_label_overlay)
# Compute image properties and return them as a pandas-compatible table.
# Available regionprops: area, bbox, centroid, convex_area, coords, eccentricity,
# equivalent diamater, euler number, label, intensity image, major axis length,
# max intensity, mean intensity, moments, orientation, perimeter, solidity, and
many more.
props = measure.regionprops_table(label_image, image,
                      properties=['label',
                                   'area', 'equivalent diameter',
                                   'mean_intensity', 'solidity'] )
# .DataFrame() converts image properties above to a .csv file
df = pd.DataFrame(props)
print(df.head())
df.to csv("images/image01/image properties.csv")
# To delete small regions
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\#df2 = df[df['area'] > 20] \# 20 pixels
#print(df2.head())
#df2.to_csv("deleted_small_regions.csv")
# Convert to micron scale
df['area_sq_microns'] = df['area'] * (scale**2)
df['equivalent diameter microns'] = df['equivalent diameter'] * (scale)
print(df.head())
# Blob Detector for segmentation based on feature properties
# Set up the SimpleBlobDetector with default parameters
params = cv2.SimpleBlobDetector_Params()
# Define thresholds
params.minThreshold = 0
params.maxThreshold = 255
# Filter by area
params.filterByArea = True
params.minArea = 20
params.maxArea = 1000
# Filter by color (black = 0)
params.filterByColor = True #set True for image01.jpg as we'll be detecting black
regions
params.blobColor = 0
# Filter by Circularity
# params.filterbyCircularity = True
# params.minCircularity = 0.5
# params.maxCircularity = 1
# Filter by Convexity
params.filterByConvexity = True
params.minConvexity = 0.5
params.maxConvexity = 1
# Filter by InertiaRatio
# params.filterByInertia = True
# params.minIntertiaRatio = 0
# params.maxIntertiaRatio = 1
# Distance Between Blobs
params.minDistBetweenBlobs = 0
```

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# Setup the detector with parameters
detector = cv2.SimpleBlobDetector create(params)
# Detect blobs
keypoints = detector.detect(image)
print("Number of blobs detected are : ", len(keypoints))
# Draw blobs
img_with_blobs = cv2.drawKeypoints(image, keypoints, np.array([]), (0,0,255),
cv2.DRAW MATCHES_FLAGS_DRAW_RICH_KEYPOINTS)
plt.imshow(img_with_blobs)
cv2.imshow("Keypoints", img with blobs)
cv2.waitKey(0)
cv2.destroyAllWindows()
# Save result
cv2.imwrite("images/image01/image01 blobs.jpg", img with blobs)
# Extracting features using Gabor filters
image1 = cv2.imread("for-instance-segmentation/Gabor95 rawprediction.ome.tiff")
image1 = cv2.cvtColor(image1, cv2.COLOR BGR2GRAY) # to convert image to grayscale
# Save original image pixels into a data frame. This is Feature #1.
image2 = image1.reshape(-1)
df3 = pd.DataFrame()
df3['Original Image'] = image2
# Generate Gabor features
num = 1 #To count numbers up to give Gabor features a label in the data frame
kernels = [] # Create empty list to hold all kernels that we will generate in a
loop
for theta in range(4): # Define number of thetas. Here only 2 theta values 0 and
1/4 . pi
    theta = theta / 4. * np.pi
   for sigma in (1, 3, 5): # Sigma with values of 1 and 3
        for lamda in np.arange(0, np.pi, np.pi / 4): # range of wavelengths
            for gamma in (0.05, 0.5): # Gamma values of 0.05 and 0.5
                gabor_label = 'Gabor' + str(num) # label Gabor columns as Gabor1,
Gabor2, etc.
                print(gabor_label)
                ksize = 9 # Try 15 for hidden image (or 9 for others)
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phi = 0 # 0.8 for hidden image, otherwise leave it at 0
                kernel = cv2.getGaborKernel((ksize, ksize), sigma, theta, lamda,
gamma, phi, ktype = cv2.CV_32F)
                kernels.append(kernel)
                # Now filter the image and add values to a new column
                fimg = cv2.filter2D(image1, cv2.CV 8UC3, kernel) # originally
image2 but was checked
                filtered img = fimg.reshape(-1)
cv2.imwrite("images/image01/gabor filtered image01/"+gabor label+".jpg",
filtered_img.reshape(image1.shape))
                df3[gabor_label] = filtered_img # labels columns as Gabor1,
Gabor2, etc.
                print(gabor_label, ': theta=', theta, ': sigma=', sigma, ':
lamda=', lamda, ': gamma=', gamma)
                num += 1 # to increment Gabor column label
#print(df3.head())
#df3.to csv("images/image01/Gabor3.csv")
######
# Generate other features and add them to the data frame
# CANNY EDGE
edges = cv2.Canny(image1, 100,200) # image, min. and max values
edges1 = edges.reshape(-1)
df3['Canny Edge'] = edges1 # add column to original dataframe
from skimage.filters import roberts, sobel, scharr, prewitt
# ROBERTS EDGE
edge_roberts = roberts(image1)
edge_roberts1 = edge_roberts.reshape(-1)
df3['Roberts'] = edge_roberts1
# SOBEL
edge sobel = sobel(image1)
edge_sobel1 = edge_sobel.reshape(-1)
df3['Sobel'] = edge_sobel1
```

```
# SCHARR
edge_scharr = scharr(image1)
edge scharr1 = edge scharr.reshape(-1)
df3['Scharr'] = edge_scharr1
# PREWITT
edge_prewitt = prewitt(image1)
edge prewitt1 = edge prewitt.reshape(-1)
df3['Prewitt'] = edge_prewitt1
# GAUSSIAN with sigma3
from scipy import ndimage as nd
gaussian img = nd.gaussian filter(image1, sigma=3)
gaussian_img1 = gaussian_img.reshape(-1)
df3['Gaussian s3'] = gaussian_img1
# GAUSSIAN with sigma7
gaussian img2 = nd.gaussian filter(image1, sigma=7)
gaussian_img3 = gaussian_img2.reshape(-1)
df3['Gaussian s7'] = gaussian_img3
# MEDIAN with size = 3
median img = nd.median filter(image1, size=3)
median_img1 = median_img.reshape(-1)
df3['Median s3'] = median img1
# VARIANCE with size=3
#variance img = nd.generic filter(image1, np.var, size=3)
#variance_img1 = variance_img.reshape(-1)
#df3['Variance s3'] = variance_img1 # Add comlumn to original datafram
# Now, add a column in the data frame for the labels
# For this, we need to import the labeled image (mask)
labeled_img = cv2.imread('for-instance-segmentation/Gabor95_binarymask.tiff')
# Remember that you can load an image with partial labels
# But, drop the rows with unlabeled data
labeled img = cv2.cvtColor(labeled img, cv2.COLOR BGR2GRAY)
labeled img1 = labeled img.reshape(-1)
df3['Labels'] = labeled_img1 # originally labeled_img1
print(df3.head())
```

```
original img data = df3.drop(labels = ["Labels"], axis=1) # Use for prediction
#df3.to_csv("Gabor_image01.csv")
df3 = df3[df3.Labels != 0]
# Define the dependent variable that needs to be predicted (labels)
Y = df3["Labels"].values
# Encode Y values to 0, 1, 2, 3... (Not necessary but makes it easy to use other
tools..)
# from sklearn.preprocessing import LabelEncoder # import necessary library first
# Y = LabelEncoder().fit transform(Y)
# Define the independent variables
X = df3.drop(labels = ["Labels"], axis = 1)
# Split data into train and test to verify accuracy after fitting the model.
from sklearn.model_selection import train_test_split
X_train, X_test, y_train, y_test = train_test_split(X, Y, test_size = 0.2,
random_state = 20)
# Import the model we are using
# RandomForestRegressor is for regression type of problem.
# For classification we use RandomForestClassifier.
# Both yield similar results except for regressor the result is float
# and for classifier it is an integer.
from sklearn.ensemble import RandomForestClassifier
# Instantiate model with n number of decision trees
model = RandomForestClassifier(n_estimators = 20, random_state = 42)
# Train the model on training data
model.fit(X_train, y_train)
# Get numerical featuyre importances
# importances = list(model.feature_importances_)
# let us print them into a nice format.
feature list = list(X.columns)
feature_imp = pd.Series(model.feature_importances_,
index=feature_list).sort_values(ascending = False)
print(feature imp)
```

```
# MAKE PREDICTION
# You can store the model for future use. In fact, this is how you do machine
learning.
# Train on training images, validate on test images and deploy the model on
unknown images
import pickle
# Save the trained model as pickle string to disk for future use
filename = "animals_model"
pickle.dump(model, open(filename, 'wb'))
# To test the model on future datasets
loaded model = pickle.load(open(filename, 'rb'))
result = loaded_model.predict(original_img_data)
segmented = result.reshape((image1.shape))
plt.imshow(segmented, cmap='jet')
plt.imsave('images/image01/image01_feature_extraction4.jpg', segmented,
cmap='jet')
           ######## INSTANCE SEGMENTATION USING BBOXES ##########
import pixellib
from pixellib.instance import instance_segmentation
segment image = instance segmentation()
segment_image.load_model("mask_rcnn_coco.h5")
segment_image.segmentImage("images/image05.jpg", show_bboxes = True,
output_image_name = "images/image05_bbox.jpg")
```

## Outputs









































