

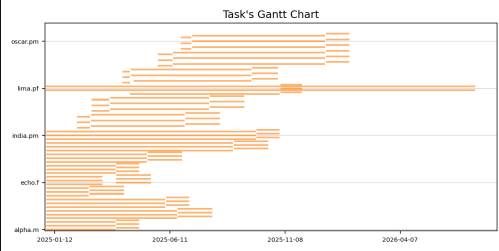
Yumbo. Scheduling, Planning and Resource Allocation

Zbigniew Romanowski, Paweł Koczyk

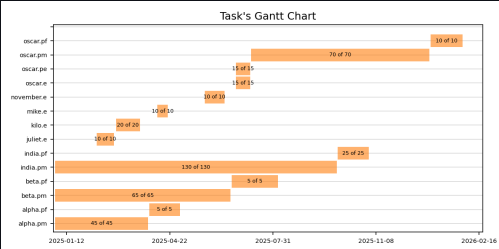
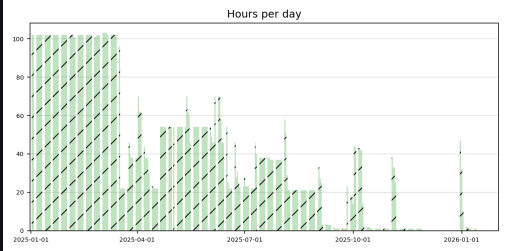
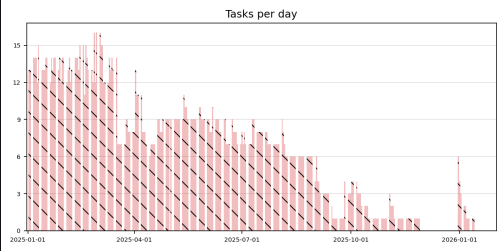
Source code, documentation and sample data report files are on [GitHub](#), [Gitea](#) or [public repository](#)

16 January 2025, 08:52:24 AM

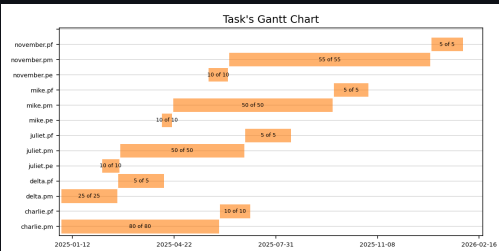
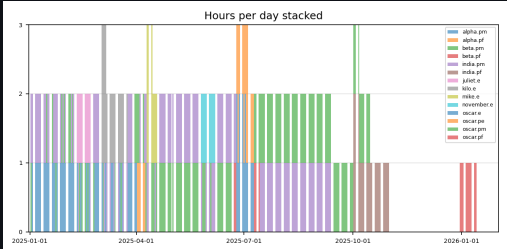
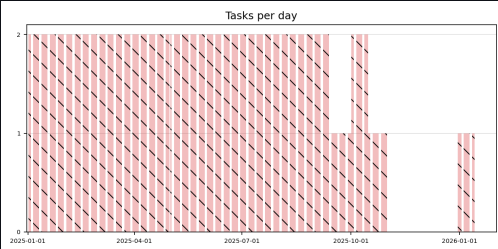
Experts overview



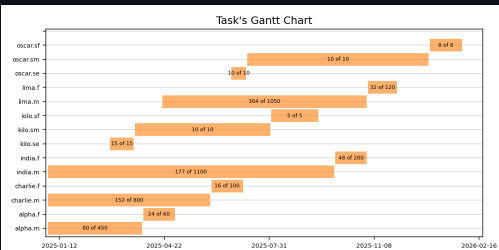
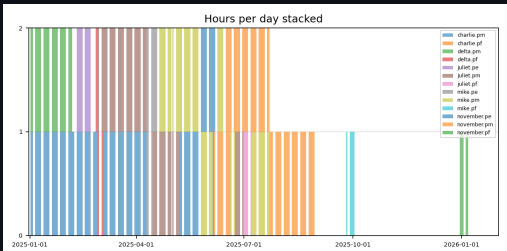
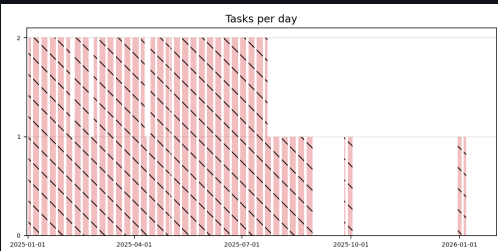
PM, Daniel the 1st unit



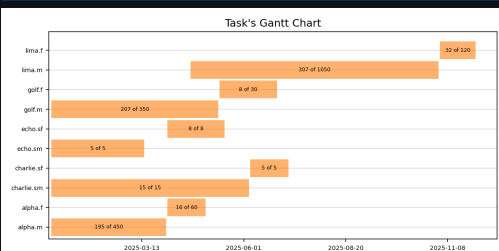
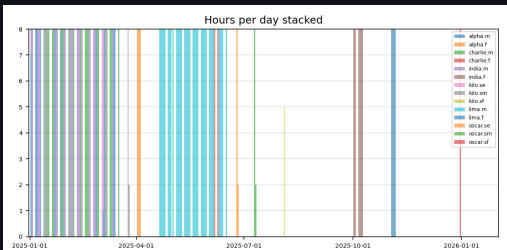
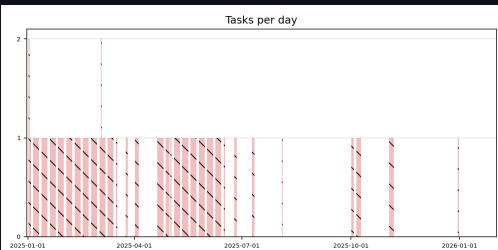
PM, Angel the 1st unit



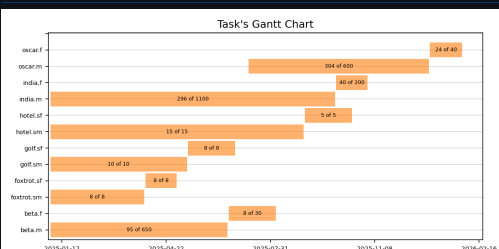
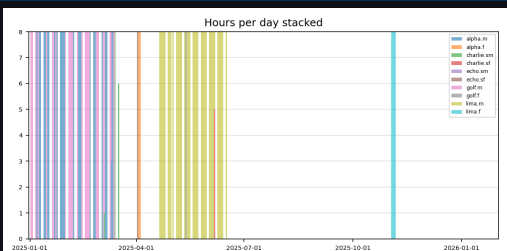
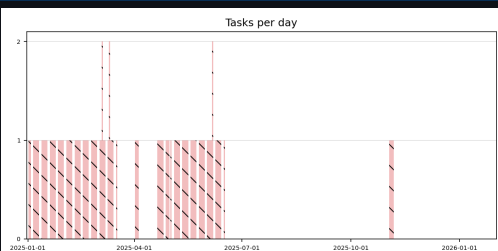
DEV, Paul the 1st unit



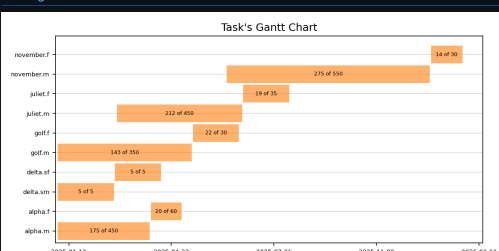
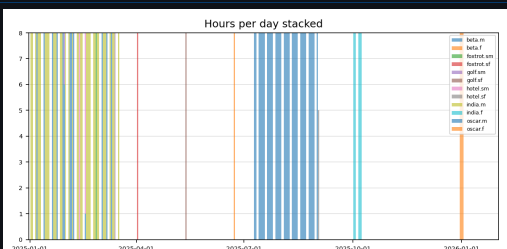
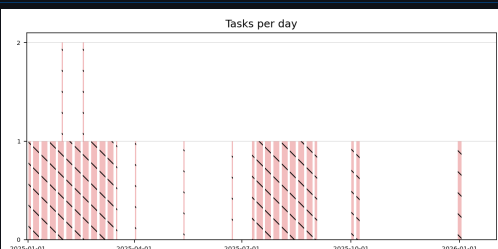
SA, Adrian the 1st unit



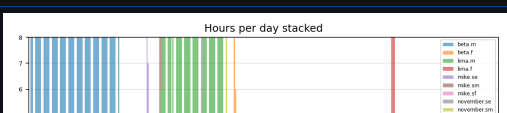
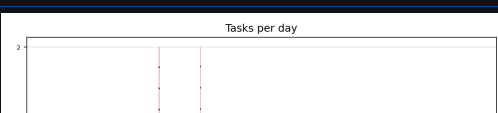
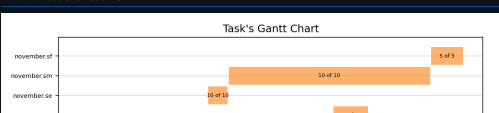
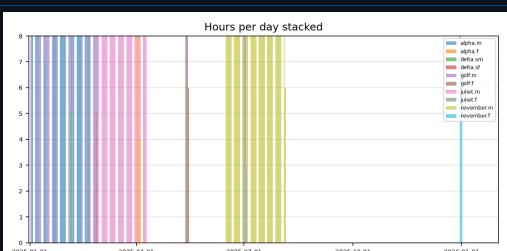
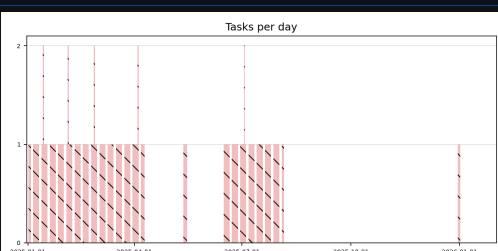
SA, Robert the 1st unit

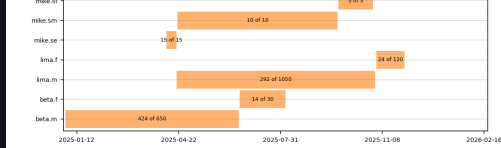


DEV, Hugo the 1st unit

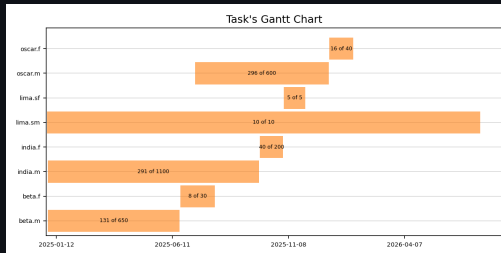


DEV, Frances the 1st unit

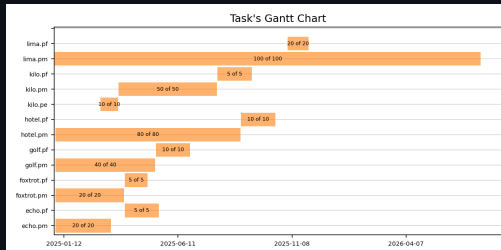




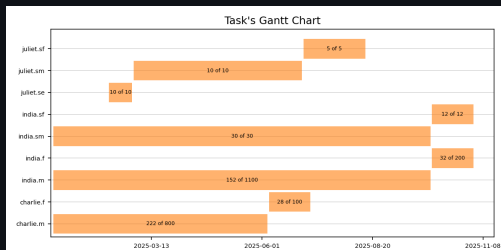
DEV:Tom the 1st unit



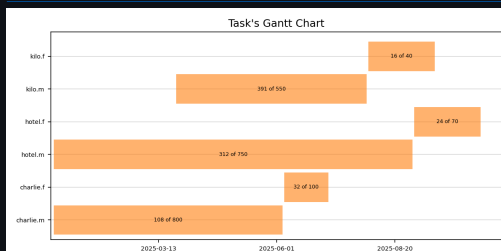
PM:Lisa the 1st unit



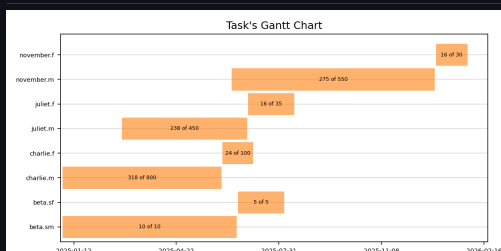
DEV:Charles the 1st unit



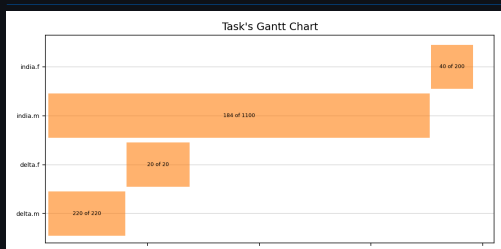
DEV:Francis the 1st unit



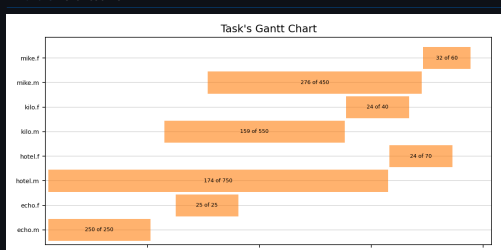
DEV:Carl the 1st unit



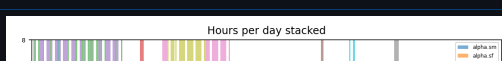
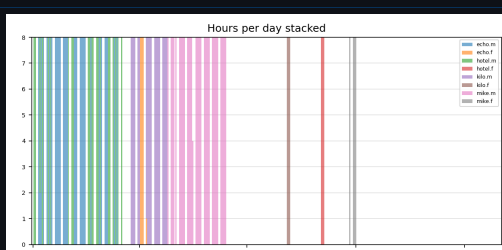
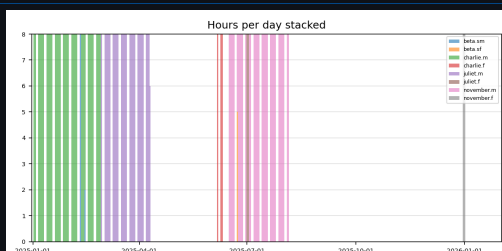
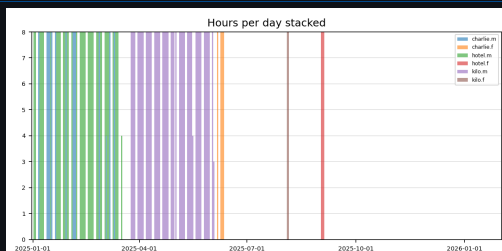
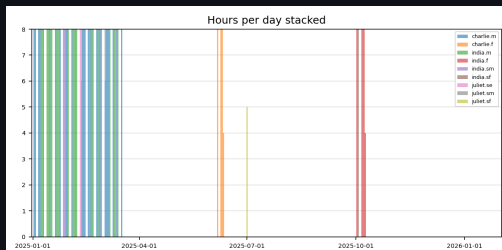
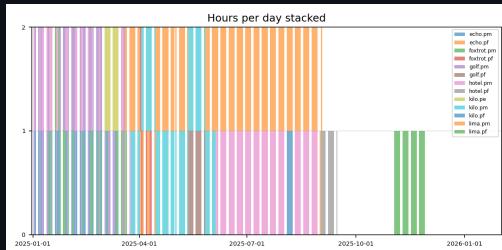
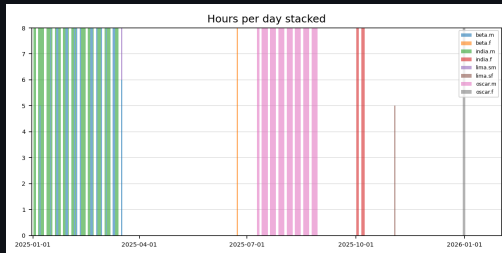
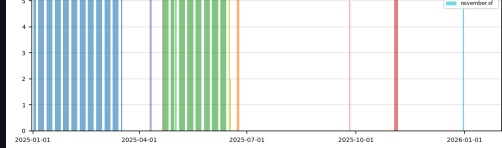
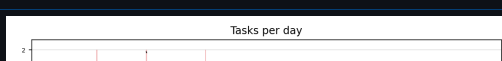
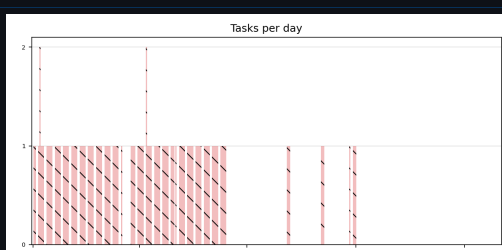
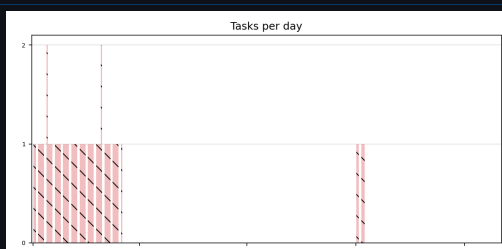
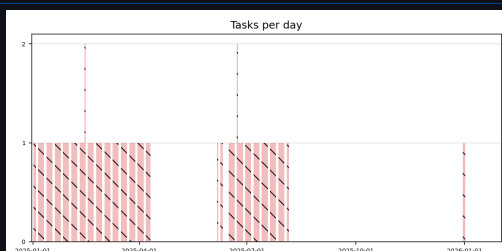
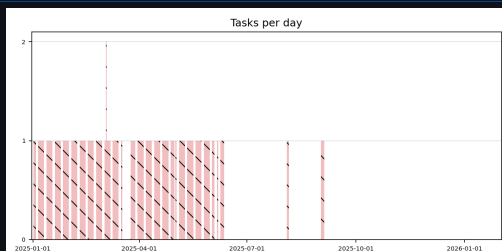
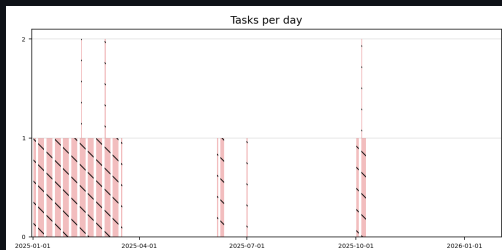
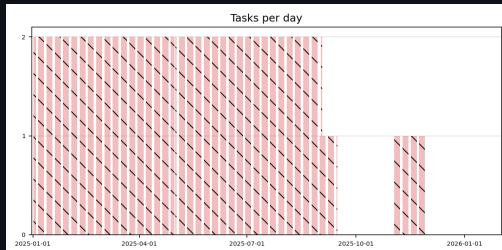
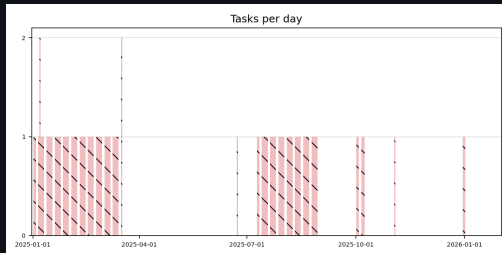
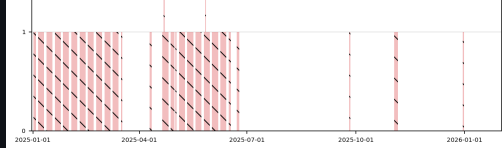
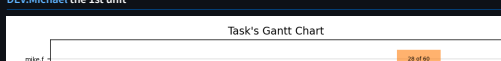
DEV:Lars the 1st unit

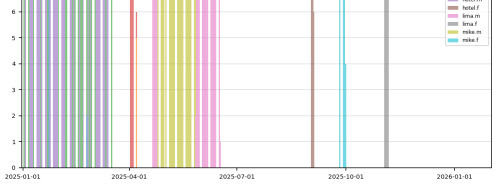
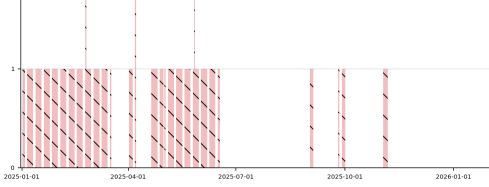
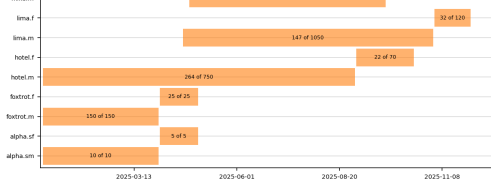


DEV:Martin the 1st unit



DEV:Michael the 1st unit





Solver output at 06 January 2025, 08:49:39 AM

```
HIGGS 1.7.1: tech-outlet - 1
Running HIGGS 1.7.1 (git hash: dcf8111): Copyright (c) 2024 HIGGS under MIT Licence terms
Coefficient ranges:
  Matrix [[a(0), b(0)]
  Cost    [[a(0), b(0)]
  Bound   [[a(0), b(0)]
  RHS     [[a(0), b(0)]
Practicing model
10420 rows, 11112 cols, 40140 nonzeros, 0s
10120 rows, 10120 cols, 40120 nonzeros, 0s
10097 rows, 17347 cols, 15504 nonzeros, 0s
10090 rows, 17347 cols, 15504 nonzeros, 0s
Solving MIP model with:
  10420 rows
  17347 cols (17347 binary, 7027 integer, 0 implied int., 0 continuous)
  15504 nonzeros
Nodes | BSB Tree | Objective Bounds | Gap | Dynamic Constraints | Work |
Proc. | Columns | Nodes | Expl. | BestBound | BestSol. | Cuts | Step Conf. | Leftovers | Time
0 | 0 | 0 | 0 | 0.00% | 102.2208027 | Inf | 0 | 0 | 0 | 0 | 0.7s
0 | 0 | 0 | 0 | 0.00% | 102.2610285 | 102.2610285 | 0.00% | 0 | 0 | 0 | 107s | 0.9s
Solving report
Status: Optimal
Primal bound: 102.2610285
Dual bound: 102.2610285
Gap: 0% (tolerance: 0.00%)
Feasible: 102.2610285 (objective)
0 (bound viol.)
0 (int. viol.)
0 (row viol.)
0.00 (total)
0.7s (prelude)
0.9s (postlude)
Nodes: 1
LP iterations: 1000 (total)
0 (strong br.)
0 (heuristic)
0 (reparation)
HIGGS 1.7.1: optimal solution: objective 102.2610285
102.2610285 iterations
1 branching nodes
"Optim. obj. bound(s) 1.004277026810285e-01"
or "Optim. obj. bound(s) 1.004277026810285e-01"
will change deduced dual values.
```