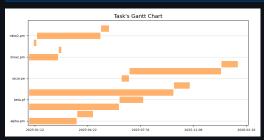
Yumbo. Scheduling, Planning and Resource Allocation

Zbigniew Romanowski, Paweł Koczyk

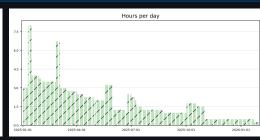
Source code, documentation and sample Excel input files can be found on Yumbo's GitHub repository

23 January 2025, 18:17:51 PM

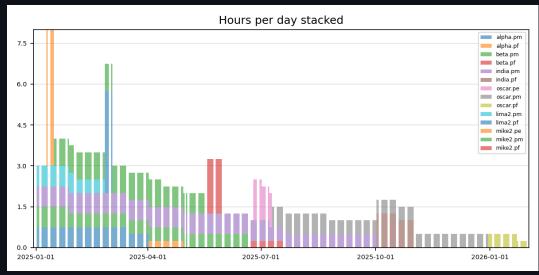
Experts overview

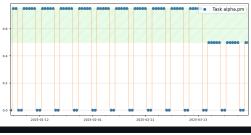




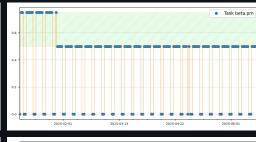


PM.Daniel the 1st unit

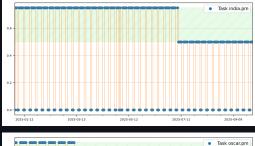


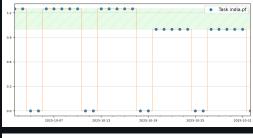


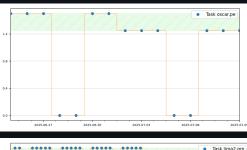


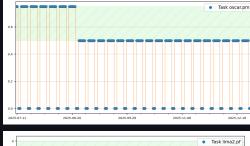


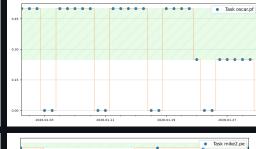


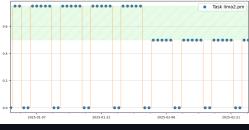


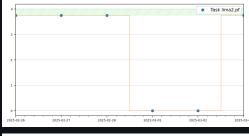


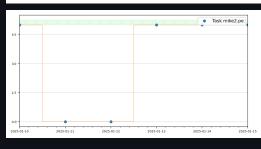


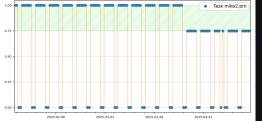


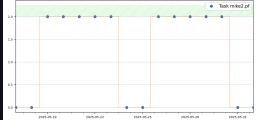












Solver output at 23 January 2025, 18:16:07 PM

```
\label{eq:highs}  \mbox{HiGHS 1.8.1:} \quad \mbox{tech:outlev = 1} \\ \mbox{Running HiGHS 1.8.1 (git hash: 4a7f24a): Copyright (c) 2024 HiGHS under MIT licence terms}
Coefficient ranges:
   Cost [1e+00, 1e+00]
Bound [1e+00, 2e+02]
Presolving model
11 rows 738 cols (54 binary, 684 integer, 0 implied int., 0 continuous)
      738 nonzeros
=Timing: 0.0054 - starting analytic centre calculation
MIP-Timing:
Src: B \Rightarrow Branching; C \Rightarrow Central rounding; F \Rightarrow Feasibility pump; H \Rightarrow Heuristic; L \Rightarrow Sub-MIP; P \Rightarrow Empty MIP; R \Rightarrow Randomized rounding; S \Rightarrow Solve LP; T \Rightarrow Evaluate node; U \Rightarrow Unbounded; z \Rightarrow Trivial zero; L \Rightarrow Trivial lower; u \Rightarrow Trivial upper; p \Rightarrow Trivial point
                                     B&B Tree
                                                                               Objective Bounds
                                                                                                                                 | Dynamic Constraints |
            Nodes
                                                                                                                                                                                 Work
                                                                                                                                                                                           0.0s
0.0s
  Status
Primal bound
                                Optimal
   Gap
P-D integral
                                0% (tolerance: 0.01%)
                               0 (int. viol.)
0 (row viol.)
                               0.00 (presolve)
0.00 (solve)
   Max sub-MIP depth 0
Nodes 1
                             0 (0 feasible; 0 iterations)
11 (total)
   LP iterations
                                0 (strong br.)
                                0 (heuristics)
1 branching nodes
```

Elapsed time for chart creation

Hours per day stacked	simg		7.039
Plot task with its constrains	bimg	14	2.682
Task's Gantt Chart	gimg		0.000
Hours per day	himg		0.000
Tasks per day	timg		0.000
Invoicing Periods Workload	wimg		0.000