

DFS:**Code:**

```
import java.io.*;
import java.util.*;

class Graph {
    private int V;
    private LinkedList<Integer> adj[];
    @SuppressWarnings("unchecked") Graph(int v)
    {
        V = v;
        adj = new LinkedList[V];
        for (int i = 0; i < v; ++i)
            adj[i] = new LinkedList();
    }
    void addEdge(int v, int w)
    {
        adj[v].add(w); // Add w to v's list.
    }
    void DFSUtil(int v, boolean visited[])
    {
        visited[v] = true;
        System.out.print(v + " ");
        Iterator<Integer> i = adj[v].listIterator();
        while (i.hasNext()) {
            int n = i.next();
            if (!visited[n])
                DFSUtil(n, visited);
        }
    }

    void DFS(int v)
    {
        boolean visited[] = new boolean[V];

        DFSUtil(v, visited);
    }
    public static void main(String args[])
    {
        Graph g = new Graph(4);

        g.addEdge(0, 1);
        g.addEdge(0, 2);
```

```

        g.addEdge(1, 2);
        g.addEdge(2, 0);
        g.addEdge(2, 3);
        g.addEdge(3, 3);

        System.out.println(
            "Following is Depth First Traversal "
            + "(starting from vertex 2)");
        g.DFS(2);
    }
}

```

Output:

Depth First Traversal

2 0 1 3

BFS:

Code:

```

import java.io.*;
import java.util.*;
class Graph {
    private int V; // No. of vertices
    private LinkedList<Integer> adj[]; // Adjacency Lists
    Graph(int v)
    {
        V = v;
        adj = new LinkedList[V];
        for (int i = 0; i < v; ++i)
            adj[i] = new LinkedList();
    }
    void addEdge(int v, int w) { adj[v].add(w); }
    void BFS(int s)
    {

        boolean visited[] = new boolean[V];
        LinkedList<Integer> queue
            = new LinkedList<Integer>();
        visited[s] = true;
        queue.add(s);

        while (queue.size() != 0) {

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        s = queue.poll();
        System.out.print(s + " ");
        Iterator<Integer> i = adj[s].listIterator();
        while (i.hasNext()) {
            int n = i.next();
            if (!visited[n]) {
                visited[n] = true;
                queue.add(n);
            }
        }
    }
}

public static void main(String args[])
{
    Graph g = new Graph(4);

    g.addEdge(0, 1);
    g.addEdge(0, 2);
    g.addEdge(1, 2);
    g.addEdge(2, 0);
    g.addEdge(2, 3);
    g.addEdge(3, 3);

    System.out.println(
        "Following is Breadth First Traversal "
        + "(starting from vertex 2)");

    g.BFS(2);
}
}

```

Output:

Breadth First Traversal
2 0 3 1

A*

Code:

```

class Node():
    """A node class for A* Pathfinding"""

    def __init__(self, parent=None, position=None):
        self.parent = parent

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self.position = position

self.g = 0
self.h = 0
self.f = 0

def __eq__(self, other):
    return self.position == other.position

```

```

def astar(maze, start, end):
    """Returns a list of tuples as a path from the given start to the given end in the given maze"""
    start_node = Node(None, start)
    start_node.g = start_node.h = start_node.f = 0
    end_node = Node(None, end)
    end_node.g = end_node.h = end_node.f = 0

    open_list = []
    closed_list = []
    open_list.append(start_node)
    while len(open_list) > 0:
        current_node = open_list[0]
        current_index = 0
        for index, item in enumerate(open_list):
            if item.f < current_node.f:
                current_node = item
                current_index = index
        closed_list.append(current_node)
        if current_node == end_node:
            path = []
            current = current_node
            while current is not None:
                path.append(current.position)
                current = current.parent
            return path[::-1] # Return reversed path
        children = []
        for new_position in [(0, -1), (0, 1), (-1, 0), (1, 0), (-1, -1), (-1, 1), (1, -1), (1, 1)]: # Adjacent
            squares

            node_position = (current_node.position[0] + new_position[0], current_node.position[1] +
new_position[1])

            if node_position[0] > (len(maze) - 1) or node_position[0] < 0 or node_position[1] >
(len(maze[len(maze)-1]) - 1) or node_position[1] < 0:

```

```

        continue

    if maze[node_position[0]][node_position[1]] != 0:
        continue

    new_node = Node(current_node, node_position)

    children.append(new_node)

    for child in children:

        for closed_child in closed_list:
            if child == closed_child:
                continue

        # Create the f, g, and h values
        child.g = current_node.g + 1
        child.h = ((child.position[0] - end_node.position[0]) ** 2) + ((child.position[1] -
end_node.position[1]) ** 2)
        child.f = child.g + child.h

        for open_node in open_list:
            if child == open_node and child.g > open_node.g:
                continue

        open_list.append(child)

def main():

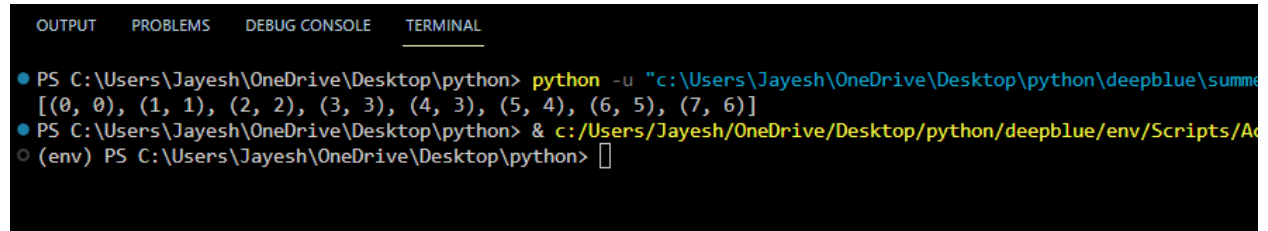
    maze = [[0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 0, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 0, 0, 0, 0, 0, 0]]

    start = (0, 0)
    end = (7, 6)

```

```
        path = astar(maze, start, end)
        print(path)
if __name__ == '__main__':
    main()
```

Output:



```
OUTPUT  PROBLEMS  DEBUG CONSOLE  TERMINAL
● PS C:\Users\Jayesh\OneDrive\Desktop\python> python -u "c:\Users\Jayesh\OneDrive\Desktop\python\deepblue\summe
[(0, 0), (1, 1), (2, 2), (3, 3), (4, 3), (5, 4), (6, 5), (7, 6)]
● PS C:\Users\Jayesh\OneDrive\Desktop\python> & c:/Users/Jayesh/OneDrive/Desktop/python/deepblue/env/Scripts/Activate.ps1
○ (env) PS C:\Users\Jayesh\OneDrive\Desktop\python> █
```