

**# python implementation of particle swarm optimization (PSO)
minimizing rastrigin and sphere function**

**import random
import math # cos() for Rastrigin
import copy # array-copying convenience
import sys # max float**

#-----fitness functions-----

**# rastrigin function
def fitness_rastrigin(position):
 fitnessVal = 0.0
 for i in range(len(position)):
 xi = position[i]
 fitnessVal += (xi * xi) - (10 * math.cos(2 * math.pi * xi)) + 10
 return fitnessVal**

**#sphere function
def fitness_sphere(position):
 fitnessVal = 0.0
 for i in range(len(position)):
 xi = position[i]
 fitnessVal += (xi*xi);
 return fitnessVal;**

#-----

**#particle class
class Particle:
 def __init__(self, fitness, dim, minx, maxx, seed):
 self.rnd = random.Random(seed)

 # initialize position of the particle with 0.0 value
 self.position = [0.0 for i in range(dim)]

 # initialize velocity of the particle with 0.0 value
 self.velocity = [0.0 for i in range(dim)]

 # initialize best particle position of the particle with 0.0 value
 self.best_part_pos = [0.0 for i in range(dim)]

 # loop dim times to calculate random position and velocity
 # range of position and velocity is [minx, maxx]
 for i in range(dim):
 self.position[i] = ((maxx - minx) *
 self.rnd.random() + minx)
 self.velocity[i] = ((maxx - minx) *
 self.rnd.random() + minx)

 # compute fitness of particle
 self.fitness = fitness(self.position) # curr fitness

 # initialize best position and fitness of this particle
 self.best_part_pos = copy.copy(self.position)**

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self.best_part_fitnessVal = self.fitness # best fitness

# particle swarm optimization function
def pso(fitness, max_iter, n, dim, minx, maxx):
    # hyper parameters
    w = 0.729 # inertia
    c1 = 1.49445 # cognitive (particle)
    c2 = 1.49445 # social (swarm)

    rnd = random.Random(0)

    # create n random particles
    swarm = [Particle(fitness, dim, minx, maxx, i) for i in range(n)]

    # compute the value of best_position and best_fitness in swarm
    best_swarm_pos = [0.0 for i in range(dim)]
    best_swarm_fitnessVal = sys.float_info.max # swarm best

    # computer best particle of swarm and it's fitness
    for i in range(n): # check each particle
        if swarm[i].fitness < best_swarm_fitnessVal:
            best_swarm_fitnessVal = swarm[i].fitness
            best_swarm_pos = copy.copy(swarm[i].position)

    # main loop of pso
    Iter = 0
    while Iter < max_iter:

        # after every 10 iterations
        # print iteration number and best fitness value so far
        if Iter % 10 == 0 and Iter > 1:
            print("Iter = " + str(Iter) + " best fitness = %.3f" % best_swarm_fitnessVal)

        for i in range(n): # process each particle

            # compute new velocity of curr particle
            for k in range(dim):
                r1 = rnd.random() # randomizations
                r2 = rnd.random()

                swarm[i].velocity[k] = (
                    (w * swarm[i].velocity[k]) +
                    (c1 * r1 * (swarm[i].best_part_pos[k] - swarm[i].position[k])) +
                    (c2 * r2 * (best_swarm_pos[k] - swarm[i].position[k]))
                )

            # if velocity[k] is not in [minx, maxx]
            # then clip it
            if swarm[i].velocity[k] < minx:
                swarm[i].velocity[k] = minx
            elif swarm[i].velocity[k] > maxx:
                swarm[i].velocity[k] = maxx

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# compute new position using new velocity
for k in range(dim):
    swarm[i].position[k] += swarm[i].velocity[k]

# compute fitness of new position
swarm[i].fitness = fitness(swarm[i].position)

# is new position a new best for the particle?
if swarm[i].fitness < swarm[i].best_part_fitnessVal:
    swarm[i].best_part_fitnessVal = swarm[i].fitness
    swarm[i].best_part_pos = copy.copy(swarm[i].position)

# is new position a new best overall?
if swarm[i].fitness < best_swarm_fitnessVal:
    best_swarm_fitnessVal = swarm[i].fitness
    best_swarm_pos = copy.copy(swarm[i].position)

# for-each particle
Iter += 1
#end_while
return best_swarm_pos
# end pso

#-----
# Driver code for rastrigin function

print("\nBegin particle swarm optimization on rastrigin function\n")
dim = 3
fitness = fitness_rastrigin

print("Goal is to minimize Rastrigin's function in " + str(dim) + " variables")
print("Function has known min = 0.0 at (", end="")
for i in range(dim-1):
    print("0, ", end="")
print("0")

num_particles = 50
max_iter = 100

print("Setting num_particles = " + str(num_particles))
print("Setting max_iter = " + str(max_iter))
print("\nStarting PSO algorithm\n")

best_position = pso(fitness, max_iter, num_particles, dim, -10.0, 10.0)

print("\nPSO completed\n")
print("\nBest solution found:")
print(["%.6f"%best_position[k] for k in range(dim)])
fitnessVal = fitness(best_position)
print("fitness of best solution = %.6f" % fitnessVal)

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```
print("\nEnd particle swarm for rastrigin function\n")
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```
print()  
print()
```

```
# Driver code for Sphere function
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```
print("\nBegin particle swarm optimization on sphere function\n")
```

```
dim = 3
```

```
fitness = fitness_sphere
```

```
print("Goal is to minimize sphere function in " + str(dim) + " variables")
```

```
print("Function has known min = 0.0 at (", end="")
```

```
for i in range(dim-1):
```

```
    print("0, ", end="")
```

```
print("0")
```

```
num_particles = 50
```

```
max_iter = 100
```

```
print("Setting num_particles = " + str(num_particles))
```

```
print("Setting max_iter  = " + str(max_iter))
```

```
print("\nStarting PSO algorithm\n")
```

```
best_position = pso(fitness, max_iter, num_particles, dim, -10.0, 10.0)
```

```
print("\nPSO completed\n")
```

```
print("\nBest solution found:")
```

```
print(["%.6f"%best_position[k] for k in range(dim)])
```

```
fitnessVal = fitness(best_position)
```

```
print("fitness of best solution = %.6f" % fitnessVal)
```

```
print("\nEnd particle swarm for sphere function\n")
```