

261102

Computer Programming

Lecture 18: Dynamic Memory Allocation

Types of Program Data

- Global variable

 • *Static Data*: Memory allocation exists throughout execution of program
- *Automatic Data*: Automatically created at function entry, resides in activation frame of the function, and is destroyed when returning from function
- *Dynamic Data*: Explicitly allocated and deallocated (จัดสรรและคืนค่า) during program execution (ซึ่งเกิดขึ้นระหว่างการรันโปรแกรม) by C++ instructions written by programmer

Allocation of Memory

`int x;
int *i;
int y[100];`

- **Static Allocation**: Allocation of memory space at **compile time**. *static php*
- **Dynamic Allocation**: Allocation of memory space at **run time**.

↳ static compile → memory allocation

static in exe. → memory allocation

Dynamic Memory Allocation

- Dynamic allocation is useful when
 - arrays need to be created whose extent is ^{unknown} not known until run time `int x [1000];` ^{1/200}
 - complex structures of unknown size and/or shape need to be constructed as the program runs
 - objects need to be created and the constructor arguments are not known until run time
_{class}

Dynamic Memory Allocation

คำชี้แจง

- **Pointers** need to be used for dynamic allocation of memory
- Use the operator **new** to dynamically allocate space
- Use the operator **delete** to later free this space

จอง mem
↑

↑ คืน mem

The **new** operator

- If memory is available, the **new** operator allocates memory space for the requested object/array, and returns a pointer to (address of) the memory allocated.
- If sufficient memory is **NOT** available, the **new** operator returns **NULL**.
- The dynamically allocated object/array exists until the **delete** operator destroys it.

The **delete** operator

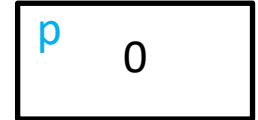
- The **delete** operator deallocates the object or array currently pointed to by the pointer which was previously allocated at run-time by the **new** operator.
- If the value of the pointer is **NULL** there is no effect.

Dynamic Memory Allocation

```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = NULL;
7      cout << "p = " << p << "\t\t&p = " << &p << "\n";
8
9      p = new int;
10     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
11
12     *p = 12;
13     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
14
15     delete p;
16     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
17
18     p = NULL;
19     cout << "p = " << p << "\t\t&p = " << &p ;
20
21     return 0;
22 }
```

&p fe38



how int @ ?

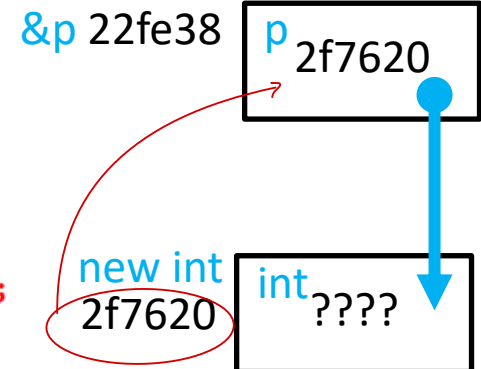
p = 0	&p = 0x22fe38	
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0x2f7620	&p = 0x22fe38	*p = 12
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0	&p = 0x22fe38	

Dynamic Memory Allocation

```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = NULL;
7      cout << "p = " << p << "\t\t&p = " << &p << "\n";
8
9      p = new int;
10     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
11
12     *p = 12;
13     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
14
15     delete p;
16     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
17
18     p = NULL;
19     cout << "p = " << p << "\t\t&p = " << &p ;
20
21     return 0;
22 }

```



p = 0	&p = 0x22fe38	
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0x2f7620	&p = 0x22fe38	*p = 12
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0	&p = 0x22fe38	

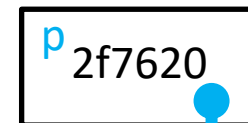
Dynamic Memory Allocation

```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = NULL;
7      cout << "p = " << p << "\t\t&p = " << &p << "\n";
8
9      p = new int;
10     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
11
12     *p = 12;
13     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
14
15     delete p;
16     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
17
18     p = NULL;
19     cout << "p = " << p << "\t\t&p = " << &p ;
20
21     return 0;
22 }

```

&p 22fe38



new int
2f7620



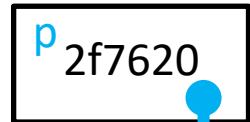
p = 0	&p = 0x22fe38	
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0x2f7620	&p = 0x22fe38	*p = 12
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0	&p = 0x22fe38	

Dynamic Memory Allocation

```

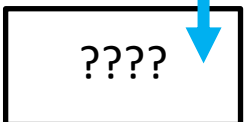
1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = NULL;
7      cout << "p = " << p << "\t\t&p = " << &p << "\n";
8
9      p = new int;
10     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
11
12     *p = 12;
13     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
14
15     delete p;
16     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
17
18     p = NULL;
19     cout << "p = " << p << "\t\t&p = " << &p ;
20
21     return 0;
22 }
```

&p 22fe38



Dangling
Pointer

2f7620



Free memory
space here

p = 0	&p = 0x22fe38	
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0x2f7620	&p = 0x22fe38	*p = 12
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0	&p = 0x22fe38	

Dynamic Memory Allocation

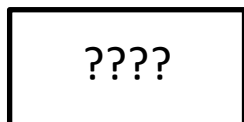
```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = NULL;
7      cout << "p = " << p << "\t\t&p = " << &p << "\n";
8
9      p = new int;
10     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
11
12     *p = 12;
13     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
14
15     delete p;
16     cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
17
18     p = NULL;
19     cout << "p = " << p << "\t\t&p = " << &p ;
20
21     return 0;
22 }
```

&p 22fe38



2f7620



p = 0	&p = 0x22fe38	
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0x2f7620	&p = 0x22fe38	*p = 12
p = 0x2f7620	&p = 0x22fe38	*p = 3111712
p = 0	&p = 0x22fe38	

Dynamic Memory Allocation

```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = new int;
7      *p = 12;
8      cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
9
10     int *q = new int;
11     *q = 25;
12     cout << "q = " << q << "\t&q = " << &q << "\t*q = " << *q << "\n";
13
14     delete p,q;
15
16     return 0;
17 }
```

← *ठीक, सही/सुचारु*
delete p;
delete q;

Output

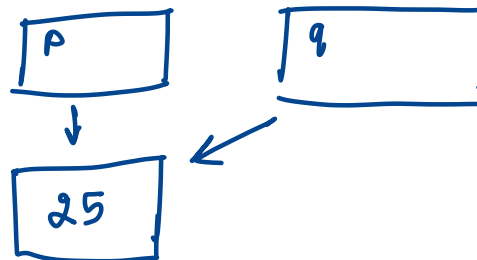
p = 0x577620	&p = 0x22fe38	*p = 12
q = 0x577640	&q = 0x22fe30	*q = 25

Dynamic Memory Allocation

```

1  #include<iostream>
2  using namespace std;
3
4  int main(){
5
6      int *p = new int;
7      *p = 12;
8      cout << "p = " << p << "\t&p = " << &p << "\t*p = " << *p << "\n";
9
10     delete p;
11
12     int *q = new int;
13     *q = 25;
14     cout << "q = " << q << "\t&q = " << &q << "\t*q = " << *q << "\n";
15     cout << "*p = " << *p << "\n";
16
17     delete q;
18
19     return 0;
20 }

```



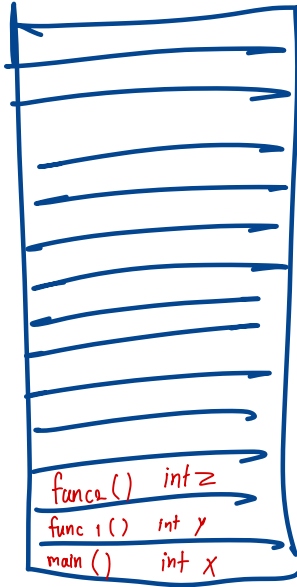
↳ ที่ชี้เหมือนกัน 25

Output

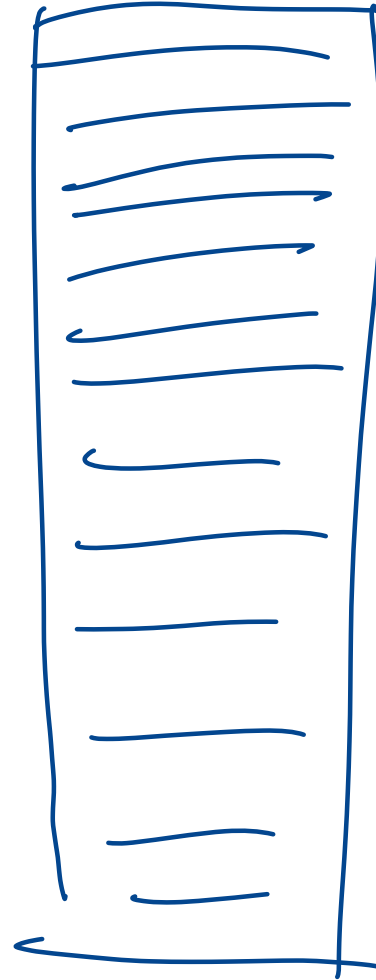
p = 0x2f7620	&p = 0x22fe38	*p = 12
q = 0x2f7620	&q = 0x22fe30	*q = 25
*p = 25		

RAM

stack . memory



heap memory



global



Dynamic allocation of Arrays

- Use the `[array_size]` on the `new` statement to create an `array of objects` instead of a single instance.
- On the `delete` statement use `[]` to indicate that an `array of objects` is to be deallocated.
- `std::vector` is the dynamic arrays in C++.

Array of Runtime Bound

```

1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N;
7      cout << "Input number of your data: ";
8      cin >> N;
9      float c[N]; Array of runtime bound
10     for(int i=0;i<N;i++){
11         cout << "Input your data [" << i+1 << "]: ";
12         cin >> c[i];
13     }
14
15     cout << "Your data = ";
16     for(int i=0;i<N;i++) cout << c[i] << " ";
17
18     return 0;
19 }
```

```

Input number of your data: 3
Input your data [1]: 1.2
Input your data [2]: 3.6
Input your data [3]: 6.9
Your data = 1.2 3.6 6.9

```

May be illegal in some compiler where array size must be specified with constant variable (**const**)

(automatic storage)

Arrays of Runtime Bound = Arrays of Variable Length

Dynamic allocation of Arrays

```

1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N;
7      cout << "Input number of your data: ";
8      cin >> N;
9      float *c = new float[N]; //float c[N];
10     for(int i=0;i<N;i++){
11         cout << "Input your data [" << i+1 << "]: ";
12         cin >> c[i];
13     }
14
15     cout << "Your data = ";
16     for(int i=0;i<N;i++) cout << c[i] << " ";
17
18     delete [] c; //Don't forget to free memory
19
20     return 0;
21 }

```

```

Input number of your data: 3
Input your data [1]: 1.2
Input your data [2]: 3.6
Input your data [3]: 6.9
Your data = 1.2 3.6 6.9

```

`float *c;`

`c = new float[10]`

Pointer name can used as array name

Dynamic allocation of 2D-Arrays

- A two dimensional array is really an array of arrays (rows).
- To dynamically declare a two dimensional array of `int` type, you need to declare **a pointer to a pointer** as:

```
int **matrix;
```

Dynamic allocation of 2D-Arrays

- To allocate space for the 2D array with **r** rows and **c** columns:
 - You first allocate the **array of pointers** which will point to the arrays (rows)

```
matrix = new int*[r];
```

- This creates space for **r** addresses; each being a **pointer to an int**.
- Then you need to allocate the space for the 1D arrays themselves, each with a size of **c**

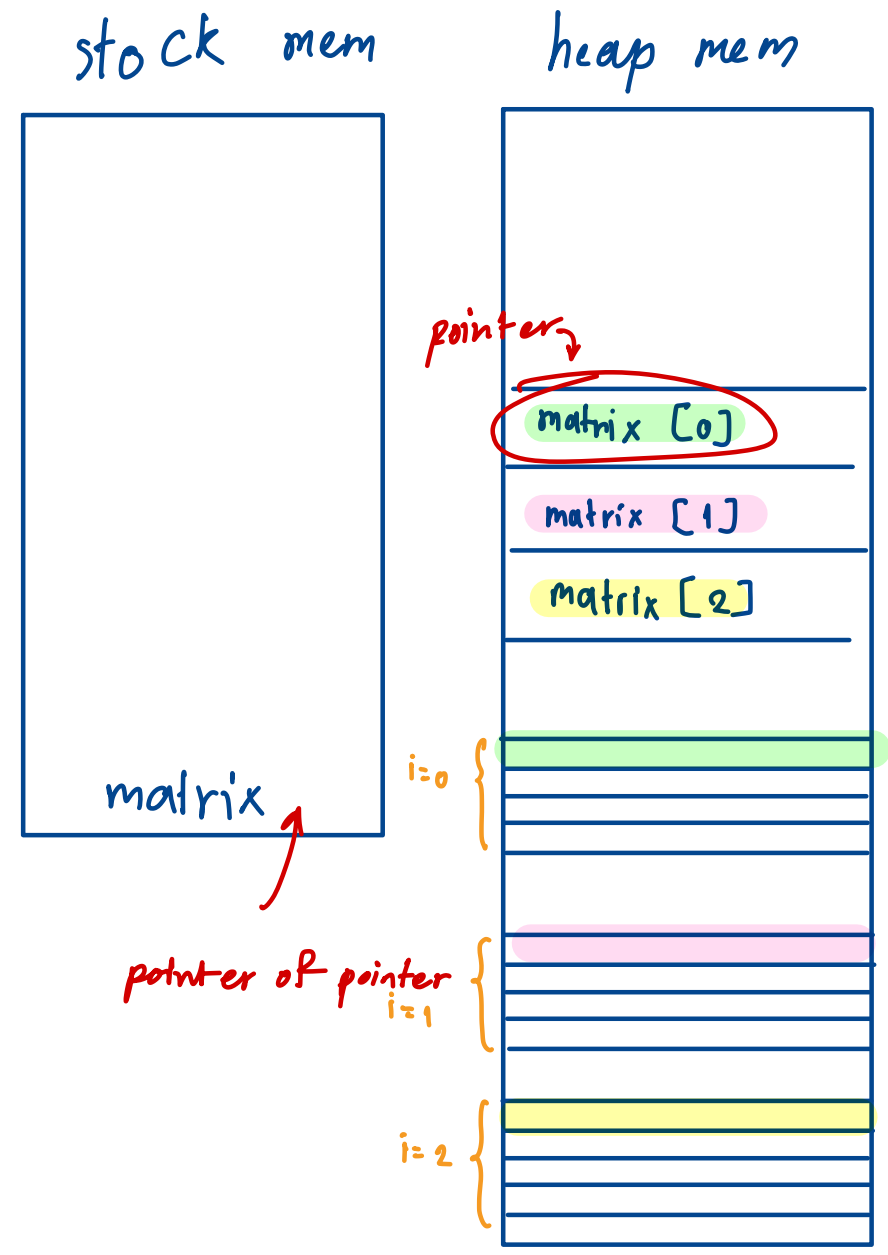
```
for(i=0; i<r; i++)  
    matrix[i] = new int[c];
```

assign ตำแหน่งใน RAM ไม่เสียอีก

```
int **matrix ;  
matrix = new int* [3]  
for (int i=0 ; i < 3 ; i++)  
    matrix[i] = new int [4]
```

matrix

แถวที่ 0
แถวที่ 1
แถวที่ 2



Dynamic allocation of 2D-Arrays

- The elements of the array `matrix` now can be accessed by the `matrix[i][j]` notation
- Keep in mind, the entire array is **not in contiguous space** (unlike a static 2D array) *row-major order*
- The elements of **each row are in contiguous space**, but the rows themselves are not.
 - `matrix[i][j+1]` is after `matrix[i][j]` in memory, but `matrix[i][0]` may be before or after `matrix[i+1][0]` in memory

Array of Runtime Bound

```
1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N,M;
7      cout << "Input size of your matrix: ";
8      cin >> N >> M;
9      float c[N][M];
10     for(int i=0;i<N;i++){
11         cout << "Input row [" << i+1 << "]: ";
12         for(int j=0;j<M;j++){
13             cin >> c[i][j];
14         }
15     }
16
17     return 0;
18 }
```

Array of arrays of runtime bound

May be illegal in some compiler where array size must be specified with constant variable (**const**)

```
Input size of your matrix: 2 4
Input row [1]: 1 2 5 8
Input row [2]: 4 9 9 8
```

Dynamic allocation of 2D-Arrays

Input size of your matrix: 2 4
 Input row [1]: 1 2 5 8
 Input row [2]: 4 9 9 8

```

1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N,M;
7      cout << "Input size of your matrix: ";
8      cin >> N >> M;
9
10     float **c = new float *[N];
11     for(int i = 0; i<N; i++) c[i] = new float[M];
12
13
14     for(int i=0;i<N;i++){
15         cout << "Input row [" << i+1 << "]: ";
16         for(int j=0;j<M;j++){
17             cin >> c[i][j];
18         }
19     }
20     ลบแถวได้ใหม่
21     for(int i=0; i<N; i++) delete [] c[i];
22     delete [] c;
23
24     return 0;
25 }
```

Dynamic Allocation
 Equivalent to float c[N][M]

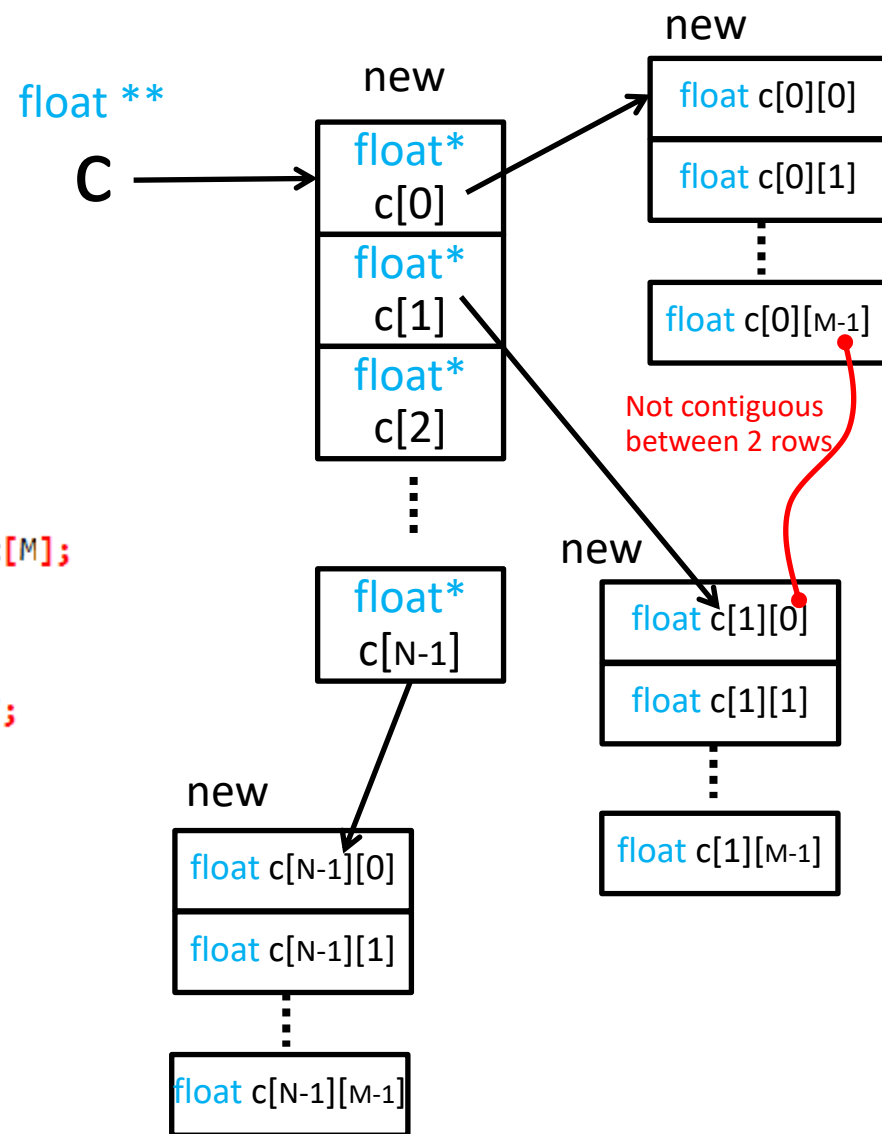
Deallocation of 2D Array

Dynamic allocation of 2D-Arrays

```

1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N,M;
7      cout << "Input size of your matrix: ";
8      cin >> N >> M;
9
10     float **c = new float *[N];
11     for(int i = 0; i<N; i++) c[i] = new float[M];
12
13
14     for(int i=0;i<N;i++){
15         cout << "Input row [" << i+1 << "]: ";
16         for(int j=0;j<M;j++){
17             cin >> c[i][j];
18         }
19     }
20
21     for(int i=0; i<N; i++) delete [] c[i];
22     delete [] c;
23
24     return 0;
25 }

```



Dynamic allocation of 2D-Arrays

```

10 float **c = new float *[N];
11 for(int i = 0; i<N; i++) c[i] = new float[M];
12
13

```

```

14 for(int i=0;i<N;i++){
15     cout << "Input row [" << i+1 << "]: ";
16     for(int j=0;j<M;j++){
17         cin >> c[i][j];
18     }
19 }
20

```

```

21 for(int i=0;i<N;i++){
22     for(int j=0;j<M;j++){
23         cout << &c[i][j] << " ";
24     }
25     cout << "\n";
26 }
27

```

```

28
29 for(int i=0; i<N; i++) delete [] c[i];
30 delete [] c;

```

Input size of your matrix: 5 5

Input row [1]: 1 2 3 4 5

Input row [2]: 4 5 5 7 5

Input row [3]: 1 2 3 4 5

Input row [4]: 4 5 6 6 7

Input row [5]: 1 5 7 4 7

0x2f7650 0x2f7654 0x2f7658 0x2f765c 0x2f7660

0x2f7b20 0x2f7b24 0x2f7b28 0x2f7b2c 0x2f7b30

0x2f7b40 0x2f7b44 0x2f7b48 0x2f7b4c 0x2f7b50

0x2f7b60 0x2f7b64 0x2f7b68 0x2f7b6c 0x2f7b70

0x2f7b80 0x2f7b84 0x2f7b88 0x2f7b8c 0x2f7b90

Array of Runtime Bound

```

1  #include <iostream>
2  using namespace std;
3
4  int main()
5  {
6      int N,M;
7      cout << "Input size of your matrix: ";
8      cin >> N >> M;
9
10     float c[N][M];
11
12     for(int i=0;i<N;i++){
13         cout << "Input row [" << i+1 << "]: ";
14         for(int j=0;j<M;j++){
15             cin >> c[i][j];
16         }
17     }
18
19     for(int i=0;i<N;i++){
20         for(int j=0;j<M;j++){
21             cout << &c[i][j] << " ";
22         }
23         cout << "\n";
24     }
25
26     return 0;
27 }

```

```

Input size of your matrix: 5 5
Input row [1]: 1 2 3 4 5
Input row [2]: 6 7 8 9 10
Input row [3]: 4 5 7 8 3
Input row [4]: 1 1 2 2 2
Input row [5]: 1 4 7 5 5
0x22fd40 0x22fd44 0x22fd48 0x22fd4c 0x22fd50
0x22fd54 0x22fd58 0x22fd5c 0x22fd60 0x22fd64
0x22fd68 0x22fd6c 0x22fd70 0x22fd74 0x22fd78
0x22fd7c 0x22fd80 0x22fd84 0x22fd88 0x22fd8c
0x22fd90 0x22fd94 0x22fd98 0x22fd9c 0x22fda0

```

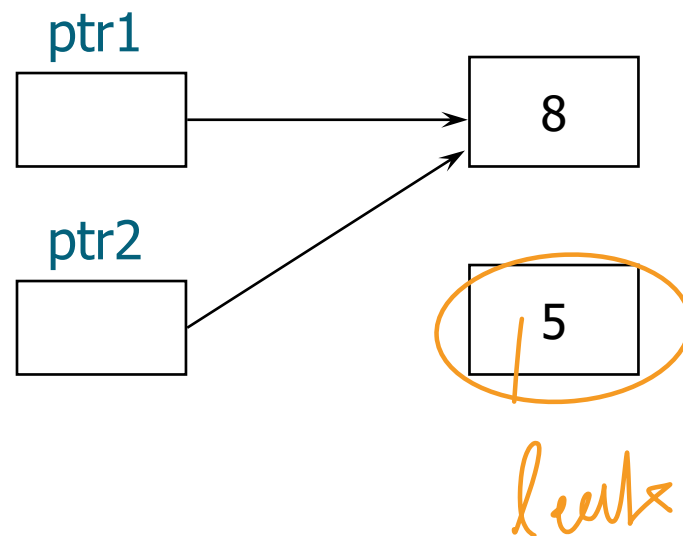
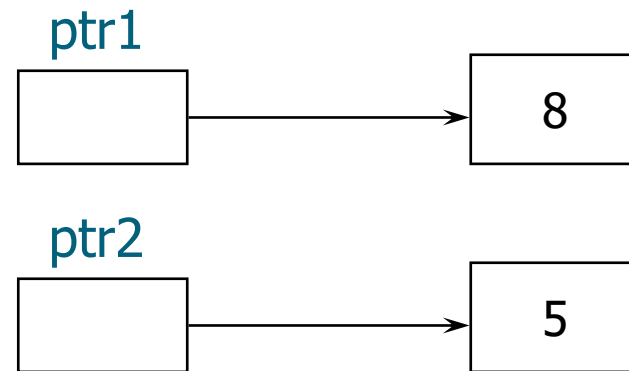
Memory Leaks

- When you dynamically create objects, you can access them through the pointer which is assigned by the **new** operator
- Reassigning a pointer without deleting the memory it pointed to previously is called a memory leak
- It results in **loss of available memory space**

Memory Leaks

```
int *ptr1 = new int;  
int *ptr2 = new int;  
*ptr1 = 8;  
*ptr2 = 5;  
ptr2 = ptr1;
```

How to avoid?



Inaccessible Object

- An inaccessible object is an unnamed object that was created by operator **new** and which a programmer has left without a pointer to it.
- It is a logical error and causes memory leaks.

Dangling Pointer

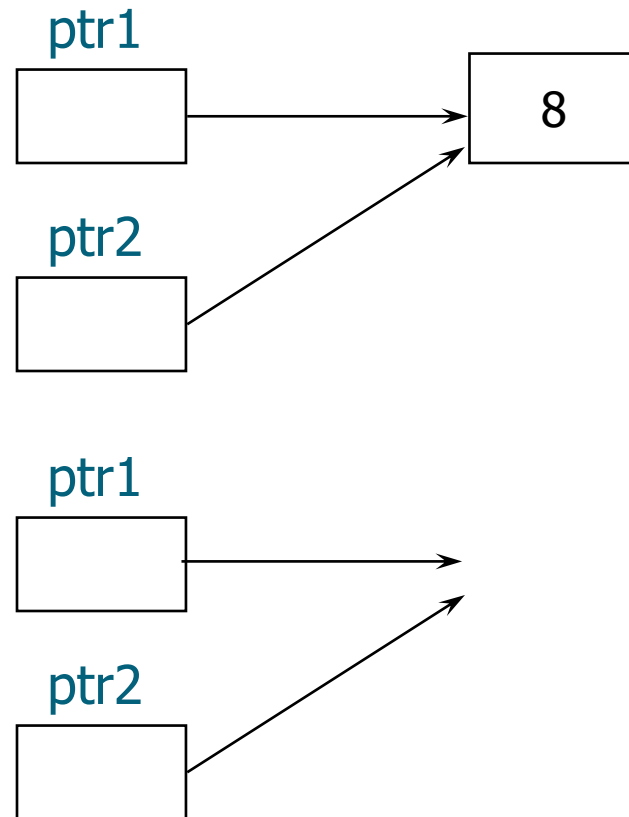
- It is a pointer that points to dynamic memory that has been deallocated.
- The result of dereferencing a dangling pointer is unpredictable.

Dangling Pointer

```
int *ptr1 = new int;  
int *ptr2;  
*ptr1 = 8;  
ptr2 = ptr1;  
delete ptr1;
```

How to avoid?

*ptr1 = 0
ptr2 = 0*



Dangling Pointer

```

1  #include <iostream>
2  using namespace std;
3
4  int * become69(){
5      int *p; local
6      int temp;
7      p = &temp;
8      temp = 69;
9      cout << "p = " << p << "\n";
10     return p;
11 }
12
13 int main(){
14     int *myPtr;
15     myPtr = become69();
16     cout << "myPtr = " << myPtr << "\n";
17     cout << "*myPtr = " << *myPtr << "\n";
18 }

```

Automatic Data

int *
myPtr

int *
p = 22fdf4

&temp = 22fdf4

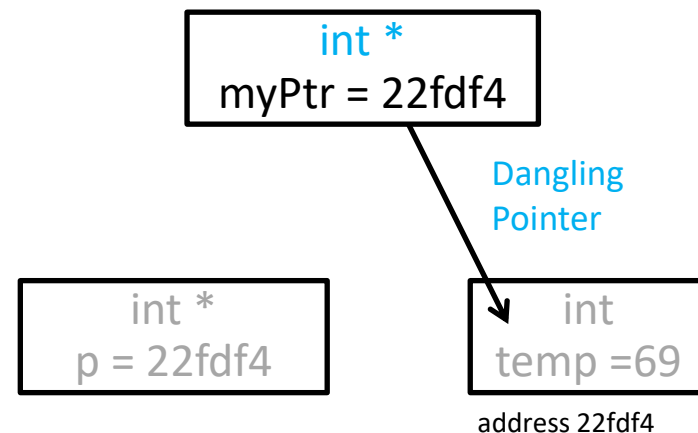
int
temp = 69

p = 0x22fdf4
myPtr = 0x22fdf4
*myPtr = 0

Dangling Pointer

```
1  #include <iostream>
2  using namespace std;
3
4  int * become69(){
5      int *p;
6      int temp;
7      p = &temp;
8      temp = 69;
9      cout << "p = " << p << "\n";
10     return p;
11 }
12
13 int main(){
14     int *myPtr;
15     myPtr = become69();
16     cout << "myPtr = " << myPtr << "\n";
17     cout << "*myPtr = " << *myPtr << "\n";
18 }
```

Automatic Data



`p` and `temp` are destroyed
after leaving function

`p = 0x22fdf4`
`myPtr = 0x22fdf4`
`*myPtr = 0`

Dangling Pointer

1/0~ 1

Dynamic Data

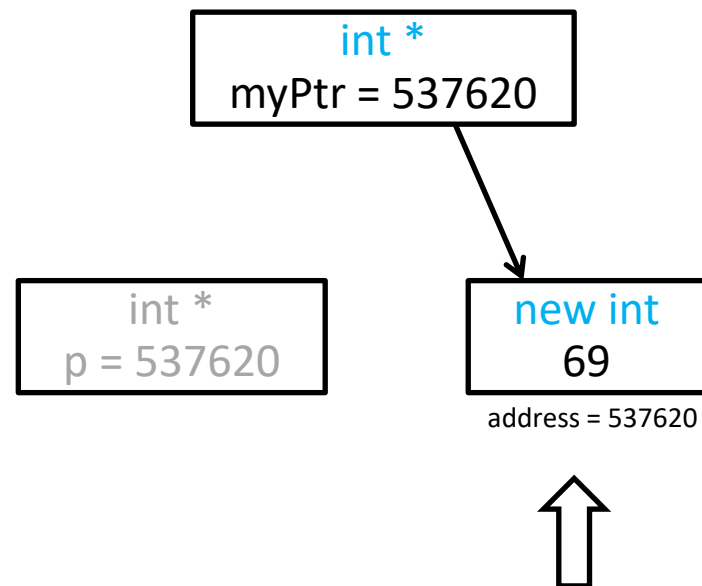
```

1  #include <iostream>
2  using namespace std;
3
4  int * become69(){
5      int *p;
6      p = new int;
7      *p = 69;
8      cout << "p = " << p << "\n";
9      return p;
10 }
11
12 int main(){
13     int *myPtr;
14     myPtr = become69();
15     cout << "myPtr = " << myPtr << "\n";
16     cout << "*myPtr = " << *myPtr << "\n";
17     delete myPtr;
18 }

```

ออกมาแล้วไม่ทำอะไร

p = 0x537620
myPtr = 0x537620
***myPtr = 69**



Before **delete** operator

Dangling Pointer

1/10²

Static Data -

≈ global variable

Q2' 9k new

```

1  #include <iostream>
2  using namespace std;
3
4  int * become69(){
5      int *p;
6      static int temp;
7      p = &temp;
8      temp = 69;
9      cout << "p = " << p << "\n";
10     return p;
11 }
12
13 int main(){
14     int *myPtr;
15     myPtr = become69();
16     cout << "myPtr = " << myPtr << "\n";
17     cout << "*myPtr = " << *myPtr << "\n";
18 }

```

Pur : stack

in temp 4a7034

int *
myPtr = 4a7034

int *
p = 4a7034

int
temp = 69

&temp = 4a7034

p = 0x4a7034
myPtr = 0x4a7034
*myPtr = 69

p is destroyed after leaving function

temp is not destroyed after leaving function

```

void func() {
    static int x = 1;
    cout << x;
    x++;
}

```

```

int main() {
    func();
    func();
    func();
}

```

initial state

1	1	1
---	---	---

and state

1	2	3
---	---	---

std::Vector

- Vector is a class of sequence container representing array that can **change in size**.
- Vectors use **contiguous storage** locations for their elements, which means that their elements can also be **accessed using offsets on regular pointers** to its elements.
- Vectors use a **dynamically allocated** array to store their elements. Vector need to be **reallocated in order to grow in size** when new elements are inserted, which implies allocating a new array and moving all elements to it. This is a relatively expensive task in terms of processing time, and thus, vectors do not reallocate each time an element is added to the container.

std::Vector

- Vectors = sequence containers representing arrays that **can change in size** dynamically
- **#include<vector>**
- Declaring a vector:

```
std::vector< type > vectorName (vectorSize) ;  
std::vector< type > vectorName ;
```

- Referring to an element:

```
vectorName [ index ]  
vectorName .at ( index )
```

std::Vector

- Adding an element to a vector :



vectorName.push_back (value) ;

(add new element to the end of vector)

vectorName.insert (position, value) ;

(use **vectorName**.begin() to obtain position of the 1st element)

- Removing element(s) of a vector :

vectorName.pop_back () ;

(removes the last element in the vector)

vectorName.erase (position) ;

vectorName.erase (firstPosition, lastPosition) ;

vectorName.clear () ;

(removes all elements from the vector)

std::Vector

- Changing value of an element of a vector :

vectorName [*index*] = *newValue* ;

vectorName.at(*index*) = *newValue* ;

- Vector can be return from a function:

vector<*type*> **func**(*parameter_list*) ;

- Pass a vector to a function:

	By Value	By Reference
Prototype	<i>type</i> func (vector< <i>type</i> >) ;	<i>type</i> func (vector< <i>type</i> > &) ;
Definition	<i>type</i> func (vector< <i>type</i> > v) { } }	<i>type</i> func (vector< <i>type</i> > &v) { } }
Calling	func (v)	func (v)

std::Vector

0	0	0	1	10	100
17	0	60	1	10	100

```
1  #include <iostream>
2  #include <vector>
3  using namespace std;
4
5  int main()
6  {
7      int N = 3;
8      vector<int> x(N);
9      x.push_back(1);
10     x.push_back(10);
11     x.push_back(100);
12
13     for(unsigned int i=0; i < x.size();i++) cout << x[i] << " ";
14
15     x[0] = 17;
16     x.at(2) = x.at(4)+x[5]/2;
17
18     cout << "\n";
19     for(unsigned int i=0; i < x.size();i++) cout << x[i] << " ";
20
21     return 0;
22 }
```

std::Vector

```

1  #include<iostream>
2  #include<vector>
3  using namespace std;
4
5  int main(){
6      vector<int> myVector(2);
7      myVector[0] = 4; myVector[1] = 10; // 4 10
8
9      myVector.push_back(55); // 4 10 55
10
11     myVector.insert(myVector.begin()+2,3); // 4 10 3 55
12     myVector.insert(myVector.begin(),8); // 8 4 10 3 55
13
14     myVector.erase(myVector.begin()+1); // 8 10 3 55
15
16     for(int i = 0; i < myVector.size(); i++){
17         cout << &myVector[i] << ": " << myVector[i] << "\n";
18     }
19
20     return 0;
21 }

```

Handwritten notes:
 - A red arrow points from the `myVector.begin()` in line 11 to the first element (8) in the output.
 - A red arrow points from the `myVector.begin()+2` in line 11 to the third element (3) in the output.
 - A red arrow points from the `myVector.begin()` in line 12 to the first element (8) in the output.
 - A red arrow points from the `myVector.begin()+1` in line 14 to the second element (10) in the output.
 - A red arrow points from the `myVector.begin()` in line 17 to the first element (8) in the output.

Output

```

0x617bf0: 8
0x617bf4: 10
0x617bf8: 3
0x617bfc: 55

```

std::Vector

2 hr.

Passed by value

9 4 49

Return vector


```
1  #include <iostream>
2  #include <vector>
3  using namespace std;
4
5  vector<int> square(vector<int>);
6
7  int main()
8  {
9      vector<int> x;
10     x.push_back(3);
11     x.push_back(-2);
12     x.push_back(7);
13
14     vector<int> y = square(x);
15
16     for(unsigned int i=0; i < y.size();i++) cout << y[i] << " ";
17
18     return 0;
19 }
20
21 vector<int> square(vector<int> v){
22     vector<int> w(v.size());
23     for(unsigned int i=0; i < v.size();i++) w[i] = v[i]*v[i];
24     return w;
25 }
```

std::Vector

69 69 69 69 69 69 69

```
1  #include <iostream>
2  #include <vector>
3  using namespace std;
4
5  void fill69(vector<int> &,int);
6
7  int main()
8  {
9      vector<int> x;
10
11      fill69(x,7);
12
13      for(unsigned int i=0; i < x.size();i++) cout << x[i] << " ";
14
15      return 0;
16  }
17
18  void fill69(vector<int> &v,int N){
19      for(int i=0; i < N;i++) v.push_back(69);
20  }
```

Passed by reference



$$C[i] \equiv^* (C + i)$$

love love