

Practical Machine Learning Project

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November 4, 2017

Summary

The aim of the study is to predict if a physical activity is performed correctly. We use data from accelerometers on the belt, forearm, arm, and dumbbell of 6 participants. They were asked to perform barbell lifts correctly and incorrectly in 5 different ways. We identify primary and statistical measures in our dataset and restrict our study to primary measures. Using 5-fold cross-validation we test three models: k-nearest neighbours, naive Bayes and random Forest. Based on an estimated accuracy of 99.29% we select the random forest model classifier, confirm its accuracy on our test set at above 99.29% and apply it to predict our final results.

Source for the dataset

Velloso, E.; Bulling, A.; Gellersen, H.; Ugulino, W.; Fuks, H. Qualitative Activity Recognition of Weight Lifting Exercises. Proceedings of 4th International Conference in Cooperation with SIGCHI (Augmented Human '13) . Stuttgart, Germany: ACM SIGCHI, 2013.

Read more: http://groupware.les.inf.puc-rio.br/har#wle_paper_section#ixzz4y8Ou0ILz

Data analysis

load data and libraries

```
setwd("C:/Users/Patrick/Documents/R/MachineLearning/Project")
getwd()
library(caret)
library(dplyr)
library(magrittr)
library(Hmisc)
train <- read.csv("../data/pml-training.csv")
test <- read.csv("../data/pml-testing.csv")
```

field selection

The training test contains 19622 observations of 160 variables. The first fields are identifier, user name (6 users), time stamps, window identifier and indicator for new window

```
dim(train)

## [1] 19622 160

dim(test)

## [1] 20 160

str(train[,1:7])
```

```
## 'data.frame':   19622 obs. of  7 variables:
## $ X              : int  1 2 3 4 5 6 7 8 9 10 ...
## $ user_name       : Factor w/ 6 levels "adelmo","carlitos",...: 2 2 2 2 2 2 2 2 2 ...
## $ raw_timestamp_part_1: int  1323084231 1323084231 1323084231 1323084232 1323084232 1323084232 1323084232 1323084232 ...
## $ raw_timestamp_part_2: int  788290 808298 820366 120339 196328 304277 368296 440390 484323 484434 ...
## $ cvtd_timestamp     : Factor w/ 20 levels "02/12/2011 13:32",...: 9 9 9 9 9 9 9 9 9 9 ...
## $ new_window         : Factor w/ 2 levels "no","yes": 1 1 1 1 1 1 1 1 1 1 ...
## $ num_window         : int  11 11 11 12 12 12 12 12 12 12 ...
```

From the data description at “<http://groupware.les.inf.puc-rio.br/har>” we know the dataset contains measures for 4 sensors: arm, forearm, belt and dumbbell

```
names(train)[grep("belt", names(train))]
```

```
## [1] "roll_belt"          "pitch_belt"         "yaw_belt"
## [4] "total_accel_belt"   "kurtosis_roll_belt" "kurtosis_pitch_belt"
## [7] "kurtosis_yaw_belt"  "skewness_roll_belt" "skewness_roll_belt.1"
## [10] "skewness_yaw_belt"  "max_roll_belt"      "max_pitch_belt"
## [13] "max_yaw_belt"       "min_roll_belt"      "min_pitch_belt"
## [16] "min_yaw_belt"       "amplitude_roll_belt" "amplitude_pitch_belt"
## [19] "amplitude_yaw_belt" "var_total_accel_belt" "avg_roll_belt"
## [22] "stddev_roll_belt"   "var_roll_belt"      "avg_pitch_belt"
## [25] "stddev_pitch_belt"  "var_pitch_belt"     "avg_yaw_belt"
## [28] "stddev_yaw_belt"    "var_yaw_belt"       "gyros_belt_x"
## [31] "gyros_belt_y"       "gyros_belt_z"       "accel_belt_x"
## [34] "accel_belt_y"       "accel_belt_z"       "magnet_belt_x"
## [37] "magnet_belt_y"      "magnet_belt_z"
```

```
names(train)[grep("_arm", names(train))]
```

```
## [1] "roll_arm"          "pitch_arm"         "yaw_arm"
## [4] "total_accel_arm"   "var_accel_arm"      "avg_roll_arm"
## [7] "stddev_roll_arm"   "var_roll_arm"       "avg_pitch_arm"
## [10] "stddev_pitch_arm"  "var_pitch_arm"      "avg_yaw_arm"
## [13] "stddev_yaw_arm"    "var_yaw_arm"        "gyros_arm_x"
## [16] "gyros_arm_y"       "gyros_arm_z"        "accel_arm_x"
## [19] "accel_arm_y"       "accel_arm_z"        "magnet_arm_x"
## [22] "magnet_arm_y"      "magnet_arm_z"       "kurtosis_roll_arm"
## [25] "kurtosis_pitch_arm" "kurtosis_yaw_arm"   "skewness_roll_arm"
## [28] "skewness_pitch_arm" "skewness_yaw_arm"   "max_roll_arm"
## [31] "max_pitch_arm"     "max_yaw_arm"        "min_roll_arm"
## [34] "min_pitch_arm"     "min_yaw_arm"        "amplitude_roll_arm"
## [37] "amplitude_pitch_arm" "amplitude_yaw_arm"
```

```
names(train)[grep("forearm", names(train))]
```

```
## [1] "roll_forearm"      "pitch_forearm"
## [3] "yaw_forearm"       "kurtosis_roll_forearm"
## [5] "kurtosis_pitch_forearm" "kurtosis_yaw_forearm"
## [7] "skewness_roll_forearm" "skewness_pitch_forearm"
## [9] "skewness_yaw_forearm" "max_roll_forearm"
## [11] "max_pitch_forearm"  "max_yaw_forearm"
## [13] "min_roll_forearm"   "min_pitch_forearm"
## [15] "min_yaw_forearm"    "amplitude_roll_forearm"
## [17] "amplitude_pitch_forearm" "amplitude_yaw_forearm"
## [19] "total_accel_forearm" "var_accel_forearm"
## [21] "avg_roll_forearm"   "stddev_roll_forearm"
```

```
## [23] "var_roll_forearm"      "avg_pitch_forearm"
## [25] "stddev_pitch_forearm"  "var_pitch_forearm"
## [27] "avg_yaw_forearm"       "stddev_yaw_forearm"
## [29] "var_yaw_forearm"       "gyros_forearm_x"
## [31] "gyros_forearm_y"       "gyros_forearm_z"
## [33] "accel_forearm_x"       "accel_forearm_y"
## [35] "accel_forearm_z"       "magnet_forearm_x"
## [37] "magnet_forearm_y"      "magnet_forearm_z"
```

```
names(train)[grep("dumbbell", names(train))]
```

```
## [1] "roll_dumbbell"      "pitch_dumbbell"
## [3] "yaw_dumbbell"       "kurtosis_roll_dumbbell"
## [5] "kurtosis_pitch_dumbbell" "kurtosis_yaw_dumbbell"
## [7] "skewness_roll_dumbbell" "skewness_pitch_dumbbell"
## [9] "skewness_yaw_dumbbell" "max_roll_dumbbell"
## [11] "max_pitch_dumbbell" "max_yaw_dumbbell"
## [13] "min_roll_dumbbell" "min_pitch_dumbbell"
## [15] "min_yaw_dumbbell" "amplitude_roll_dumbbell"
## [17] "amplitude_pitch_dumbbell" "amplitude_yaw_dumbbell"
## [19] "total_accel_dumbbell" "var_accel_dumbbell"
## [21] "avg_roll_dumbbell" "stddev_roll_dumbbell"
## [23] "var_roll_dumbbell" "avg_pitch_dumbbell"
## [25] "stddev_pitch_dumbbell" "var_pitch_dumbbell"
## [27] "avg_yaw_dumbbell" "stddev_yaw_dumbbell"
## [29] "var_yaw_dumbbell" "gyros_dumbbell_x"
## [31] "gyros_dumbbell_y" "gyros_dumbbell_z"
## [33] "accel_dumbbell_x" "accel_dumbbell_y"
## [35] "accel_dumbbell_z" "magnet_dumbbell_x"
## [37] "magnet_dumbbell_y" "magnet_dumbbell_z"
```

There are 13 primary measures for the belt: roll, pitch, yaw, total acceleration, 'gyros', 'accel' and 'magnet' measures on 3 axes

```
beltm <- names(train)[grep("belt", names(train))]
i <- grep("(^[a-z]+_belt)|(^total_[a-z]+_belt)", beltm)
beltm[i]
```

```
## [1] "roll_belt"      "pitch_belt"      "yaw_belt"
## [4] "total_accel_belt" "gyros_belt_x"    "gyros_belt_y"
## [7] "gyros_belt_z"    "accel_belt_x"    "accel_belt_y"
## [10] "accel_belt_z"    "magnet_belt_x"   "magnet_belt_y"
## [13] "magnet_belt_z"
```

```
anyNA(train[,beltm[i]])
```

```
## [1] FALSE
```

```
apply(train[,beltm[i]], 2, function(x) sum(x == ''))
```

```
##      roll_belt      pitch_belt      yaw_belt total_accel_belt
##           0           0           0           0
## gyros_belt_x gyros_belt_y gyros_belt_z accel_belt_x
##           0           0           0           0
## accel_belt_y accel_belt_z magnet_belt_x magnet_belt_y
##           0           0           0           0
## magnet_belt_z
```

```
## 0
```

There are 25 statistics on those measures, with mostly NAs or errors when the new window indicator is False. The reasonable explanation is that for every new window, statistics are given for all measures in that window.

```
beltm[-i]
```

```
## [1] "kurtosis_roll_belt" "kurtosis_picth_belt" "kurtosis_yaw_belt"
## [4] "skewness_roll_belt" "skewness_roll_belt.1" "skewness_yaw_belt"
## [7] "max_roll_belt" "max_picth_belt" "max_yaw_belt"
## [10] "min_roll_belt" "min_pitch_belt" "min_yaw_belt"
## [13] "amplitude_roll_belt" "amplitude_pitch_belt" "amplitude_yaw_belt"
## [16] "var_total_accel_belt" "avg_roll_belt" "stddev_roll_belt"
## [19] "var_roll_belt" "avg_pitch_belt" "stddev_pitch_belt"
## [22] "var_pitch_belt" "avg_yaw_belt" "stddev_yaw_belt"
## [25] "var_yaw_belt"
```

```
t <- train[train$new_window=='no',beltm[-i]]
str(t)
```

```
## 'data.frame': 19216 obs. of 25 variables:
## $ kurtosis_roll_belt : Factor w/ 397 levels "", "-0.016850", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_picth_belt : Factor w/ 317 levels "", "-0.021887", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ kurtosis_yaw_belt : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_belt : Factor w/ 395 levels "", "-0.003095", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_roll_belt.1: Factor w/ 338 levels "", "-0.005928", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ skewness_yaw_belt : Factor w/ 2 levels "", "#DIV/0!": 1 1 1 1 1 1 1 1 1 1 ...
## $ max_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ max_picth_belt : int NA NA NA NA NA NA NA NA NA NA NA ...
## $ max_yaw_belt : Factor w/ 68 levels "", "-0.1", "-0.2", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ min_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ min_pitch_belt : int NA NA NA NA NA NA NA NA NA NA NA ...
## $ min_yaw_belt : Factor w/ 68 levels "", "-0.1", "-0.2", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ amplitude_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ amplitude_pitch_belt: int NA NA NA NA NA NA NA NA NA NA NA ...
## $ amplitude_yaw_belt : Factor w/ 4 levels "", "#DIV/0!", "0.00", ...: 1 1 1 1 1 1 1 1 1 1 ...
## $ var_total_accel_belt: num NA NA NA NA NA NA NA NA NA NA NA ...
## $ avg_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ stddev_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ var_roll_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ avg_pitch_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ stddev_pitch_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ var_pitch_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ avg_yaw_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ stddev_yaw_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
## $ var_yaw_belt : num NA NA NA NA NA NA NA NA NA NA NA ...
```

For example for window 2, avg_roll_belt contains average of all measures in that window.

```
mean(train[train$num_window==2,'roll_belt'])
```

```
## [1] -27.43333
```

```
train[train$num_window==2 & train$new_window == 'yes',]$avg_roll_belt
```

```
## [1] -27.4
```

We will leave the statistics out as they are mostly redundant with the raw measure. We will revisit this choice if we find we don't have enough data after all

```

train2 <- train %>%
  select(-starts_with("kurtosis"),
         -starts_with("skewness"),
         -starts_with("max"),
         -starts_with("min"),
         -starts_with("amplitude"),
         -starts_with("avg"),
         -starts_with("var"),
         -starts_with("stddev"),
         -contains("timestamp"),
         -X, -new_window, -num_window
  )

test2 <- test %>%
  select(-starts_with("kurtosis"),
         -starts_with("skewness"),
         -starts_with("max"),
         -starts_with("min"),
         -starts_with("amplitude"),
         -starts_with("avg"),
         -starts_with("var"),
         -starts_with("stddev"),
         -contains("timestamp"),
         -X, -new_window, -num_window, -problem_id
  )

```

The variable names are now consistent between train and test set, there are no NAs in our filtered dataset and a quick summary shows nothing untoward.

```
data.frame(names(train2[,1:53]), names(test2))
```

##	names.train2...1.53..	names.test2.
## 1	user_name	user_name
## 2	roll_belt	roll_belt
## 3	pitch_belt	pitch_belt
## 4	yaw_belt	yaw_belt
## 5	total_accel_belt	total_accel_belt
## 6	gyros_belt_x	gyros_belt_x
## 7	gyros_belt_y	gyros_belt_y
## 8	gyros_belt_z	gyros_belt_z
## 9	accel_belt_x	accel_belt_x
## 10	accel_belt_y	accel_belt_y
## 11	accel_belt_z	accel_belt_z
## 12	magnet_belt_x	magnet_belt_x
## 13	magnet_belt_y	magnet_belt_y
## 14	magnet_belt_z	magnet_belt_z
## 15	roll_arm	roll_arm
## 16	pitch_arm	pitch_arm
## 17	yaw_arm	yaw_arm
## 18	total_accel_arm	total_accel_arm
## 19	gyros_arm_x	gyros_arm_x
## 20	gyros_arm_y	gyros_arm_y
## 21	gyros_arm_z	gyros_arm_z
## 22	accel_arm_x	accel_arm_x
## 23	accel_arm_y	accel_arm_y

```

## 24      accel_arm_z      accel_arm_z
## 25      magnet_arm_x      magnet_arm_x
## 26      magnet_arm_y      magnet_arm_y
## 27      magnet_arm_z      magnet_arm_z
## 28      roll_dumbbell      roll_dumbbell
## 29      pitch_dumbbell      pitch_dumbbell
## 30      yaw_dumbbell      yaw_dumbbell
## 31 total_accel_dumbbell total_accel_dumbbell
## 32      gyros_dumbbell_x      gyros_dumbbell_x
## 33      gyros_dumbbell_y      gyros_dumbbell_y
## 34      gyros_dumbbell_z      gyros_dumbbell_z
## 35      accel_dumbbell_x      accel_dumbbell_x
## 36      accel_dumbbell_y      accel_dumbbell_y
## 37      accel_dumbbell_z      accel_dumbbell_z
## 38      magnet_dumbbell_x      magnet_dumbbell_x
## 39      magnet_dumbbell_y      magnet_dumbbell_y
## 40      magnet_dumbbell_z      magnet_dumbbell_z
## 41      roll_forearm      roll_forearm
## 42      pitch_forearm      pitch_forearm
## 43      yaw_forearm      yaw_forearm
## 44 total_accel_forearm total_accel_forearm
## 45      gyros_forearm_x      gyros_forearm_x
## 46      gyros_forearm_y      gyros_forearm_y
## 47      gyros_forearm_z      gyros_forearm_z
## 48      accel_forearm_x      accel_forearm_x
## 49      accel_forearm_y      accel_forearm_y
## 50      accel_forearm_z      accel_forearm_z
## 51      magnet_forearm_x      magnet_forearm_x
## 52      magnet_forearm_y      magnet_forearm_y
## 53      magnet_forearm_z      magnet_forearm_z

```

```
anyNA(train2)
```

```
## [1] FALSE
```

```
anyNA(test2)
```

```
## [1] FALSE
```

```
summary(train2)
```

```

##      user_name      roll_belt      pitch_belt      yaw_belt
## adelmo :3892  Min.   :-28.90  Min.   :-55.8000  Min.   :-180.00
## carlitos:3112  1st Qu.:  1.10  1st Qu.:  1.7600  1st Qu.: -88.30
## charles :3536  Median :113.00  Median :  5.2800  Median : -13.00
## eurico  :3070  Mean    : 64.41  Mean    :  0.3053  Mean    : -11.21
## jeremy  :3402  3rd Qu.:123.00  3rd Qu.: 14.9000  3rd Qu.:  12.90
## pedro   :2610  Max.    :162.00  Max.    : 60.3000  Max.    : 179.00
## total_accel_belt gyros_belt_x      gyros_belt_y      gyros_belt_z
## Min.   : 0.00  Min.   :-1.040000  Min.   :-0.64000  Min.   :-1.4600
## 1st Qu.: 3.00  1st Qu.: -0.030000  1st Qu.:  0.00000  1st Qu.: -0.2000
## Median :17.00  Median :  0.030000  Median :  0.02000  Median : -0.1000
## Mean    :11.31  Mean    :-0.005592  Mean     : 0.03959  Mean    :-0.1305
## 3rd Qu.:18.00  3rd Qu.:  0.110000  3rd Qu.:  0.11000  3rd Qu.: -0.0200
## Max.    :29.00  Max.     : 2.220000  Max.     :  0.64000  Max.     :  1.6200
## accel_belt_x      accel_belt_y      accel_belt_z      magnet_belt_x

```

```

## Min.      :-120.000    Min.      :-69.00    Min.      :-275.00    Min.      :-52.0
## 1st Qu.:  -21.000    1st Qu.:   3.00    1st Qu.: -162.00    1st Qu.:   9.0
## Median :  -15.000    Median :  35.00    Median : -152.00    Median :  35.0
## Mean   :   -5.595    Mean   :  30.15    Mean   :  -72.59    Mean   :  55.6
## 3rd Qu.:   -5.000    3rd Qu.:  61.00    3rd Qu.:  27.00    3rd Qu.:  59.0
## Max.    :   85.000    Max.    : 164.00    Max.    :  105.00    Max.    : 485.0
## magnet_belt_y  magnet_belt_z      roll_arm      pitch_arm
## Min.    :354.0    Min.    : -623.0    Min.    : -180.00    Min.    : -88.800
## 1st Qu.:581.0    1st Qu.: -375.0    1st Qu.: -31.77    1st Qu.: -25.900
## Median :601.0    Median : -320.0    Median :   0.00    Median :   0.000
## Mean   :593.7    Mean   : -345.5    Mean   :  17.83    Mean   :  -4.612
## 3rd Qu.:610.0    3rd Qu.: -306.0    3rd Qu.:  77.30    3rd Qu.:  11.200
## Max.    :673.0    Max.    :  293.0    Max.    :  180.00    Max.    :  88.500
## yaw_arm      total_accel_arm  gyros_arm_x      gyros_arm_y
## Min.    : -180.0000    Min.    :   1.00    Min.    : -6.37000    Min.    : -3.4400
## 1st Qu.: -43.1000    1st Qu.: 17.00    1st Qu.: -1.33000    1st Qu.: -0.8000
## Median :   0.0000    Median : 27.00    Median :  0.08000    Median : -0.2400
## Mean   :  -0.6188    Mean   : 25.51    Mean   :  0.04277    Mean   : -0.2571
## 3rd Qu.:  45.8750    3rd Qu.: 33.00    3rd Qu.:  1.57000    3rd Qu.:  0.1400
## Max.    :  180.0000    Max.    :  66.00    Max.    :  4.87000    Max.    :  2.8400
## gyros_arm_z    accel_arm_x      accel_arm_y      accel_arm_z
## Min.    : -2.3300    Min.    : -404.00    Min.    : -318.0    Min.    : -636.00
## 1st Qu.: -0.0700    1st Qu.: -242.00    1st Qu.:  -54.0    1st Qu.: -143.00
## Median :  0.2300    Median :  -44.00    Median :  14.0    Median :  -47.00
## Mean   :  0.2695    Mean   :  -60.24    Mean   :  32.6    Mean   :  -71.25
## 3rd Qu.:  0.7200    3rd Qu.:  84.00    3rd Qu.: 139.0    3rd Qu.:  23.00
## Max.    :  3.0200    Max.    :  437.00    Max.    :  308.0    Max.    :  292.00
## magnet_arm_x    magnet_arm_y      magnet_arm_z      roll_dumbbell
## Min.    : -584.0    Min.    : -392.0    Min.    : -597.0    Min.    : -153.71
## 1st Qu.: -300.0    1st Qu.:  -9.0    1st Qu.: 131.2    1st Qu.: -18.49
## Median :  289.0    Median :  202.0    Median :  444.0    Median :  48.17
## Mean   :  191.7    Mean   :  156.6    Mean   :  306.5    Mean   :  23.84
## 3rd Qu.:  637.0    3rd Qu.:  323.0    3rd Qu.:  545.0    3rd Qu.:  67.61
## Max.    :  782.0    Max.    :  583.0    Max.    :  694.0    Max.    : 153.55
## pitch_dumbbell  yaw_dumbbell      total_accel_dumbbell
## Min.    : -149.59    Min.    : -150.871    Min.    :  0.00
## 1st Qu.: -40.89    1st Qu.: -77.644    1st Qu.:  4.00
## Median : -20.96    Median :  -3.324    Median : 10.00
## Mean   : -10.78    Mean   :   1.674    Mean   : 13.72
## 3rd Qu.:  17.50    3rd Qu.:  79.643    3rd Qu.: 19.00
## Max.    :  149.40    Max.    : 154.952    Max.    : 58.00
## gyros_dumbbell_x  gyros_dumbbell_y      gyros_dumbbell_z
## Min.    : -204.0000    Min.    : -2.10000    Min.    :  -2.380
## 1st Qu.:  -0.0300    1st Qu.: -0.14000    1st Qu.:  -0.310
## Median :   0.1300    Median :  0.03000    Median :  -0.130
## Mean   :   0.1611    Mean   :  0.04606    Mean   :  -0.129
## 3rd Qu.:   0.3500    3rd Qu.:  0.21000    3rd Qu.:   0.030
## Max.    :   2.2200    Max.    : 52.00000    Max.    : 317.000
## accel_dumbbell_x  accel_dumbbell_y      accel_dumbbell_z      magnet_dumbbell_x
## Min.    : -419.00    Min.    : -189.00    Min.    : -334.00    Min.    : -643.0
## 1st Qu.: -50.00    1st Qu.:  -8.00    1st Qu.: -142.00    1st Qu.: -535.0
## Median :  -8.00    Median :  41.50    Median :  -1.00    Median : -479.0
## Mean   : -28.62    Mean   :  52.63    Mean   : -38.32    Mean   : -328.5
## 3rd Qu.:  11.00    3rd Qu.: 111.00    3rd Qu.:  38.00    3rd Qu.: -304.0

```

```

## Max. : 235.00 Max. : 315.00 Max. : 318.00 Max. : 592.0
## magnet_dumbbell_y magnet_dumbbell_z roll_forearm pitch_forearm
## Min. : -3600 Min. : -262.00 Min. : -180.0000 Min. : -72.50
## 1st Qu.: 231 1st Qu.: -45.00 1st Qu.: -0.7375 1st Qu.: 0.00
## Median : 311 Median : 13.00 Median : 21.7000 Median : 9.24
## Mean : 221 Mean : 46.05 Mean : 33.8265 Mean : 10.71
## 3rd Qu.: 390 3rd Qu.: 95.00 3rd Qu.: 140.0000 3rd Qu.: 28.40
## Max. : 633 Max. : 452.00 Max. : 180.0000 Max. : 89.80
## yaw_forearm total_accel_forearm gyros_forearm_x
## Min. : -180.00 Min. : 0.00 Min. : -22.000
## 1st Qu.: -68.60 1st Qu.: 29.00 1st Qu.: -0.220
## Median : 0.00 Median : 36.00 Median : 0.050
## Mean : 19.21 Mean : 34.72 Mean : 0.158
## 3rd Qu.: 110.00 3rd Qu.: 41.00 3rd Qu.: 0.560
## Max. : 180.00 Max. : 108.00 Max. : 3.970
## gyros_forearm_y gyros_forearm_z accel_forearm_x accel_forearm_y
## Min. : -7.02000 Min. : -8.0900 Min. : -498.00 Min. : -632.0
## 1st Qu.: -1.46000 1st Qu.: -0.1800 1st Qu.: -178.00 1st Qu.: 57.0
## Median : 0.03000 Median : 0.0800 Median : -57.00 Median : 201.0
## Mean : 0.07517 Mean : 0.1512 Mean : -61.65 Mean : 163.7
## 3rd Qu.: 1.62000 3rd Qu.: 0.4900 3rd Qu.: 76.00 3rd Qu.: 312.0
## Max. : 311.00000 Max. : 231.0000 Max. : 477.00 Max. : 923.0
## accel_forearm_z magnet_forearm_x magnet_forearm_y magnet_forearm_z
## Min. : -446.00 Min. : -1280.0 Min. : -896.0 Min. : -973.0
## 1st Qu.: -182.00 1st Qu.: -616.0 1st Qu.: 2.0 1st Qu.: 191.0
## Median : -39.00 Median : -378.0 Median : 591.0 Median : 511.0
## Mean : -55.29 Mean : -312.6 Mean : 380.1 Mean : 393.6
## 3rd Qu.: 26.00 3rd Qu.: -73.0 3rd Qu.: 737.0 3rd Qu.: 653.0
## Max. : 291.00 Max. : 672.0 Max. : 1480.0 Max. : 1090.0
## classe
## A:5580
## B:3797
## C:3422
## D:3216
## E:3607
##

```

```
summary(test2)
```

```

## user_name roll_belt pitch_belt yaw_belt
## adelmo :1 Min. : -5.9200 Min. : -41.600 Min. : -93.70
## carlitos:3 1st Qu.: 0.9075 1st Qu.: 3.013 1st Qu.: -88.62
## charles :1 Median : 1.1100 Median : 4.655 Median : -87.85
## eurico :4 Mean : 31.3055 Mean : 5.824 Mean : -59.30
## jeremy :8 3rd Qu.: 32.5050 3rd Qu.: 6.135 3rd Qu.: -63.50
## pedro :3 Max. : 129.0000 Max. : 27.800 Max. : 162.00
## total_accel_belt gyros_belt_x gyros_belt_y gyros_belt_z
## Min. : 2.00 Min. : -0.500 Min. : -0.050 Min. : -0.4800
## 1st Qu.: 3.00 1st Qu.: -0.070 1st Qu.: -0.005 1st Qu.: -0.1375
## Median : 4.00 Median : 0.020 Median : 0.000 Median : -0.0250
## Mean : 7.55 Mean : -0.045 Mean : 0.010 Mean : -0.1005
## 3rd Qu.: 8.00 3rd Qu.: 0.070 3rd Qu.: 0.020 3rd Qu.: 0.0000
## Max. : 21.00 Max. : 0.240 Max. : 0.110 Max. : 0.0500
## accel_belt_x accel_belt_y accel_belt_z magnet_belt_x
## Min. : -48.00 Min. : -16.00 Min. : -187.00 Min. : -13.00

```


##	1st Qu.:-19.00	1st Qu.: 2.00	1st Qu.: -24.00	1st Qu.: 5.50
##	Median :-13.00	Median : 4.50	Median : 27.00	Median : 33.50
##	Mean :-13.50	Mean : 18.35	Mean : -17.60	Mean : 35.15
##	3rd Qu.: -8.75	3rd Qu.: 25.50	3rd Qu.: 38.25	3rd Qu.: 46.25
##	Max. : 46.00	Max. : 72.00	Max. : 49.00	Max. :169.00
##	magnet_belt_y	magnet_belt_z	roll_arm	pitch_arm
##	Min. :566.0	Min. : -426.0	Min. : -137.00	Min. : -63.800
##	1st Qu.:578.5	1st Qu.: -398.5	1st Qu.: 0.00	1st Qu.: -9.188
##	Median :600.5	Median : -313.5	Median : 0.00	Median : 0.000
##	Mean :601.5	Mean : -346.9	Mean : 16.42	Mean : -3.950
##	3rd Qu.:631.2	3rd Qu.: -305.0	3rd Qu.: 71.53	3rd Qu.: 3.465
##	Max. :638.0	Max. : -291.0	Max. : 152.00	Max. : 55.000
##	yaw_arm	total_accel_arm	gyros_arm_x	gyros_arm_y
##	Min. : -167.00	Min. : 3.00	Min. : -3.710	Min. : -2.0900
##	1st Qu.: -60.15	1st Qu.:20.25	1st Qu.: -0.645	1st Qu.: -0.6350
##	Median : 0.00	Median :29.50	Median : 0.020	Median : -0.0400
##	Mean : -2.80	Mean :26.40	Mean : 0.077	Mean : -0.1595
##	3rd Qu.: 25.50	3rd Qu.:33.25	3rd Qu.: 1.248	3rd Qu.: 0.2175
##	Max. : 178.00	Max. :44.00	Max. : 3.660	Max. : 1.8500
##	gyros_arm_z	accel_arm_x	accel_arm_y	accel_arm_z
##	Min. : -0.6900	Min. : -341.0	Min. : -65.00	Min. : -404.00
##	1st Qu.: -0.1800	1st Qu.: -277.0	1st Qu.: 52.25	1st Qu.: -128.50
##	Median : -0.0250	Median : -194.5	Median :112.00	Median : -83.50
##	Mean : 0.1205	Mean : -134.6	Mean :103.10	Mean : -87.85
##	3rd Qu.: 0.5650	3rd Qu.: 5.5	3rd Qu.:168.25	3rd Qu.: -27.25
##	Max. : 1.1300	Max. : 106.0	Max. :245.00	Max. : 93.00
##	magnet_arm_x	magnet_arm_y	magnet_arm_z	roll_dumbbell
##	Min. : -428.00	Min. : -307.0	Min. : -499.0	Min. : -111.118
##	1st Qu.: -373.75	1st Qu.: 205.2	1st Qu.: 403.0	1st Qu.: 7.494
##	Median : -265.00	Median : 291.0	Median : 476.5	Median : 50.403
##	Mean : -38.95	Mean : 239.4	Mean : 369.8	Mean : 33.760
##	3rd Qu.: 250.50	3rd Qu.: 358.8	3rd Qu.: 517.0	3rd Qu.: 58.129
##	Max. : 750.00	Max. : 474.0	Max. : 633.0	Max. : 123.984
##	pitch_dumbbell	yaw_dumbbell	total_accel_dumbbell	
##	Min. : -54.97	Min. : -103.3200	Min. : 1.0	
##	1st Qu.: -51.89	1st Qu.: -75.2809	1st Qu.: 7.0	
##	Median : -40.81	Median : -8.2863	Median :15.5	
##	Mean : -19.47	Mean : -0.9385	Mean :17.2	
##	3rd Qu.: 16.12	3rd Qu.: 55.8335	3rd Qu.:29.0	
##	Max. : 96.87	Max. : 132.2337	Max. :31.0	
##	gyros_dumbbell_x	gyros_dumbbell_y	gyros_dumbbell_z	accel_dumbbell_x
##	Min. : -1.0300	Min. : -1.1100	Min. : -1.180	Min. : -159.00
##	1st Qu.: 0.1600	1st Qu.: -0.2100	1st Qu.: -0.485	1st Qu.: -140.25
##	Median : 0.3600	Median : 0.0150	Median : -0.280	Median : -19.00
##	Mean : 0.2690	Mean : 0.0605	Mean : -0.266	Mean : -47.60
##	3rd Qu.: 0.4625	3rd Qu.: 0.1450	3rd Qu.: -0.165	3rd Qu.: 15.75
##	Max. : 1.0600	Max. : 1.9100	Max. : 1.100	Max. : 185.00
##	accel_dumbbell_y	accel_dumbbell_z	magnet_dumbbell_x	magnet_dumbbell_y
##	Min. : -30.00	Min. : -221.0	Min. : -576.0	Min. : -558.0
##	1st Qu.: 5.75	1st Qu.: -192.2	1st Qu.: -528.0	1st Qu.: 259.5
##	Median : 71.50	Median : -3.0	Median : -508.5	Median : 316.0
##	Mean : 70.55	Mean : -60.0	Mean : -304.2	Mean : 189.3
##	3rd Qu.:151.25	3rd Qu.: 76.5	3rd Qu.: -317.0	3rd Qu.: 348.2
##	Max. :166.00	Max. : 100.0	Max. : 523.0	Max. : 403.0

```
## magnet_dumbbell_z roll_forearm pitch_forearm yaw_forearm
## Min. :-164.00 Min. :-176.00 Min. :-63.500 Min. :-168.000
## 1st Qu.: -33.00 1st Qu.: -40.25 1st Qu.: -11.457 1st Qu.: -93.375
## Median : 49.50 Median : 94.20 Median : 8.830 Median : -19.250
## Mean : 71.40 Mean : 38.66 Mean : 7.099 Mean : 2.195
## 3rd Qu.: 96.25 3rd Qu.: 143.25 3rd Qu.: 28.500 3rd Qu.: 104.500
## Max. : 368.00 Max. : 176.00 Max. : 59.300 Max. : 159.000
## total_accel_forearm gyros_forearm_x gyros_forearm_y gyros_forearm_z
## Min. :21.00 Min. :-1.0600 Min. :-5.9700 Min. :-1.2600
## 1st Qu.:24.00 1st Qu.: -0.5850 1st Qu.: -1.2875 1st Qu.: -0.0975
## Median :32.50 Median : 0.0200 Median : 0.0350 Median : 0.2300
## Mean :32.05 Mean :-0.0200 Mean :-0.0415 Mean : 0.2610
## 3rd Qu.:36.75 3rd Qu.: 0.2925 3rd Qu.: 2.0475 3rd Qu.: 0.7625
## Max. :47.00 Max. : 1.3800 Max. : 4.2600 Max. : 1.8000
## accel_forearm_x accel_forearm_y accel_forearm_z magnet_forearm_x
## Min. :-212.0 Min. :-331.0 Min. :-282.0 Min. :-714.0
## 1st Qu.: -114.8 1st Qu.: 8.5 1st Qu.: -199.0 1st Qu.: -427.2
## Median : 86.0 Median : 138.0 Median : -148.5 Median : -189.5
## Mean : 38.8 Mean : 125.3 Mean : -93.7 Mean : -159.2
## 3rd Qu.: 166.2 3rd Qu.: 268.0 3rd Qu.: -31.0 3rd Qu.: 41.5
## Max. : 232.0 Max. : 406.0 Max. : 179.0 Max. : 532.0
## magnet_forearm_y magnet_forearm_z
## Min. :-787.0 Min. :-32.0
## 1st Qu.: -328.8 1st Qu.: 275.2
## Median : 487.0 Median : 491.5
## Mean : 191.8 Mean : 460.2
## 3rd Qu.: 720.8 3rd Qu.: 661.5
## Max. : 800.0 Max. : 884.0
```

Model Fit

creation of training and a testing set

```
set.seed(1342)
inTrain <- createDataPartition(y=train2$classe,
                                p=0.75, list=FALSE)
training <- train2[inTrain,]
testing <- train2[-inTrain,]
```

set training parameters: we will run 5-fold cross validation

```
fitControl <- trainControl(method = "cv", number=5)
```

knn

We run a k-nearest neighbours models with 1, 2 and 5 neighbours

```
tuneGrid <- expand.grid(k = c(1,2,5))
set.seed(32343)
modelFit <- train(classe ~. ,data=training, method="knn",
```

```

                                trControl = fitControl, tuneGrid=tuneGrid, preProcess=c("center", "scale"))
modelFit

## k-Nearest Neighbors
##
## 14718 samples
##    53 predictor
##    5 classes: 'A', 'B', 'C', 'D', 'E'
##
## Pre-processing: centered (57), scaled (57)
## Resampling: Cross-Validated (5 fold)
## Summary of sample sizes: 11775, 11775, 11775, 11773, 11774
## Resampling results across tuning parameters:
##
##  k  Accuracy  Kappa
##  1  0.9866830  0.9831547
##  2  0.9730263  0.9658804
##  5  0.9574676  0.9461943
##
## Accuracy was used to select the optimal model using  the largest value.
## The final value used for the model was k = 1.

The best result is achieved for k=1, with an accuracy of 98.66%

```

naive Bayes

```

library("naivebayes")
library("fastICA")
tuneGrid <- expand.grid(fL = c(0,0.5,1),
                        usekernel = c(TRUE,FALSE),
                        adjust=c(TRUE,FALSE))

set.seed(32343)
modelFit <- train(classe ~. ,data=training, method="naive_bayes",
                  trControl = fitControl, tuneGrid=tuneGrid)
modelFit

## Naive Bayes
##
## 14718 samples
##    53 predictor
##    5 classes: 'A', 'B', 'C', 'D', 'E'
##
## No pre-processing
## Resampling: Cross-Validated (5 fold)
## Summary of sample sizes: 11775, 11775, 11775, 11773, 11774
## Resampling results across tuning parameters:
##
##  fL  usekernel  adjust  Accuracy  Kappa
##  0.0 FALSE      FALSE   0.4888584  0.3684171
##  0.0 FALSE      TRUE    0.4888584  0.3684171
##  0.0 TRUE       FALSE   0.7363102  0.6627087
##  0.0 TRUE       TRUE    0.7363102  0.6627087
##  0.5 FALSE      FALSE   0.4888584  0.3684171

```

```
## 0.5 FALSE TRUE 0.4888584 0.3684171
## 0.5 TRUE FALSE 0.7363102 0.6627087
## 0.5 TRUE TRUE 0.7363102 0.6627087
## 1.0 FALSE FALSE 0.4888584 0.3684171
## 1.0 FALSE TRUE 0.4888584 0.3684171
## 1.0 TRUE FALSE 0.7363102 0.6627087
## 1.0 TRUE TRUE 0.7363102 0.6627087
##
## Accuracy was used to select the optimal model using the largest value.
## The final values used for the model were fL = 0, usekernel = TRUE
## and adjust = FALSE.
```

The best result is an accuracy of 73.6%

random Forest

```
library("randomForest")
rfGrid <- expand.grid(mtry = 7)
set.seed(32343)
model <- train(classe~., data=training, trControl=fitControl, method="rf",
               tuneGrid=rfGrid, ntree=100)
model
```

```
## Random Forest
##
## 14718 samples
## 53 predictor
## 5 classes: 'A', 'B', 'C', 'D', 'E'
##
## No pre-processing
## Resampling: Cross-Validated (5 fold)
## Summary of sample sizes: 11775, 11775, 11775, 11773, 11774
## Resampling results:
##
## Accuracy Kappa
## 0.99307 0.9912331
##
## Tuning parameter 'mtry' was held constant at a value of 7
```

```
model$finalModel
```

```
##
## Call:
## randomForest(x = x, y = y, ntree = 100, mtry = param$mtry)
## Type of random forest: classification
## Number of trees: 100
## No. of variables tried at each split: 7
##
## OOB estimate of error rate: 0.62%
## Confusion matrix:
## A B C D E class.error
## A 4182 1 1 1 0 0.0007168459
## B 14 2827 7 0 0 0.0073735955
## C 1 23 2540 3 0 0.0105181145
```

```
## D    0    0   27 2382    3 0.0124378109
## E    0    0    2    8 2696 0.0036954915
```

Accuracy is predicted at 99.31%, for an out of bag error estimate of 0.62%. This is our best model, let's double-check its accuracy on our test set

```
predictions <- predict.train(model,newdata=testing[,1:53])
confusionMatrix(predictions,testing$classe)
```

```
## Confusion Matrix and Statistics
```

```
##
```

```
##           Reference
```

```
## Prediction    A    B    C    D    E
##           A 1392    3    0    0    0
##           B    2   943    9    0    0
##           C    0    3   846   11    2
##           D    0    0    0   793    3
##           E    1    0    0    0   896
```

```
##
```

```
## Overall Statistics
```

```
##
```

```
##           Accuracy : 0.9931
##           95% CI : (0.9903, 0.9952)
##           No Information Rate : 0.2845
##           P-Value [Acc > NIR] : < 2.2e-16
```

```
##
```

```
##           Kappa : 0.9912
```

```
## Mcnemar's Test P-Value : NA
```

```
##
```

```
## Statistics by Class:
```

```
##
```

```
##           Class: A Class: B Class: C Class: D Class: E
## Sensitivity      0.9978  0.9937  0.9895  0.9863  0.9945
## Specificity      0.9991  0.9972  0.9960  0.9993  0.9998
## Pos Pred Value   0.9978  0.9885  0.9814  0.9962  0.9989
## Neg Pred Value   0.9991  0.9985  0.9978  0.9973  0.9988
## Prevalence       0.2845  0.1935  0.1743  0.1639  0.1837
## Detection Rate   0.2838  0.1923  0.1725  0.1617  0.1827
## Detection Prevalence 0.2845  0.1945  0.1758  0.1623  0.1829
## Balanced Accuracy 0.9985  0.9954  0.9928  0.9928  0.9971
```

The results for the test set are consistent with the cross-validation, we now apply our model to the second set and create our submission.

```
submission <- predict.train(model,newdata=test2)
submission
```

```
## [1] B A B A A E D B A A B C B A E E A B B B
```

```
## Levels: A B C D E
```