Approximate Computing and Data Analysis

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Introduction

- Sometimes, computing the best possible output of some algorithm requires a significant amount of resources
- For some applications, the best possible output is not actually needed, since minor degradations will possibly not even be recognized by users.
- This can be exploited in a resource-constrained environment in order to trade-off the quality of the output against resources.
- A certain deviation of the actual output is accepted, for example, for lossy audio, video and image encoding.







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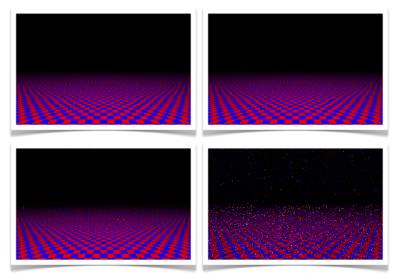
This leads us to consider approximate computing







An Example



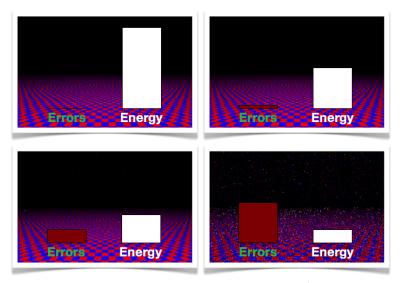






slides from Sampson et al. 2013.

An Example

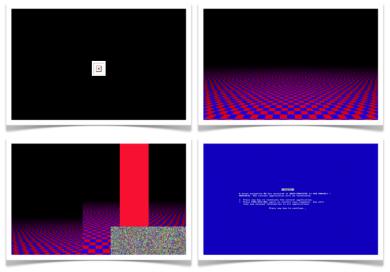








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According to, Mittal, S.: "A survey of techniques for approximate computing." ACM Comput. Surv. 48(4), 62:1-62:33 (2016).

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It is essential to compare the best possible output (real) values x_1 , x_2 , ..., x_n with the approximated output (signal) values y_1 , y_2 , ..., y_n , for n samples.







Possible Metrics to Compare \vec{x} and \vec{y}

Definition

The Mean-Squared Error (MSE) is defined as

$$MSE(\vec{x}, \vec{y}) = \frac{1}{n} \sum_{i=1}^{n} (x_i - y_i)^2$$



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Definition

The Root-Mean-Squared Error (RMSE) is defined as

$$RMSE(\vec{x}, \vec{y}) = \sqrt{\frac{1}{n} \sum_{i=1}^{n} (x_i - y_i)^2}$$





Possible Metrics to Compare \vec{x} and \vec{y} (cont.)

Definition

The Mean-Absolute Error (MAE) is defined as

$$MAE(\vec{x}, \vec{y}) = \frac{1}{n} \sum_{i=1}^{n} |x_i - y_i|$$

For identical deviations of the measured signal y from real values x, the MAE is equal to the RMSE. However, the RMSE emphasizes large deviations between real and measured values (so-called outliers).







Peak Signal to Noise Ratio

Definition

The Peak-Signal-to-Noise Ratio (PSNR) is defined as

$$PSNR(\vec{x}, \vec{y}) = 10 \log_{10} \left(\frac{x_{max}^2}{MSE(x, y)} \right) = 20 \log_{10} \left(\frac{x_{max}}{RMSE(x, y)} \right)$$

where x_{max} is defined as the $\max_{i=1}^{n} x_i$



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- There are several other metrics, especially for images
- None of these metrics is really superior to others
- Several of these metrics should be computed and a careful comparison should be performed







Data Analysis in Approximating Computing

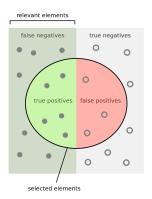
- For data analysis, classification of objects is a frequent goal
- Suppose that we restrict ourselves to binary classification
- Four cases are possible
 - True positives (TP): we classify some object as a cat and it is actually a cat
 - False positives (FP): we classify some object as a cat and it is not a cat
 - True negatives (TN): we classify some object as not a cat and it is actually not a cat
 - False negatives (FN): we classify some object as not a cat and it is actually a cat.







Precision and Recall





Definition

The precision is defined as

True Positives

True Positives + False Positives

Definition

The recall is defined as

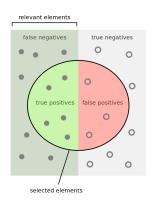
True Positives

True Positives + False Negatives





Precision and Recall





Definition

The precision is defined as

True Positives

True Positives + False Positives

Definition

The recall is defined as

True Positives

True Positives + False Negatives

Definition

The F1 score or F-measure is defined as the harmonic mean of precision and recall







Accuracy and Specificity

Definition

The accuracy is defined

True Positives + False Positives + True Negatives + False Negatives

Definition

The specificity is defined

True Negatives

False Positives + True Negatives







Approximate Computing: Some Examples

- Qualifiers of data types
 - @approx int a := ...; @precise int p := ...;
- Variable a is not accurate and variable p is accurate
- Statements
 - p := a; (this is problematic)
 - a := p; (this is okay)
- Approximate Conditions

```
if (a = 10) { p :=2;} (this can be problematic, approximate bool)
```





Controlling Approximation

- Approximate should not interfere with precise
- Semantically, approximate results are unspecified best effort
- Only higher levels can measure quality, but application specific
- Lower (hardware or system software) levels can make monitoring convenient
- Offline: Profile, auto-tune
- Online: React, i.e., recompute or decrease the approximation level





Approximation-aware ISA

An example (in MIPS ISA):

```
lw r1, 0x04($0)
lw r2, 0x08($0)
add r3, r1, r2
sw r3, 0x0c($0)
```

An example (in Approximate MIPS ISA):

```
lw r1, 0x04($0)
lw r2, 0x08($0)
add.a r3, r1, r2
sw.a r3, 0x0c($0)
```

 add.a and sw.a need approximate ALU and approximate storage, respectively.



Floating-Point to Fixed-Point Conversion

- Pros:
 - Lower cost
 - Faster
 - Lower power consumption
 - Sufficient SNR, if properly used
 - Suitable for portable applications
- Cons:
 - Decreased dynamic range
 - Finite word-length effect, unless properly scaled
 - · Overflow and excessive quantization noise
 - Extra programming effort







An Example: ADPCM

