

# 19. Vectors & Templates

vector: create  
 copy: asgt & init  
 release mem  
 access `[]`

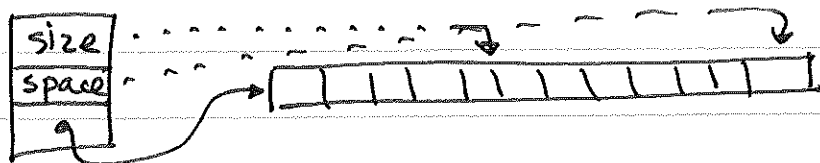
C++  
 move ctor  
~~no op~~  
 move op =

more: change nr elements  
 report out of range  
 spec elt type

ex: `vector<double> d`  
`d.push_back(x)`  
`d.resize(n)`

alloc space - too little  $\rightarrow$  run out  
 too much  $\rightarrow$  waste memory

representation



size - amt used

space - len of array

`push_back` - usu  $O(1)$   
 - sometimes  $O(n)$

but w. doubling

amortized  $\rightarrow O(1)$  average

## 19.2.2 Reserve & capacity

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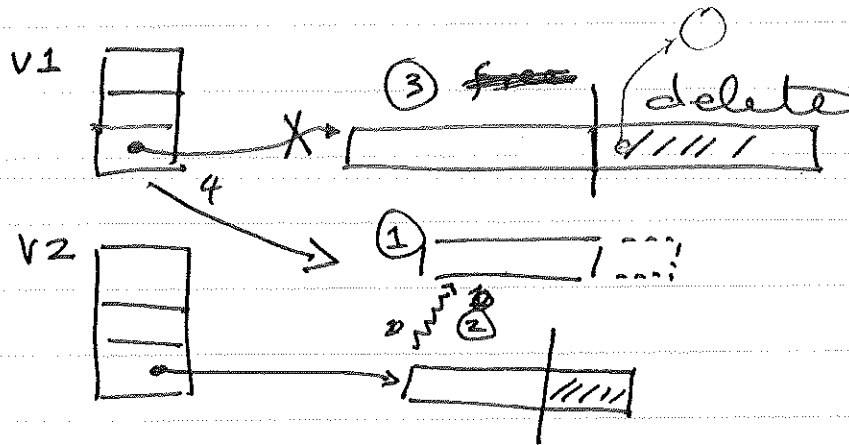
```
size_t vector::capacity() const {  
    return space  
}
```

```
void vector::reserve(size_t cap cap) {  
    if (cap <= space) return;  
    double *p = new double [cap]  
    for // loop copy elements  
    delete [] data  
    data = p  
    space = cap  
}
```

$\text{space} - \text{size} = \# \text{elems avail space}$

## 19.2.4 push-back

```
void vector::push-back(double d) {  
    if (space == 0) reserve(8)  
    else if (size == space) reserve(2 * space)  
    data[size++] = d  
}
```

19.2.5 op =

`v1 = v2;` if (this  $\neq$  that)

(1) alloc new space = size v2

(2) copy v2 elts to new alloc

(3) delete [] v1 data

(4) v1 data  $\rightarrow$  new alloc

19.3 Templates

```
template <class typename T>
class vector {
```

```
    ...
};
```

```
vector<char>
vector<double>
```

```
...
```

- no problems w. primitives

# 19.3.2 Generic Prog

- works with a variety of types

Polyimorphism — ad hoc ← conversion overloading

~~universal~~ — templates (generics)

~~objects~~ inheritance overriding

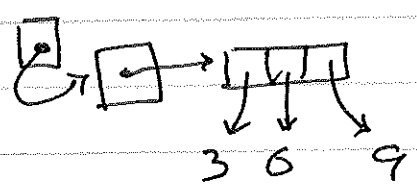
templates — static  
— compile time  
— recompilation

inheritance — dynamic  
— runtime dispatch

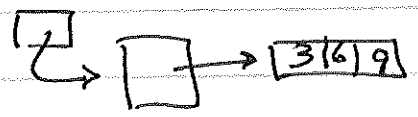
Java class — compiled once as Object  
Generic — can't have primitives  
— must use boxes like Integer

C++ template = macros.  
— can lead to code bloat  
— faster  
— uses less data space

Java



C++



### 19.3.3 Containers & Inheritance

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`vector<base*>` = OK

`vector<base>` fails due to slicing

### 19.3.4 Integer Templates

```
template <typename T, size_t N>
class array {
    T data a[N];
}
```

- useful in limited memory systems  
~~not~~ without free store
- can alloc static memory for it
- vector can't.

~~array~~

```
array<int, 10> x1;
array<double, 20> x2;
```

- not so useful for ~~comp~~ complicated objects.

## 19.3.6 Generalizing

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Problems:

- vector  $\langle X \rangle$ , but  $X$  has no default value
- elements destroyed when finished

- types w/o default:

template  $\langle$ class  $T \rangle$

void vector  $\langle T \rangle ::$  resize (size\_t  $n$ ,  $T$  def =  $T()$ ).

— use  $T()$  as default.

note  $\text{int}() == 0$

$\text{double}() == 0.0$

- uninit data

data struct has both init & uninit data

template  $\langle$ class  $T$ , class  $A = \text{allocator} \langle T \rangle \rangle$

class vector {

class allocator in STL has:

allocate } memory

deallocate

construct

destroy

} objects

19.4 Exceptions

exception (hierarchy)

bad\_alloc

bad\_cast

bad\_exception

bad\_typeid

ios\_base::failure

std::

logic\_error

domain\_error

invalid\_argument

length\_error

out\_of\_range

runtime\_error

overflow\_error

range\_error

underflow\_error

catch (exception &amp;)

- by reference to avoid slicing  
 - not by value

op[] vs at

- compatibility
- efficiency
- constraints

what about realtime prog?

- hard
- soft

## 19.5 Resources

- memory
- locks
- file handles
- thread handles
- sockets
- windows

## Resource Problems.

~~not~~ foo \*p = new foo()  
- where delete

```
void f() {
    foo *p = new foo
    ==
    if () p = q
    ==
    delete p // what obj?
}
```

if () return  
delete p  
never got here

## exception

```
void f() {
    foo *p = new
    ==
    throw exn
    ==
    delete p // never got here.
```



```

again() {
    foo *p = new...
    try {
        ≡
    } catch ( ) {
        delete p
        throw;
    }
    delete p
}

```

← re throw caught exn.

## 19.5.2 RAII

resource acquisition is initialization.

```

beller() {
    foo p; foo a;
    foo a; foo b
    ≡
}

```

{ ← frees obj's @ return or exn  
whenever ~~foo~~ go a, b exit scope

## ~~19.5.3 Guarantee~~

precondition  
postcondition  
invariant

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### 19.5.3 Guarantees

problem: alloc structs & return  
 $\therefore$  need a pointer

Basic guarantee: succeed or throw  
but no leaked resource.

Strong guarantee: all other resources  
are same after failure

No throw guarantee:

- avoid throw, new, dynamic cast.
- avoid deref  $\phi$ ,  $\div 0$ , etc.

### 19.5.4 auto\_ptr

- deprecated in C++11.

```
vector *make( ... ) {  
    auto_ptr<vector<int>> p(new vector<int>)  
    ≡  
    return p.release();  
}
```

C++ 11

shared\_ptr  
weak\_ptr  
unique\_ptr

19.5.5 ~~RAII~~  
RAII

ch 19  
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memory for vector is resource

~~allocator~~

```
template < class T > class allocator {  
    T *allocate (int n)  
    void deallocate (T *p, int n)  
    void construct (T *p, const T &v)  
    void destroy (T *p)
```