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Context Aware Data Reduction:

**Selectively Lossless Data Reduction through
Partially Synthetic Representations for
Highly Automated Driving**

Gefördert durch:



Bundesministerium
für Wirtschaft
und Energie

aufgrund eines Beschlusses
des Deutschen Bundestages

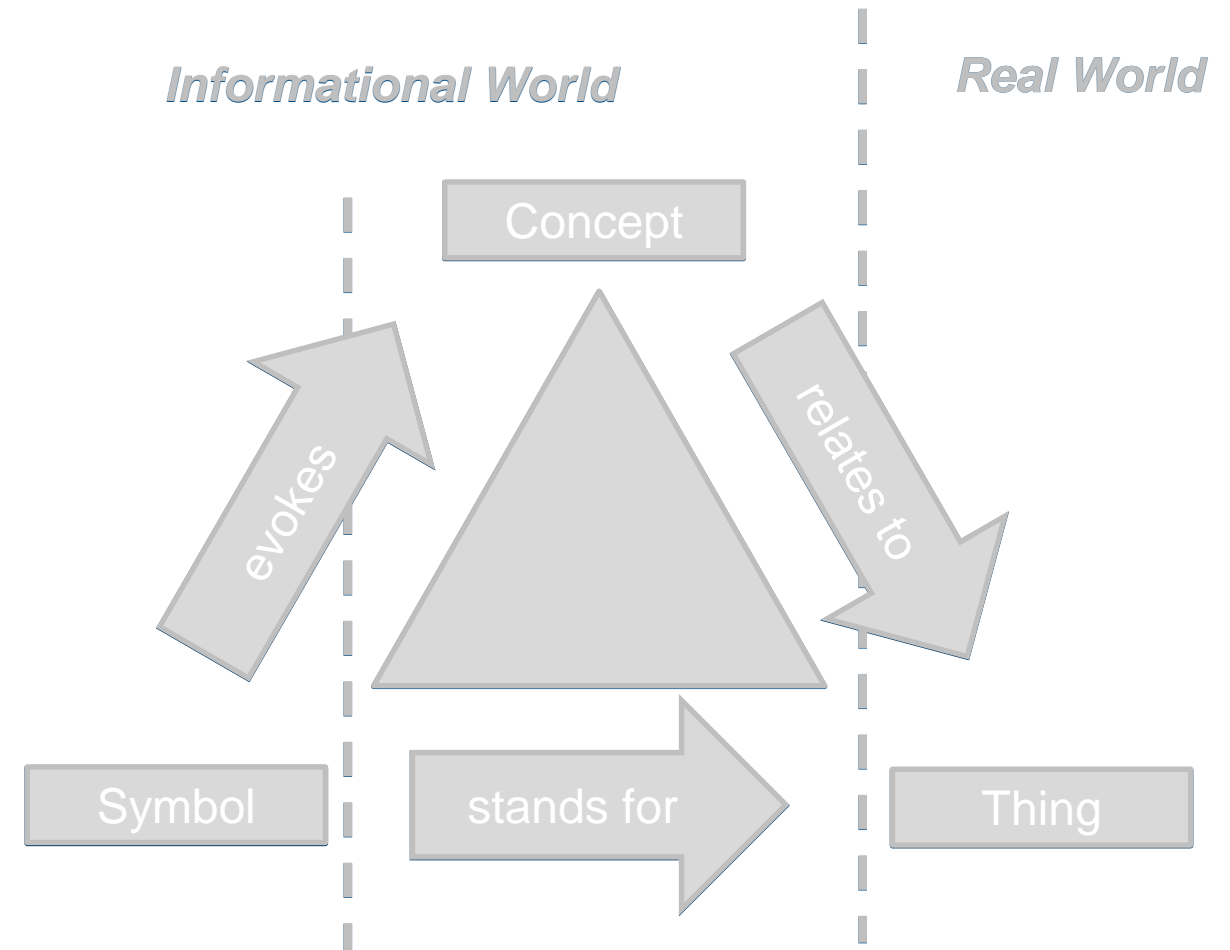
Agenda

1. Information for Highly Automated Driving
2. Data reduction
3. Components of Context Aware Data Reduction
4. Prototype
5. Outlook
6. Discussion

Information for Highly Automated Driving

What is Information?

- Describes the real world
- Can be distinguished into ¹
 - Data := stored / transferred symbols
 - Messages := stored / transferred concepts



¹ Werner, Martin: Information und Codierung, Vieweg Verlag (2002)

Illustration based on: Thomas, Oliver; Fellmann Michael, Semantische Integration von Ontologien und Ereignisgesteuerten Prozessketten

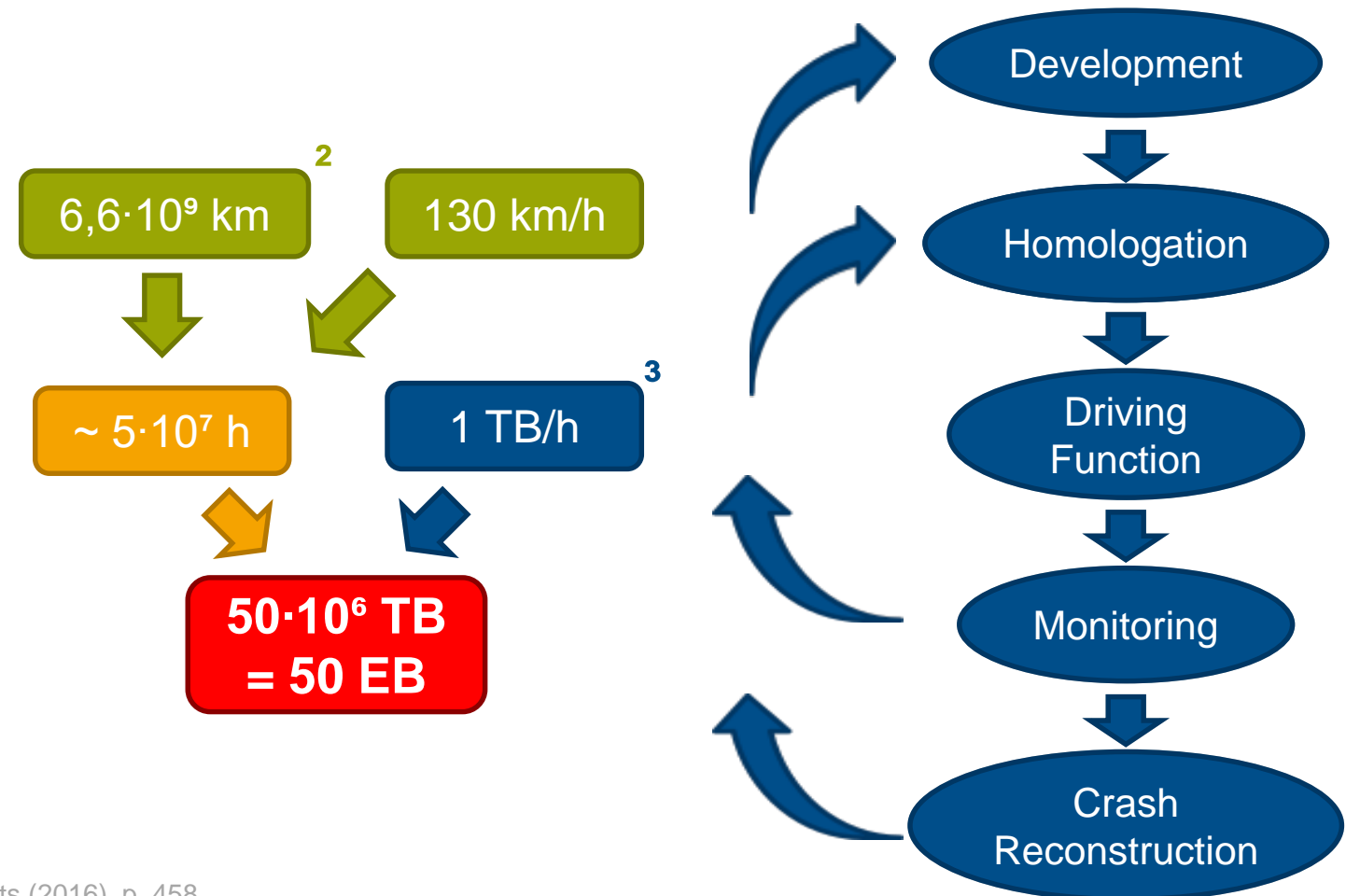
Information for Highly Automated Driving

What does Data mean for HAD?

- Present throughout the lifecycle

Why Data Reduction?

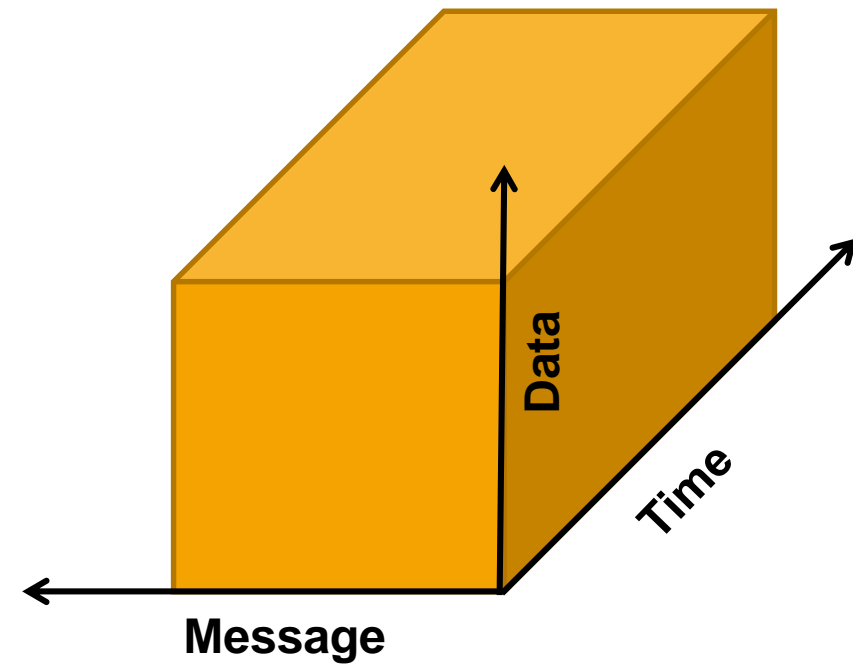
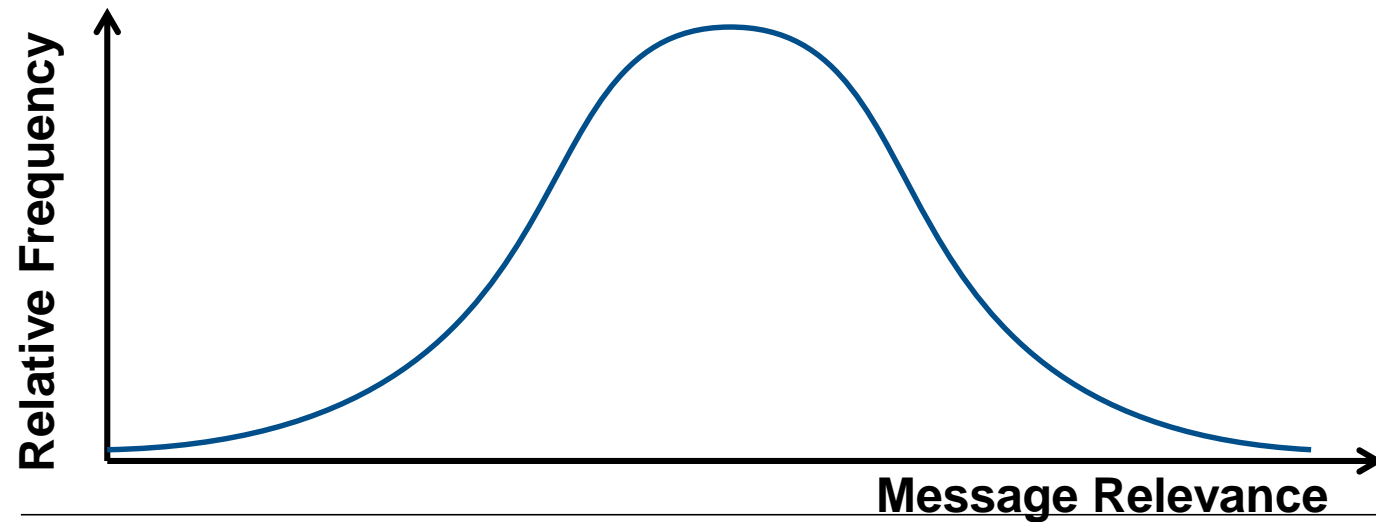
- Need for large amounts of Data
- Growing Data rates
- Scalable approaches are necessary



² Winner, H. et al.: Autonomous Driving: Technical, Legal and Social Aspects (2016), p. 458.

³ Patzer, Andreas: Data Recording for ADAS Development (2017), p. 1.

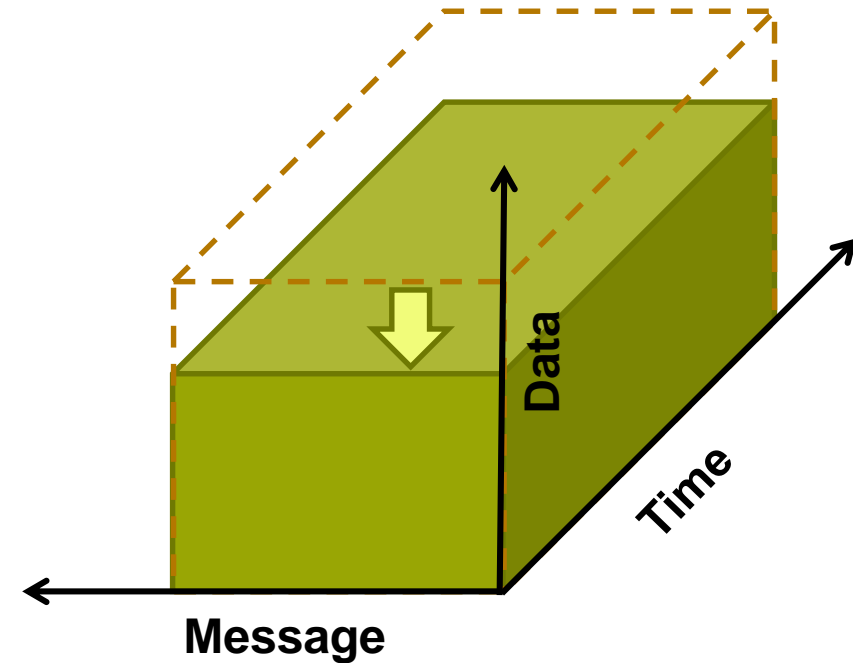
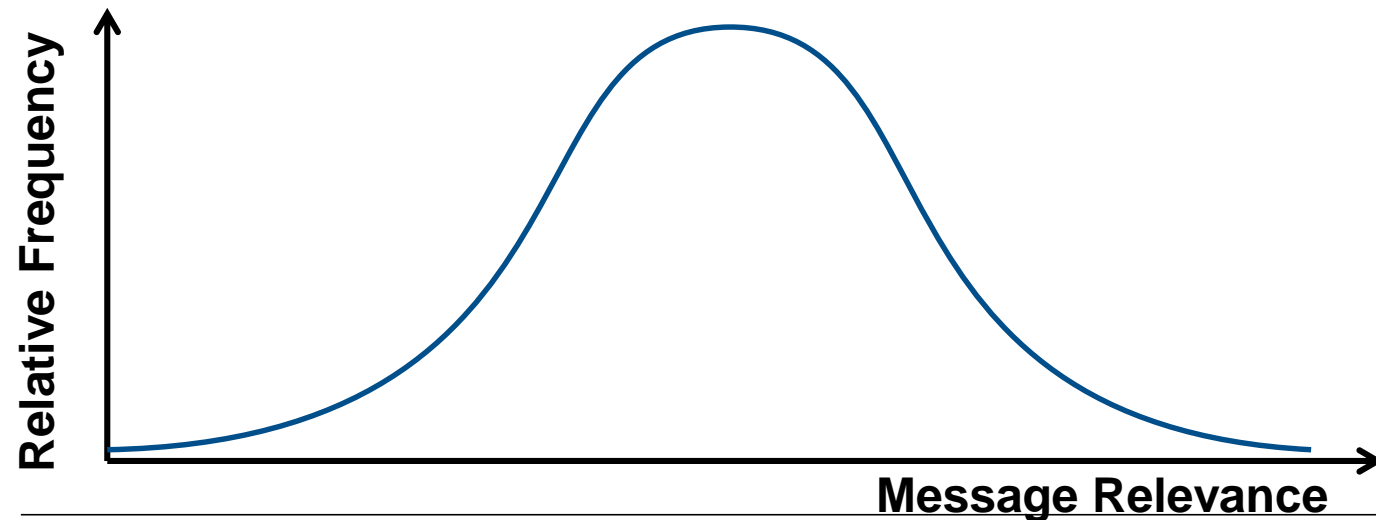
Data Reduction



Data Reduction

State of the Art

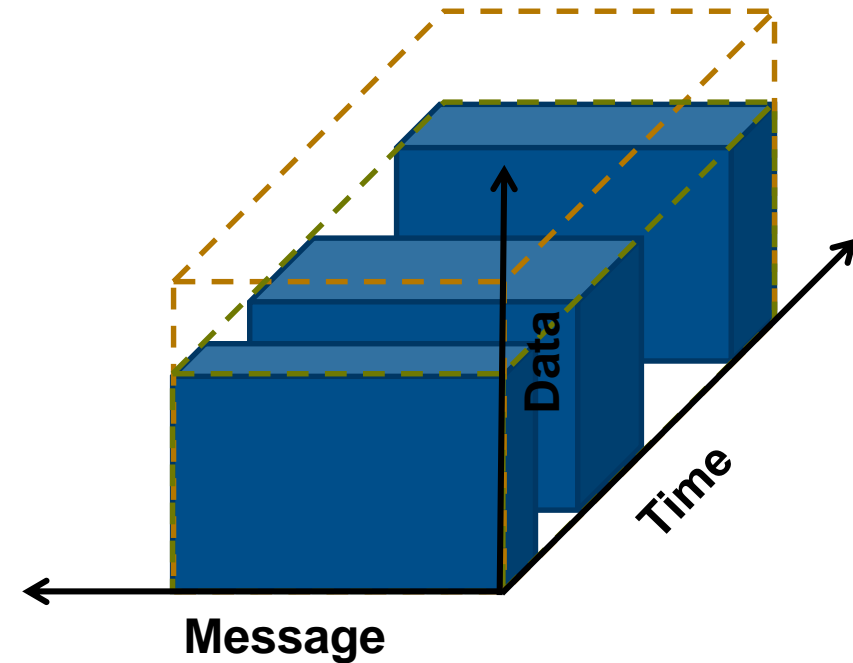
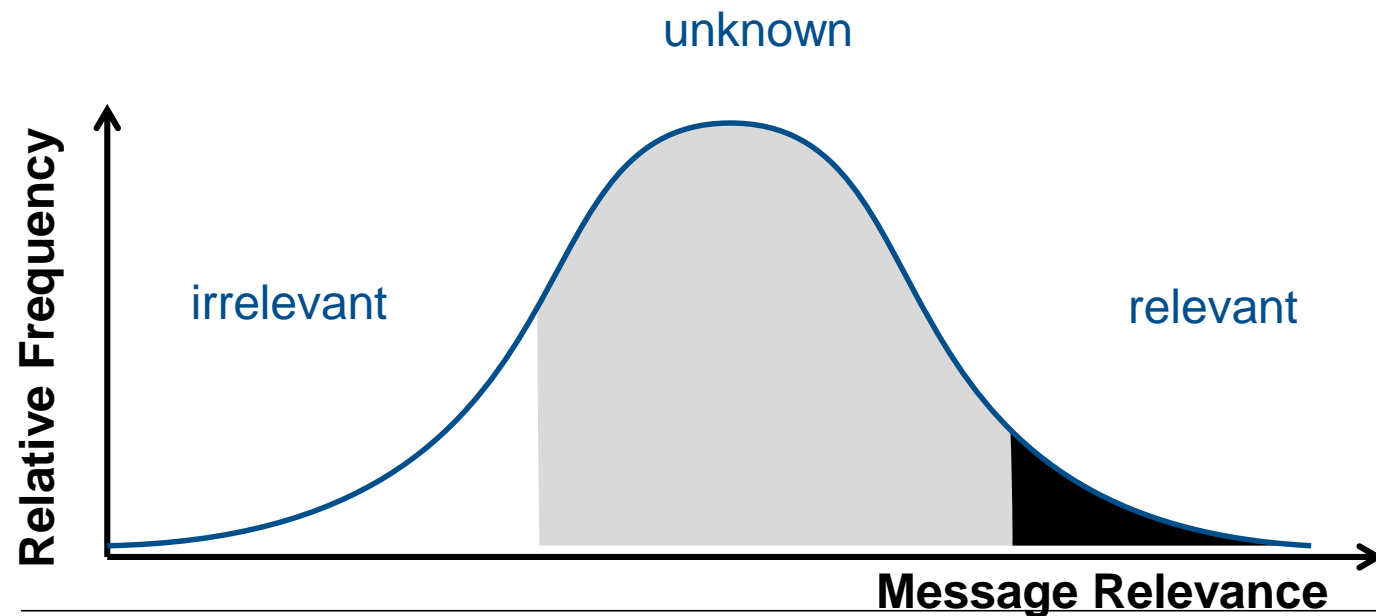
- (En-)Coding



Data Reduction

State of the Art

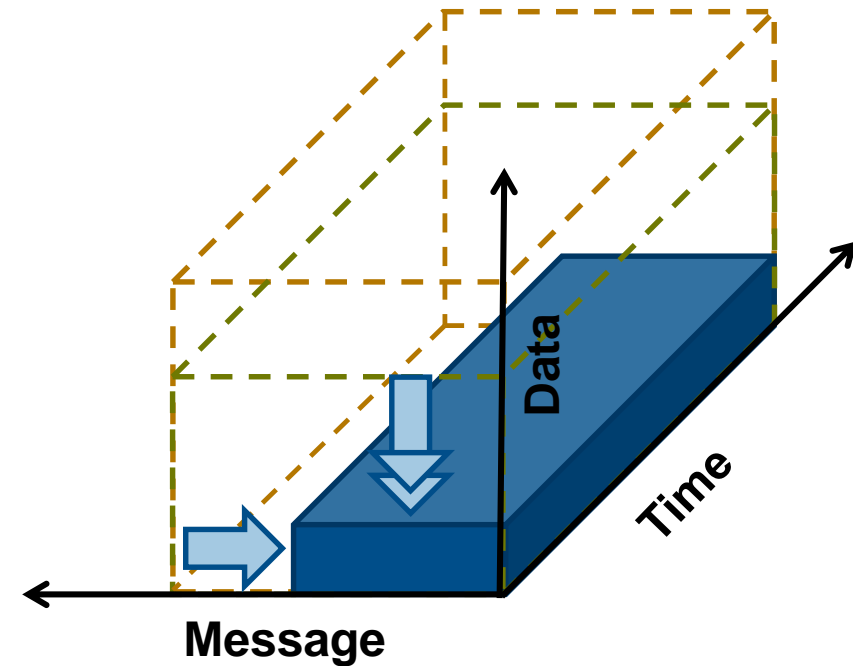
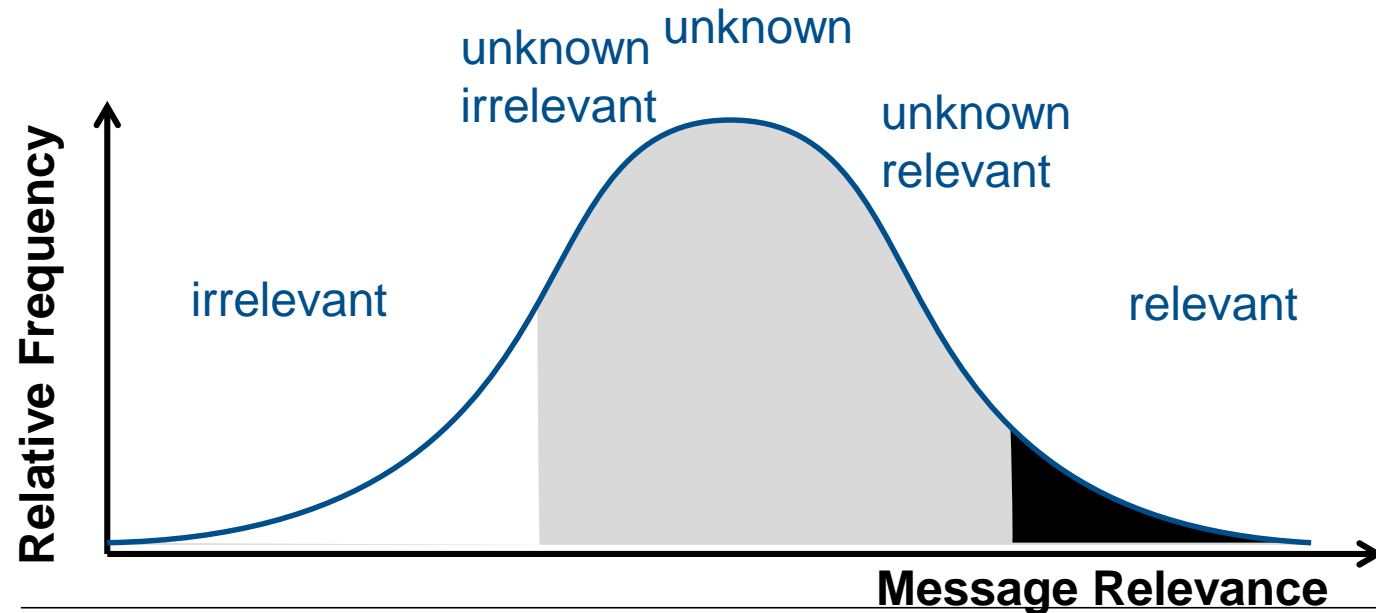
- (En-)Coding
- Selection



Data Reduction

State of the Art

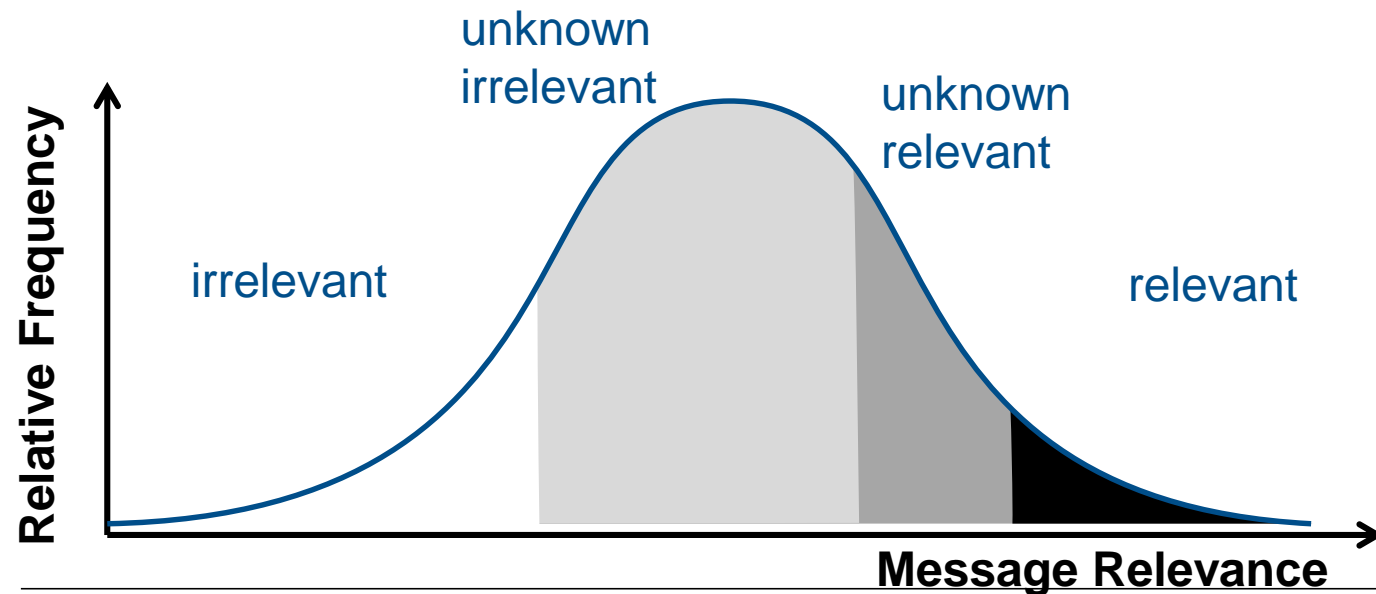
- (En-)Coding
- Selection
- Compression



Data Reduction

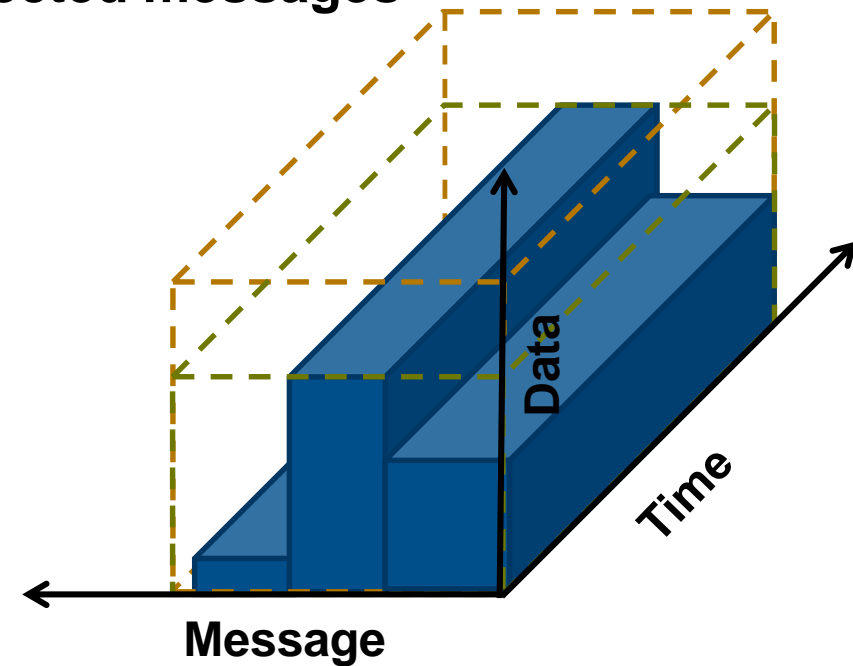
State of the Art

- (En-)Coding
- Selection
- Compression



Context Aware Data Reduction

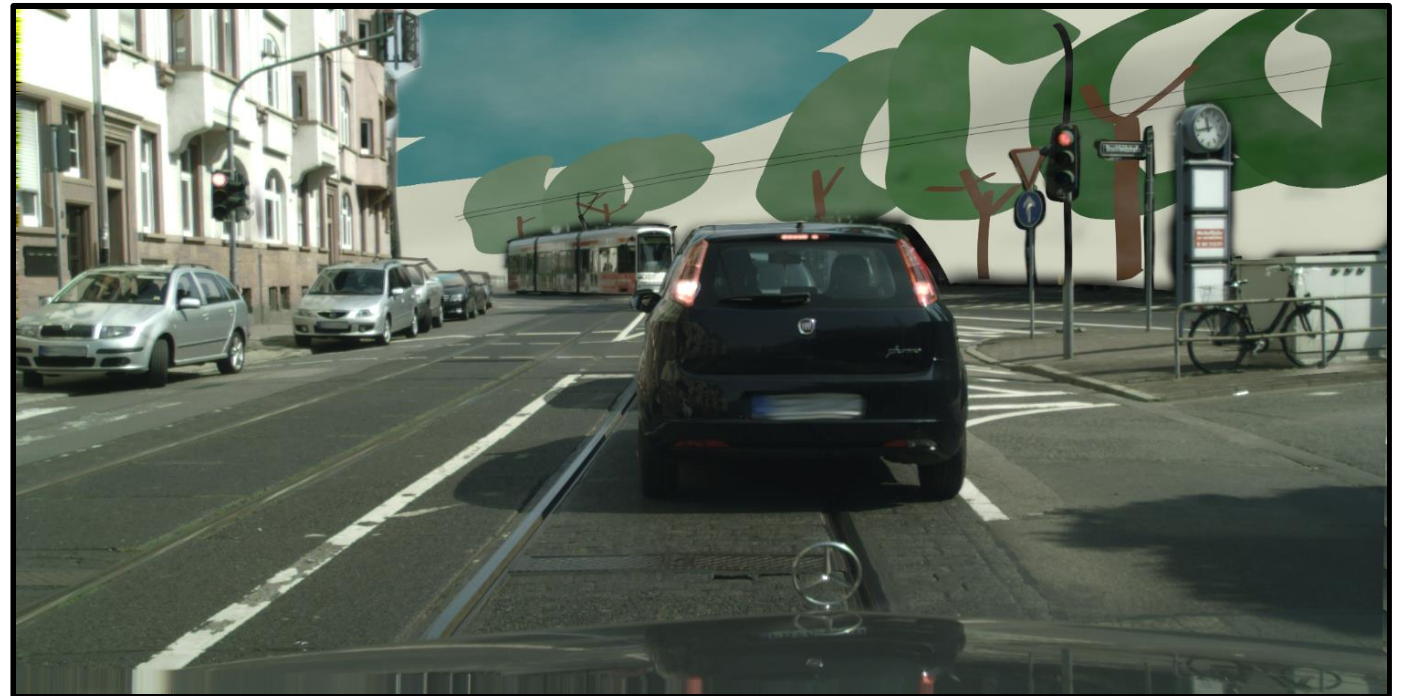
- Compression on selected messages



Components of Context Aware Data Reduction

Basic Concept

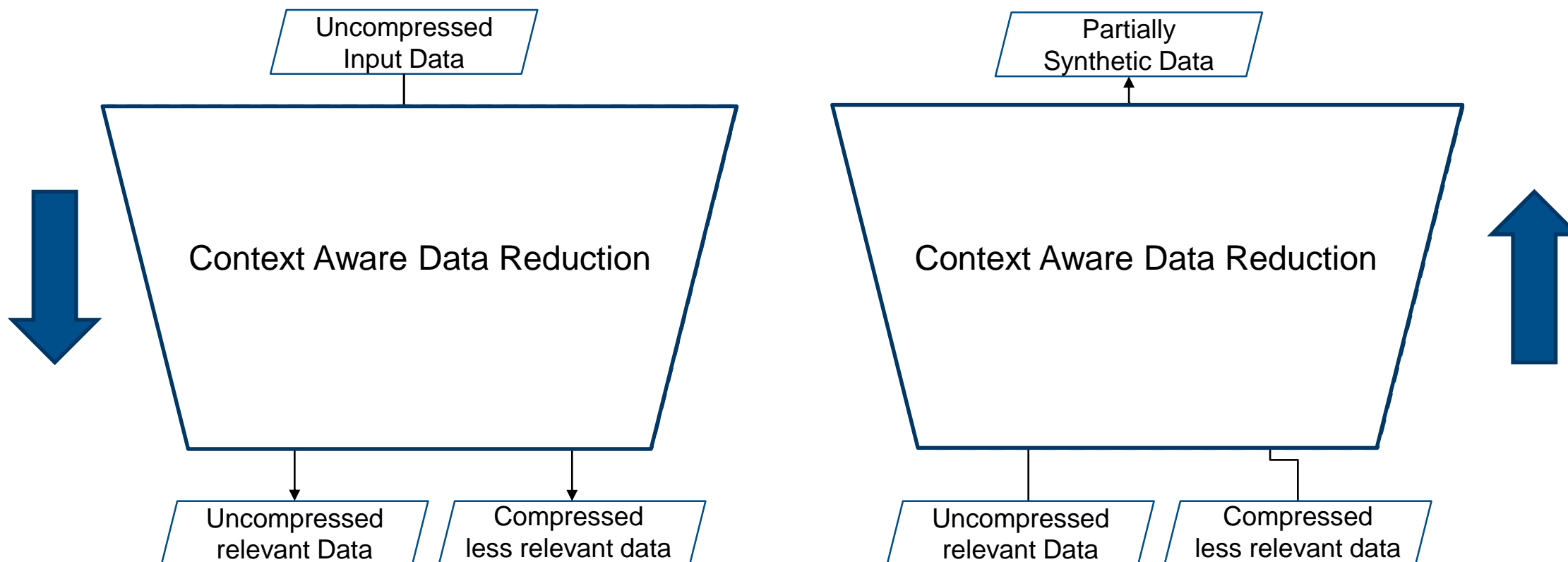
- Messages summarizes data
- Use Cases rely on messages
- Messages and data use different representations
- Relevant data:
presented as is
- Less relevant data:
presented as plausible lie



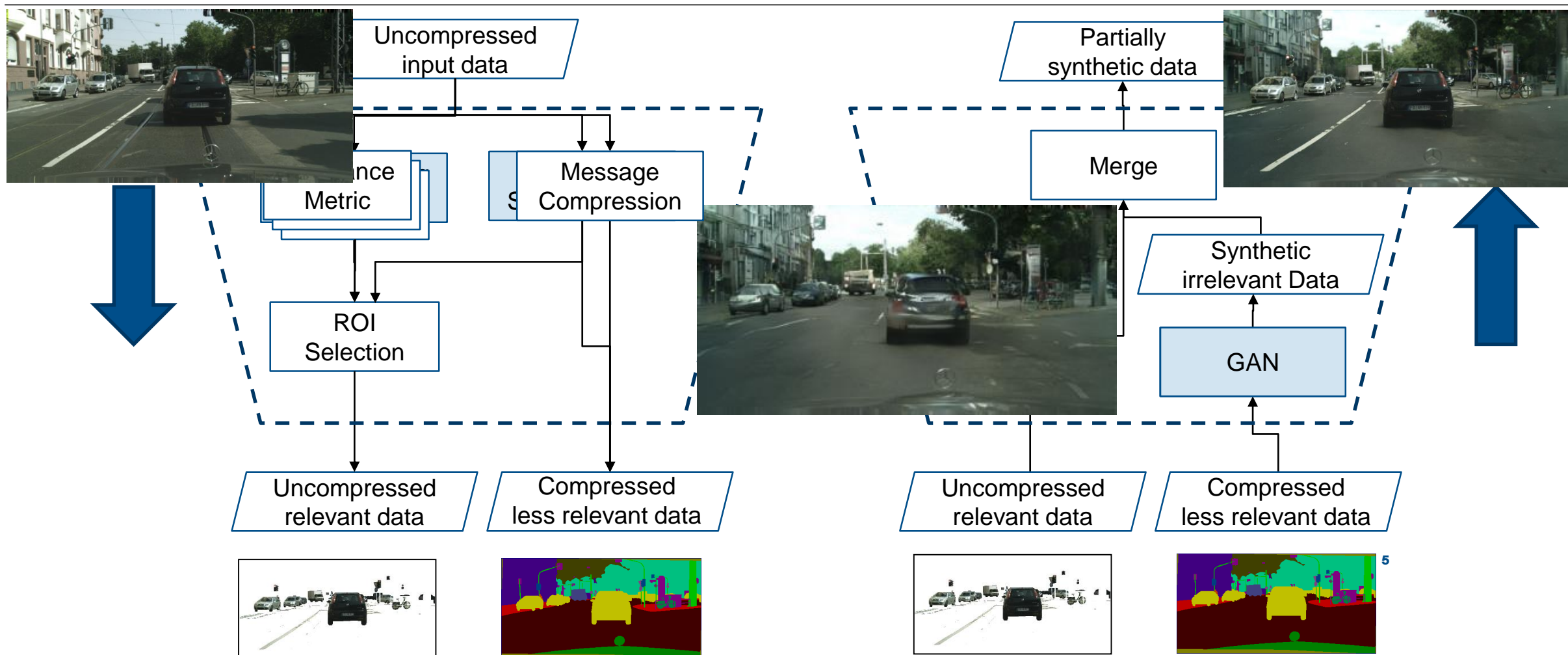
⁴ Background Image from: M. Cordts et. al, The Cityscapes Dataset for Semantic Urban Scene Understanding, in Proc. of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2016



Components of Context Aware Data Reduction



Prototype

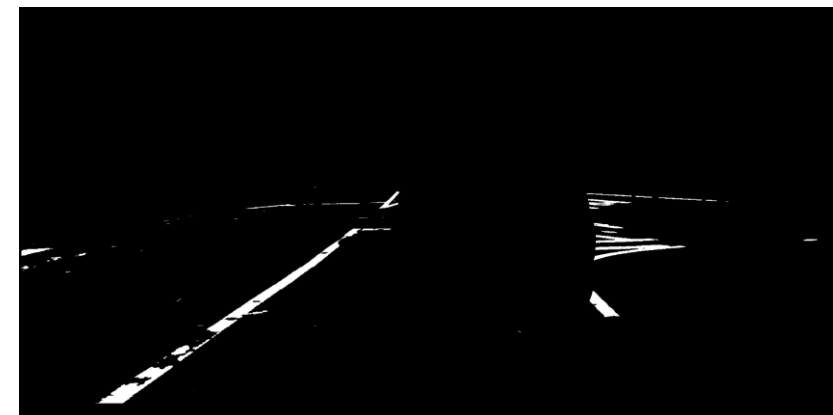
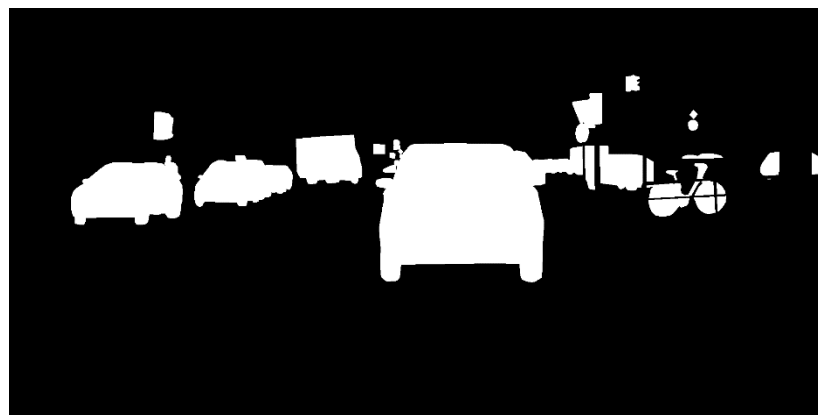


⁵ Scenario data based on: M. Cordts et. al, The Cityscapes Dataset for Semantic Urban Scene Understanding, in Proc. of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2016

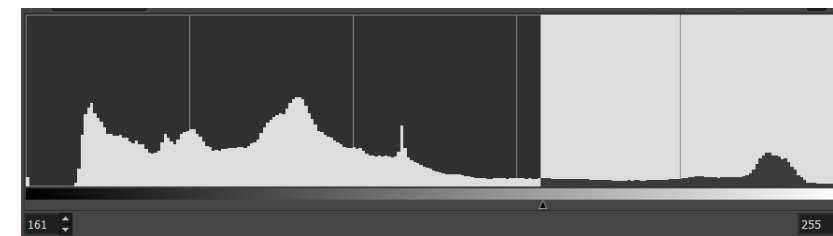
Prototype

Class based Selection

- Semantic segmentation as baseline
- Lane marking detection as additional selection



Relevant	Irrelevant
Car, Truck, Bus	Ground, Road
Caravan, Train, Trailer	Sidewalk, Parking, Rail track
Person, Rider, Motorcycle, Bicycle	Building, Wall, Fence, Guard Rail
Traffic Light, Traffic Sign	Bridge, Tunnel, Pole, PoleGroup
	Vegetation, Terrain, Sky



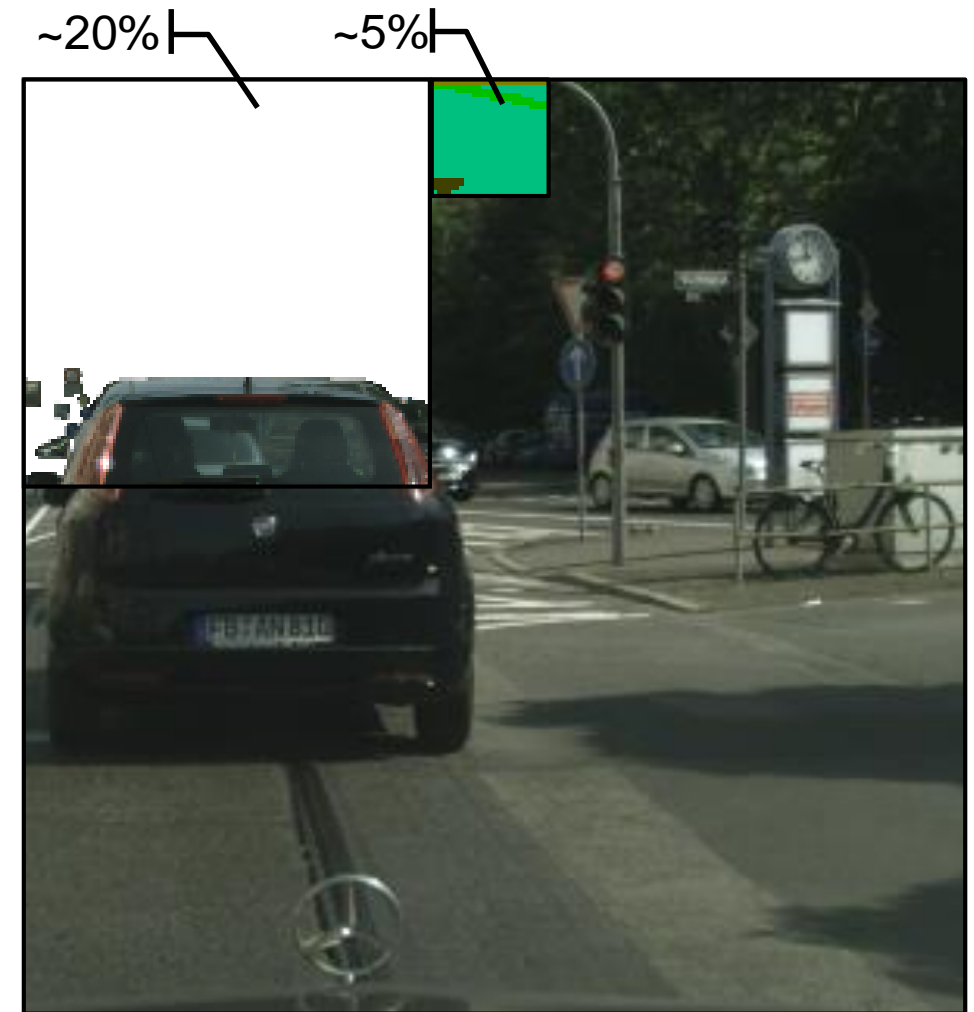
Prototype | Results

Benefits of Context Aware Data Reduction

- ~ 25% storage space needed
- Lossless storage of relevant regions
- Relies on already present algorithms in HAD

Challenges of Context Aware Data Reduction

- Exact knowledge of use case necessary
- Relevance harder to define than irrelevance



Outlook

What are the missing Pieces?

- Substantiated selection criteria

What defines relevance?

- Verification method

*How can we assure that nothing
import will be lost?*

- Application process

*How can the method be
established in an operational
environment?*

What are the next steps?

- Extend Prototype to:
 - Different selection criteria
 - Video data
 - Heterogenic sensor setups



Original Representation



TECHNISCHE
UNIVERSITÄT
DARMSTADT



Original Representation



Partially Synthetic Representation

