

Coursework Assessment

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Data Structures and Algorithms COS5021-B

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Task 01: Stack–Queue Algorithm Trace

Algorithm:

```
while
  (!stack.isEmpty(
  )) { int x =
  stack.pop(); if
  (x < 20) {
    queue.enqueue(x * 2);
  } else {
    stack.push(x - 5);
  }
}
```

Initial state:

- Stack (top → bottom): [30, 15, 25, 10]
- Queue (front → rear): []

Trace Table:

Step	Operation	Stack After Step	Queue After Step	Explanation
1	pop → x = 30 → push(25)	[25, 15, 25, 10]	[]	30 > 20 → push 30–5 = 25
2	pop → x = 25 → push(20)	[20, 15, 25, 10]	[]	25 > 20 → push 25–5 = 20
3	pop → x = 20 → push(15)	[15, 15, 25, 10]	[]	20 = 20 (still not less than 20) → push 20–5 = 15
4	pop → x = 15 → enqueue(30)	[15, 25, 10]	[30]	15 < 20 → enqueue 15×2 = 30
5	pop → x = 15 → enqueue(30)	[25, 10]	[30, 30]	15 < 20 → enqueue 30
6	pop → x = 25 → push(20)	[20, 10]	[30, 30]	25 > 20 → push 20
7	pop → x = 20 → push(15)	[15, 10]	[30, 30]	20 = 20 (still not less than 20) → push 15
8	pop → x = 15 → enqueue(30)	[10]	[30, 30, 30]	15 < 20 → enqueue 30
9	pop → x = 10 → enqueue(20)	[]	[30, 30, 30, 20]	10 < 20 → enqueue 20. Stack empty → stop.

Final state:

- Stack: []
- Queue: [30, 30, 30, 20]

Explanation - what is happening and why that change occurs:

The algorithm processes elements from the stack until it is empty. For each element popped from the stack, if it is less than 20, it is doubled and added to the queue. If it is 20 or greater, 5 is subtracted from it and pushed back onto the stack. This continues until all elements have been processed, resulting in an empty stack and a queue containing the doubled values of all elements that were less than 20.

Efficiency Analysis - Task 1 :

Time Complexity

The algorithm repeatedly subtracts 5 from any value $x \geq 20$ and pushes it back onto the stack. A value of size x may go through this process about $x/5$ times before it becomes less than 20. Therefore, processing one value takes $O(x)$ time.

If the stack has n values and the largest one is M , the worst-case total time is:

$$O(nM)$$

Space Complexity


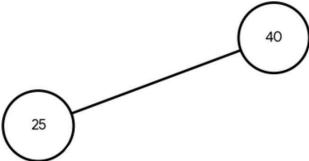
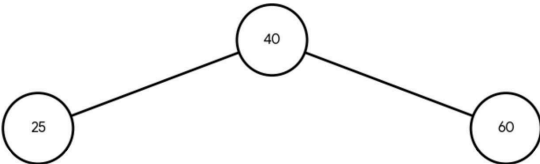
The algorithm only uses a stack, a queue, and one temporary variable. Together, they can hold at most all n elements.

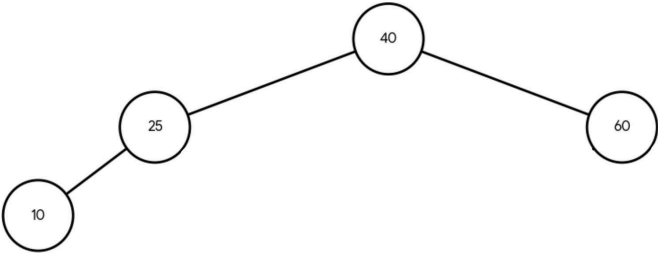
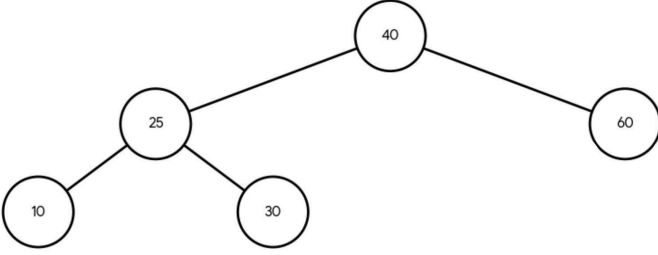
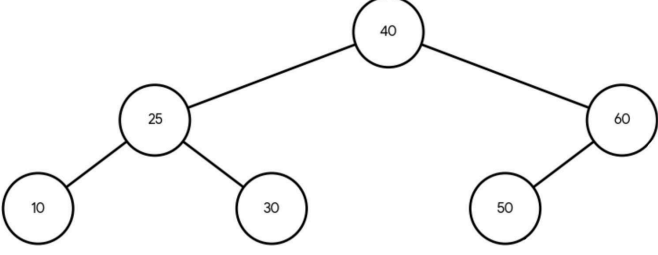
$$O(n)$$

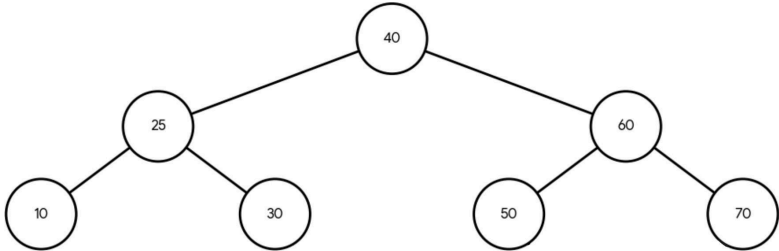
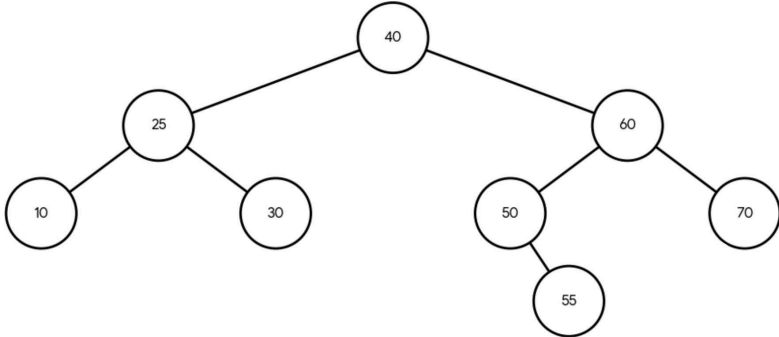
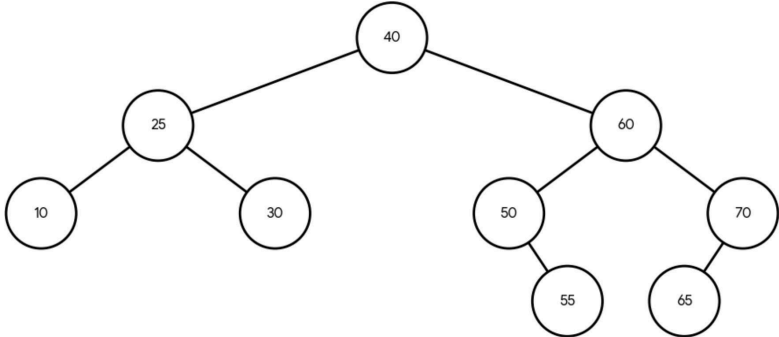
Task 02: Binary Search Tree — Deletion and Structural Reasoning

a) BST Insertion Trace

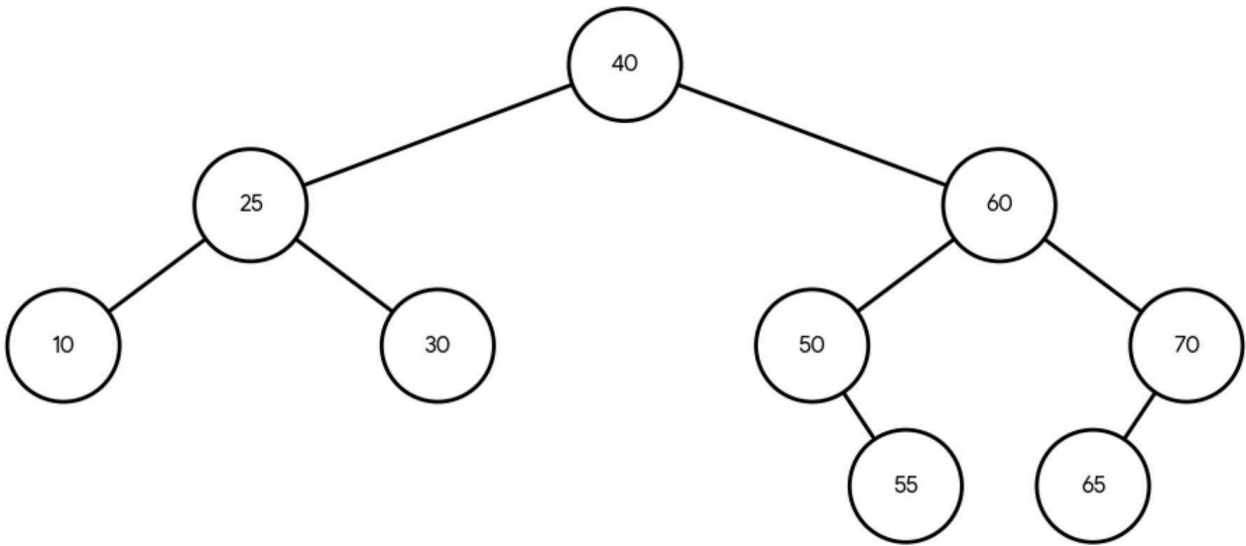
Insertion maintain the BST property by placing smaller keys to the left and larger keys to the right. For each insertion, I have compared the key to be inserted with the current node's key and decide to go left or right until I find an appropriate null position.

Step	Key Inserted	BST After Insertion	Explanation
1	40		Tree was empty, so 40 becomes the root node.
2	25		$25 < 40$, so it is inserted as the left child of 40.
3	60		$60 > 40$, so it is inserted as the right child of 40.

Step	Key Inserted	BST After Insertion	Explanation
4	10	 <pre>graph TD; 40((40)) --- 25((25)); 40 --- 60((60)); 25 --- 10((10));</pre>	$10 < 40 \rightarrow$ go left; $10 < 25 \rightarrow$ go left again; inserted as left child of 25.
5	30	 <pre>graph TD; 40((40)) --- 25((25)); 40 --- 60((60)); 25 --- 10((10)); 25 --- 30((30));</pre>	$30 < 40 \rightarrow$ go left; $30 > 25 \rightarrow$ go right; inserted as right child of 25.
6	50	 <pre>graph TD; 40((40)) --- 25((25)); 40 --- 60((60)); 25 --- 10((10)); 25 --- 30((30)); 60 --- 50((50));</pre>	$50 > 40 \rightarrow$ go right; $50 < 60 \rightarrow$ go left; inserted as left child of 60.

Step	Key Inserted	BST After Insertion	Explanation
7	70	 <pre> graph TD 40((40)) --- 25((25)) 40 --- 60((60)) 25 --- 10((10)) 25 --- 30((30)) 60 --- 50((50)) 60 --- 70((70)) </pre>	<p>$70 > 40 \rightarrow \text{right}$; $70 > 60 \rightarrow \text{right}$; inserted as right child of 60.</p>
8	55	 <pre> graph TD 40((40)) --- 25((25)) 40 --- 60((60)) 25 --- 10((10)) 25 --- 30((30)) 60 --- 50((50)) 60 --- 70((70)) 50 --- 55((55)) </pre>	<p>$55 > 40 \rightarrow \text{right}$; $55 < 60 \rightarrow \text{left}$; $55 > 50 \rightarrow \text{right}$; inserted as right child of 50.</p>
9	65	 <pre> graph TD 40((40)) --- 25((25)) 40 --- 60((60)) 25 --- 10((10)) 25 --- 30((30)) 60 --- 50((50)) 60 --- 70((70)) 50 --- 55((55)) 70 --- 65((65)) </pre>	<p>$65 > 40 \rightarrow \text{right}$; $65 > 60 \rightarrow \text{right}$; $65 < 70 \rightarrow \text{left}$; inserted as left child of 70.</p>

b) Final BST With All Nodes Inserted



c) Node Annotations (Height + Number of Children)

Height definition: Distance from a node up to the furthest leaf.
Leaf nodes → height = 0

Node	Height	Children Count	Explanation
10	0	0	Leaf
30	0	0	Leaf
55	0	0	Leaf
65	0	0	Leaf
25	1	2	Children = 10, 30
50	1	1	Only child = 55
70	1	1	Only child = 65
60	2	2	Children = 50, 70
40	3	2	Children = 25, 60

d) In-Order Traversal

(Left → Node → Right)

The in-order traversal in BST produces sorted order of

elements! **Step-by-step explanation**

1. Visit **left subtree of 40**
2. Visit **left subtree of 25 → 10**
3. Visit **25**
4. Visit **right subtree of 25 → 30**
5. Visit **40**
6. Visit **left subtree of 60 → 50 → 55**
7. Visit **60**
8. Visit **right subtree of 60 → 70 → 65**

Final In-Order Output

[10, 25, 30, 40, 50, 55, 60, 65, 70]

e) Pre-Order Traversal

(Node → Left → Right) (Top-down

approach) **Step-by-step explanation**

1. Visit **40**
2. Visit **left subtree of 40 → 25**
3. Visit **left subtree of 25 → 10**
4. Visit **right subtree of 25 → 30**
5. Visit **right subtree of 40 → 60**
6. Visit **left subtree of 60 → 50 → 55**
7. Visit **right subtree of 60 → 70 → 65**

Final Pre-Order Output

[40, 25, 10, 30, 60, 50, 55, 70, 65]

f) Delete Node = 60

To delete a node with two children (like 60), I find its in-order successor (the smallest node in its right subtree), which is 65. I replace 60 with 65 and then delete the original 65 node.

Step by step explanation:

Node 60 has two children → Case 3.

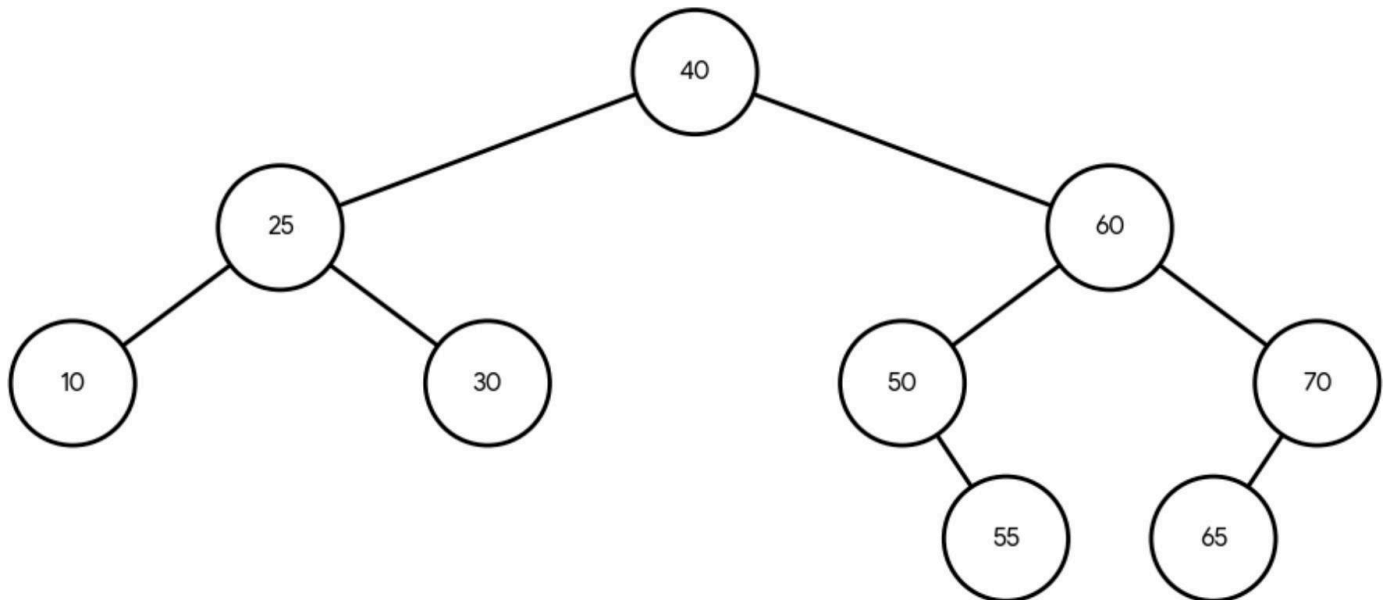
1. Find the in-order successor

- Successor = smallest value in right
- Subtree Right subtree of 60 = {70, 65}
- Smallest = 65

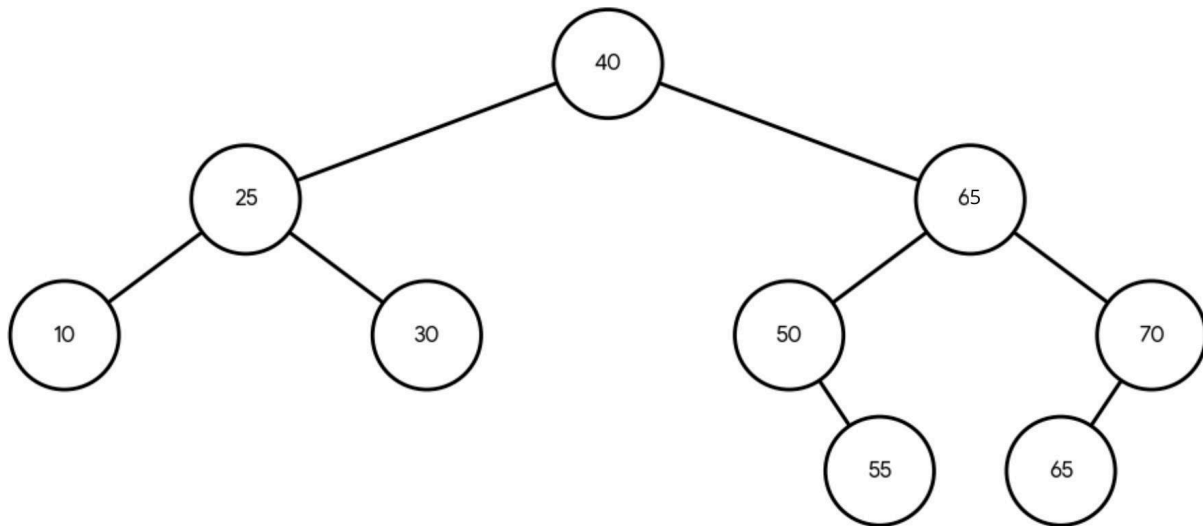
2. Replace 60 with 65

3. Delete the original node 65 from the right subtree (case 1: leaf node)

Before deletion:

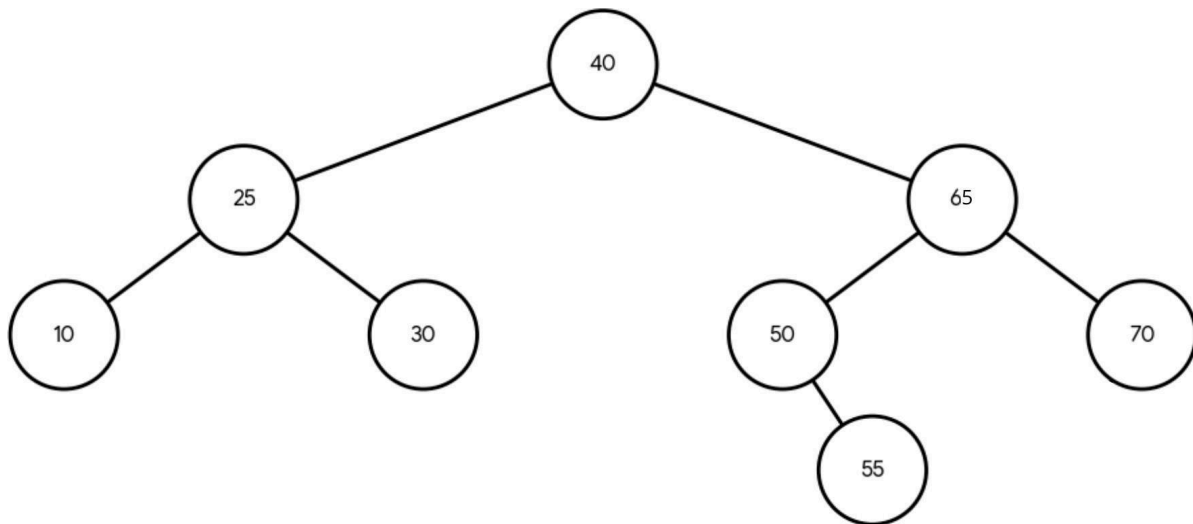


After replacement of 60 with 65:



After removing the original 65:

Final tree after deletion:



Efficiency Analysis - Task 2:

The cost of BST operations depends on the tree height (h).

- **Search & Insertion** — $O(h)$

Move down one branch from the root to a leaf.

In a balanced tree, $h \approx \log n$.

In the worst case (skewed), $h = n$.

For this tree, $n = 9$ and $h = 3$, so operations behave close to $O(\log n)$.

- **Deletion** — $O(h)$

Deleting 60 required finding the node, finding the successor, and removing it.

All of this follows at most one or two downward paths \rightarrow still $O(h)$.

With this height 3 tree, this is effectively logarithmic.

- **Traversals** — $\Theta(n)$

In-order and pre-order visit each node exactly once, so they always take linear time.

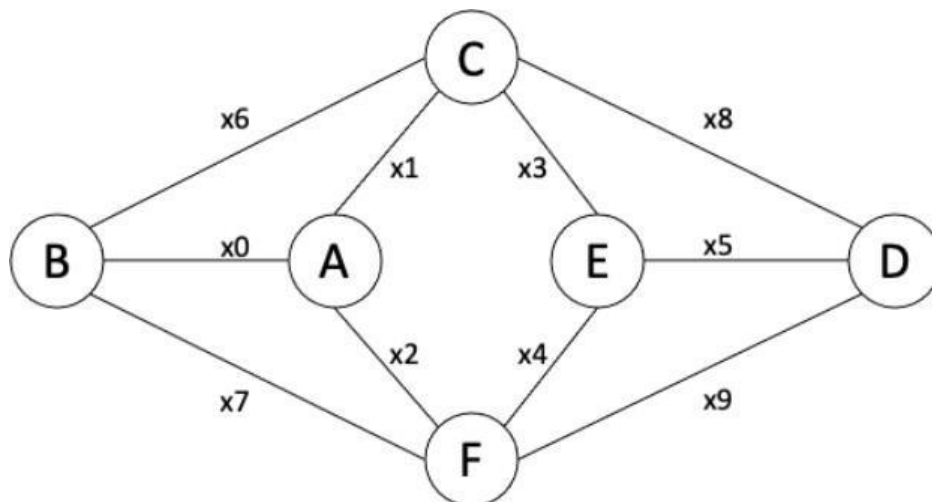
Summary:

Search, insertion, and deletion run in $O(h)$, which is $O(\log n)$ for balanced trees and $O(n)$ in the worst case. Traversals always run in $\Theta(n)$.

Task 03: Dijkstra's algorithm

The Dijkstra's algorithm finds the shortest path from a starting node to all other nodes in a weighted graph with non-negative edge weights.

I am using set S to track visited nodes with known shortest distances, and set Q for unvisited nodes with tentative distances.



The edge weights are given by:

Key = [74,7,84,90,94,81,99,48,17,36]

$x_0 = 74$ (A–B)

$x_1 = 7$ (A–C)

$x_2 = 84$ (A–F)

$x_3 = 90$ (C–E)

$x_4 = 94$ (F–E)

$x_5 = 81$ (D–E)

$x_6 = 99$ (C–B)

$x_7 = 48$ (B–F)

$x_8 = 17$ (C–D)

$x_9 = 36$ (D–F)

STEP 1: Visit A

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	No	A
C	7	No	A
D	∞	No	–
E	∞	No	–
F	84	No	A

From A (distance 0):

- B: $\text{new} = 0 + 74 = 74 \rightarrow \text{update}$
- C: $\text{new} = 0 + 7 = 7 \rightarrow \text{update}$
- F: $\text{new} = 0 + 84 = 84 \rightarrow \text{update}$
- D, E: no direct edges \rightarrow ignored

Sets

- $S = \{ A(0) \}$
- $Q = \{ C(7), B(74), F(84), D(\infty), E(\infty) \}$

STEP 2: Visit C

- The distances are updated based on the neighbors of C. The new values are calculated from the distance to C (7) plus the edge weights to its neighbors. Weights bigger than the current known distances are ignored (as node B).

From C (distance 7):

- D:
old = ∞
new = $7 + 17 = 24 \rightarrow$ update
- E:
old = ∞
new = $7 + 90 = 97 \rightarrow$ update
- B:
old = 74
new = $7 + 99 = 106 \rightarrow 106 > 74 \rightarrow$ no update

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	No	A
C	7	Yes	A
D	24	No	C
E	97	No	C
F	84	No	A

Sets

- $S = \{ A(0), C(7) \}$
- $Q = \{ B(74), F(84), D(24), E(97) \}$

STEP 3: Visit D

- The distances are updated based on the neighbors of D. The new values are calculated from the distance to D (24) plus the edge weights to its neighbors. Weights bigger than the current known distances are ignored (as node E).

From D (distance 24):

- F:
old = 84
new = $24 + 36 = 60 \rightarrow$ update
- E:
old = 97
new = $24 + 81 = 105 \rightarrow 105 > 97 \rightarrow$ no update

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	No	A
C	7	Yes	A
D	24	Yes	C
E	97	No	C
F	60	No	D

Sets

- $S = \{ A(0), C(7), D(24) \}$
- $Q = \{ B(74), F(84), E(97) \}$

STEP 4: Visit F

From F (distance 60):

- B:

old = 74
 new = 60 + 48 = 108
 → 108 > 74 → no update
- E:

old = 97
 new = 60 + 94 = 154
 → 154 > 97 → no update

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	No	A
C	7	Yes	A
D	24	Yes	C
E	97	No	C
F	60	Yes	D

Sets

- $S = \{ A(0), C(7), D(24), F(60) \}$
- $Q = \{ B(74), E(97) \}$

STEP 5: Visit B

From B (distance 74):

- No updates to neighbors (F already visited).

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	Yes	A
C	7	Yes	A
D	24	Yes	C
E	97	No	C
F	60	Yes	D

Sets

- $S = \{ A(0), C(7), D(24), F(60), B(74) \}$
- $Q = \{ E(97) \}$

STEP 6: Visit E

From E (distance 97):

- No updates to neighbors.

Node	Distance	Visited?	Predecessor
A	0	Yes	–
B	74	Yes	A
C	7	Yes	A
D	24	Yes	C
E	97	Yes	C
F	60	Yes	D

Sets

- $S = \{ A(0), C(7), D(24), F(60), B(74), E(97) \}$
- $Q = \{ \}$

Final Shortest Paths from A:

Target node	Minimum distance	Shortest path
A	0	A
B	74	A → B
C	7	A → C
D	24	A → C → D
E	97	A → C → E
F	60	A → C → D → F

Efficiency Analysis - Task 3:

Time Complexity

In this assignment, Dijkstra's algorithm is carried out using tables and a simple linear scan to choose the next smallest tentative distance. Since at each step it may be needed to check up to V nodes, and repeat this process for all V nodes, the total running time becomes:

$$O(V^2)$$

This is the standard complexity for the basic (non-optimized) version of Dijkstra.

If the algorithm is implemented with a priority queue (e.g., a binary heap), selecting and updating the minimum becomes faster, and the running time improves to:

$$O((V + E) \log V)$$

Space Complexity

When storing the graph using adjacency lists, the memory required includes:

- the graph itself (all nodes and edges) → $O(V + E)$;
- one distance value for each node → $O(V)$;
- one predecessor for each node → $O(V)$;
- a visited marker for each node → $O(V)$;

All of these grow linearly with the size of the graph, so the total space required is:

$$O(V + E)$$

Task 4: Hash Table

The hash table has a size of 11 slots (0 to 10) and uses open addressing with double hashing for collision resolution.

{key : [22, 12, 13, 24, 14, 16, 27, 20, 31, 10]}

Primary hash function: $h1(x) = x \bmod 11$

Secondary hash function: $h2(x) = (x \bmod 3) + 1$

a) Insertion Trace Table (for my own understanding)

Step	Key	$h1(x)$	Initial Index	Collision?	$h2(x)$	Inserted Index	Explanation
1	22	0	0	No	--	0	P0 - Inserted at index 0
2	12	1	1	No	--	1	P1 - Inserted at index 1
3	13	2	2	No	--	2	P2 - Inserted at index 2
4	24	2	2	Yes	1	3	(P2) Collision at 2; (2nd attempt $\rightarrow 2 + 1$) P3 \rightarrow inserted at index 3
5	14	3	3	Yes	3	6	(P3) Collision at 3; (2nd attempt $\rightarrow 3 + 3$) P6 \rightarrow inserted at index 6
6	16	5	5	No	--	5	P5 - Inserted at index 5
7	27	5	5	Yes	1	7	(P5) Collision at 5; (2nd attempt $\rightarrow 5+1$) P6 (occupied), then (3rd attempt $\rightarrow 6+1$) P7 \rightarrow inserted at index 7
8	20	9	9	No	--	9	P9 - Inserted at index 9
9	31	9	9	Yes	2	4	(P9) Collisions at 9, (2nd attempt $\rightarrow 9+2 \rightarrow$ wrap around to index 0 \rightarrow P0 \rightarrow occupied), (3rd attempt - 0+2) P2 (occupied); (4th attempt - 2+2) P4 \rightarrow inserted at index 4
10	10	10	10	No	--	10	P10 - Inserted at index 10

b) Final Hash Table State

Bucket	0	1	2	3	4	5	6	7	8	9	10
Value	22	12	13	24	31	16	14	27	—	20	10

c) Hash Table trace 1

Hash Table trace 1

P0
I22@0
P1
I12@1
P2
I13@2
P2
P3
I24@3
P3
P6
I14@6
P5
I16@5
P5
P6
P7
I27@7
P9
P0
P2
P4
I31@4
P10
I10@10

d) Algorithm - I am using Python for this implementation:

```
# Size of the hash table (array of buckets)
TABLE_SIZE = 11

# hash function 1 (primary
hash) def hash1(x):
    return x % TABLE_SIZE

# hash function 2 (used only after a
collision) def hash2(x):
    return (x % 3) + 1

# function to insert a key into the table using
double hashing def insert(table, key):
    # Step 2: apply the first hash
    function initial_index = hash1(key)

    # Step 3: check if the bucket
    is free if table[initial_index]
    is None:
        # Step 4: if free, insert
        here table[initial_index] =
        key
        print(f"Inserted {key} at index {initial_index} (no
        collision)") return

    # Step 5: if the slot is occupied, apply the second
    hash function step = hash2(key)

    # number of collisions /
    attempts i = 1

    # Step 6: try new positions while respecting table
    boundaries # try at most TABLE_SIZE times (one for
    each bucket)
    while i < TABLE_SIZE:
        new_index = (initial_index + i * step) % TABLE_SIZE

        # If found an empty spot,
        insert if table[new_index]
        is None:
            table[new_index] = key
            print(
                f"Inserted {key} at index {new_index}
                " f"(after {i} collision(s))"
            )
            return

        # otherwise, keep
        trying i += 1

    # If reached this point, the table is full or no valid
    position was found print(f"Could not insert {key}: table is
    full or all positions probed")
```

Algorithm (in words):

1. Compute $\text{index} = h_1(\text{key})$.
2. If $\text{table}[\text{index}]$ is empty, insert key there.
3. Otherwise, compute $\text{step} = h_2(\text{key})$.
4. For i from 1 to $\text{TABLE_SIZE} - 1$:
 - $\text{new_index} = (\text{index} + i * \text{step}) \bmod \text{TABLE_SIZE}$
 - If $\text{table}[\text{new_index}]$ is empty, insert and stop.
5. If no empty slot is found, report that the table is full.

Efficiency Analysis - Task 4:

Time Complexity

In the average case, each insertion takes constant time, $O(1)$, because most keys will find an empty slot quickly. However, in the worst case, when many collisions occur, the time complexity can degrade to $O(n)$, where n is the number of keys already in the table. This happens when the table is nearly full, and many probes are needed to find an empty slot.

Space Complexity

The space complexity of the hash table is $O(m)$, where m is the size of the table. This is because we need to allocate space for each bucket in the table, regardless of how many keys are actually stored.

Task 5: AVL Tree

AVL trace

Sequence of keys: **53, 65, 40, 79, 69, 92, 50, 30, 10, 55**

- lxx = insert xx at root
- lxxLyy = insert xx as left child of yy
- lxxRyy = insert xx as right child of yy
- Rxx = rotate the node with key xx with its parent

AVL trace

I53

I65R53

I40L53

I79R65

I69L79

R69

R69

I92R79

R69

I50R40

I30L40

I10L30

R40

I55L65

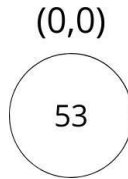
R53

R53

AVL Construction – Step-by-Step Explanation (14 Steps)

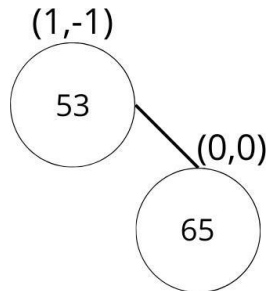
In each step, I will describe the insertion, any imbalance that occurs, the type of imbalance, and the rotations applied to restore balance. The height and the balance factors (BF) are written on top of each node in the diagrams as (height, BF).

Step 1 – Insert 53



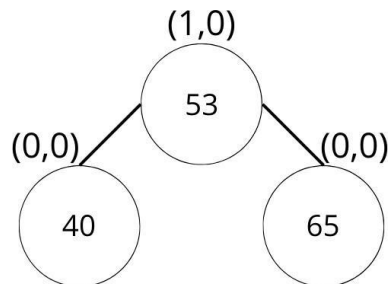
The tree is empty, so 53 becomes the root. Balanced.

Step 2 – Insert 65



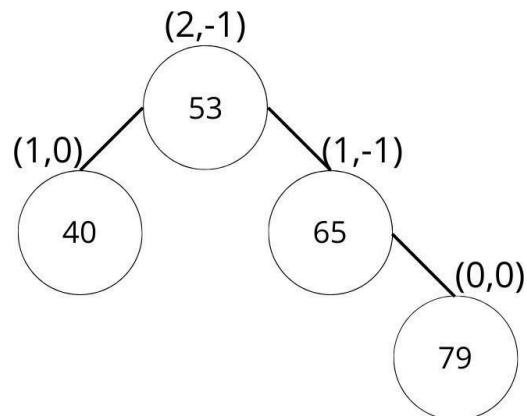
65 is inserted as the right child of 53. $BF(53) = -1$, still valid.

Step 3 – Insert 40



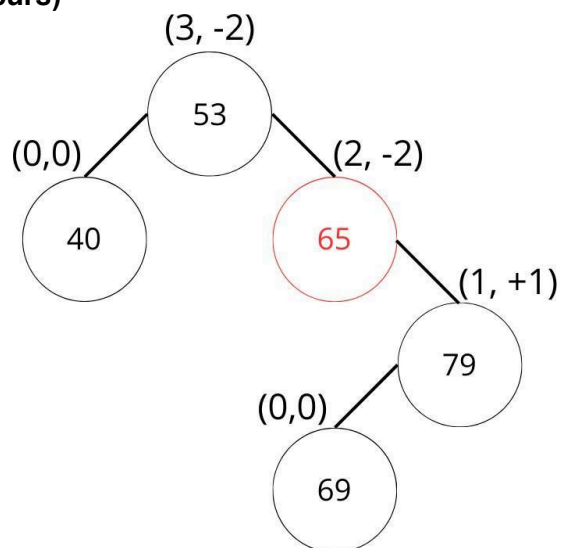
40 is inserted as the left child of 53. $BF(53) = 0$. Tree remains balanced.

Step 4 – Insert 79



79 is inserted as the right child of 65. All balance factors remain within range.

Step 5 – Insert 69 (Imbalance occurs)



69 is inserted as the left child of 79, causing imbalance at node 65.

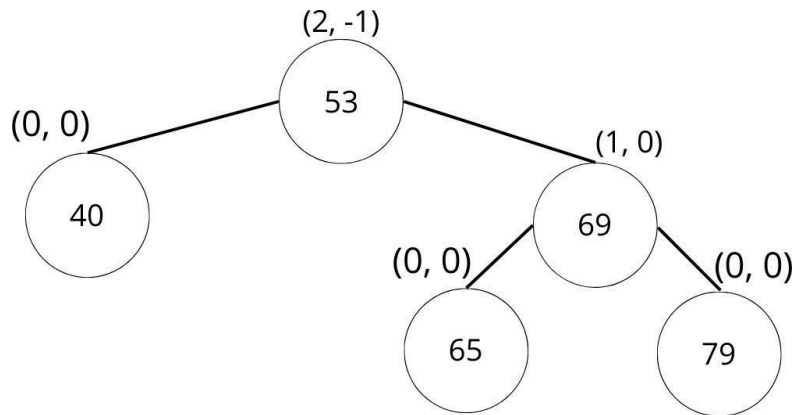
Imbalance type: Right–Left (RL)

Justification:

Node 65 becomes right-heavy (BF = -2), but its right child 79 is left-heavy.

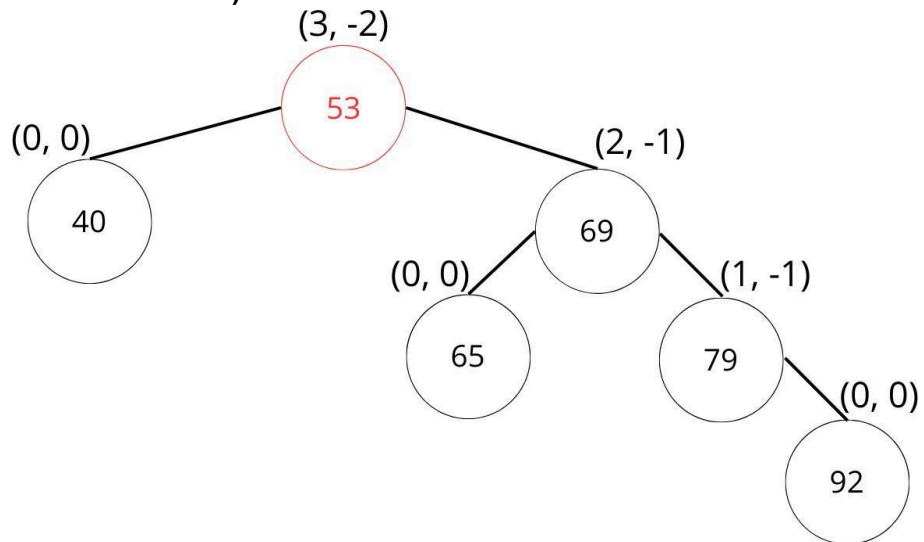
The insertion path goes: right → left.

Step 6 – RL Rotation



A double rotation is applied (right rotation on 79, then left rotation on 65).
The subtree becomes balanced.

Step 7 – Insert 92 (Imbalance occurs)



92 is inserted as the right child of 79, causing imbalance at the root 53.

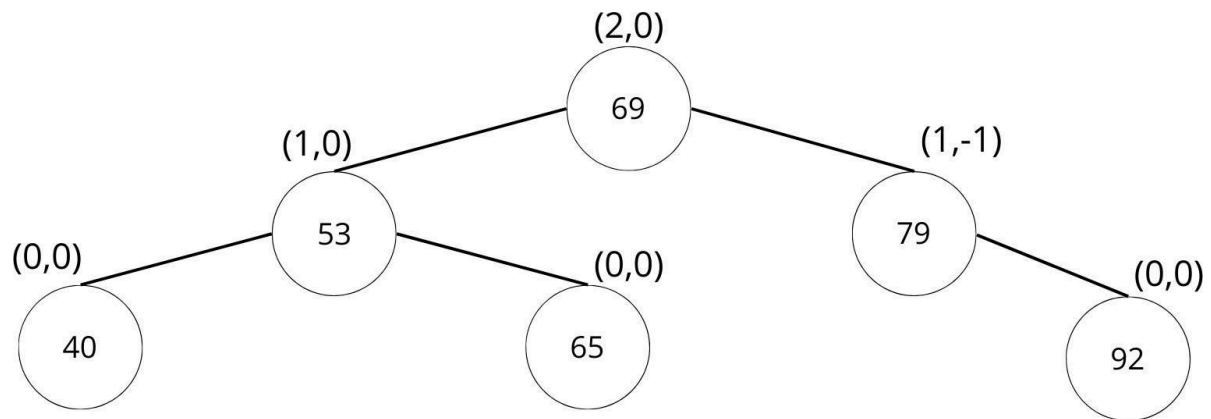
Imbalance type: Right–Right (RR)

Justification:

The insertion path from 53 goes right → right → right.

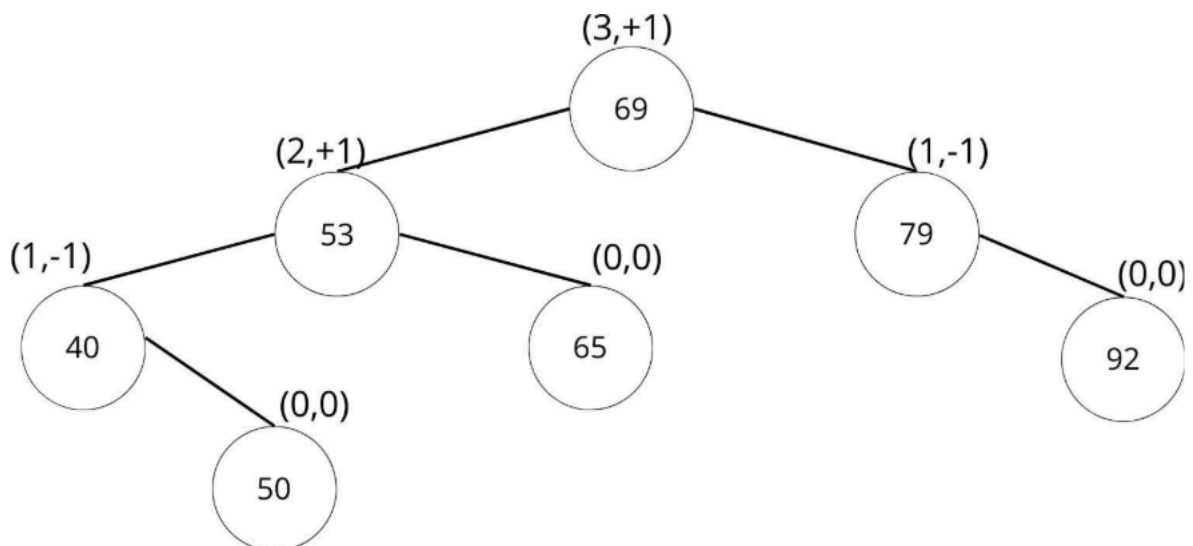
Node 53 becomes right-heavy with a right-heavy child.

Step 8 – RR Rotation



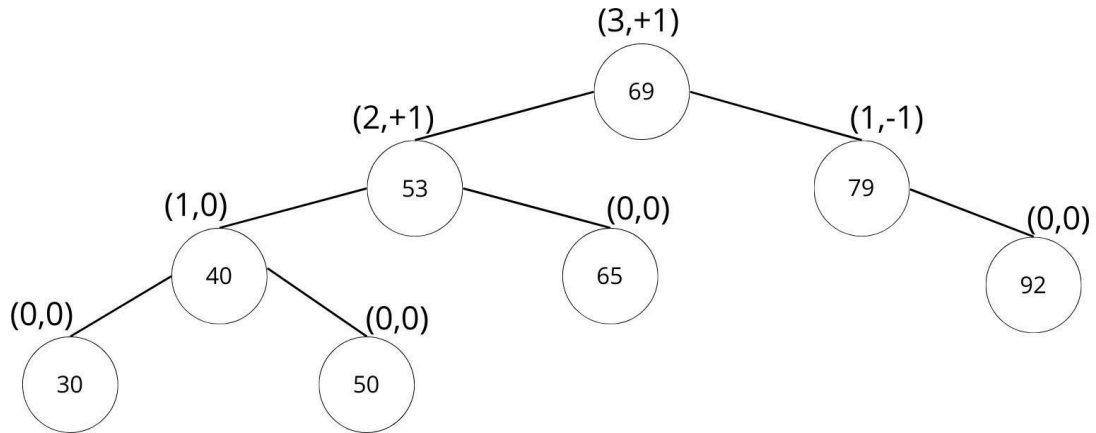
A single left rotation is applied at node 53.
Node 69 becomes the new root.

Step 9 – Insert 50



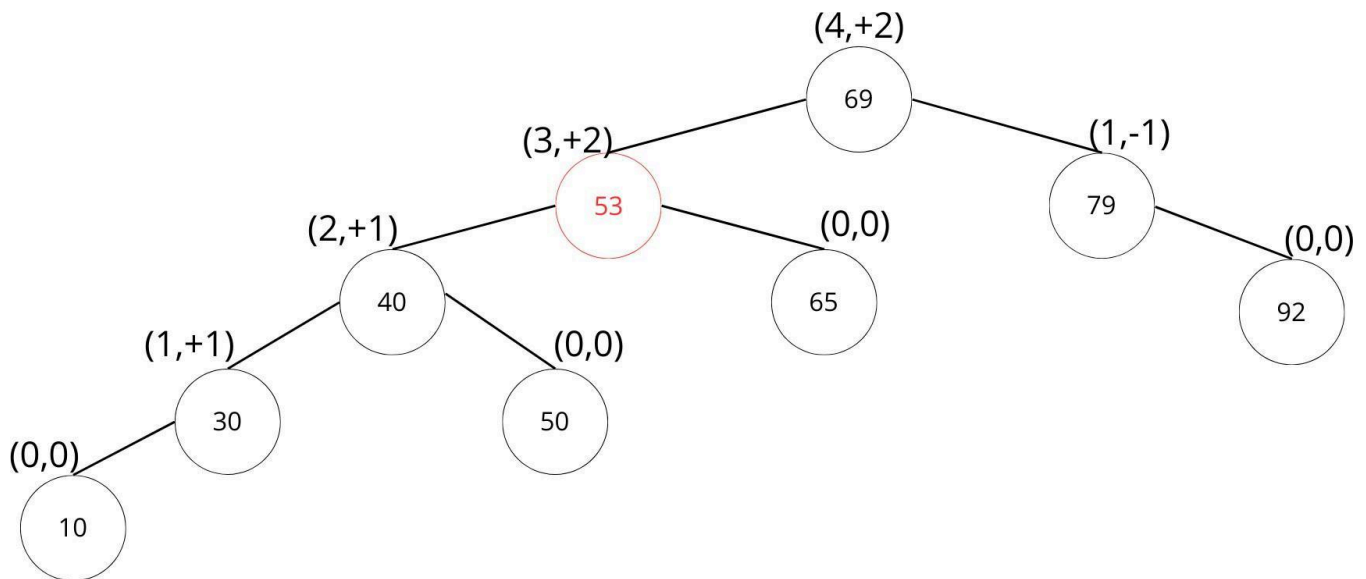
50 is inserted as the right child of 40.
All balance factors remain valid.

Step 10 – Insert 30



30 is inserted as the left child of 40.
BF(40) becomes +1, still within limits.
No imbalance occurs.

Step 11 – Insert 10 (Imbalance occurs)



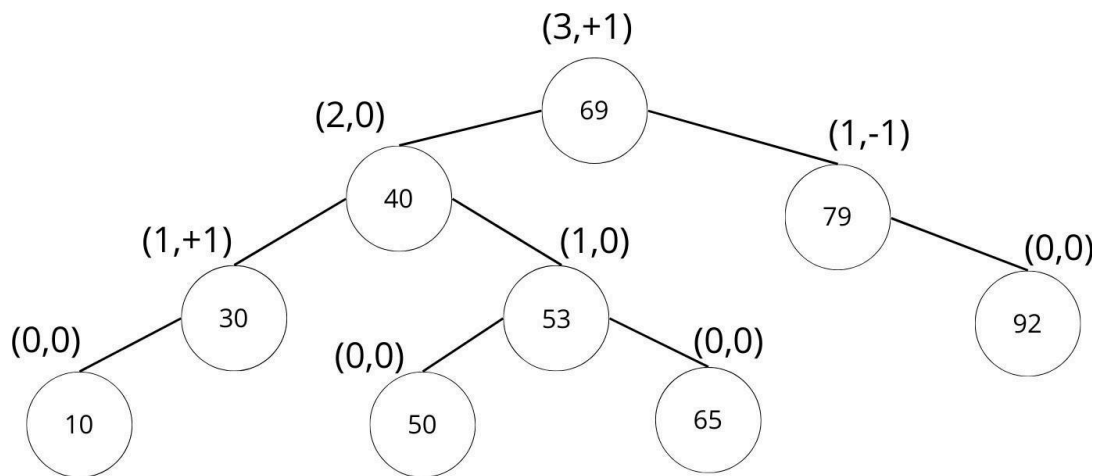
10 is inserted as the left child of 30, causing imbalance at node 53.

Imbalance type: Left-Left (LL)

Justification:

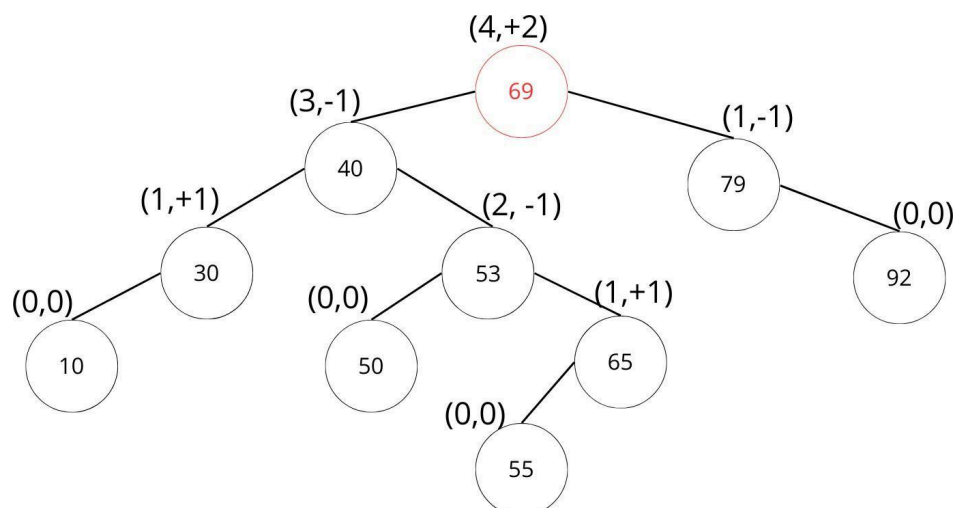
The insertion path goes left → left → left.

Node 53 becomes left-heavy with a left-heavy child 40.

Step 12 – LL Rotation

A single right rotation is applied at node 53.

Heights realign correctly and the tree becomes balanced again.

Step 13 – Insert 55 (Imbalance occurs)

55 is inserted as the left child of 65, causing imbalance at the root 69.

Imbalance type: Left-Right (LR)

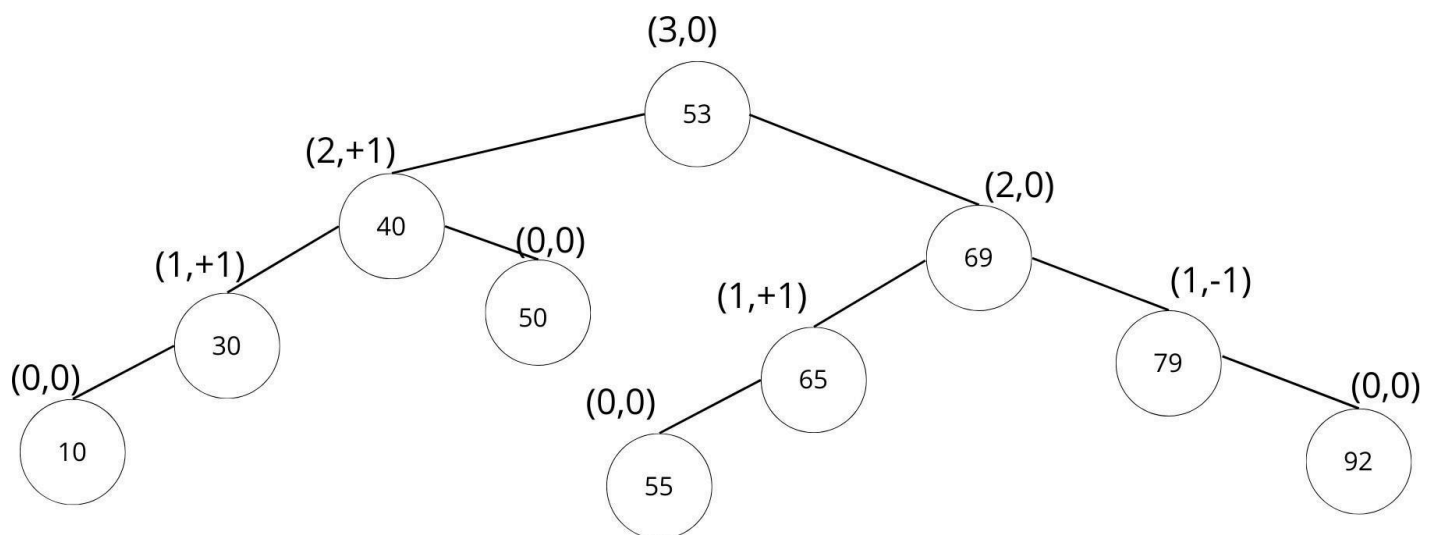
Justification:

Node 69 becomes left-heavy (BF = +2),

but its left subtree (rooted at 53) is right-heavy through 65 → 55.

Insertion path: left → right.

Step 14 – LR Rotation



A double rotation corrects the imbalance:

1. Left rotation under the 53-subtree,
2. Then right rotation at 69.

This produces the final balanced AVL tree.

In-order traversal and height of final tree

- **In-order traversal** (should be sorted):
10, 30, 40, 50, 53, 55, 65, 69, 79, 92
- **Height of final tree (root)** with leaf = 0:
height(53) = 3

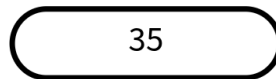
Task 6: 2–4 Tree Construction and Deletion

Keys: [35, 60, 25, 40, 70, 20, 10, 90, 80, 30, 45, 50, 55]

Insertion

Step 1 — Insert 35

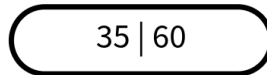
35 is inserted into an empty 2–4 tree and becomes the root.



Step 2 — Insert 60

60 is inserted into the same node as 35.

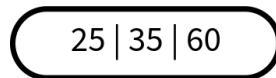
The root now contains two keys, which is valid.



Step 3 — Insert 25

25 is inserted into the same node.

The root now contains three keys, the maximum allowed before splitting.



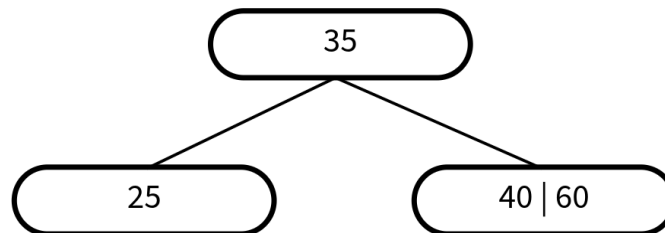
Step 4 — Insert 40 (first overflow and split)

Inserting 40 creates a four-key node: 25, 35, 40, 60. A 2–4 node cannot have four keys, so it must be split.



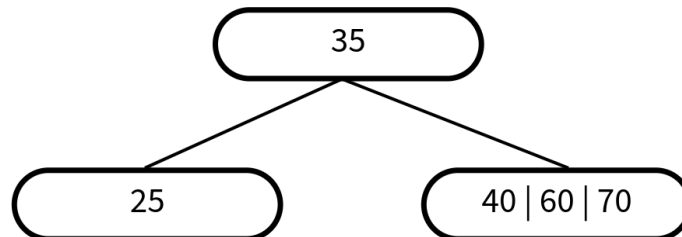
Split details:

- The middle key 35 is promoted to become the new root.
- Left child becomes [25].
- Right child becomes [40|60].



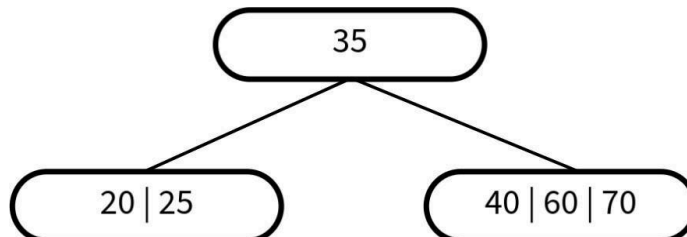
Step 5 — Insert 70

70 is inserted into the right child, producing [40|60|70], which is full but valid.



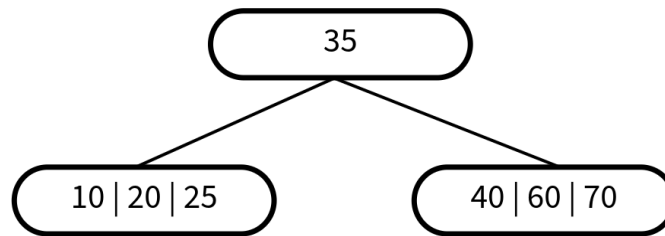
Step 6 — Insert 20

20 is inserted into the left child, becoming [20|25].



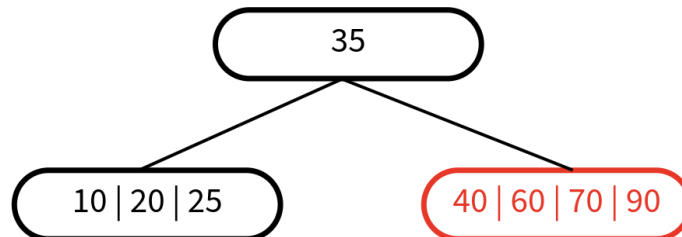
Step 7 — Insert 10

10 is inserted into the left child, forming [10|20|25].



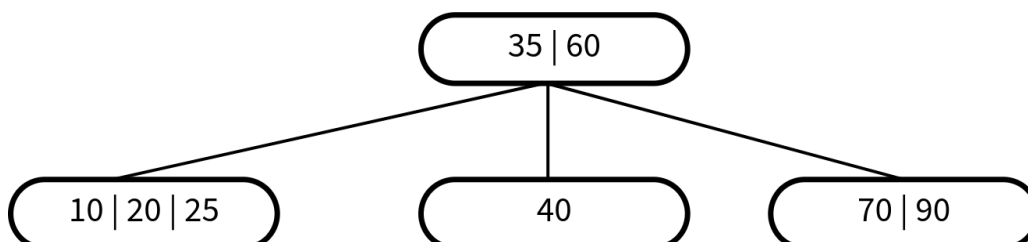
Step 8 — Insert 90 (right child overflow and split)

The node [40|60|70] overflows when inserting 90.



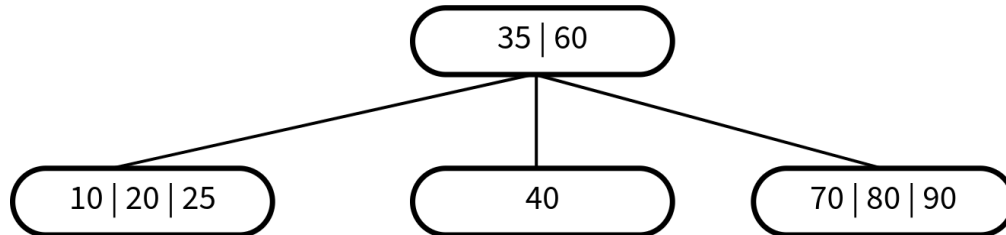
Split details:

- Promote 60 to the root.
- Left part becomes [40].
- Right part becomes [70|90].
- Root becomes [35|60].



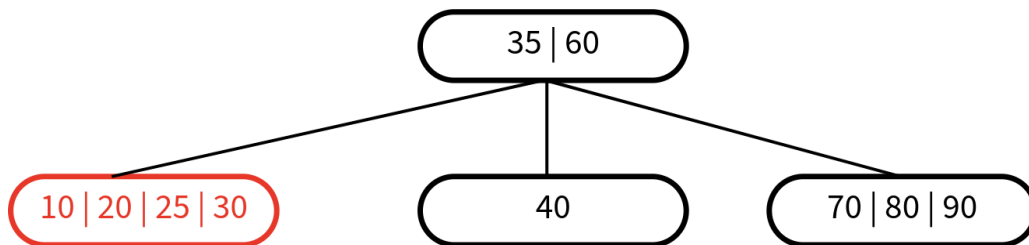
Step 9 — Insert 80

80 is inserted into the rightmost child, forming [70|80|90].



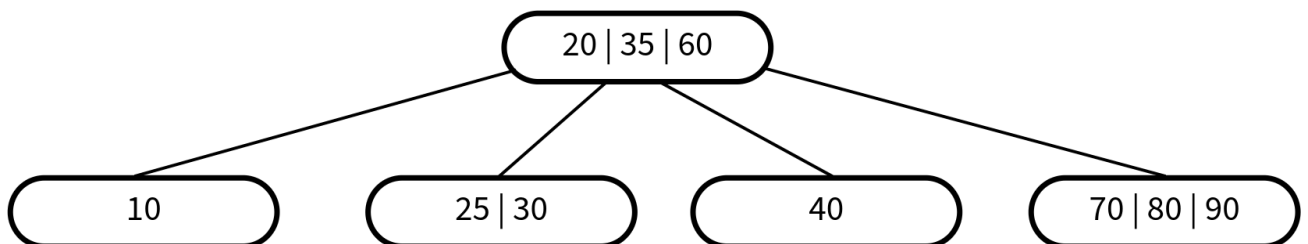
Step 10 — Insert 30 (left child overflow and split)

Left node [10|20|25] overflows when inserting 30.



Split details:

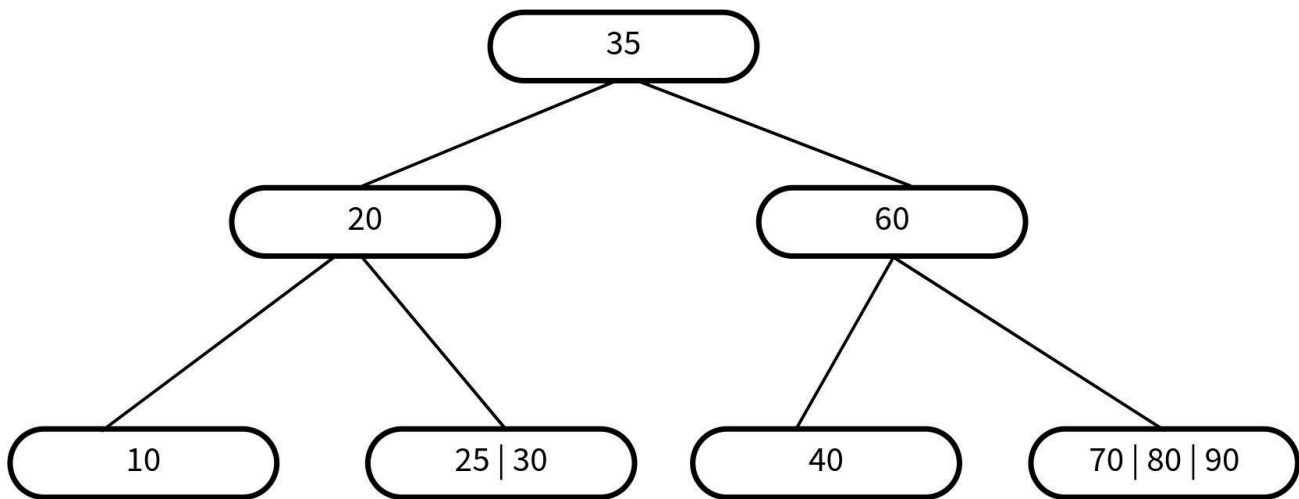
- Promote 20 to the root.
- Left becomes [10].
- Right becomes [25|30].
- Root becomes [20|35|60].



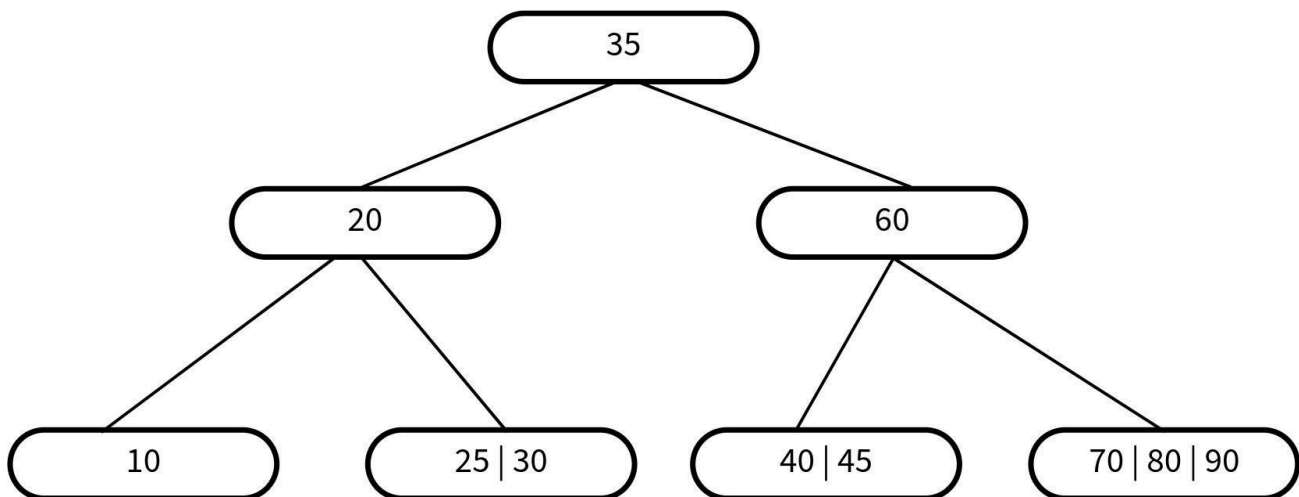
Step 11 — Insert 45 (root split)

Before insertion, root is full [20, 35, 60].

Standard 2-4 insertion: when root is full, split root first.

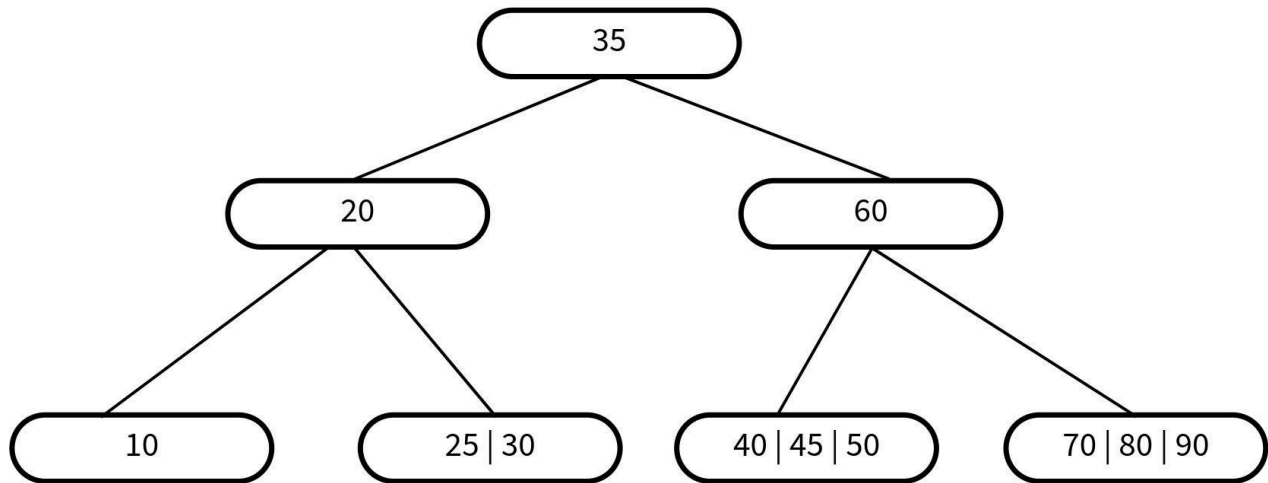


Now insert 45 into the appropriate child [40|45].



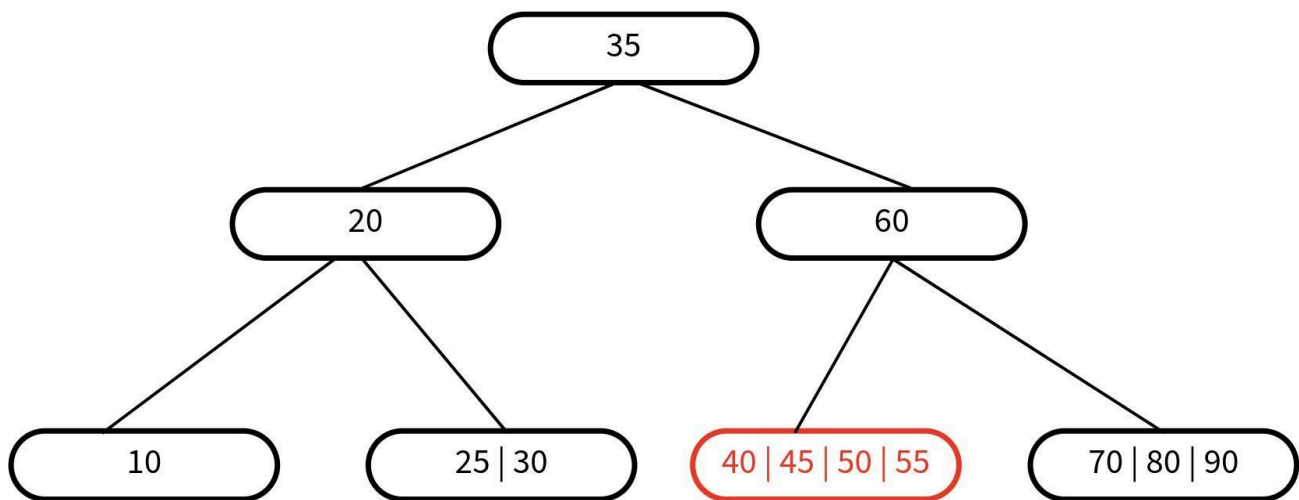
Step 12 — Insert 50

50 is inserted into the same node, forming [40|45|50].



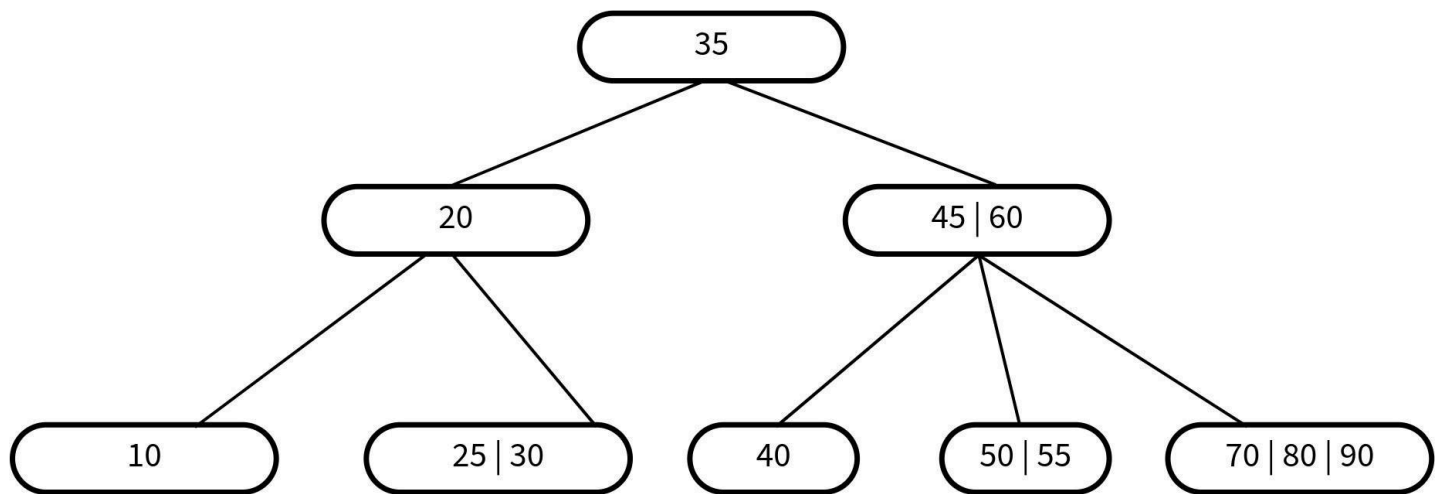
Step 13 — Insert 55 (overflow of middle-right node)

The node [40|45|50] overflows when inserting 55.



Split details:

- Promote 45.
- Left becomes [40].
- Right becomes [50|55].



Deletion

Delete the keys sequentially

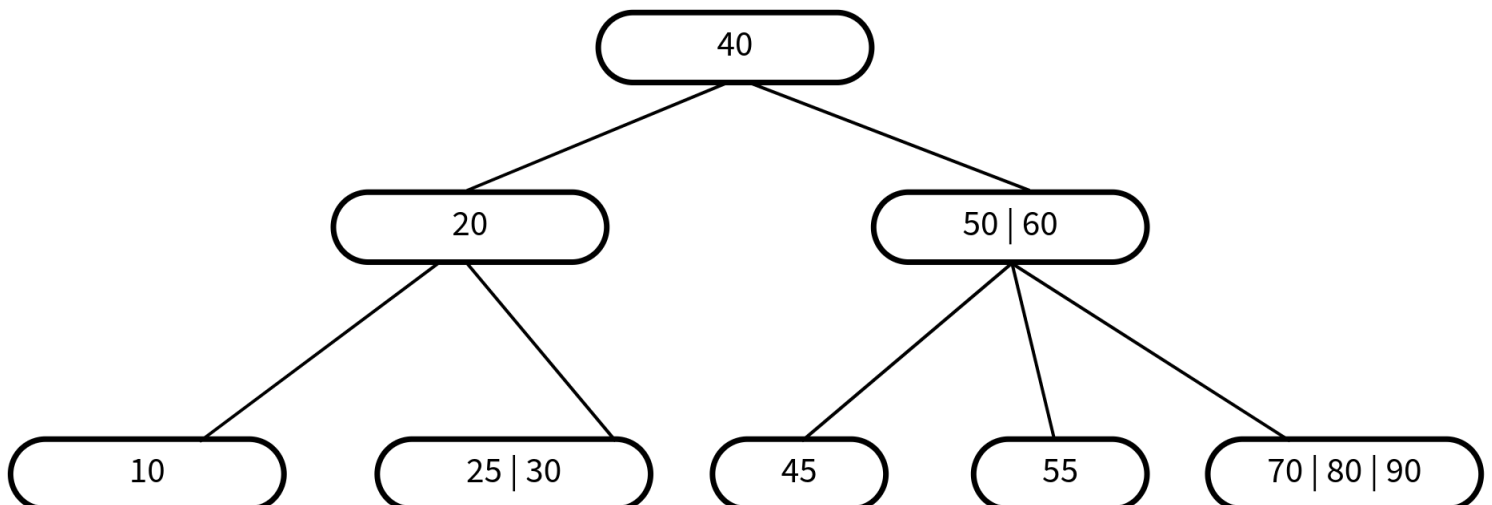
Keys: [35, 60, 25, 40, 70, 20, 10, 90, 80, 30, 45, 50, 55]

Step 1 — Delete 35 (internal key replaced by successor)

35 is in the root (internal node).

I am going to replace it with its in-order successor, which is **40** from the subtree.

Then delete 40 from the leaf, causing a redistribution in that subtree (rebalances by pulling 50 up to its internal node).

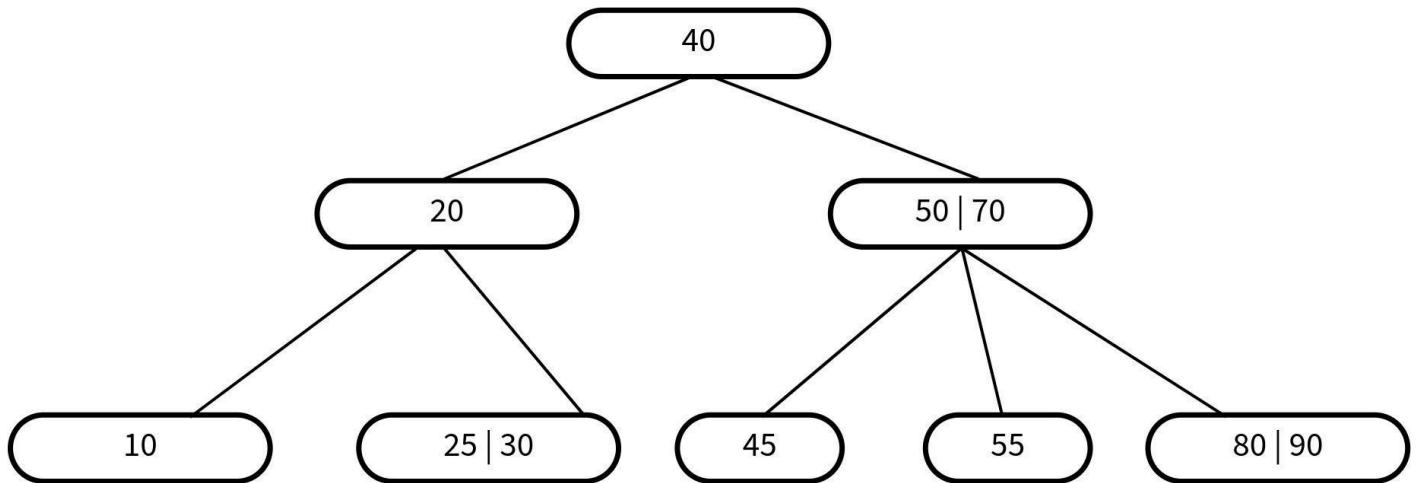


Step 2 — Delete 60 (internal key replaced by successor)

60 is an internal key in node [50|60].

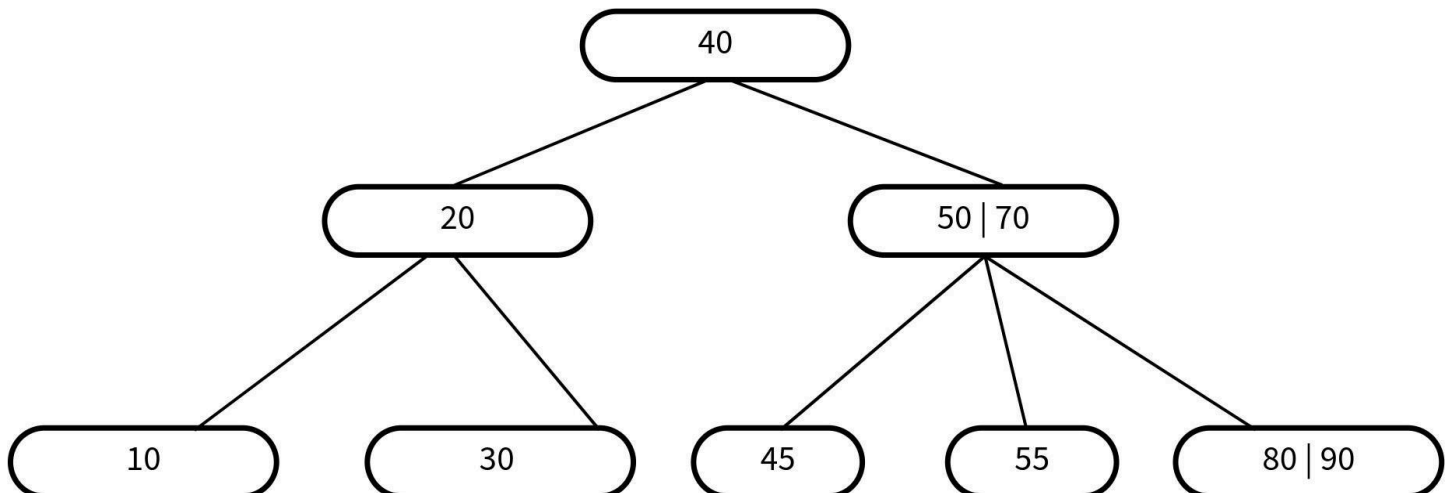
Its successor is **70** from the rightmost leaf.

After removing 70, the leaf becomes [80|90] and no merge is needed.



Step 3 — Delete 25

25 is in a leaf. Removed from the leaf [25|30].

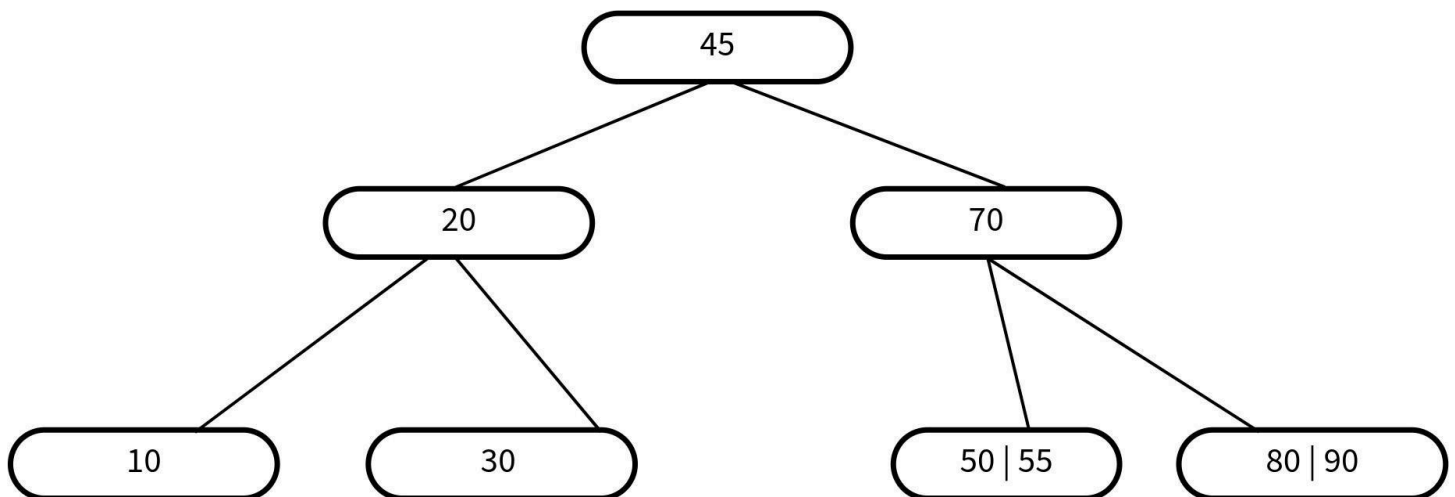


Step 4 — Delete 40 (root replaced by successor + merge)

40 is replaced by its successor **45**, then 45 is removed from its leaf.

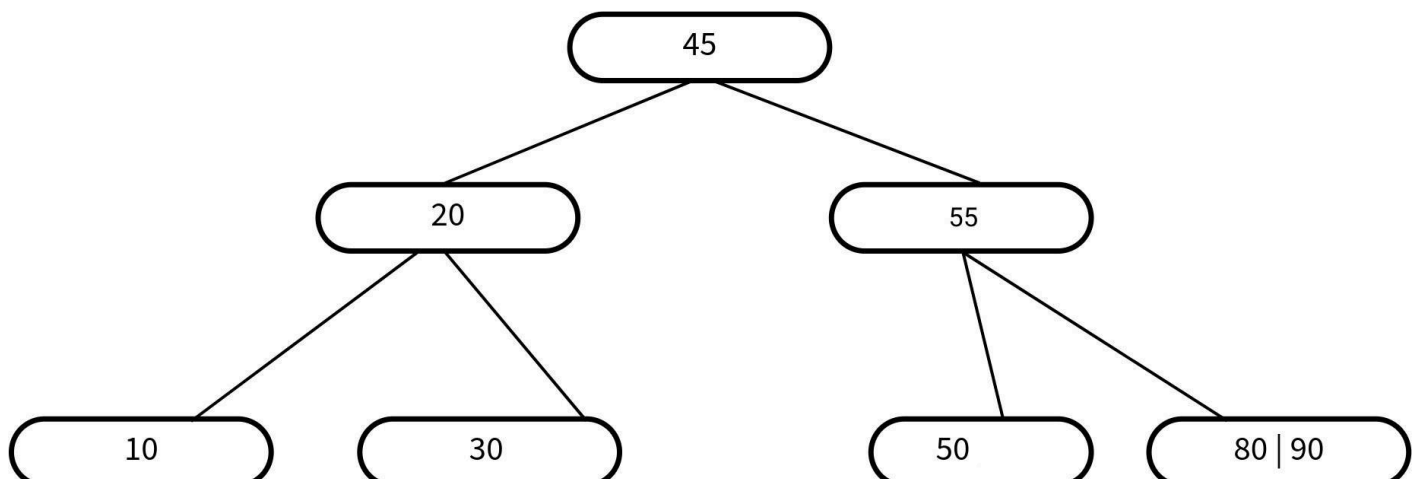
Substeps:

- 40 (root) replaced by 45.
- Merge $[45] + 50 + [55] \rightarrow [45|50|55]$ (Parent $[50|70]$ loses key 50).
- Now delete 45 from leaf $[45|50|55] \rightarrow [50|55]$



Step 5 — Delete 70 (internal key replaced by successor)

- Replace 70 with 55 in that internal node $\rightarrow [55]$.
- Delete 55 from leaf $[50|55] \rightarrow [50]$.



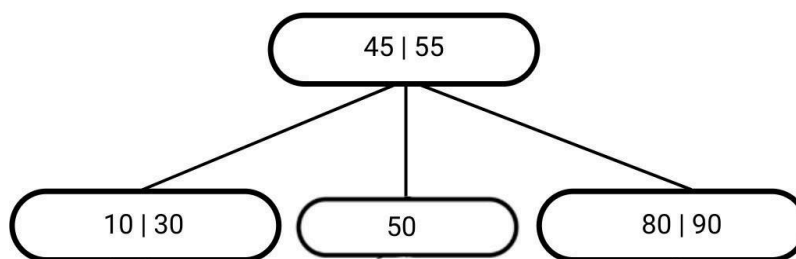
Step 6 — Delete 20 (internal key replaced by successor + merge)

a) Prepare the child before descent

- Merge [20] + 45 + [55] into one node [20|45|55]
- Combine their children: [10], [30], [50], [80|90].

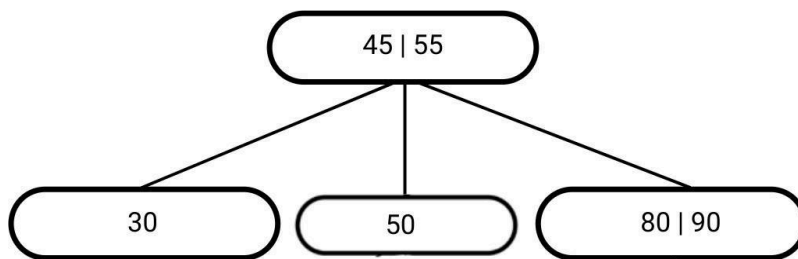
b) Now delete 20 from leaf [20|45|55] → [45|55]

- Predecessor and successor child is [30] (1 key).
- Both minimal → merge [10] + 20 + [30] into
- [10|20|30]. Delete 20 from leaf → [10|30].



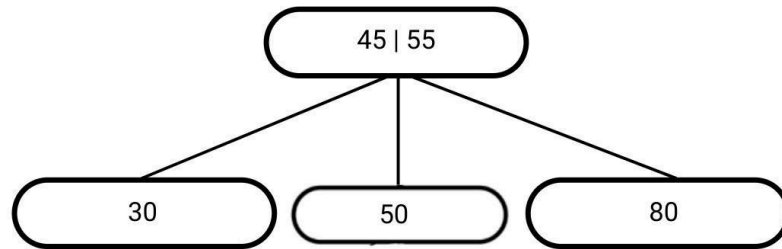
Step 7 — Delete 10 (simple leaf deletion)

- 10 is removed from the leftmost leaf.



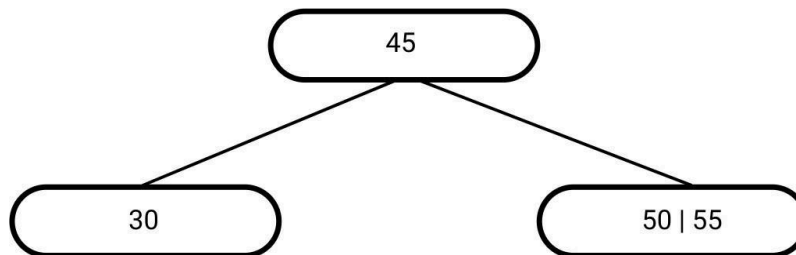
Step 8 — Delete 90 (simple leaf deletion)

- 90 is removed from the rightmost leaf.



Step 9 — Delete 80 (underflow)

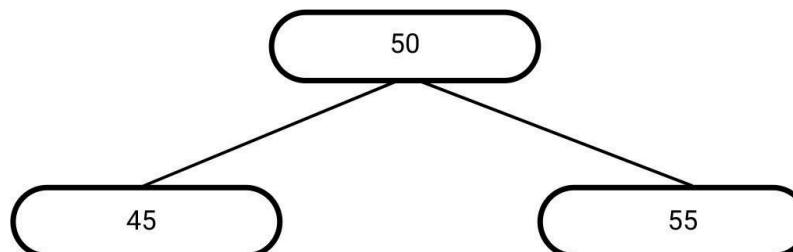
- Merge [50], key 55, and [80].
- The merged node becomes [50|55|80]. Delete 80 from leaf.



Step 10 — Delete 30 (borrow from the right sibling)

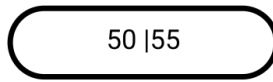
Borrow from right sibling:

- Move root key 45 down to left child.
- Move sibling key 50 up to root.



Step 11 — Delete 45 (root absorbs keys)

Deleting 45 from the left child allows the root to absorb 55, forming a single leaf-level node.



Step 12 — Delete 50 (simple deletion from leaf)

Removing 50 leaves [55].



Step 13 — Delete 55 (tree becomes empty)

Final key removed.

Tree is now:

(empty)