

Exercise 9

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Task 1 Reinforce on the Cart-Pole

a.)

softmax: $\pi(a|s, \theta) = \frac{e^{h(s,a,\theta)}}{\sum_b e^{h(s,a,\theta)}}$

linear features: $h(s, a, \theta) = \theta_a^T s$

for the 2 actions space $a \in \{0, 1\}$ of the cart pole this results in $\pi(a|s, \theta) = \frac{e^{\theta_a^T s}}{e^{\theta_0^T s} + e^{\theta_1^T s}}$ for the softmax function. With state $s = (p, \dot{p}, \alpha, \dot{\alpha})^T \in \mathbb{R}^4$ follows $\theta \in \mathbb{R}^4$

This results for the given actions in:

$$\pi(a=0|s, \theta) = \frac{e^{\theta_0^T s}}{e^{\theta_0^T s} + e^{\theta_1^T s}} \quad \text{and} \quad \pi(a=1|s, \theta) = \frac{e^{\theta_1^T s}}{e^{\theta_0^T s} + e^{\theta_1^T s}}$$

These can be rewritten as a sigmoid function:

$$\begin{aligned} \pi(a=0|s, \theta) &= \frac{e^{\theta_0^T s}}{e^{\theta_0^T s} + e^{\theta_1^T s}} \\ &= \frac{e^{\theta_0^T s}}{e^{\theta_0^T s} (e^{\theta_1^T s - \theta_0^T s} + 1)} \\ &= \frac{1}{e^{\theta_1^T s - \theta_0^T s} + 1} \\ &= \sigma(\theta_0^T s - \theta_1^T s) \\ &= \sigma(s^T (\theta_0 - \theta_1)) \end{aligned}$$

similar for $\pi(a=1|s, \theta) = \sigma(s^T (\theta_1 - \theta_0))$

Also due to $\sigma(z) = \frac{1}{1+e^{-z}} = \frac{e^z}{1+e^z}$ we have

$$\begin{aligned} \pi(a=0|s, \theta) &= 1 - \pi(a=1|s, \theta) \\ &= 1 - \sigma(s^T (\theta_1 - \theta_0)) \end{aligned}$$

and vice versa

$$\pi(a=1|s, \theta) = 1 - \sigma(s^T (\theta_0 - \theta_1))$$

With $\sigma'(z) = \sigma(z)(1 - \sigma(z))$ being the derivative of the sigma function we get:

$$\begin{aligned}\nabla_{\theta_0} \pi(a=0|s, \theta) &= \sigma(s^T(\theta_0 - \theta_1))(1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ \nabla_{\theta_1} \pi(a=0|s, \theta) &= -\sigma(s^T(\theta_0 - \theta_1))(1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ \nabla_{\theta_1} \pi(a=1|s, \theta) &= \sigma(s^T(\theta_1 - \theta_0))(1 - \sigma(s^T(\theta_1 - \theta_0)))s \\ \nabla_{\theta_0} \pi(a=1|s, \theta) &= -\sigma(s^T(\theta_1 - \theta_0))(1 - \sigma(s^T(\theta_1 - \theta_0)))s\end{aligned}$$

b.)

The derivate $\nabla_{\theta} \log \pi(a=0|s, \theta)$ can be calculated in a similar fashion:

$$\begin{aligned}\nabla_{\theta_0} \log \pi(a=0|s, \theta) &= \frac{1}{\pi(a=0|s, \theta)} \sigma(s^T(\theta_0 - \theta_1))(1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ &= \frac{1}{\sigma(s^T(\theta_0 - \theta_1))} \sigma(s^T(\theta_0 - \theta_1))(1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ &= (1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ \nabla_{\theta_1} \log \pi(a=0|s, \theta) &= (1 - \sigma(s^T(\theta_0 - \theta_1)))(-s)\end{aligned}$$

and

$$\begin{aligned}\nabla_{\theta_1} \log \pi(a=1|s, \theta) &= (1 - \sigma(s^T(\theta_1 - \theta_0)))s \\ \nabla_{\theta_0} \log \pi(a=1|s, \theta) &= (1 - \sigma(s^T(\theta_1 - \theta_0)))(-s)\end{aligned}$$

This can again be rewritten with the results from **a.)**:

$$\begin{aligned}\nabla_{\theta} \log \pi(a=0|s, \theta) &= (1 - \sigma(s^T(\theta_0 - \theta_1)))s \\ &= \sigma(s^T(\theta_1 - \theta_0))s\end{aligned}$$

and

$$\begin{aligned}\nabla_{\theta} \log \pi(a=1|s, \theta) &= (1 - \sigma(s^T(\theta_1 - \theta_0)))s \\ &= \sigma(s^T(\theta_0 - \theta_1))s\end{aligned}$$