

$$\mathcal{L}_{\text{SM}} = \mathcal{L}_{\text{Dirac}} + \mathcal{L}_{\text{mass}} + \mathcal{L}_{\text{gauge}} + \mathcal{L}_{\text{gauge}/\psi} . \quad (1)$$

Here,

$$\mathcal{L}_{\text{Dirac}} = i\bar{e}_L^i \not{\partial} e_L^i + i\bar{\nu}_L^i \not{\partial} \nu_L^i + i\bar{e}_R^i \not{\partial} e_R^i + i\bar{u}_L^i \not{\partial} u_L^i + i\bar{d}_L^i \not{\partial} d_L^i + i\bar{u}_R^i \not{\partial} u_R^i + i\bar{d}_R^i \not{\partial} d_R^i ; \quad (2)$$

$$\mathcal{L}_{\text{mass}} = -v \left( \lambda_e^i \bar{e}_L^i e_R^i + \lambda_u^i \bar{u}_L^i u_R^i + \lambda_d^i \bar{d}_L^i d_R^i + \text{h.c.} \right) - M_W^2 W_\mu^+ W^{-\mu} - \frac{M_W^2}{2 \cos^2 \theta_W} Z_\mu Z^\mu ; \quad (3)$$

$$\mathcal{L}_{\text{gauge}} = -\frac{1}{4} (G_{\mu\nu}^a)^2 - \frac{1}{2} W_{\mu\nu}^+ W^{-\mu\nu} - \frac{1}{4} Z_{\mu\nu} Z^{\mu\nu} - \frac{1}{4} F_{\mu\nu} F^{\mu\nu} + \mathcal{L}_{WZA} , \quad (4)$$

where

$$\begin{aligned} G_{\mu\nu}^a &= \partial_\mu A_\nu^a - \partial_\nu A_\mu^a - g_3 f^{abc} A_\mu^b A_\nu^c \\ W_{\mu\nu}^\pm &= \partial_\mu W_\nu^\pm - \partial_\nu W_\mu^\pm \\ Z_{\mu\nu} &= \partial_\mu Z_\nu - \partial_\nu Z_\mu \\ F_{\mu\nu} &= \partial_\mu A_\nu - \partial_\nu A_\mu , \end{aligned} \quad (5)$$

and

$$\begin{aligned} \mathcal{L}_{WZA} = & ig_2 \cos \theta_W \left[ (W_\mu^- W_\nu^+ - W_\nu^- W_\mu^+) \partial^\mu Z^\nu + W_{\mu\nu}^+ W^{-\mu} Z^\nu - W_{\mu\nu}^- W^{+\mu} Z^\nu \right] \\ & + ie \left[ (W_\mu^- W_\nu^+ - W_\nu^- W_\mu^+) \partial^\mu A^\nu + W_{\mu\nu}^+ W^{-\mu} A^\nu - W_{\mu\nu}^- W^{+\mu} A^\nu \right] \\ & + g_2^2 \cos^2 \theta_W (W_\mu^+ W_\nu^- Z^\mu Z^\nu - W_\mu^+ W^{-\mu} Z_\nu Z^\nu) \\ & + g_2^2 (W_\mu^+ W_\nu^- A^\mu A^\nu - W_\mu^+ W^{-\mu} A_\nu A^\nu) \\ & + g_2 e \cos \theta_W [W_\mu^+ W_\nu^- (Z^\mu A^\nu + Z^\nu A^\mu) - 2W_\mu^+ W^{-\mu} Z_\nu A^\nu] \\ & + \frac{1}{2} g_2^2 (W_\mu^+ W_\nu^-) (W^{+\mu} W^{-\nu} - W^{+\nu} W^{-\mu}) ; \end{aligned} \quad (6)$$

and

$$\mathcal{L}_{\text{gauge}/\psi} = -g_3 A_\mu^a J_{(3)}^{\mu a} - g_2 (W_\mu^+ J_{W^+}^\mu + W_\mu^- J_{W^-}^\mu + Z_\mu J_Z^\mu) - e A_\mu J_A^\mu , \quad (7)$$

where

$$\begin{aligned} J_{(3)}^{\mu a} &= \bar{u}^i \gamma^\mu T_{(3)}^a u^i + \bar{d}^i \gamma^\mu T_{(3)}^a d^i \\ J_{W^+}^\mu &= \frac{1}{\sqrt{2}} (\bar{\nu}_L^i \gamma^\mu e_L^i + V^{ij} \bar{u}_L^i \gamma^\mu d_L^j) \\ J_{W^-}^\mu &= (J_{W^+}^\mu)^* \\ J_Z^\mu &= \frac{1}{\cos \theta_W} \left[ \frac{1}{2} \bar{\nu}_L^i \gamma^\mu \nu_L^i + \left( -\frac{1}{2} + \sin^2 \theta_W \right) \bar{e}_L^i \gamma^\mu e_L^i + (\sin^2 \theta_W) \bar{e}_R^i \gamma^\mu e_R^i \right. \\ &\quad + \left( \frac{1}{2} - \frac{2}{3} \sin^2 \theta_W \right) \bar{u}_L^i \gamma^\mu u_L^i + \left( -\frac{2}{3} \sin^2 \theta_W \right) \bar{u}_R^i \gamma^\mu u_R^i \\ &\quad \left. + \left( -\frac{1}{2} + \frac{1}{3} \sin^2 \theta_W \right) \bar{d}_L^i \gamma^\mu d_L^i + \left( \frac{1}{3} \sin^2 \theta_W \right) \bar{d}_R^i \gamma^\mu d_R^i \right] \\ J_A^\mu &= (-1) \bar{e}^i \gamma^\mu e^i + \left( \frac{2}{3} \right) \bar{u}^i \gamma^\mu u^i + \left( -\frac{1}{3} \right) \bar{d}^i \gamma^\mu d^i . \end{aligned} \quad (8)$$