

# Ordinary Differential Equations A-H (MA230)

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Spring 2025

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Q: Which of the following equations are DEs?

$$(a) \ y'(t) + t - y = 0 \quad (b) \ \frac{\partial u}{\partial t} - \frac{\partial^2 u}{\partial x^2} = \sin t \quad (c) \ \sin y(t) = t.$$

# Motivations and Goals

**Motivations:** Many natural phenomena and processes in physics, chemistry, biology, and other disciplines could be modeled and simulated by differential equations.

**Our Goals:** We mainly study ODEs in this course.

- ▶ To learn the methods that have proved effective in finding solutions.
- ▶ To learn the tools that help us to know the qualitative properties of solutions without solving them explicitly. (Direction fields, phase-line analysis, phase-plane analysis, etc.)
- ▶ Existence, uniqueness, comparison, and stability of solutions.
- ▶ To solve application problems, i.e., modeling.

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Examples:

$$(i) \quad y''(t) + 2[y'(t)]^3 + \cos t = 3,$$



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- General form of an ODE of order  $n$  with independent variable  $t$  and unknown function  $y$ :

$$F(t, y(t), y'(t), \dots, y^{(n)}(t)) = 0,$$

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- General form of a first-order ODE:

$$F(t, y, y') = 0 \quad \text{or} \quad y' = F(t, y).$$

- General form of a first-order ODE system with independent variable  $t$  and unknown functions  $\vec{y}(t) = (y_1(t), \dots, y_m(t))^T$ :

$$\begin{cases} y_1'(t) = F_1(t, y_1, \dots, y_m) \\ y_2'(t) = F_2(t, y_1, \dots, y_m) \\ \dots \\ y_m'(t) = F_m(t, y_1, \dots, y_m) \end{cases}$$

or, in short,

$$\vec{y}'(t) = \vec{F}(t, \vec{y}), \quad \text{where } \vec{F} = (F_1, \dots, F_m)^T.$$

**Def 1.5.** The ODE  $F(t, y, y', \dots, y^{(n)}) = 0$  is said to be **linear 线性** if  $F$  is a linear function of  $y, y', \dots, y^{(n)}$ . Otherwise, the ODE is **nonlinear 非线性**.



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In vector form:  $\vec{a}(t) := (a_0(t), \dots, a_n(t))^T$ ,  $\vec{y}(t) := (y^{(n)}, y^{(n-1)}, \dots, y)^T$ ,

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$$3t^2y'' + 2[\sin(t)]y' + e^ty = \ln t$$

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L, L, NL, NL.

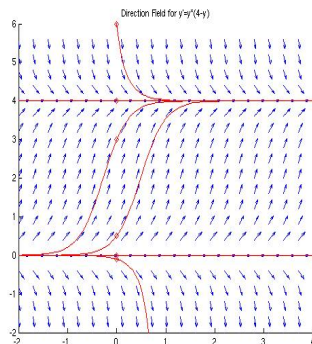
## Direction Fields. I

**Def 1.6.** Consider  $\frac{dy}{dt} = f(t, y)$ . The **direction field** 方向场/线索场 or **slope field** 斜率场 of this eq. is the picture in  $ty$ -plane that assigns each point  $(t, y)$  a short arrow or line segment with slope  $f(t, y)$ . **Nullclines** 零斜率线/零增长等值线 are the curves of zero inclination, i.e.,  $f(t, y) = 0$ .

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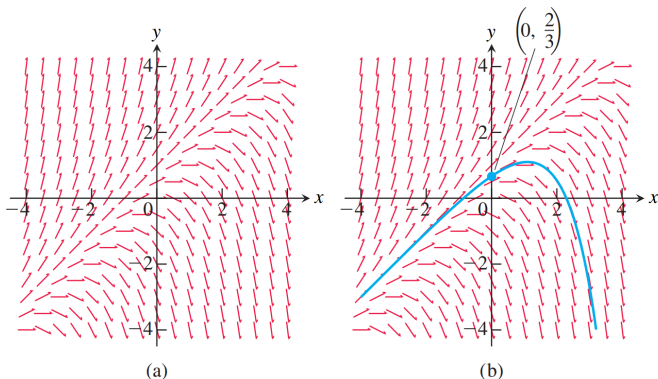
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Example 1. Direction field of  $y' = y(4 - y)$ .



# Direction Fields. II

## Example 2.



**FIGURE 9.2** (a) Slope field for  $\frac{dy}{dx} = y - x$ . (b) The particular solution curve through the point  $(0, \frac{2}{3})$  (Example 2).



For  $\frac{dy}{dt} = f(t, y)$ :

The set of all the solutions is called the **general solution**.

The solution curves in  $ty$ -plane are called **integral curves**.

# Modeling with ODEs

## Strategy:

1. Identify the independent and dependent variables. Choose the units of measurement for each variable.

Dimensionally consistent: all the terms in the equation should have the same units.

2. Articulate the basic principle that underlies or governs the problem, and express the principle into an equation.
3. Solve the equation.

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**Sol:** Step 1. Introduce variables

$M$ : mass of the object in unit  $kg$

$v(t)$ : velocity in unit  $m/s$

$a(t) = \frac{dv}{dt}$ : acceleration in unit  $m/s^2$

$G = Mg$ : gravity,  $g = 9.8 m/s^2$

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Dimensionally consistent:

$$kg \cdot \frac{m}{s} = (\text{unit of } \gamma) \cdot \frac{m}{s} \Rightarrow (\text{unit of } \gamma) = kg/s$$

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$r = 0.5$  per month: growth rate of mouse without owls, i.e.,  
 $\frac{dp}{dt} = rp$ .

Assume that the owls kill 15 mice per day, and thus kill  
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(rate of change of population = birth rate – death rate)



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Step 2. Set up the ODE:

$$\frac{dy}{dt} = 0.01 \times 300 - \frac{y}{10^6} \times 300, \quad y(0) = y_0.$$

(rate of change = rate in – rate out)



Solving initial value problem of the type:

$$\begin{cases} \frac{dy}{dt} = ay - b, \\ y(0) = y_0, \end{cases} \quad (1)$$

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The general solution of the DE (1)<sub>1</sub> is  $y(t) = -bt + C$ , where  $C$  is any constant.

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Let  $x(t) = y(t) - \frac{b}{a}$ . Then  $\frac{dx}{dt} = ax$ . Thus,  $x(t) = Ce^{at}$ , where  $C$  is any constant.

The general solution is  $y(t) = Ce^{at} + \frac{b}{a}$ , where  $C$  is any constant.

The special solution satisfying the given initial value is the one with  $C = y_0 - \frac{b}{a}$ . □