# Kai-Chieh Hsu

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I work on combining game-theoretic reasoning and machine learning techniques for safe human-centered robotic systems.

## Research Interests

**Machine Learning Human-Robot Interaction Multi-Agent Planning** 

Safe reinforcement learning (RL), adversarial RL and safe Sim2Real transfer Generative models and imitation learning for strategy and intent inference Game-theoretic counterfactual reasoning and iterative linear quadratic game

# **Education**

# **Princeton University (PU)**

Ph.D. Candidate in Electrical and Computer Engineering (ECE)

M.A. in Electrical and Computer Engineering

- Concentration: Machine learning and Robotics
- Achieved 4.0/4.0 GPA
- Thesis Advisor: Prof. Jaime Fernández Fisac

#### **National Taiwan University (NTU)**

B.S. in Electrical Engineering (EE)

· Concentration: Signal processing and Digital IC design

- Achieved 4.19/4.30 overall GPA and ranked in top 5%
- Research Advisors: Prof. An-Yeu (Andy) Wu and Prof. Jean-Fu Kiang

# **Work Experiences**

### **Engineering Intern**

San Diego, CA

Taipei, Taiwan

Qualcomm Technologies Inc. (Manager: Stephen Chaves, Mentor: Pranav Desai)

May 2023 - Aug. 2023

May 2022 - Dec. 2022

Princeton, NJ, USA

Sept. 2019 - May 2021

Sept. 2014 - Jan. 2019

Sept. 2021 - June 2024 (EXPECTED)

- · Proposed a unified neural backbone for agent predictor and behavior planner in autonomous vehicles software stack
- Used reinforcement learning and imitation learning for implementing behavior planners

#### Research Scientist Intern [C2]

Remote

NVIDIA Corporation (Manager: Prof. Marco Pavone, Mentor: Prof. Karen Leung, Yuxiao Chen)

- Formalized responsibility by safety margin decrease and policy shift with counterfactual reasoning
- Estimated the responsibility level online with hidden Markov model
- Incorporated the estimated responsibility into **trajectory prediction** models

# **Selected Publications**

#### **Journal Papers**

- [J1] K.-C. Hsu, Haimin Hu, and J. F. Fisac, The Safety Filter: A Unified View of Safety-Critical Control in Autonomous Systems, in Annual Review of Control, Robotics, and Autonomous Systems, (preprint).
- [J2] A. R. Kumar, K.-C. Hsu, P. J. Ramadge, and J. F. Fisac, Fast, Smooth, and Safe: Implicit Control Barrier Functions through Reach-Avoid Differential Dynamic Programming, in IEEE Control Systems Letters, vol. 7, pp. 2994-2999, June 2023.
- [J3] K.-C. Hsu\*, A. Z. Ren\*, D. P. Nguyen, A. Majumdar+, and J. F. Fisac+, Sim-to-Lab-to-Real: Safe Reinforcement Learning with Shielding and Generalization Guarantees, in Artificial Intelligence, Jan 2023. | Spotlight in ICLR Workshop and **NeurIPS Workshop**
- [J4] C.-Y. Chou, K.-C. Hsu, B.-H. Cho, K.-C. Chen, and A.-Y. (Andy) Wu, Low-Complexity On-demand Reconstruction for Compressively Sensed Problematic Signals, in IEEE Transactions Signal Processing, vol. 68, pp. 4094-4107, July 2020.

#### **Conference Papers**

- [C1] H. Hu, K. Nakamura, K.-C. Hsu, N. E. Leonard, and J. F. Fisac, Emergent Coordination through Game-Induced Nonlinear Opinion Dynamics, in Proc. IEEE Conf. Decision and Control, Singapore, Dec 2023.
- [C2] K.-C. Hsu, K. Leung, Y. Chen, J. F. Fisac, and M. Pavone, Interpretable Trajectory Prediction for Autonomous Vehicles via Counterfactual Responsibility, in IEEE/RSJ Int. Conf. Intelligent Robots & Systems, Detroit, MI, USA, Oct 2023.
- [C3] K.-C. Hsu\*, D. P. Nguyen\*, and J. F. Fisac, ISAACS: Iterative Soft Adversarial Actor-Critic for Safety, in Learning for Dynamics & Control, Philadelphia, PA, USA, Jun 2023.
- [C4] S. Narain, D. Chee, P. Iyer, E. Mak, R. Valdez, M. Zhu, N. Jha, J. F. Fisac, K.-C. Hsu, P. Terway, K. Pochiraju, B. Englot, E. Pitz, S. Rooney, and Y. Huang, AIMED: Al-Mediated Exploration of Design: An Experience Report, in Proc. IEEE Workshop on Design Automation for CPS and IoT, San Antonio, TX, USA, May 2023.
- [C5] H. Chen, K.-C. Hsu, W. Turner, P.-H. Wei, K. Zhu, D. Pan, and H. Ren, Reinforcement Learning Guided Detailed Routing for FinFET Custom Circuits, in Proc. Int. Symp. Physical Design, Virtually, Mar 2023.
- [C6] K.-C. Hsu\*, V. Rubies-Royo\*, C. J. Tomlin, and J. F. Fisac, Safety and Liveness Guarantees through Reach-Avoid Reinforcement Learning, in Proc. Robotics: Science and Systems, Virtually, July 2021.

# Honors & Awards

**SEAS Travel Grant** SEAS, PU, NJ, USA

Nov. 2022

**Teaching Assistant Award** Dept. of ECE, PU, NJ, USA

Sept. 2022

**3rd Prize** in Integrated Circuit Design Contest

Ministry of Education, Taiwan

· Out of about 300 teams

July 2018 High-speed RF and mm-Wave Tech. Center, Taiwan

**2nd Prize** in Taiwan Creative Electromagnetic Implementation Competition

• For the new Intelligent Robotic Systems course

Aug. 2017

• Under the supervision of Prof. Tzong-Lin Wu

Cadence, Taiwan

8th place in Data Structure and Programming Contest

Mar. 2017

· Out of about 250 students

Dept. of EE, NTU, Taiwan

**Graduate Representative** in NTUEE graduate ceremony

June 2018

• Given to top ten students of four years

Electromagnetic Industry-Academia Consortium, Taiwan

**Professor Chun-Hsiung Chen Scholarship** • Rewarded outstanding performances in electromagnetic fields

Jan. 2018

**Presidential Awards** 

Dept. of EE, NTU, Taiwan

• Given to top ten students of that semester

second semester of 2014 and 2016

# **Research & Teaching Experiences**

ELE364: Machine Learning for Predictive Data Analytics, Prof. Niraj Jha

**Teaching Assistant** ECE346/566: Intelligent Robotic Systems, Prof. Jaime Fernández Fisac

PU, NJ, USA Jan. 2022 - May 2022 Sept. 2020 - Dec. 2020

**Research Assistant** 

NTU, Taiwan Feb. 2018 - Mar. 2019

Access IC Lab, Prof. An-Yeu (Andy) Wu Group of Electromagnetic Applications, Prof. Jean-Fu Kiang

Feb. 2017 - Mar. 2019

**Teaching Assistant** 

NTU, Taiwan

Digital System Design

Feb. 2018 - June 2018

# **Professional Activities**

Reviewer Artificial Intelligence, IEEE RA-L, IEEE OJCS, IEEE TVT, IEEE TSP, IJRR, ICRA, L4DC, AAAI, CDC

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Program Committee NeurIPS Workshop on Human in the Loop Learning and Trustworthy Embodied Al

Skills

Program Languages Python, MATLAB, Verilog, C++

**Others** PyTorch, Jax, Git, SLURM, NumPyro, CVX, LTFX

# References.

**Karen Leung** 

Assistant Professor, Electrical and Computer Engineering, Princeton University Jaime Fernández Fisac

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Assistant Professor, Mechanical and Aerospace Engineering, Princeton University Anirudha Majumdar

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Assistant Professor, Aeronautics & Astronautics, University of Washington

Research Scientist, Autonomous Vehicle Research, NVIDIA

kymleungkymleung@uw.edu

Professor, Electrical and Computer Engineering, Princeton University **Peter Ramadge** 

ramadge@princeton.edu

Staff Research Scientist, Google Deepmind Jie Tan

jietan@google.com

Senior Staff Engineer, Qualcomm Research **Stephen Chaves** 

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