

# Kai-Chieh Hsu

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## Research Interests

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### Machine Learning

Safe reinforcement learning and safe Sim2Real transfer

### Human-Robot Interaction

Inverse reinforcement learning with active human feedback queries

### Multi-Agent Planning

Game-theoretic approach in a zero-sum differential game

## Education

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### Princeton University (PU)

Ph.D. Candidate in Electrical and Computer Engineering

M.A. in Electrical and Computer Engineering

Princeton, NJ, USA

Sept. 2021 - June 2024 (EXPECTED)

Sept. 2019 - May 2021

- Concentration: Machine learning and Robotics
- Achieved 4.0/4.0 GPA
- Thesis Advisor: Prof. Jaime Fernández Fisac

### National Taiwan University (NTU)

Taipei, Taiwan

B.S. in Electrical Engineering

Sept. 2014 - Jan. 2019

- Concentration: Signal processing and Digital IC design
- Achieved 4.19/4.30 overall GPA and ranked in **top 5%**
- Research Advisors: Prof. An-Yeu (Andy) Wu and Prof. Jean-Fu Kiang

## Research Projects

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### Safe Sim2Real Transfer

PU, NJ, USA

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

Intelligent Robot Motion Lab, Prof. Anirudha Majumdar, Allen Z. Ren

May 2021 - PRESENT

- Use a **supervisory control** scheme to allow the least-restrictive safe exploration
- Combine with **PAC-Bayes control** to provide a tight performance lower bound to unseen environments

### Inverse Specification

PU, NJ, USA

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

July 2020 - PRESENT

- Use Bayesian optimization to infer constraints **interactively with humans** by asking for ranking feedback
- **Select queries actively** to speed up the convergence to the true preference based on information-theoretic metrics
- Survey in **inverse optimal control** and **imitation learning**

### Reach-Avoid Reinforcement Learning

PU, NJ, USA

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

Hybrid Systems Laboratory, Prof. Claire J. Tomlin, Vicenç Rubies-Royo

July 2020 - March 2021

- Derive a time-discounted formulation of the reach-avoid optimal control problem that lends itself to **(deep) reinforcement learning** methods by inducing contraction mapping property
- Deploy our reach-avoid Q-Learning in a range of nonlinear systems, including an **attack-defense game**
- Reach-avoid reinforcement learning allows learning from near defeat and fits in **safe reinforcement learning**

### ECG Real-Time Telemonitoring

NTU, Taiwan

Access IC Lab, Prof. An-Yeu (Andy) Wu

Aug. 2017 - Mar. 2019

- **Edge Classification:** Incorporate **compressed sensing**, task-driven dictionary learning (predictive sparse coding) and PCA to render light-weighted classifier and overcome limited labeled data challenge
- **On-Demand Recovery:** Design a two-stage algorithm that classifies and reconstructs only problematic signals. This algorithm utilizes the information from classification stage to speed up the reconstruction algorithm
- **Hardware Design and Chip Implementation:** Propose a hardware architecture for on-demand recovery to allow hardware sharing between classification and reconstruction algorithms

## Direction-of-Arrival (DOA) Estimation








NTU, Taiwan

Group of Electromagnetic Applications, Prof. Jean-Fu Kiang

Feb. 2017 - Mar. 2019

- **Antenna Uncertainty:** Utilized special matrix structure with Khatri-Rao subspace-based Multiple Signal Classification (MUSIC) to improve immunity to uncertainties and detect DOAs with sensors half the number of sources
- **More Sources Than Sensors:** Proposed a new antenna array structure to increase the number of detectable sources based on fourth-order statistics and compressive sensing approach
- **Mixed Carrier Frequency (CF) Known and Unknown Sources:** Proposed a two-step algorithm to first estimate DOA of CF-known sources and then joint estimate the DOA and CF of CF-unknown sources

## Publications

- [7] **K.-C. Hsu\***, V. Rubies-Royo\*, C. J. Tomlin and J. F. Fisac, "Safety and Liveness Guarantees through Reach-Avoid Reinforcement Learning," in *Proceedings of Robotics: Science and Systems (RSS)*, Held Virtually, July 2021. | 
- [6] C.-Y. Chou, **K.-C. Hsu**, B.-H. Cho, K.-C. Chen and A.-Y. (Andy) Wu, "Low-Complexity On-demand Reconstruction for Compressively Sensed Problematic Signals," in *IEEE Trans. Signal Process.*, vol. 68, pp. 4094-4107, July 2020. | 
- [5] **K.-C. Hsu** and J.-F. Kiang, "Joint Estimation of DOA and Frequency From A Mixture of Frequency Known and Unknown Sources with Orthogonal Coprime Arrays," in *Sensors*, 19(2), 335, Jan. 2019. | 
- [4] **K.-C. Hsu\***, B.-H. Cho\*, C.-Y. Chou and A.-Y. (Andy) Wu, "Low-Complexity Compressed Analysis in Eigenspace with Limited Labeled Data for Real-Time Electrocardiography Telemonitoring," in *IEEE Global Conference on Signal and Information Processing (Global-SIP)*, Anaheim, USA, Nov. 2018. | 
- [3] **K.-C. Hsu** and J.-F. Kiang, "DOA Estimation With Triply Primed Arrays Based on Fourth-Order Statistics," in *IEEE AP-S Symposium on Antennas and Propagation and USNC-URSI Radio Science Meeting*, Boston, USA, July 2018. | 
- [2] **K.-C. Hsu** and J.-F. Kiang, "DOA Estimation Using Triply Primed Arrays Based on Fourth-Order Statistics," in *Progress In Electromagnetics Research M*, Vol. 67, pp. 55-64, Mar. 2018. | 
- [1] **K.-C. Hsu** and J.-F. Kiang, "DOA Estimation of Quasi-Stationary Signals Using a Partly-Calibrated Uniform Linear Array with Fewer Sensors Than Sources," in *Progress In Electromagnetics Research M*, Vol. 63, pp. 185-193, Jan. 2018. | 

## Honors & Awards

**3rd Prize** in Integrated Circuit Design Contest


Ministry of Education, Taiwan

- Out of about 300 teams

July 2018

**2nd Prize** in Taiwan Creative Electromagnetic Implementation Competition

High-speed RF and mm-Wave Tech. Center, Taiwan

- Under the supervision of Prof. Tzong-Lin Wu | 

Aug. 2017

**8th place** in Data Structure and Programming Contest

Cadence, Taiwan

- Out of about 250 students

Mar. 2017

**Digital IC Design Certificate**

National Chip Implementation Center, Taiwan

- Familiar with Verilog, logic synthesis, simulation and STA

Nov. 2018

**Graduate Representative** in NTUEE graduate ceremony

Dept. of EE, NTU, Taiwan

- Given to top ten students of four years

June 2018

**Professor Chun-Hsiung Chen Scholarship**

Electromagnetic Industry-Academia Consortium, Taiwan

- Rewarded outstanding performances in electromagnetic fields

Jan. 2018

**Presidential Awards**

Dept. of EE, NTU, Taiwan

- Given to top ten students of that semester

second semester of 2014 and 2016

## Research & Teaching Experiences

**Research Assistant**

PU, NJ, USA

Safe Robotics Lab, Prof. Jaime Fernández Fisac

Aug. 2020 - PRESENT

**Teaching Assistant**

PU, NJ, USA

ELE364: Machine Learning for Predictive Data Analytics

Sept. 2020 - Dec. 2020

**Research Assistant**

NTU, Taiwan

Access IC Lab, Prof. An-Yeu (Andy) Wu

Feb. 2018 - Mar. 2019

## Undergraduate Researcher

Group of Electromagnetic Applications, Prof. Jean-Fu Kiang

NTU, Taiwan

Feb. 2017 - Mar. 2019

## Teaching Assistant

Digital System Design

NTU, Taiwan

Feb. 2018 - June 2018

## Professional Activities

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**Reviewer** IEEE Transactions on Vehicular Technology, IETE Technical Review

## Skills

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- **Program Languages** Python, MATLAB, Verilog, C++
- **Others** PyTorch, Git, SLURM, NumPyro, CVX,  $\text{\LaTeX}$