Kai-Chieh Hsu

F-310 Engineering Quadrangle, 41 Olden Street, Princeton, New Jersey, U.S.A.

I work on combining safety analysis and machine learning techniques to enable autonomous systems in safety-critical setting and human-robot interaction.

Research Interests

Machine Learning Safe reinforcement learning and safe Sim2Real transfer

Human-Robot Interaction Inverse reinforcement learning with active human feedback queries

Multi-Agent Planning Game-theoretic approach in a zero-sum differential game

Education

Princeton University (PU)

Princeton, NJ, USA Ph.D. Candidate in Electrical and Computer Engineering Sept. 2021 - June 2024 (EXPECTED)

M.A. in Electrical and Computer Engineering Sept. 2019 - May 2021

• Concentration: Machine learning and Robotics

• Achieved 4.0/4.0 GPA

• Thesis Advisor: Prof. Jaime Fernández Fisac

National Taiwan University (NTU)

B.S. in Electrical Engineering Sept. 2014 - Jan. 2019

• Concentration: Signal processing and Digital IC design

 Achieved 4.19/4.30 overall GPA and ranked in top 5% • Research Advisors: Prof. An-Yeu (Andy) Wu and Prof. Jean-Fu Kiang

Research Projects

Inverse Specification PU, NJ, USA

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

July 2020 - PRESENT

Taipei, Taiwan

- Use Bayesian optimization to infer constraints interactively with humans by asking for ranking feedback
- Select queries actively to speed up the convergence to the true preference based on information-theoretic metrics
- Survey in inverse optimal control and imitation learning

Safe Sim2Real Transfer (Sim-to-Lab-to-Real)

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

Intelligent Robot Motion Lab, Prof. Anirudha Majumdar, Allen Z. Ren

May 2021 - January 2022

July 2020 - March 2021

- Use Reachability-Based RL and a supervisory control scheme to allow the least-restrictive safe exploration
- · Combine with PAC-Bayes control to provide a tight performance lower bound to unseen environments

Reach-Avoid Reinforcement Learning

Safe Robotics Laboratory, Prof. Jaime Fernández Fisac

Hybrid Systems Laboratory, Prof. Claire J. Tomlin, Vicenç Rubies-Royo

PU, NJ, USA

PU, NJ, USA

- Derive a time-discounted formulation of the reach-avoid optimal control problem that lends itself to (deep) reinforcement **learning** methods by inducing contraction mapping property
- Deploy our reach-avoid O-Learning in a range of nonlinear systems, including an attack-defense game
- Reach-avoid reinforcement learning allows learning from near defeat and fits in safe reinforcement learning

ECG Real-Time Telemonitoring

NTU, Taiwan

Access IC Lab, Prof. An-Yeu (Andv) Wu

Aug. 2017 - Mar. 2019

- Edge Classification: Incorporate compressed sensing, task-driven dictionary learning (predictive sparse coding) and PCA to render light-weighted classifier and overcome limited labeled data challenge
- **On-Demand Recovery**: Design a two-stage algorithm that classifies and reconstructs only problematic signals. This algorithm utilizes the information from classification stage to speed up the reconstruction algorithm
- Hardware Design and Chip Implementation: Propose a hardware architecture for on-demand recovery to allow hardware sharing between classification and reconstruction algorithms

January 2022

Direction-of-Arrival (DOA) Estimation

Group of Electromagnetic Applications, Prof. Jean-Fu Kiang

Feb. 2017 - Mar. 2019

NTU, Taiwan

- Antenna Uncertainty: Utilized special matrix structure with Khatri-Rao subspace-based MUltiple SIgnal Classification (MUSIC) to improve immunity to uncertainties and detect DOAs with sensors half the number of sources
- More Sources Than Sensors: Proposed a new antenna array structure to increase the number of detectable sources based on fourth-order statistics and compressive sensing approach
- Mixed Carrier Frequency (CF) Known and Unknown Sources: Proposed a two-step algorithm to first estimate DOA of CF-known sources and then joint estimate the DOA and CF of CF-unknown sources

Publications

- [1] K.-C. Hsu*, V. Rubies-Royo*, C. J. Tomlin and J. F. Fisac, "Safety and Liveness Guarantees through Reach-Avoid Reinforcement Learning," in Proceedings of Robotics: Science and Systems (RSS), Held Virtually, July 2021.
- [2] C.-Y. Chou, K.-C. Hsu, B.-H. Cho, K.-C. Chen and A.-Y. (Andy) Wu, "Low-Complexity On-demand Reconstruction for Compressively Sensed Problematic Signals," in IEEE Trans. Signal Process., vol. 68, pp. 4094-4107, July 2020.
- [3] K.-C. Hsu and J.-F. Kiang, "Joint Estimation of DOA and Frequency From A Mixture of Frequency Known and Unknown Sources with Orthogonal Coprime Arrays," in Sensors, 19(2), 335, Jan. 2019.
- [4] K.-C. Hsu*, B.-H. Cho*, C.-Y. Chou and A.-Y. (Andy) Wu, "Low-Complexity Compressed Analysis in Eigenspace with Limited Labeled Data for Real-Time Electrocardiography Telemonitoring," in IEEE Global Conference on Signal and Information Processing (GlobalSIP), Anaheim, USA, Nov. 2018. |
- [5] K.-C. Hsu and J.-F. Kiang, "DOA Estimation With Triply Primed Arrays Based on Fourth-Order Statistics," in IEEE AP-S Symposium on Antennas and Propagation and USNC-URSI Radio Science Meeting, Boston, USA, July 2018. |
- [6] K.-C. Hsu and J.-F. Kiang, "DOA Estimation Using Triply Primed Arrays Based on Fourth-Order Statistics," in *Progress In Electromagnetics* Research M, Vol. 67, pp. 55-64, Mar. 2018.
- [7] K.-C. Hsu and J.-F. Kiang, "DOA Estimation of Quasi-Stationary Signals Using a Partly-Calibrated Uniform Linear Array with Fewer Sensors Than Sources," in Progress In Electromagnetics Research M, Vol. 63, pp. 185-193, Jan. 2018. |

Honors & Awards

3rd Prize in Integrated Circuit Design Contest

· Out of about 300 teams

2nd Prize in Taiwan Creative Electromagnetic Implementation Competition

• Under the supervision of Prof. Tzong-Lin Wu

8th place in Data Structure and Programming Contest

· Out of about 250 students

Digital IC Design Certificate

• Familiar with Verilog, logic synthesis, simulation and STA

Graduate Representative in NTUEE graduate ceremony

• Given to top ten students of four years

Professor Chun-Hsiung Chen Scholarship

Rewarded outstanding performances in electromagnetic fields

Presidential Awards

• Given to top ten students of that semester

Ministry of Education, Taiwan

July 2018

High-speed RF and mm-Wave Tech. Center, Taiwan

Aug. 2017

Cadence, Taiwan

Mar. 2017

National Chip Implementation Center, Taiwan

Nov. 2018

Dept. of EE, NTU, Taiwan

June 2018

Electromagnetic Industry-Academia Consortium, Taiwan

Jan. 2018

Dept. of EE, NTU, Taiwan

second semester of 2014 and 2016

Research & Teaching Experiences

Teaching Assistant

ECE346/566: Intelligent Robotic Systems, Prof. Jaime Fernández Fisac ELE364: Machine Learning for Predictive Data Analytics, Prof. Niraj Jha

Research Assistant

Access IC Lab, Prof. An-Yeu (Andy) Wu Group of Electromagnetic Applications, Prof. Jean-Fu Kiang

Teaching Assistant

Digital System Design

PU, NJ, USA

Jan. 2022 - May 2022 Sept. 2020 - Dec. 2020

NTU, Taiwan Feb. 2018 - Mar. 2019

Feb. 2017 - Mar. 2019

NTU, Taiwan

Feb. 2018 - June 2018

2 January 2022

Professional Activities

Reviewer

IEEE Transactions on Vehicular Technology, IETE Technical Review, IEEE Transactions on Signal Processing, Conference on Information Sciences and Systems

Skills_

• Program Languages

Python, MATLAB, Verilog, C++

Others

PyTorch, Git, SLURM, NumPyro, CVX, ŁTEX

January 2022

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