

push_pop

Fig.3 Face & Fink

- node A can be "pushed" into A' & B
- node A' & B can be "popped" into A

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```
In [1]: import numpy as np
import networkx as nx
import matplotlib.pyplot as plt
import random
```

```
In [2]: def get_adj(H):          ①
    A = nx.adjacency_matrix(H)
    print(A.todense())
    print("\n")
    return
```

① function to return adjacency matrix from graph

```
def get_maxclique(H, num):
    check = False
    n = 1
    Y = nx.find_cliques(H)
    ② for i in Y:
        #print(i)
    ③ if len(i) != 3:
        check = True
        print(i)
    ④ if num == 0:
        plt.figure(n, figsize=(1,1))
        nx.draw(H.subgraph(i).copy(), pos=nx.spring_layout(H), node_color='lightgray',
                edge_color='black', with_labels=True)
        n += 1
    print("\n")
    return check
```

② find_cliques finds all the cliques within the graph

③ Did a check to make sure all cliques remain 3

④ if input parameter is a zero, print out all the cliques graphically, rather than in list form.

```
(5) def get_testgraph():
    list = [i for i in range(0,8)]
    print(list)
    H = nx.Graph()
    for i in list:
        H.add_node(i)
    H.add_edge(0,1)
```

⑤ function to create a triangular planar graph like in fig 3 of Face & Fink.
(mainly for troubleshooting purposes)

```

H.add_edge(0,2)
H.add_edge(0,3)
H.add_edge(0,4)
H.add_edge(0,5)
H.add_edge(1,2)
H.add_edge(1,5)
H.add_edge(1,6)
H.add_edge(1,7)

H.add_edge(2,3)
H.add_edge(3,4)
H.add_edge(4,5)
H.add_edge(5,6)
H.add_edge(6,7)
H.add_edge(2,7)

nx.draw(H, pos=nx.spring_layout(H), node_color='lightgray', \
         edge_color='black', with_labels=True)
return H

```

In [4]: def push(G):
 check = True
 (6) while check is True:

(6) while loop
because sometimes
the random chosen
node cannot be
"pushed" so the
process will have
to start over.

```

listofnodes = [k for k in G] (7)
node = random.choice(listofnodes)
print('random node: ', node)

nbr = [n for n in G[node]] (8)
print('neighbor: ', nbr)

p = random.choice(nbr)
for q in nbr:
    #print(q)
    (9) boo = p in G.neighbors(q)
    if boo == False and p != q:
        print('Chosen neighbors: ', p,q)
        break

    if boo == True or p == q:
        (10) print('ERROR: Did not find neighbors\n')
        continue

```

(10) Sometimes we loop through nbr
and none of the q is satisfactory,
we "continue", meaning "check=True"
throughout the rest of the while loop
restarts the process

2

(7) get a list of all the nodes,
nodes get added & deleted as
graph evolves so the random.
choice has to be from this list.

(8) getting a list of neighbours
of the randomly chosen nodes.

(9) - nodes P & Q (refer to fig 3
Farr & Fink) must have at
least 1 node separating them.

- I randomly choose p from
nbr and I loop through
nbr to see if they are
connected, if boo ("boolean")
is false, meaning P
and the current q are
not neighbors (and $p \neq q$),
we can break out of loop.

(11) nodes are enumerated, $\max(G.nodes)$ gives the highest value of all current existing nodes. We name the new_node the next value.

else:

```
(11)
    new_node = max(G.nodes)+1
    G.add_node(new_node)
    print('Adding new_node: ', new_node)
```

(12) Remove all edges to A ("Farr & Fink fig 3")

```
(12)
    for i in nbr:
        G.remove_edge(node,i)
        #print('Removing all edges to ...', node)
    G.add_edge(node,new_node) (13)
```

(13) A' & B are always connected (fig 3)

(15) I sorted the list of neighbors ("nbr")

into a clockwise or anti-clockwise manner,
i.e. [0, 5, 6, 7, 2]

or

[0, 2, 7, 6, 5]

which makes it easier to distinguish the "left" and "right" side of nodes P & Q (fig 3).

(17) We need the "not already in sort-nbr" condition because of the following:

MAP a - d - c - b

nbr = [a, b, c, d]
sort-nbr = [a]

- As we loop through nbr, d gets appended first as it is connected to a.

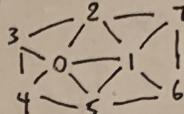
sort-nbr = [a, d]

- next, c gets appended as it is connected to d, however, c is also connected to a,

we'd end up with
[a, d, c, c]

(14) Tricky part. Looking at the RHS of fig 3, we see half the neighbors belong to A' and the other half belong to B. However, networkx will list out the nodes neighbors in numerical ascending order.

Ex.



neighbors of node 1 will be [0, 2, 5, 6, 7] so its hard to split them into left & right half like in fig. 3.

sort_nbr = [nbr[0]] (14)

check1 = False

while check1 is False:

(15) for i in range(1, len(nbr)):

if (nbr[i] in G.neighbors(sort_nbr[-1])) == True and (nbr[i] in so

rt_nbr.append(nbr[i])

(16) if (nbr[i] in G.neighbors(sort_nbr[0])) == True and (nbr[i] in sor

t_nbr.insert(0, nbr[i])

if len(sort_nbr) == len(nbr):

check1 = True

break

print(sort_nbr)

(17)

(16) So first I created a list ("sort-nbr") and append the first element of the existing nbr list, just because the sorting needs to start somewhere.

- 1st if statement: if i is connected to the last element of sort-nbr, append AND i is not already in sort-nbr, append.

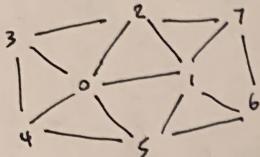
- 2nd if statement: if i is connected to the first element of sort-nbr AND i not in sort-nbr already, append.

- This algorithm creates the clockwise/counter-clockwise ordering.

(18) - Create empty lists to store
 "left" & "right" side neighbors (fig 3)
 i.e. temp1 will store all neighbors
 to the left of nodes P & Q

- Sorting method:

(19)



Assume node A = 1
 $P = 2$
 $Q = 6$

sort_nbr = [0, 2, 7, 6, 5]

- retrieve list index of P & Q

so $P = 2$ has index 1,

and $Q = 6$ has index 3.

- all values in sort_nbr with index number
 between the index of P & Q (i.e. 1 and 3),
 they are append into temp1.

- all other goes into temp2

(20) if sort_nbr is

[0, 5, 6, 7, 2]

$P = 2$ has index 4

and $Q = 6$ has index 2,
 because P now has
 a higher index than Q,
 the previous

$P \leq \text{values} \leq Q$

wouldn't work, ~~that~~
 instead we need the

condition to be

$Q \leq \text{values} \leq P$ and

append the values with
 separate conditions.

(18) temp1 = []

temp2 = []

if sort_nbr.index(p) < sort_nbr.index(q):

for i in range(0, len(sort_nbr)):

if i >= sort_nbr.index(p) and i <= sort_nbr.index(q):

(19) temp1.append(sort_nbr[i])

if i <= sort_nbr.index(p) or i >= sort_nbr.index(q):

temp2.append(sort_nbr[i])

else:

for i in range(0, len(sort_nbr)):

if i <= sort_nbr.index(p) and i >= sort_nbr.index(q):

temp1.append(sort_nbr[i])

(20) if i >= sort_nbr.index(p) or i <= sort_nbr.index(q):

temp2.append(sort_nbr[i])

print(temp1, temp2)

for i in temp1:

G.add_edge(node, i) (21)

node_nbr = [i for i in G[node]] (23)

#print('Neighbors of %i: ' % node, node_nbr)

for i in temp2:

G.add_edge(new_node, i) (24)

(21) Connecting nodes in
 temp1 with node A'
 (fig 3),
 same with temp2 to B

- (23) Storing neighbors of A' & B,
not necessary but I pointed them
for troubleshooting purposes.
- (24) Set check = False so while loop will
stop since we've already "pushed" once
successfully.

- (25) Same thing, while loop because condition
to "pop" might not be satisfactory
somewhere.

```
new_node_nbr = [i for i in G[new_node]] (23)
#print('Neighbors of %i: ' %new_node, new_node_nbr)

check = False (24)
print('SUCCESS\n')
```

In [126]: def pop(G):
 check = True (25)
 while check is True:

- (26) Check number of
elements in nbr
because we need at
least 2. Once
nbr has enough elements,
the 2nd random node, which
I called "node2" aka node B (fig 3)
is just set to be whatever
element in nbr
that we are on.

```
listofnodes = [k for k in G]
node = random.choice(listofnodes)

nbr = [n for n in G[node]]
#print('neighbor: ', nbr)
```

```
(26) nbr = []
for i in nbr:
    nbr2 = [n for n in G[i]]
    #print(nbr2)
    for j in nbr2:
        if (j in nbr) == True and j != node:
            nbr.append(j)
        else:
            continue
    if len(nbr) >= 2:
        node2 = i
        break
    else:
        nbr.clear()
```

- (27) If element i, or
"node2" or node B
does not have at least
2 shared neighbors, nbr,
clear the nbr list
and proceed to check
the next element i within
the nbr list.

(26) Here's how I choose
A' and B so they can be
popped to just A. You
start with a random chosen
node and you get all of its
neighbors, nbr. You want to
check whether a neighbor of
"random node" has two shared
neighbors with "random node".
i.e. A' is the random node,
B is the neighbor from nbr.
P & Q are the shared
neighbors.

- So I loop through nbr, choose
a neighbor, get the neighbors
of that neighbor, which I
call nbr2, and I check
whether the elements of
nbr2 are also in nbr.

- (27) If a node is in both nbr & nbr2
but not being the random node,
I append it to a list called nbr.
I keep checking because we need
2 elements in nbr2 that is also
in nbr, i.e. P & Q.

(30) need another check here because sometimes
none of the elements in nbr satisfy the condition
and nbr just remains empty, we will have to restart from beginning.

(31) if there is enough
shared neighbors, we
can just set the first
2 elements as p & q.
(30) if len(nnbr) < 2:
print('ERROR: The two chosen nodes did not have enough shared neighbors\\
continue
print('Chosen random nodes: ', node, 'and', node2)
p = nnbr[0]
q = nnbr[1]
print('Chosen neighbors: ', p, 'and', q)

(32) I made copies of neighbors of A' ("nbr") and neighbors of B ("nbr2").

(33) We need to test whether neighbors of A' are connected with neighbors of B, excluding
the "special" node which are A', B, P, and Q (aka "node", "node2", "p", and "q").
So I deleted the "special" node for temp1 and temp2, which are copies of nbr and nbr2.

(34) Start of algorithm to check if temp1 and temp2 have any ~~shared neighbors~~ connecting
elements because that's not allowed.

(32) temp1 = nbr.copy()
temp2 = nbr2.copy()

(33) temp1.remove(p)
temp1.remove(q)
temp1.remove(node2)
temp2.remove(p)
temp2.remove(q)
temp2.remove(node)

(34) check1 = False
for i in temp1:

(35) In this line of code, i is an element of temp1 and j is an element of temp2 ,
if i and j are connected, $\text{check1} = \text{true}$.

```
if check1 == True:  
    print('break') (36)  
    break  
else:  
    for j in temp2:  
        check1 = i in G.neighbors(j) (35)  
        if check1 == True:  
            break  
        else:  
            continue  
    if check1 == True:  
        print("ERROR: Neighbors of node and node2 are connected.")  
        print('Exiting... \n') (37)
```

(37) Once we break out of loop,
we have to start over.

(38) If temp1 has no connecting elements with temp2 , by the "pop" algorithm, node B disappears,
A' becomes node A, and A gets all the neighbors of A' and B, which is $\text{temp1} + \text{temp2}$.

```
else:  
    new_nbr = temp1 + temp2 (38)  
    new_nbr.append(p)  
    new_nbr.append(q)  
    #print(new_nbr)  
  
    for i in nbr:  
        #print(i)  
        G.remove_edge(node, i) (40)  
    print('Removing all edges to ...', node)  
  
    for i in nbr2:  
        if i != node:  
            G.remove_edge(node2, i)  
    print('Removing all edges to ...', node2)  
  
    G.remove_node(node2)  
  
    for i in new_nbr:  
        G.add_edge(node, i)  
    print('Adding required edges...')  
    print('SUCCESS\n')  
    check = False
```

(41) Make check equal False to break
out of while loop since we now have
one successful pop.