Large Matrix Manipulation for Unfolding Optimization

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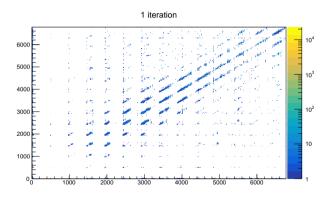
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Overview

- I have been dealing with covariance matrices of size 6776×6776 for optimizing the number of iterations in iterative unfolding.
- In this study, RooUnfold is used to calculate the covariance matrix.
- Matrix manipulation is done with PyROOT, root_numpy, and numpy.linalg.
- It turns out large matrices are hard to manipulate numerically.

Welcome to numerical linear algebra!

Visualizing a Covariance Matrix



- Log scale is used to make the structure more visible.
- Obviously this matrix is singular due to rows and columns with elements all zero. Those are unoccupied bins and unavoidable.

Metric for Iteration Optimization and Inverting (Nearly) Singular Matrices

• For the metric, we use average global correlation coefficient¹.

$$\rho_{avg} = \frac{1}{N} \sum_{j=1}^{N} \rho_j$$

$$\rho_j = \sqrt{1 - \frac{1}{[\mathbf{V}]_{jj}[\mathbf{V}^{-1}]_{jj}}}$$

, where j runs through all bins and \mathbf{V} the covariance matrix.

- Since V is singular, I have tried several ways to deal with this.
- I tried removing the zero rows and columns. I will talk about this later.
- I also tried pseudoinverse (Moore-Penrose inverse). I will not define it, but cite important properties here.
 - For any matrix A, there exists a unique pseudoinverse of it, denoted A^+ .
 - 2 If **A** is invertible, $\mathbf{A}^{-1} = \mathbf{A}^+$.

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¹Data Unfolding Methods in High Energy Physics

Playing with Pseudoinverse

```
[0,7942625476679229. 0,8002848352198804. 0,5855932326975848. 0,5704565563999852
average global correlation coefficient of a
 0.6876492929963434
  -0.027 A.
                 0.016 0.013 0.03311
rho vector
 [0.7942625476679226, 0.0, 0.8002848352198803, 0.5855932326975843, 0.5704565563999848]
average global correlation coefficient of b
 0.5501194343970744
```

- I generated a random symmetric matrix **A**, and manually set the second row and column to zero.
- The pseudoinverse of A is calculated.
- 3 The ρ vector of **A** is calculated.
- 4 A second matrix **B** is generated by copying **A** and setting the 0 on the diagonal to 0.05. (Following Matt Judah)
- 5 The inverse of **B** is calculated.
- 6 The ρ vector of ${f B}$ is calculated.
- The two results are identical except where they are different to start with.
- I did the bench testing because even I made the zero diagonal elements 0.05 in the real covariance matrices, they were still singular.

Nonphysical Values of ρ_j 's

• As the paper and the name (correlation coefficient) suggest, a valid ρ_j should be in the range

$$0 \le \rho_j = \sqrt{1 - \left(\mathbf{V}_{jj}\mathbf{V}_{jj}^{-1}\right)^{-1}} \le 1 \tag{1}$$

• Eq. (1) is satisfied if and only if

$$\mathbf{V}_{jj}\mathbf{V}_{jj}^{-1} \ge 1 \tag{2}$$

- I went on to use pseudoinverse to calculate ρ_{avg} , and found that only a fraction of all ρ_j 's satisfy Eq. (2).
- I started to suspect that the inverse process involved is numerically unstable.

Condition Number and $\mathbf{V}_{jj}\mathbf{V}_{jj}^{-1}$

- Consider the linear equation Ax = b. If small changes in b imply small changes in the solution x, then A has a small condition number. Otherwise A has a big condition number.
- Not surprisingly, nearly singular matrices have large condition numbers.
- Since I don't know how to prove Eq. (2) mathematically, I did what an experimentalist does: do some experiments.
- I generated random positive semidefinite matrices to simulate covariance matrices, and look at their condition numbers and $\mathbf{V}_{jj}\mathbf{V}_{jj}^{+}$'s.

Condition Number and $V_{jj}V_{jj}^{-1}$ (Cont.)

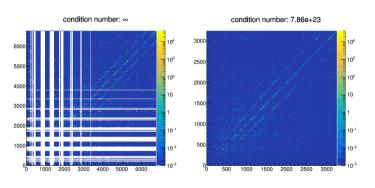
```
well-conditioned example
                                                                               ill-conditioned example
positive semidefinite matrix V
                                                                    positive semidefinite matrix V
[[ 80.844 101.687 -7.097
                            3.693 - 37.2071
                                                                    [[53.276 - 19.187 - 71.864 - 33.168 - 44.791]
 [101.687 \ 227.373 \ -87.639 \ 15.71 \ -42.425]
                                                                     [-19.187 \quad 10.654 \quad 23.82 \quad 3.057 \quad 17.234]
                                                                     [-71.864 23.82 98.07 49.632 59.81]
[-33.168 3.057 49.632 41.747 25.265]
  -7.097 -87.639 223.402 64.78
                                       61.9581
  3.693 15.71 64.78 118.352 24.211]
 [-37.207 - 42.425 \quad 61.958 \quad 24.211 \quad 78.489]]
                                                                     [-44.791 17.234 59.81 25.265 37.982]]
condition number of V
                                                                    condition number of V
                                                                    1.582e + 17
34.26
V ii *(V^+) ii
                                                                    V ii *(V^+) ii
[4.675 4.628 2.953 1.431 2.122]
                                                                    [0.13 0.097 0.204 1.237 0.142]
```

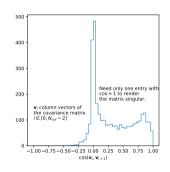
Out of those tens of random positive semidefinite matrices, they showed invariably that,

- If the condition number is small (say, < 1000), $\mathbf{V}_{jj}\mathbf{V}_{jj}^{+} \geq 1$ is always true for all j.
- If the condition number is large (i.e., in scientific notation), $\mathbf{V}_{jj}\mathbf{V}_{jj}^+ \geq 1$ is not satisfied for some or all j.

Bottom line: $\mathbf{V}_{jj}\mathbf{V}_{jj}^{+}\geq 1$ is true for all j only if \mathbf{V} is well-conditioned.

Removing Zero Rows and Columns Does Not Help!



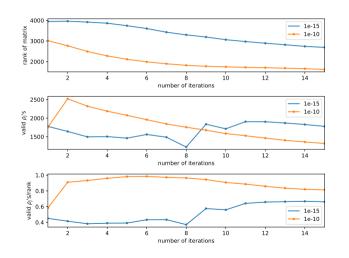


- Plots are with 2 iterations. Similar situation applies to all iterations.
- The reason is a large matrix becomes nearly singular if it contains highly correlated rows or columns.
- The adjacent columns of a covariance matrix are very often highly correlated.
- Of course, smaller matrices are always better. Will move to using the zero suppressed matrices.

The Rank and Inverse of a Large Matrix Actually Depend on a Small Tolerance!

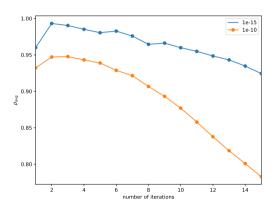
- Intuitively, the number of valid ρ_j 's should not exceed the rank of the matrix. Therefore, knowing the rank of the matrix helps understand the problem.
- Turns out the rank of a large matrix depends on a small tolerance ϵ . Singular values obtained by SVD (singular value decomposition) that are smaller than ϵ are set to exact zero to avoid numerical instability. This is called low-rank approximation (or truncated SVD), and regarded as a way of regularizing the linear system.
- The same tolerance applies to obtaining the pseudoinverse of the matrix since the most common algorithm used to calculated the pseudoinverse is using SVD.
- I am going to show you the ranks, the ρ_{avg} 's among valid ρ_j 's of the covariance matrices as a function of number of iterations and compare results obtained with two different tolerance values.

Different Tolerance Values Result in Different Number of Valid ρ_i



- Different iterations give different covariance matrices.
- With $\epsilon=10^{-15}$, some matrices have ranks larger than the size of the zero-suppressed counterparts! This is evidence of numerical instability.
- A criterion for how well a matrix is regularized in this study can be the ratio of the number of valid ρ_j 's to the rank. In this sense, $\epsilon = 10^{-10}$ should give a more reliable measure.

ρ_{avq} Results, Work to Do



- Although the results depend on tolerance, the *trends* with iterations are the same.
- Obviously I need to extend the plots to at least 100. I will sample iterations in [1, 1000] and see if a minimum exists.
- I have to run the analysis on grid, or implement a much faster covariance matrix calculation algorithm.
- If there are any other iteration optimization metrics that are much easier to wield, I am happy to switch over...