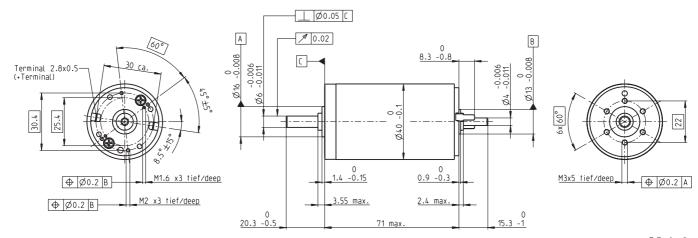
## RE 40 Ø40 mm, Graphite Brushes, 150 Watt



M 1:2

													IVI	
Stock program Standard program Special program (on request)		Part Numbers												
		148866	148867	148877	218008	218009	218010	218011	218012	218013	218014			
Motor Data														
Values at nominal voltage														
1 Nominal voltage	V	12	24	48	48	48	48	48	48	48	48			
2 No load speed	rpm	6920	7580	7590	6420	5560	3330	2690	2130	1720	1420			
3 No load current	mA	241	137	68.6	53.6	43.7	21.9	16.6	12.5	9.66	7.76			
4 Nominal speed	rpm	6380	6940	7000	5810	4930	2710	2060	1510	1080	781			
5 Nominal torque (max. continuous torque)	mNm	94.9	177	187	186	180	189	190	192	192	190			
6 Nominal current (max. continuous curren	t) A	6	6	3.17	2.66	2.23	1.4	1.13	0.909	0.73	0.6			
7 Stall torque	mNm	1720	2420	2560	2040	1620	1020	814	655	523	424			
8 Starting current	Α	105	80.2	42.4	28.6	19.7	7.43	4.79	3.06	1.97	1.32			
9 Max. efficiency	%	87	91	92	91	91	89	89	88	87	85			
Characteristics	_													
10 Terminal resistance	Ω		0.299	1.13	1.68	2.44	6.46	10	15.7	24.4	36.3			
11 Terminal inductance	mH		0.0823	0.329	0.46	0.612	1.7	2.62	4.14	6.4	9.31			
12 Torque constant	mNm/A	16.4	30.2	60.3	71.3	82.2	137	170	214	266	321			
13 Speed constant	rpm/V	581	317	158	134	116	69.7	56.2	44.7	35.9	29.8			
14 Speed / torque gradient	rpm/mNm	4.05	3.14	2.97	3.16	3.45	3.29	3.31	3.27	3.29	3.37			
15 Mechanical time constant	ms	5.89	4.67	4.28	4.2	4.19	4.16	4.15	4.15	4.15	4.16			

gcm<sup>2</sup> 139 142 137 127 116 121 120 121 120

## **Specifications Operating Range** Comments Thermal data n [rpm] 4.7 K/W Thermal resistance housing-ambient 150 W In observation of above listed thermal resistance Thermal resistance winding-housing 1.9 K/W 12000 (lines 17 and 18) the maximum permissible winding 19 Thermal time constant winding 41.5 stemperature will be reached during continuous op-20 Thermal time constant motor 736 s eration at 25°C ambient. -30...+100°C 8000 Ambient temperature = Thermal limit. 22 Max. permissible winding temperature +155°C Mechanical data (ball bearings) 4000 Short term operation Max. permissible speed 12000 rpm The motor may be briefly overloaded (recurring). 0.05 - 0.15 mm 24 Axial play Radial play 0.025 mm 100 150 M [mNm] Max. axial load (dynamic) 5.6 N Assigned power rating 2.0 3.0 4.0 LIA Max. force for press fits (static) (static, shaft supported) 110 N 1200 N Max. radial load, 5 mm from flange 28 N maxon Modular System Other specifications Overview on page 20-25 Number of pole pairs **Planetary Gearhead Encoder MR** 30 Number of commutator segments 13 Ø42 mm 256 - 1024 CPT, 480 g Weight of motor 3 - 15 Nm 3 channels Page 283 Page 320 Values listed in the table are nominal. Encoder HED\_ 5540 500 CPT, **Planetary Gearhead** Explanation of the figures on page 79. Ø52 mm 4 - 30 Nm 3 channels Option Page 287 Page 325/327 Preloaded ball bearings Brake AB 28 24 VDC 0.4 Nm Recommended Electronics: ESCON Mod. 50/5 Page 34 Page 372 Page 343 Industrial Version Encoder HEDL 9140 ESCON 50/5 ESCON 70/10 EPOS2 24/5 344 Page 331 351 EPOS2 50/5 351 Brake AB 28 EPOS2 70/10 EPOS2 P 24/5 351 Page 373 End cap 354 EPOS3 70/10 EtherCAT 357 Page 377 MAXPOS 50/5 360 Notes 114 maxon DC motor April 2014 edition / subject to change

16 Rotor inertia