Modelling 5G Network Cascade in the United States

For these simulations, I used Networkx, a python library with built in graph generators. I built a number of functions to

- Create a graph
- · Print a graph
- · Seed a starting early adopter
- · Evaluate whether a node in the graph should adopt 5G
- · Iterate through the graph in a cascade
- · Calculate the density of a cluster within the graph

I created all of this code myself with the exception of the getClusters definition, which I drew from existing code on how to find clusters in a graph.

Note: There is randomness in the seeding of the graphs and start nodes. As such, the output here may not match the results in the report.

Basic Functions

```
In [1]: import networkx as nx
   import random
   import matplotlib.pyplot as plt
   import re
   from sklearn.cluster import AffinityPropagation
   import numpy as np
```

```
In [2]: # set cluster numbers
        # drawn from this stackoverflow answer https://stackoverflow.com/questio
        ns/49064611/how-to-find-different-groups-in-networkx-using-python
        def getClusters(graph):
            nn = len(G.nodes)
            mat = np.empty((nn, nn), dtype=float)
            mat.fill(-100.0)
            np.fill diagonal(mat, -0.0)
            preds = nx.jaccard coefficient(G, G.edges)
            for u, v, j in preds:
                mat[u,v] = -100 * (1 - j)
            from sklearn.cluster import AffinityPropagation
            np.median(mat)
            af = AffinityPropagation(affinity="euclidean", random state = 0)
            lab = af.fit predict(mat)
            return lab
```

```
In [4]: # select random starting node and update attribute

def setStartNode(graph):
    eligibleNodes = [x for x,y in G.nodes(data=True) if y['access5G']==1
]
    start = random.choice(eligibleNodes)
    #start = random.randint(0, len(list(graph))-1)
    nx.set_node_attributes(graph, {start: {"adopt5G":1, "start":1, "checked":1}})
    return start
```

```
In [5]: # determine proportion of neighbors who adopted 5G
# d = number of neighbors
# p = proportion of neighbors who's adopted a

def neighborAdopters(graph, node_number):
    neighbors = list(nx.neighbors(graph, node_number))
    d = len(neighbors)
    G_small = graph.subgraph(neighbors)
    adoption = len([x for x,y in G_small.nodes(data=True) if y['adopt5G']
]==1])
    p = adoption / d
    nx.set_node_attributes(graph, {node_number: {"p":p}})
    nx.set_node_attributes(graph, {node_number: {"neighbors":neighbors}})
```

```
In [6]: # set adoption threshold
# a = payoff of both adopting a (5G)
# b = payoff of both adopting b (4G)

def updateThreshold(graph, node_number,a,b):
    nx.set_node_attributes(graph, {node_number: {"checked":1}})
    p = nx.get_node_attributes(G,'p')[node_number]
    eligible = nx.get_node_attributes(G,'access5G')[node_number]
    print('p', p)
    print('b/a+b',(b/(a+b)))
    print('access to 5g?', nx.get_node_attributes(G,'access5G')[node_number]==1)
    print('adopt 5g?', (p >= b/(a+b)) and eligible==1)

if (p >= b/(a+b)) and eligible==1:
    nx.set_node_attributes(graph, {node_number: {"adopt5G":1}})
```

```
In [7]: # print graph color coded to show adoption of 5G
        # blue = starting node
        # red = adopt 5G
        # green = access to 5G
        def printGraph(graph):
            start = [x for x,y in graph.nodes(data=True) if y['adopt5G']==1 and
        y['start']==1]
            eligibles = [x for x,y in graph.nodes(data=True) if y['access5G']==1
        and y['start']==0 and y['adopt5G']==0]
            adopters = [x for x,y in graph.nodes(data=True) if y['adopt5G']==1 a
        nd y['start']==0]
            nonadopters = [x for x,y in graph.nodes(data=True) if y['adopt5G']==
        0 and y['access5G']==0]
            labels = \{\}
            for n in G:
                if n in eligibles:
                     labels[n] = 'eligible'
                if n in adopters:
                     labels[n] = '5G'
            pos = nx.spring_layout(G, seed=3113794652) # positions for all node
            options = {"edgecolors": "tab:gray", "node_size": 800}
            options = {"edgecolors": "tab:gray", "node_size": 800, }
            nx.draw networkx nodes(G, pos, nodelist=start, node color="tab:blue"
        , **options)
            nx.draw networkx nodes(G, pos, nodelist=adopters, node color="tab:re
        d", **options)
            nx.draw networkx nodes(G, pos, nodelist=nonadopters, node color="ta
        b:grey", **options)
            nx.draw networkx nodes(G, pos, nodelist=eligibles, node color="tab:g
        reen", **options)
            nx.draw networkx edges(G, pos, width=1.0, alpha=0.5)
            labels = \{\}
            for n in G:
                labels[n] = n
            nx.draw_networkx_labels(G, pos, labels,font size=12, font color="whi
        tesmoke")
            ax = plt.gca()
            ax.margins(0.25)
            plt.axis("off")
            plt.show()
```

```
In [8]: # determine whether node will adopt

def algorithm(graph, node):
    print('node: ', node)

# check threshold
    updateThreshold(graph, node, a,b)
    next_neighbors = nx.get_node_attributes(graph, 'neighbors')[node]
    # return next up
    check_next = graph.subgraph(next_neighbors)
    printGraph(graph)
    if nx.get_node_attributes(graph, 'adopt5G')[node]==1:
        return check_next
    else:
        return []
```

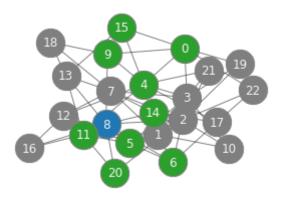
```
In [9]: # calculate the proportion of adopters across the graph

def cascade_rate(graph):
    print('access', len([x for x,y in graph.nodes(data=True) if y['access5G']==1]))
    print('adopters' ,len([x for x,y in graph.nodes(data=True) if y['adopt5G']==1]))
    print('% adopters', len([x for x,y in graph.nodes(data=True) if y['a dopt5G']==1])/len([x for x,y in graph.nodes(data=True) if y['access5G']==1]))
    print('full cascade', len([x for x,y in graph.nodes(data=True) if y['adopt5G']==1]))
    return len([x for x,y in graph.nodes(data=True) if y['access5G']==1])
/len([x for x,y in graph.nodes(data=True) if y['adopt5G']==1])
```

Run Simulations

```
In [10]: #Set up basic graph
    G = nx.barabasi_albert_graph(23, 3, seed=11)
    initializeAttributes(G)
    start = setStartNode(G)
    printGraph(G)

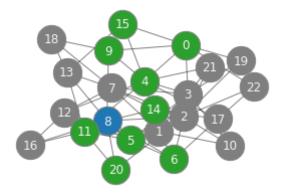
# Reset Graph, Same Start Node
# cascade = {}
# for node in list(G):
# cascade[node] = {"adopt5G": 0, "checked":0}
# nx.set_node_attributes(G, cascade)
# nx.set_node_attributes(G, {start: {"adopt5G":1, "start":1, "checked": 1}})
# printGraph(G)
```



```
In [11]:  # SET PAYOFFS HERE

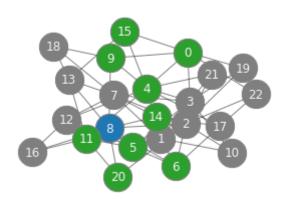
a = 2
b = 1
```

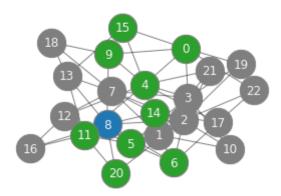
```
In [12]: # Chart network diffusion via an early adopter starter node
         startNeighbors = list(nx.neighbors(G, start))
         G_startNeighbors = G.subgraph(startNeighbors)
         printGraph(G)
         next = [x for x,y in G_startNeighbors.nodes(data=True) if y['adopt5G']==
         0 and y['access5G']==1]
         while next!= []:
             final = []
             for x in set(next):
                 neighborAdopters(G,x)
             for x in set(next):
                 next1 = algorithm(G,x)
                 final.extend(next1)
             next_iteration = G.subgraph(final)
             next = [x for x,y in next_iteration.nodes(data=True) if y['adopt5G']
         ==0 and y['access5G']==1]
             print('next', next)
```

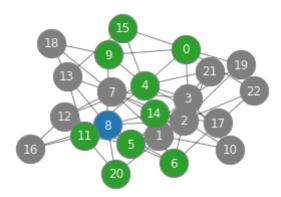


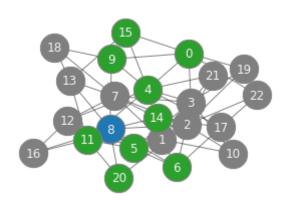
p 0.14285714285714285 b/a+b 0.3333333333333333

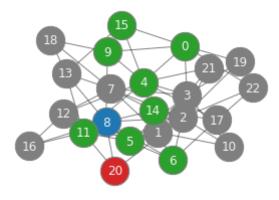
access to 5g? True adopt 5g? False

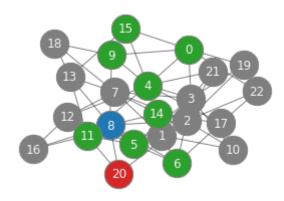












next []

```
In [13]: cascade_rate(G)
```

access 10
adopters 2
% adopters 0.2
full cascade False

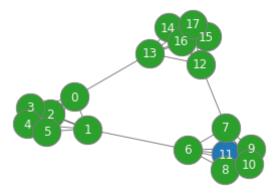
Out[13]: 0.2

Clustering as a Blocker to Cascades

```
In [14]: # get density, per Kleinberg and Easley's definiton, p574
         # density = minimum fraction of neighbors within the cluster
         # iterate through all nodes in a given cluster, find minimum density, se
         t for all nodes in the cluster
         def calculateDensity(graph):
             cascade = {}
             for node in G:
                 cluster = nx.get_node_attributes(G,'cluster')[node]
                 neighbors = nx.subgraph(G, list(nx.neighbors(G, node)))
                 density = len([x for x,y in neighbors.nodes(data=True) if y['clu
         ster']== cluster]) / len([x for x,y in neighbors.nodes(data=True)])
                 cascade[node] = {"density": density}
             nx.set_node_attributes(G, cascade)
             clusters = set(list(nx.get node attributes(G,'cluster').values()))
             for cluster in clusters:
                 all cluster = nx.subgraph(G,([x for x,y in G.nodes(data=True) if
         y['cluster']== cluster]))
                 densities = nx.get_node_attributes(all_cluster, 'density')
                 cluster_density = min(densities.values())
                 for node in all cluster:
                     nx.set_node_attributes(graph, {node: {"density": cluster_den
         sity}})
             print(set(list(nx.get node attributes(G, 'density').values())))
In [15]: # set adoption threshold
         \# a = payoff of both adopting a (5G)
         \# b = payoff of both adopting b (4G)
         def updateThreshold(graph, node number,a,b):
             nx.set node attributes(graph, {node number: {"checked":1}})
             p = nx.get node attributes(G, 'p')[node number]
             density = nx.get_node_attributes(G, 'density')[node_number]
             eligible = nx.get node attributes(G, 'access5G')[node number]
             print('p', p)
             print('b/a+b',(b/(a+b)))
             print('')
             print('1-q',(1-(b/(a+b))))
             print('cluster_density', density)
             print('density > 1-q?', density > (1-(b/(a+b))))
             print('adopt 5g?', (p >= b/(a+b)) and eligible==1)
             if (p \ge b/(a+b)) and eligible==1:
                 nx.set node attributes(graph, {node number: {"adopt5G":1}})
In [16]: # create dense graph
         G = nx.ring of cliques(3,6)
         initializeAttributes(G)
         for node in G:
             nx.set node attributes(G, {node: {"access5G":1}})
```

#printGraph(G)

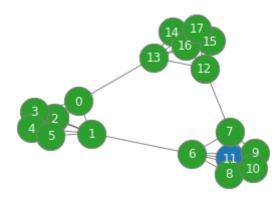
```
In [20]: # Chart network diffusion via an early adopter starter node
         startNeighbors = list(nx.neighbors(G, start))
         G_startNeighbors = G.subgraph(startNeighbors)
         printGraph(G)
         next = [x for x,y in G_startNeighbors.nodes(data=True) if y['adopt5G']==
         0 and y['access5G']==1]
         while next!= []:
             final = []
             for x in set(next):
                 neighborAdopters(G,x)
             for x in set(next):
                 next1 = algorithm(G,x)
                 final.extend(next1)
             next_iteration = G.subgraph(final)
             next = [x for x,y in next_iteration.nodes(data=True) if y['adopt5G']
         ==0 and y['access5G']==1]
             print('next', next)
```



b/a+b 0.2

1-q 0.8

density > 1-q? True
adopt 5g? False

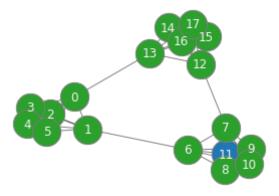


node: 7

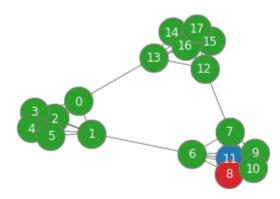
b/a+b 0.2

1-q 0.8

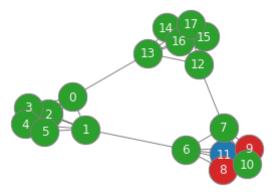
density > 1-q? True adopt 5g? False



node: 8 p 0.2 b/a+b 0.2

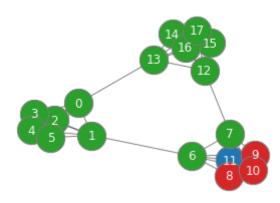


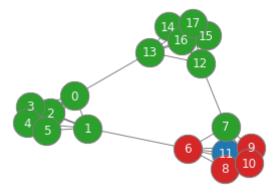
node: 9 p 0.2 b/a+b 0.2



node: 10 p 0.2 b/a+b 0.2

adopt 5g? True



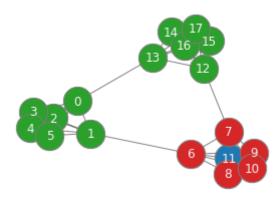


b/a+b 0.2

1-q 0.8

density > 1-q? True

adopt 5g? True



next [1, 12]

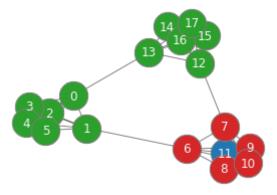
node: 1

b/a+b 0.2

1-q 0.8

density > 1-q? True

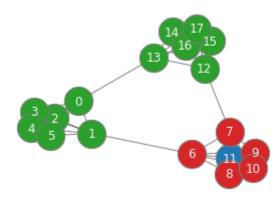
adopt 5g? False



b/a+b 0.2

1-q 0.8

density > 1-q? True
adopt 5g? False



next []

Run Larger Simulations

```
In [21]: # For Larger Graphs (same functions, no print statements)
         def updateThreshold(graph, node_number,a,b):
             nx.set_node_attributes(graph, {node_number: {"checked":1}})
             p = nx.get_node_attributes(G, 'p')[node_number]
             eligible = nx.get_node_attributes(G, 'access5G')[node_number]
             if (p \ge b/(a+b)) and eligible==1:
                 nx.set node attributes(graph, {node number: {"adopt5G":1}})
         def algorithm(graph, node):
             updateThreshold(graph, node, a,b)
             next_neighbors = nx.get_node_attributes(graph, 'neighbors')[node]
             # return next up
             check next = graph.subgraph(next neighbors)
             if nx.get_node_attributes(graph, 'adopt5G')[node]==1:
                 return check next
             else:
                 return []
```

```
In [23]: # SET PAYOFFS HERE
a = 237
b = 1
```

```
In [24]: | # run simulations
         startNeighbors = list(nx.neighbors(G, start))
         G_startNeighbors = G.subgraph(startNeighbors)
         next = [x for x,y in G_startNeighbors.nodes(data=True) if y['checked']==
         0]
         while next!= []:
             final = []
             for x in set(next):
                 neighborAdopters(G,x)
             for x in set(next):
                 next1= algorithm(G,x)
                  final.extend(next1)
             next_iteration = G.subgraph(final)
             next = [x for x,y in next_iteration.nodes(data=True) if y['checked']
         ==01
         cascade_rate(G)
         access 171
         adopters 171
```

adopters 171 % adopters 1.0 full cascade True

Out[24]: 1.0