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%===== segKmeans =====
%
% function [J, K, means] = segKmeans(I, iter, means, ncov)
%
% Perform k-means segmentation on the grayscale image I.
%
% Input:
%   I           - image I ( from |R^2 -> |R ).
%   iter        - Maximum number of iterations (can stop earlier if no change).
%   means       - initial guess at means, each column is a mean value.
%   ncov        - covariance matrix to use in the scaling (use 1 if none).
%                 can be scalar for all means to use, or can be a unique
%                 value for each mean value.
%
% Output:
%   J           - the segmentation map.
%   K           - the simplified image using the means and the segmentation.
%   means       - the final segmentation means.
%
%===== segKmeans =====

%
% Name:          segKmeans.m
%
% Author:        Patricio A. Vela, pvela@gatech.edu
%
% Created:       2010/01/05
% Modified:      2012/04/07
%
%===== segKmeans =====
function [J, K, means] = kmeans(I, iter, means, ncov)

%--[0] Parse the input arguments, set to defaults if needed.
if (nargout == 0)                % If nothing expected, then don't bother
    return;                      % doing the computations.
end

if (nargin < 3)                  % If first three not given, can't do much.
    disp('ERROR: Need at least the first three arguments');
    error('BadArgs');
end

if ((nargin == 3) || isempty(ncov))
    ncov = 1;                    % If no covariance, default is 1.
end

if (isscalar(ncov))             % If scalar, copy for each mean value.
    ncov = repmat(ncov, [1, size(means,2)]);
end

%--[1] Prep workspace and variables.
imsize = size(I);

xi = 1:length(means);           % Generate set of class labels.
diff2 = zeros([imsize, xi(end)]);

                                % Pre-allocate memory for data energy.
J = ones(imsize);              % Instantiate the return variable.
oJ = zeros(imsize);            % Want to keep track of old segmenation map.

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%--[2] Perform the segmentation iterations.
while (any(oJ(:) ~= J(:)) && (iter > 0))
    iter = iter - 1; % Update number of iterations left.
    oJ = J; % Set old copy to previous segmentation map.

    % YOUR CODE HERE. USE THE HELPER FUNCTIONS BELOW.
    % Steps:
    % (1) Compute the data energy.
    compEnergy();

    % (2) Minimize energy to generate assignments (segmentation).
    [val, J] = min(diff2,[],3);

    % (3) Update the means based on the segmentation
    compMeans();

    % Debugging code
    bins = [1];
    for vi=1:length(xi)
        bins(vi) = sum(J(J == vi));
    end
end

if (nargout >= 2) % If image expected, then create it.
    % Map segmentation to it's mean color. hint: use interp1
    K = J;
    means = means .* ncov;
    for i=1:size(means,2)
        K(J == i) = means(i);
    end
end

%
%===== Helper Functions =====
%
% These functions live within the scope of the segKmeans function.
% What that means is that they can be invoked from the loop above
% and they will have access to the variables above (think of them
% as global variables in some sense). Using functions within a
% function is a clean way to do complex thing but have the main
% code of the function look nice and clean.
%

%----- compEnergy -----
%
% Compute the k-means data matching energy. The result is k data
% matching score image slices. This function has access to all
% of the variables from the function scope above (I, means, ncov,
% diff2, etc.).
%
function compEnergy

for ei=1:length(xi) % For each class label ...
    diff2(:, :, ei) = (I - means(ei)).^2;
end
end

%----- compMeans -----
%
% Given the segmentation, compute the class means. This function

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% also has access.
%
function compMeans

for mi=1:length(xi)                                % For each class label ...
    pts_in_layer = sum(sum(J == mi));
    if (pts_in_layer > 0)
        means(mi) = sum(I(J == mi)) ./ pts_in_layer;
    else
        means(mi) = 0;
    end
end

end

end

%
%===== segKmeans =====

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