# test\_LFR\_partial-info

#### September 19, 2022

```
# --- Standard library ---
    import sys # System pathing
    from copy import deepcopy
    # --- Scientific ---
    import numpy as np # General computational tools
    from sklearn import metrics # Measuring classifier performance
    from scipy.special import comb
    # --- Network science ---
    import networkx as nx # General network tools
    from node2vec import Node2Vec as N2V # Embedding tools
    # --- Project source code ---
    sys.path.append("../src/")
    from Utils import * # Custom synthetic benchmarks
    from glee import eigenmaps
    # --- Data handling and visualization ---
    import matplotlib.pyplot as plt
    # --- Miscellaneous ---
    accuracy = metrics.accuracy_score
    auroc = metrics.roc_auc_score
[]: # Process parameters
    N = 500
    tau1 = 2.1
```

```
[]: # Process parameters
N = 500
tau1 = 2.1
tau2 = 1.0
mu = 0.1
min_community = 1
average_degree = 5
max_degree = np.sqrt(N)
prob_relabel = 1.0
```

```
largest_component = True
dimensions = 2
# Form "raw" duplex
D, _sigma1, _sigma2, _mu_temp = lfr_multiplex(N, tau1, tau2, mu,__
 average_degree, max_degree, min_community, prob_relabel)
# Split into layers
G, H = duplex_network(D, 1, 2)
# Observe partial information
R_G, R_H, testset = partial_information(G, H, pfi)
# Restrict to largest connected component (if specified)
if largest_component:
    R_G_ = nx.Graph()
    R_H_ = nx.Graph()
    R_G_.add_nodes_from(R_G.nodes())
    R_H_.add_nodes_from(R_H.nodes())
    maxcc_R_G = max(nx.connected_components(R_G), key=len)
    maxcc_R_H = max(nx.connected_components(R_H), key=len)
    edges_R_G_ = set(R_G.subgraph(maxcc_R_G).edges())
    edges_R_H_ = set(R_H.subgraph(maxcc_R_H).edges())
    R_G_.add_edges_from(edges_R_G_)
    R_H_.add_edges_from(edges_R_H_)
    testset = {
        edge: gt_
        for edge, gt_ in testset.items()
        if edge in edges_R_G_ & edges_R_H_
else:
    R_G_ = R_G
    R_H_ = R_H
setting... -N 500
setting... -mu 0.1
setting... -maxk 22.360679774997898
setting... -k 5
setting... -t1 2.1
setting... -t2 1.0
```

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```
number of nodes:
                            500
    average degree: 5
    maximum degree: 22
    exponent for the degree distribution:
    exponent for the community size distribution:
    mixing parameter:
                            0.1
    number of overlapping nodes:
    number of memberships of the overlapping nodes: 0
    ************************
    community size range automatically set equal to [3, 22]
    building communities...
    connecting communities...
    recording network...
    network of 500 vertices and 1092 edges; average degree = 4.368
    average mixing parameter: 0.0973671 +/- 0.166681
    p in: 0.506756 p out: 0.000737044
    Segmentation fault (core dumped)
[]: c = set(R_G_.edges()) \& set(R_H_.edges())
    R_G_{cut_c} = set(R_G_{edges}) - c
    R_H_{cut_c} = set(R_H_{edges}) - c
    print(
        len(c & set(testset.keys())) / len(set(testset.keys())),
        len(R_G_cut_c)/len(set(R_G_.edges())),
        len(R_H_cut_c)/len(set(R_H_.edges()))
    )
    1.0 0.3484472049689441 0.34231974921630093
[]: embedding = "n2v"
    if embedding == "glee":
        E_alpha = eigenmaps(R_G_, dimensions, method='glee', return_vals=False)
        E_beta = eigenmaps(R_H_, dimensions, method='glee', return_vals=False)
    elif embedding == "n2v":
        E_alpha = N2V(R_G_, dimensions=dimensions, walk_length=30, num_walks=200, __
      workers=4, quiet=True).fit(window=10, min_count=1, batch_words=4).wv.vectors
        E beta = N2V(R_H_, dimensions=dimensions, walk_length=30, num_walks=200,__
      workers=4, quiet=True).fit(window=10, min_count=1, batch_words=4).wv.vectors
```

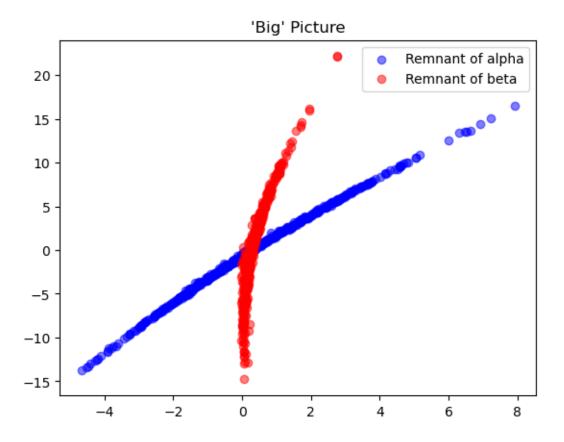
```
[]: def reconstruct_system(testset, G, H, G_, H_, metric="negexp"):
         cls = []
         scores = []
         gt = []
         for edge, gt_ in testset.items():
             i, j = edge
             gt.append(gt_)
             v_G_i = G_[i, :]
             v_G_j = G_[j, :]
             v_H_i = H_[i, :]
             v_H_j = H_[j, :]
             d_G = np.linalg.norm(v_G_i - v_G_j)
             d_H = np.linalg.norm(v_H_i - v_H_j)
              # * Thresholding to avoid inactive nodes, embedded at origin, having
      \hookrightarrow incorrect placements
             if d_G <= 1e-1:</pre>
                 d_G = sys.maxsize
             if d_H <= 1e-1:</pre>
                  d_H = sys.maxsize
             if metric == "inverse":
                  d_G = 1 / d_G
                  d_H = 1 / d_H
             elif metric == "negexp":
                 d_G = np.exp(-d_G)
                  d_H = np.exp(-d_H)
             t_G = d_G / (d_G + d_H)
             t_H = 1 - t_G
             scores.append(t_G)
             cls_ = np.random.randint(2)
             if t_G != t_H:
                  if np.random.rand() <= t_G:</pre>
                      cls_{-} = 1
                  else:
                      cls_{=} = 0
             cls.append(cls_)
         return cls, scores, gt
     def measure_performance(cls, scores, gt):
```

```
acc = accuracy(gt, cls)
auc = auroc(gt, scores)
return acc, auc
```

```
[]: cls, scores, gt = reconstruct_system(testset, G, H, E_alpha, E_beta, "inverse")
    acc, auc = measure_performance(cls, scores, gt)
    print(acc, auc)
```

0.5487179487179488 0.5183458237418274

[]: Text(0.5, 1.0, "'Big' Picture")

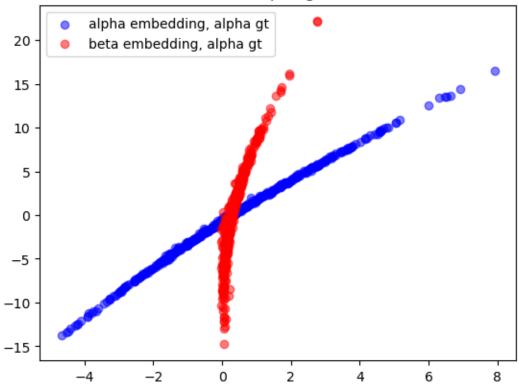


```
[]: edges_gt_alpha = [
                                             edge
                                             for edge, gt in testset.items() if gt == 1
                         edges_gt_beta = [
                                             edge
                                             for edge, gt in testset.items() if gt == 0
                        ]
                        nodes_gt_alpha = set([x[0] for x in edges_gt_alpha]) | set([x[1] for x in_u]) | set([x[1] for 
                               ⇔edges_gt_alpha])
                         nodes_gt_beta = set([x[0] for x in edges_gt_beta]) | set([x[1] for x in_u)
                               ⇔edges_gt_beta])
                         plt.figure()
                         plt.scatter(
                                             x=[E_alpha[v][0] for v in nodes_gt_alpha],
                                             y=[E_alpha[v][1] for v in nodes_gt_alpha],
                                             color="blue",
                                             label="alpha embedding, alpha gt",
```

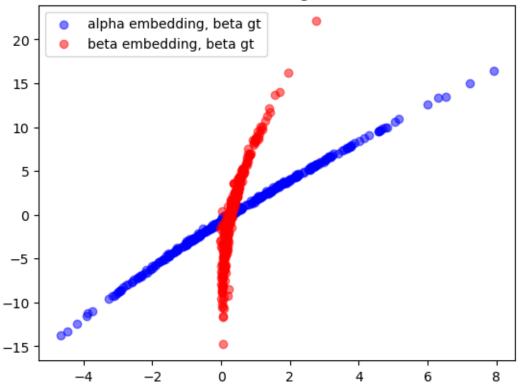
```
alpha=0.5
)
plt.scatter(
    x=[E_beta[v][0] for v in nodes_gt_alpha],
    y=[E_beta[v][1] for v in nodes_gt_alpha],
    color="red",
    label="beta embedding, alpha gt",
    alpha=0.5
plt.legend()
plt.title("Test set with alpha ground truth")
plt.figure()
plt.scatter(
    x=[E_alpha[v][0] for v in nodes_gt_beta],
    y=[E_alpha[v][1] for v in nodes_gt_beta],
    color="blue",
    label="alpha embedding, beta gt",
    alpha=0.5
)
plt.scatter(
    x=[E_beta[v][0] for v in nodes_gt_beta],
    y=[E_beta[v][1] for v in nodes_gt_beta],
    color="red",
    label="beta embedding, beta gt",
    alpha=0.5
plt.legend()
plt.title("Test set with beta ground truth")
```

[]: Text(0.5, 1.0, 'Test set with beta ground truth')





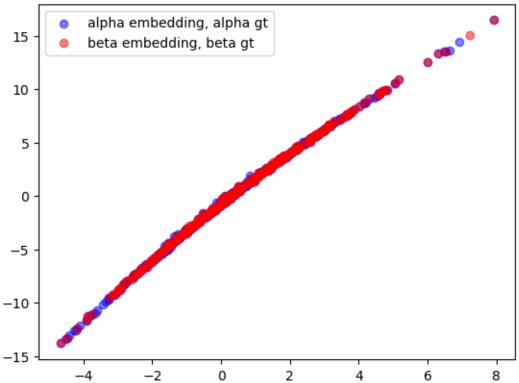
## Test set with beta ground truth



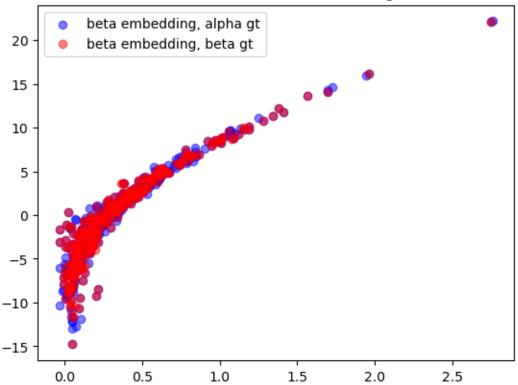
```
plt.figure()
plt.scatter(
    x=[E_beta[v][0] for v in nodes_gt_alpha],
    y=[E_beta[v][1] for v in nodes_gt_alpha],
    color="blue",
    label="beta embedding, alpha gt",
    alpha=0.5
)
plt.scatter(
    x=[E_beta[v][0] for v in nodes_gt_beta],
    y=[E_beta[v][1] for v in nodes_gt_beta],
    color="red",
    label="beta embedding, beta gt",
    alpha=0.5
)
plt.legend()
plt.title("Test set with beta embedding")
```

[]: Text(0.5, 1.0, 'Test set with beta embedding')

## Test set with alpha embedding



### Test set with beta embedding



```
[]: deltas_alpha = {edge: None for edge in set(R_G_.edges())}
deltas_beta = {edge: None for edge in set(R_H_.edges())}

for edge in deltas_alpha.keys():
    i, j = edge
    d_alpha = np.linalg.norm(E_alpha[i] - E_alpha[j])
    d_beta = np.linalg.norm(E_beta[i] - E_beta[j])
    deltas_alpha[edge] = (d_alpha, d_beta)

for edge in deltas_beta.keys():
    i, j = edge
    d_alpha = np.linalg.norm(E_alpha[i] - E_alpha[j])
    d_beta = np.linalg.norm(E_beta[i] - E_beta[j])
    deltas_beta[edge] = (d_alpha, d_beta)

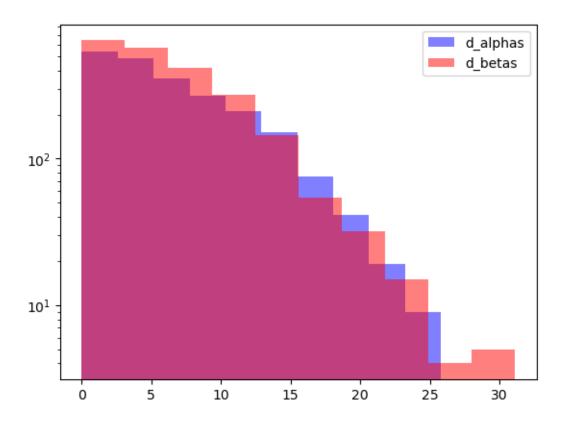
deltas = deepcopy(deltas_alpha)
deltas.update(deltas_beta)
```

plt.hist([x[0] for x in deltas.values()], color="blue", label="d\_alphas",

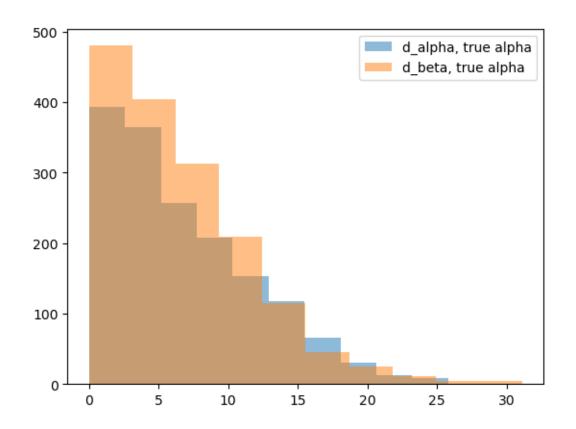
[]: plt.figure()

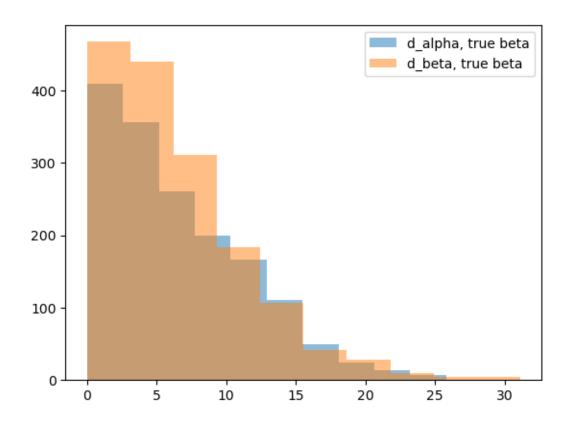
 $\rightarrow$ alpha=0.5)

#### []: <matplotlib.legend.Legend at 0x7f8bfd22fb80>



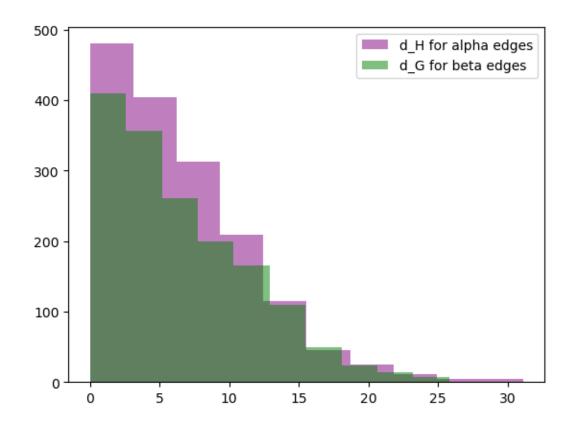
[]: <matplotlib.legend.Legend at 0x7f8bfd0073a0>





```
[]: d_a_bad = []
     d_b_b = []
     # Within 0 to 99, alpha stays same, beta goes to 100 + i
     for edge in R_G_.edges():
         i, j = edge
         _h = np.linalg.norm(E_beta[i] - E_beta[j])
         d_a_bad.append(_h)
     # Within 100 to 199, alpha stays same, beta goes to 100 - i
     for edge in R_H_.edges():
         i, j = edge
         _g = np.linalg.norm(E_alpha[i] - E_alpha[j])
         d_b_bad.append(_g)
     plt.figure()
     plt.hist(d_a_bad, color="purple", label="d_H for alpha edges", alpha=0.5)
    plt.hist(d_b_bad, color="green", label="d_G for beta edges", alpha=0.5)
    plt.legend()
```

[]: <matplotlib.legend.Legend at 0x7f8ba7626dd0>



[]: