Welcome!

2018 Spring CS101 Introduction to Programming



Week 2

Programming with robots (Function, For loops, Conditional expressions, While loops)

Elice

What is elice?

Online programming education platform

In CS101, we will use them for

- Programming tasks in lab
- Homework assignments



```
main.py

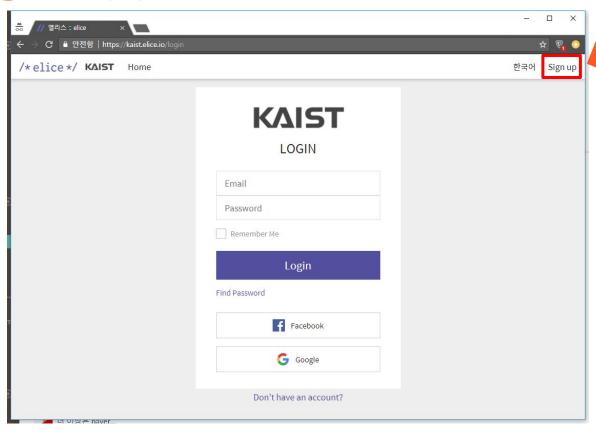
1 def main():
2 hex_cole 엘리스 p
3 r, g,???
4
5 /* 이렇게 해보세요! 토끼조교
6 도움도움도움 개념 설명 */
7
```

No need to spend a lot of time setting up your development environment for CS101! Focus fully on your ideas & writing your code.

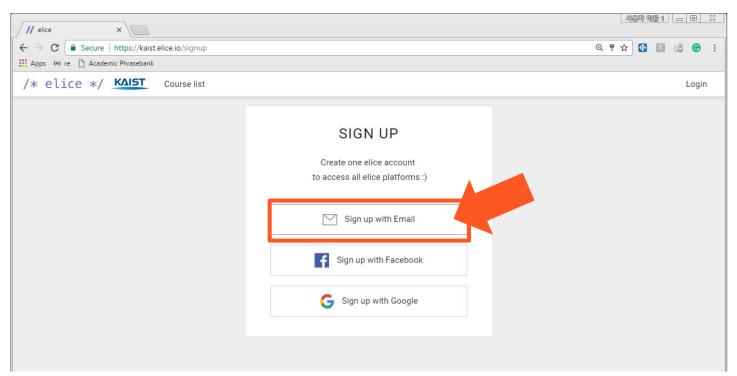
What you need to know before signing up

- 1. Your **real name**
- 2. Your KAIST email address (...@kaist.ac.kr)
- 3. Your **student ID**

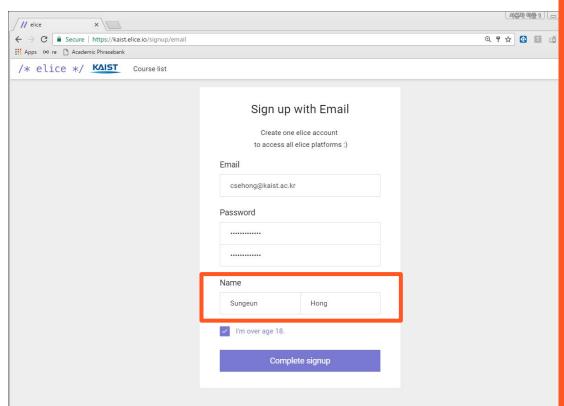
Signing up (1) - kaist.elice.io



Signing up (2)

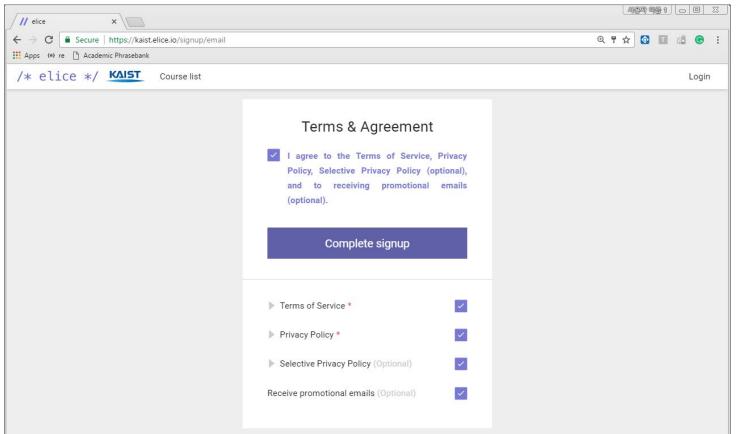


Signing up (3)

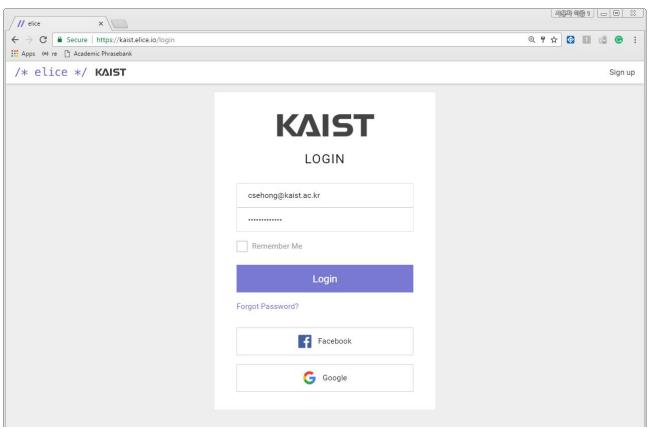


USE YOUR REAL NAME!! (Eng or Kor)

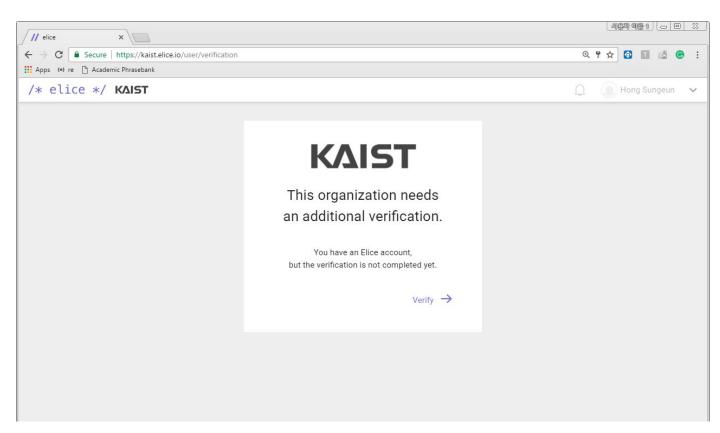
Signing up (4)



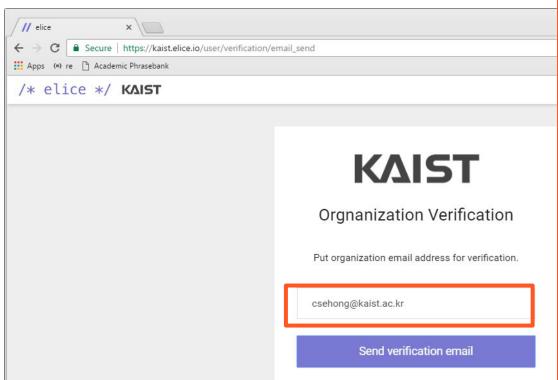
Signing up (5)



Signing up (6)



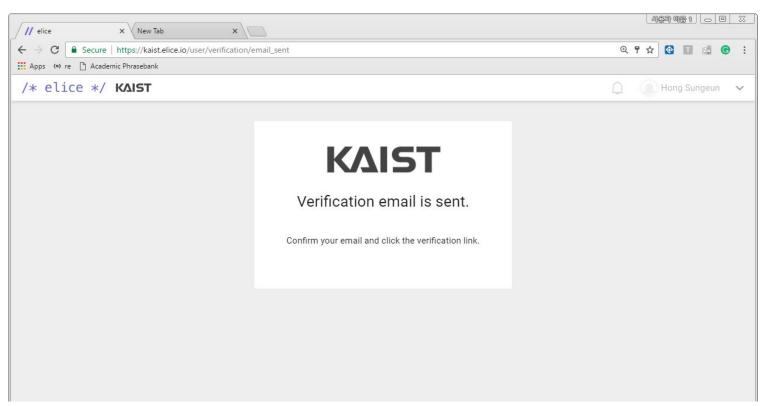
Signing up (7)



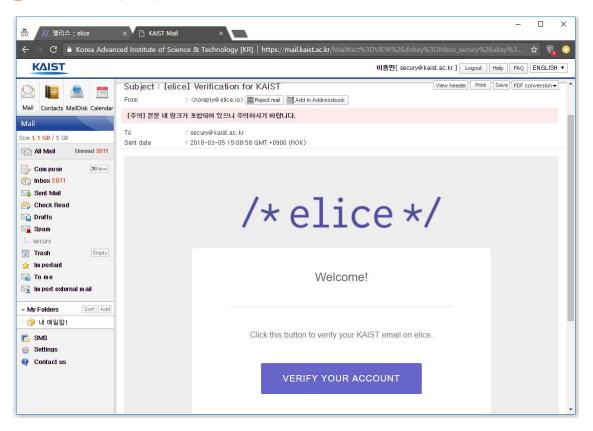
MUST USE YOUR KAIST EMAIL!!

... @kaist.ac.kr

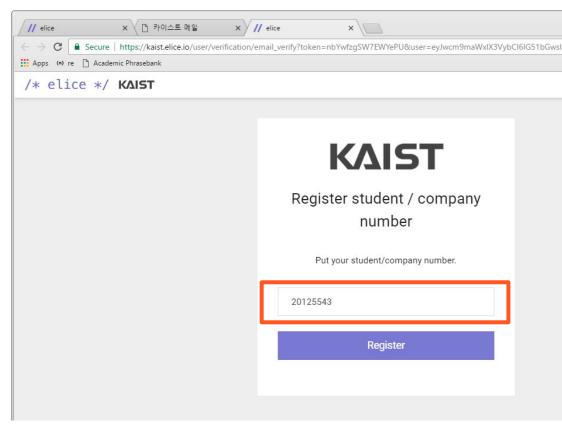
Signing up (8)



Signing up (9) - mail.kaist.ac.kr

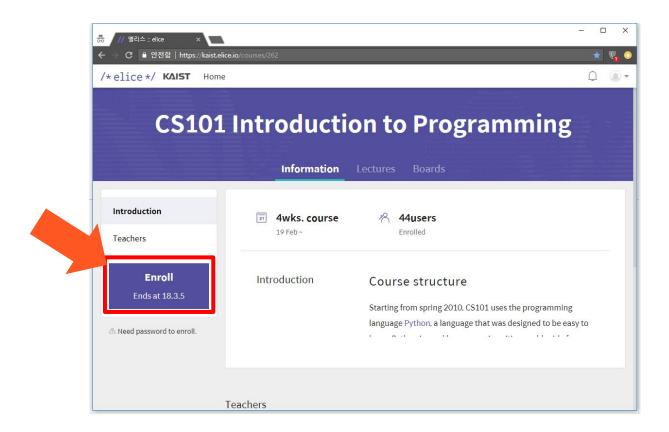


Signing up (10)

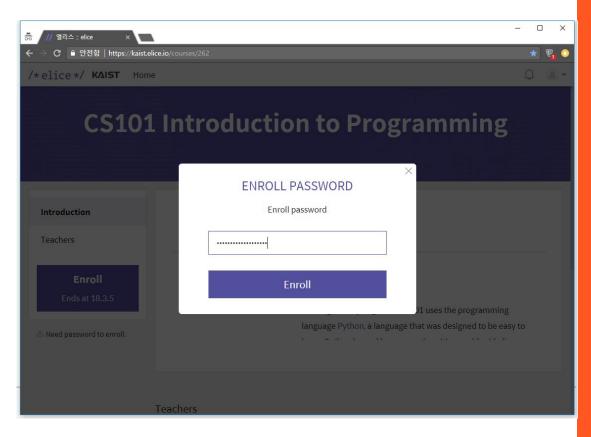


MUST USE YOUR STUDENT ID!!

kaist.elice.io/courses/262



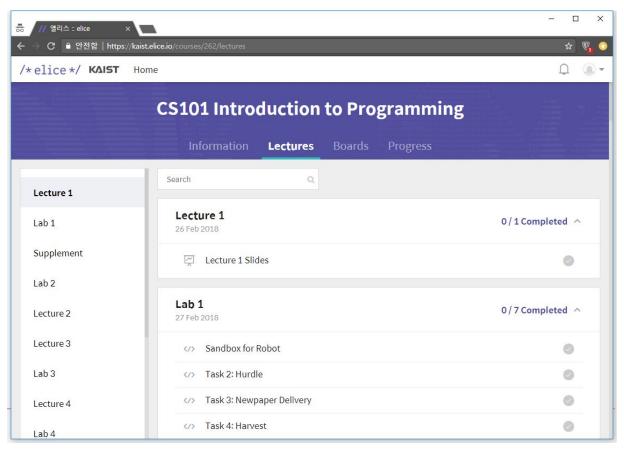
kaist.elice.io/courses/262



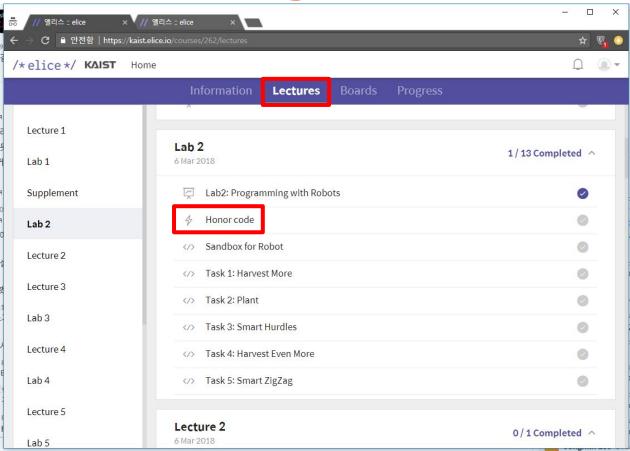
Password:

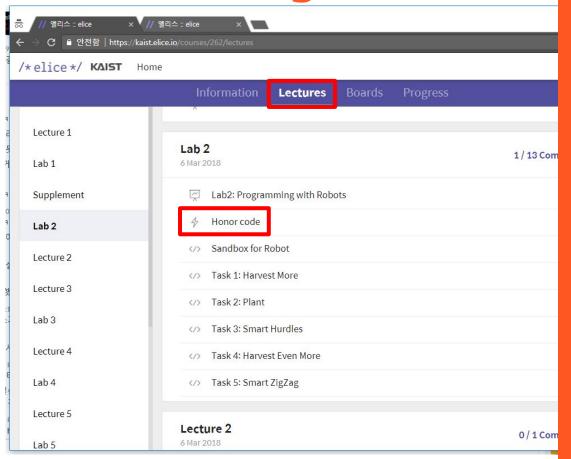
cs101_2018_kaist_?!

Signing up DONE!



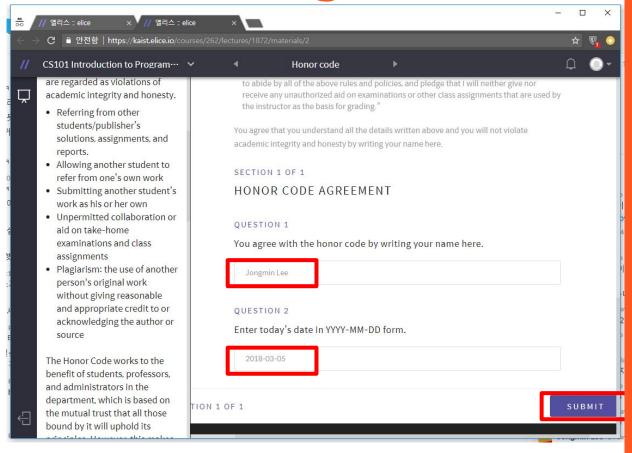
Honor Code





You should agree with Honor Code.

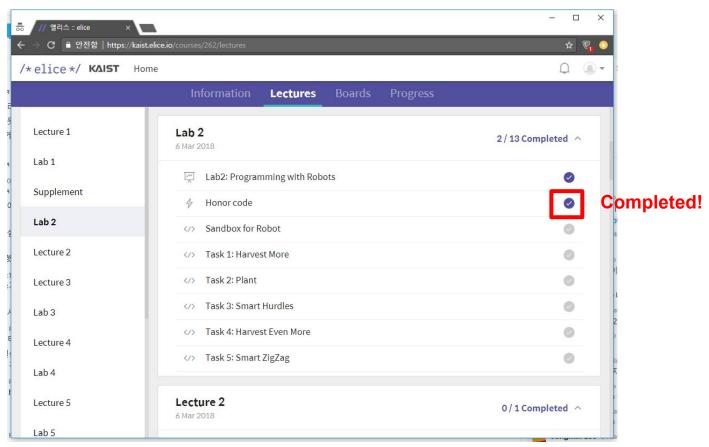
Any cheating is strictly prohibited in CS101.



Read the whole text carefully.

Write down your name & date if you agree.

If you do NOT agree, you cannot take cs101:(

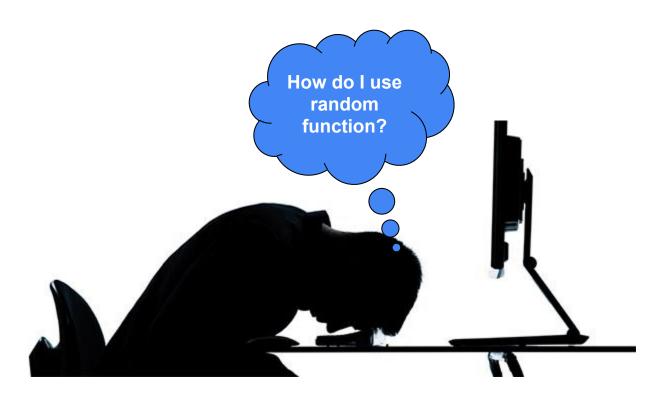


questions?

Useful resources

You're alone in your dorm room trying to study...

and stuck...





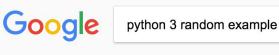
python 3 random example



Google Search

I'm Feeling Lucky

Google.co.kr offered in: 한국어





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About 6,360,000 results (0.41 seconds)

9.6. random — Generate pseudo-random numbers — Python 3.6.2 ... https://docs.python.org/3/library/random.html ▼

For **integers**, there is uniform selection from a range. ... Almost all module **functions** depend on the basic function **random**(), which ... 1, January pp.3–30 1998.

random — Generate pseudo-random numbers — Python v3.0.1 ...

https://docs.python.org/3.0/library/random.html ▼
Almost all module functions depend on the basic function random(), which 3, 2, 5, 6, 4, 1] >>> random.sample([1, 2, 3, 4, 5], 3) # Choose 3 elements [4, 1, 5].

9.6. random — Generate pseudo-random numbers — Python 2.7.13 ... https://docs.python.org/2/library/random.html ▼
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How to use the Random Module in Python - Pythonforbeginners.com www.pythonforbeginners.com/random/how-to-use-the-random-module-in-python ▼
Dec 24, 2012 - The random module provides access to functions that support many ... import random for i in range(3): print random.randrange(0, 101, 5) ...

python - Generate random integers between 0 and 9 - Stack Overflow https://stackoverflow.com/questions/.../generate-random-integers-between-0-and-9 ▼ Oct 22, 2010 - More info: https://docs.python.org/3/library/random.html#random.randint ... Generates 10 pseudo random integers in range 0 to 9 inclusive.



python 3 random example



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About 6,360,000 results (0.41 seconds)

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For **integers**, there is uniform selection from a range. ... Almost all module **functions** depend on the basic function **random**(), which ... 1, January pp.3–30 1998.

Maps

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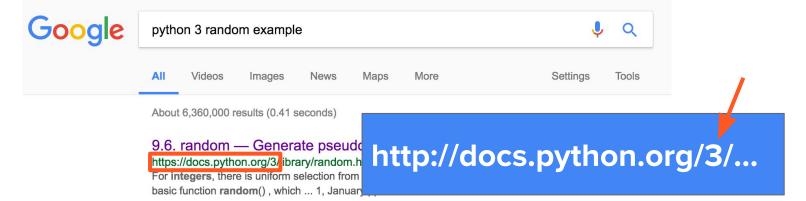
9.6. random — Generate pseudo-random numbers — Python 2.7.13 ... https://docs.python.org/2/library/random.html ▼

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How to use the Random Module in Python - Pythonforbeginners.com www.pythonforbeginners.com/random/how-to-use-the-random-module-in-python ▼

www.pythonforbeginners.com/random/how-to-use-the-random-module-in-python ▼ Dec 24, 2012 - The random module provides access to functions that support many ... import random for i in range(3): print random.randrange(0, 101, 5) ...

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These two websites are usually good signs!

random — Generate pseudo-random numbers — Python v3.0.1 ...

https://docs.python.org/3.0/library/random.html ▼

Almost all module functions depend on the basic function random(), which 3, 2, 5, 6, 4, 1] >>> random.sample([1, 2, 3, 4, 5], 3) # Choose 3 elements [4, 1, 5].

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How to use the Random Module in Python - Pythonforbeginners.com

 $www.pythonforbeginners.com/random/how-to-use-the-random-module-in-python ~ \\ \bullet$

Dec 24, 2012 - The **random** module provides access to **functions** that support many ... import **random** for i in range(3): print **random**.randrange(0, 101, 5) ...

python - Generate random integent https://stackoverflow.com/questions/.../genoct 22, 2010 - More info: https://docs.pythor 10 pseudo random integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in range 0 to 9 in the python integers in the python in the python integers in the python integers in the python

http://stackoverflow.com/...

Useful resources

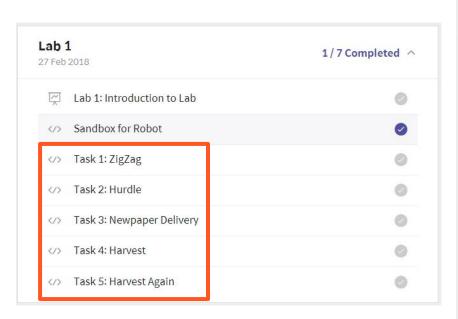
http://docs.python.org/3/
"the official python 3 documents"

http://stackoverflow.com/

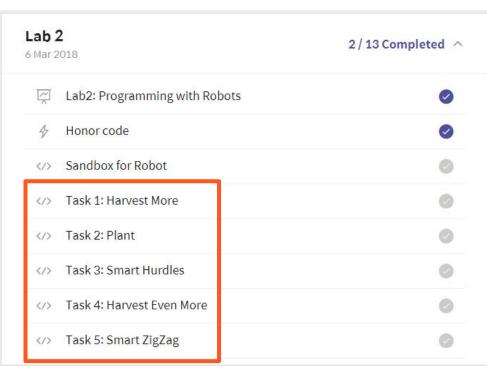
"most beloved Q&A website in computer science"

Some Basics for Today's Tasks

Today's Tasks

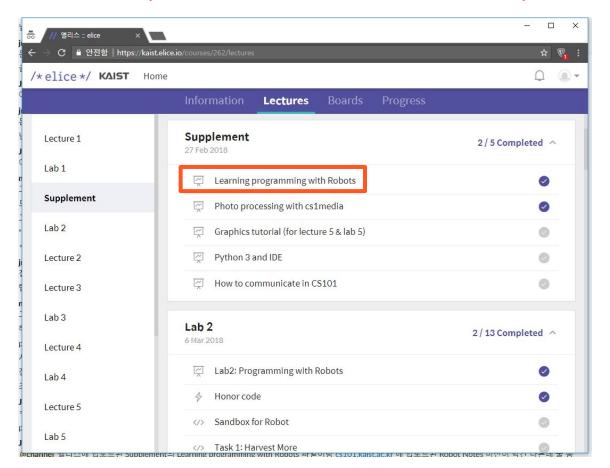


- How to define **function**
- How to use for-loop



- How to use conditional expressions
- How to use while-loop

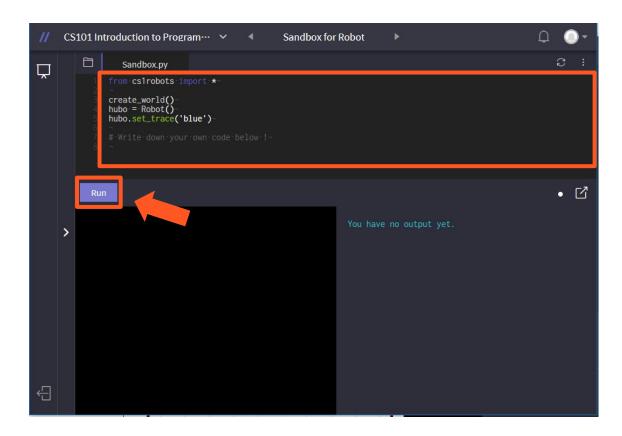
Robot World (Read the robot notes!)



Some Basics of cs1robot library

from cs1robots import *

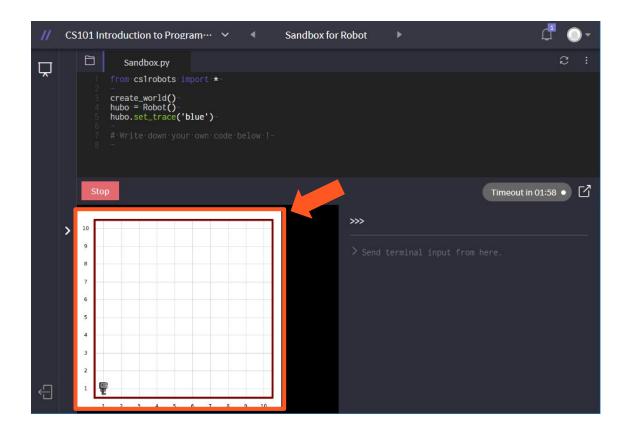
create_world()
hubo = Robot()
hubo.set trace('blue')



Some Basics of cs1robot library

from cs1robots import *

create_world()
hubo = Robot()
hubo.set trace('blue')



```
from cs1robots import * ← Import cs101 robot library!
```

```
create_world()
hubo = Robot()
hubo.set_trace('blue')
```

- ← Create a robot world (defined in cs1robots library)
- ← Create a robot named 'hubo'
- ← Turn on a trace for our robot (hubo) with 'blue' color

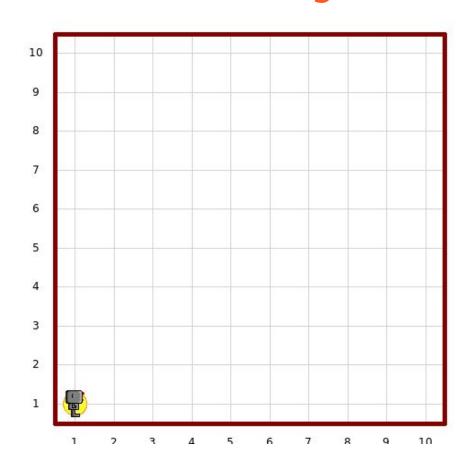
```
create_world()
hubo = Robot(beepers=10) ← Create a robot with 10 beepers
hubo.set trace('blue') (beeper={??} is optional)
```

from cs1robots import *

from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

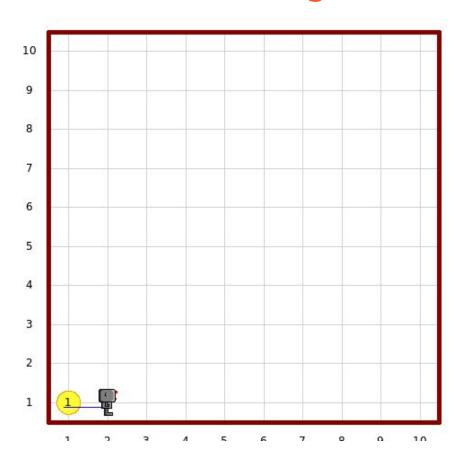
hubo.drop_beeper()



from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

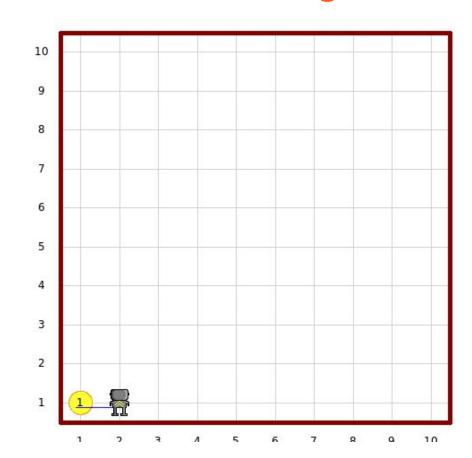
hubo.drop_beeper()
hubo.move()



from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

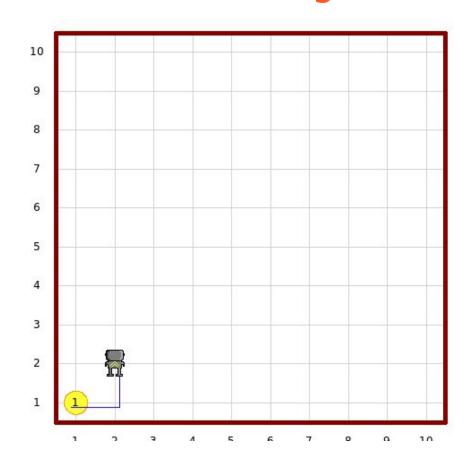
hubo.drop_beeper()
hubo.move()
hubo.turn_left()



from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

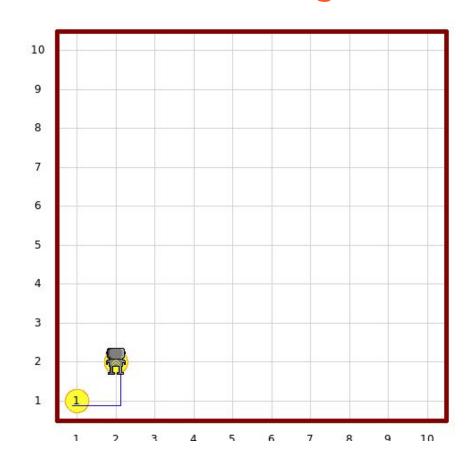
hubo.drop_beeper() hubo.move() hubo.turn_left() hubo.move()



from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

hubo.drop_beeper()
hubo.move()
hubo.turn_left()
hubo.move()
hubo.drop_beeper()



from cs1robots import *

create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')

hubo.drop_beeper()
hubo.move()

hubo.movc()

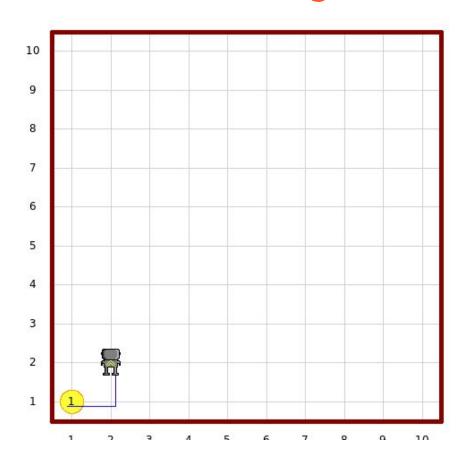
hubo.turn_left()

hubo.move()

hubo.drop_beeper()

hubo.pick_beeper()

✓ Before picking up a beeper, hubo should be on a beeper!



```
from cs1robots import *
```

```
create_world()
hubo = Robot(beepers=10)
hubo.set_trace('blue')
```

hubo.drop_beeper()

hubo.move()

hubo.turn_left()

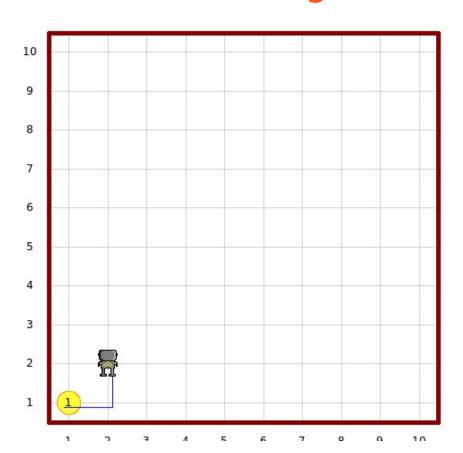
hubo.move()

hubo.drop_beeper()

hubo.pick_beeper()

hubo.pick_beeper()





How to Load World?

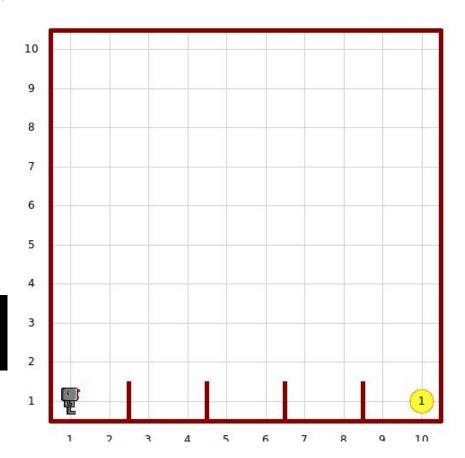
from cs1robots import *

load_world('worlds/hurdles1.wld')

hubo = Robot()
hubo.set_trace('blue')

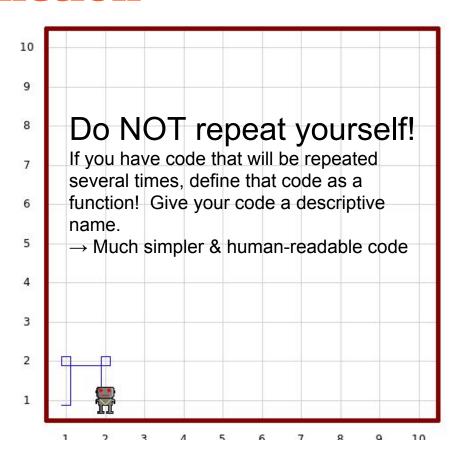
Write your own code below!

* Instead of using *create_world*, we can use *load_world*



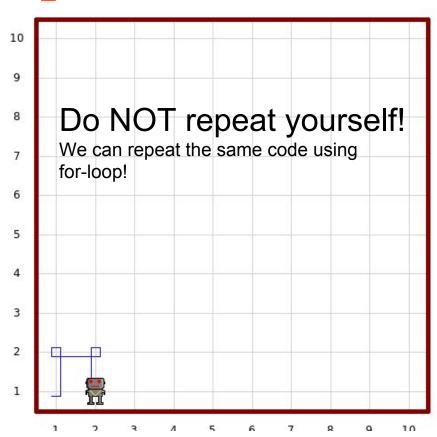
How to Define Function

```
from cs1robots import *
create world()
hubo = Robot()
hubo.set trace('blue')
# Write vour own code below!
def turn right():
  hubo.turn left()
  hubo.turn left()
  hubo.turn left()
hubo.turn left()
hubo.move()
turn right()
hubo.move()
turn right()
hubo.move()
```



How to Use For-Loop

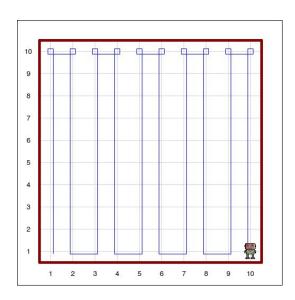
```
from cs1robots import *
create world()
hubo = Robot()
hubo.set trace('blue')
# Write vour own code below!
def turn right():
  for i in range(3):
     hubo.turn left()
hubo.turn left()
hubo.move()
turn right()
hubo.move()
turn right()
hubo.move()
```



Week 2 Today's Tasks 1

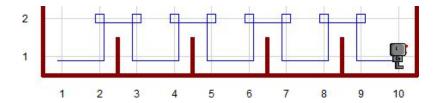
Task 1: ZigZag

- Create a default world.
- Add a robot.
- Make the robot visit the entire world in a zigzag fashion.



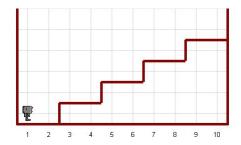
Task 2: Hurdle

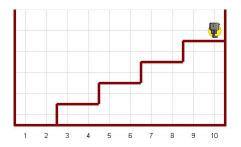
- Load the world named 'hurdles1.wld'.
- Add a robot.
- Make the robot jump all hurdles and pick up the beeper.

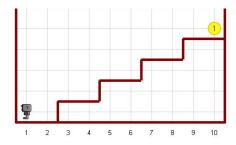


Task 3: Newspaper delivery

- Load the world named 'newspaper.wld'.
- Add a robot with one beeper.
- Make the robot deliver newspapers and return to his starting point.

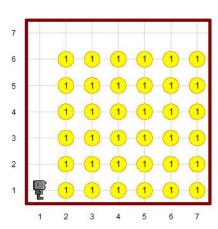






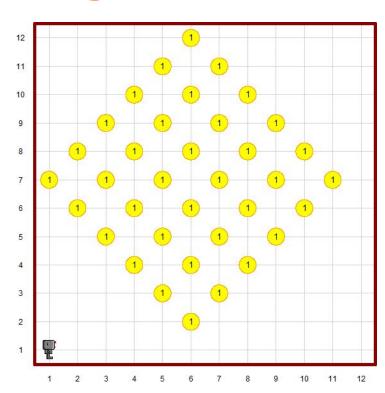
Task 4: Harvest

- Load the world named 'harvest1.wld'.
- Add a robot.
- Make the robot harvest all the carrots (beepers).



Task 5: Harvest again

- Load the world named 'harvest2.wld'.
- Add a robot.
- Make the robot harvest all the carrots with the <u>shortest path</u> possible.



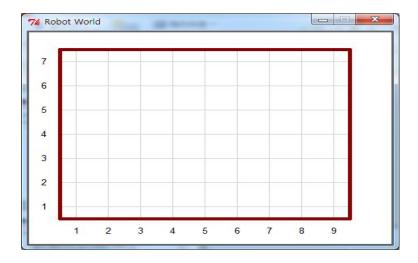
If-statement & While-statement

New functions

Create a custom world

```
create_world(streets = 7, avenues = 9)
```

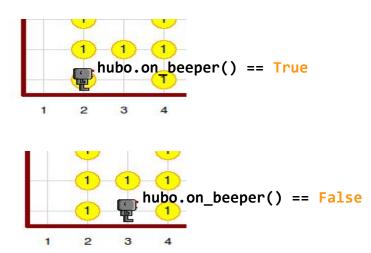
- ✓ 'streets' for the number of rows
- ✓ 'avenues' for the number of columns



New functions

Can check if there is a beeper

hubo.on_beeper()



New functions

Can check if there is a wall on each of the three sides

```
hubo.front_is_clear()
hubo.left_is_clear()
hubo.right_is_clear()
```

```
hubo.left_is_clear() == True

hubo.front_is_clear() == False

hubo.right_is_clear() == True
```

If statements

If statements sequentially checks the conditionals

```
if conditional_expression_1:
 works to do when conditional_expression_1 evaluates to True
elif conditional_expression_2:
 works to do when conditional_expression_1 evaluates to False &
                   conditional expression 2 evaluates to True
elif conditional expression 3:
 works to do when conditional_expression_1 evaluates to False &
                   conditional_expression_2 evaluates to False &
                   conditional_expression_3 evaluates to True
else:
 works to do when all the above conditions are False
```

If statements - Example

```
score = 50
if score < 60:
  print('You got F grade')
elif score < 70:
  print('You got C grade')
elif score < 80:
  print('You got B grade')
else:
  print('You got A grade')
```

Guess what will be output

- when score = 55
- when score = 65
- when score = 70
- when score = 85 respectively?

While loops

 while statement loops until the conditional evaluates to true

```
while conditional_expression:
works to do while conditional_expression evaluates to True
```

Example

```
n = 0 Result)

while n < 5:

print(n)

n = n + 1
```

Week 2 Today's Tasks

Tasks for Today!

Read sections 10~13 in the robot notes

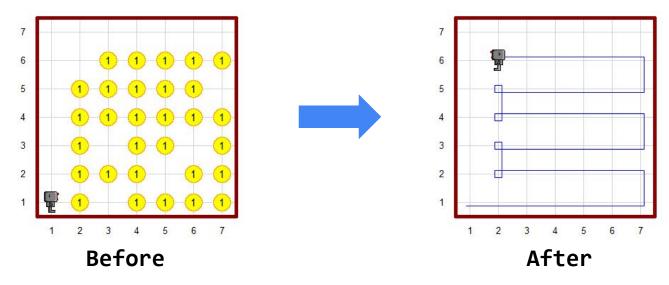
Five not so simple tasks

- Harvest More (page 6)
- Plant (page 7)
- Smart Hurdles (page 8 & 9)
- Harvest Even More (page 10)
- Smart ZigZag (page 10)
- When you have completed all the tasks, let a TA mark you off

Task 1 | Conditionals – Harvest More

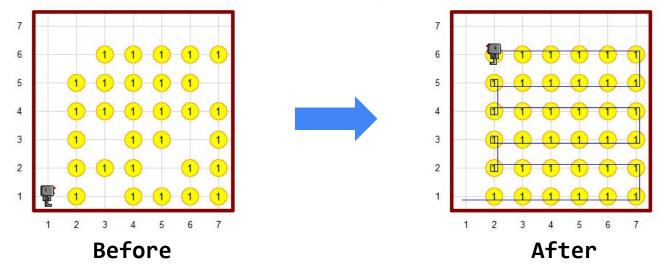
 Modify your program from the 'Harvest Again' task (Week 01) so that it works for harvest3.wld

load_world("worlds/harvest3.wld")



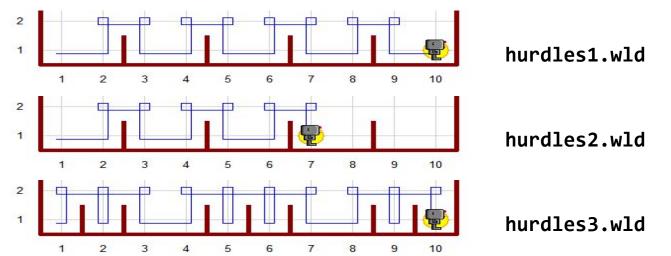
Task 2 | Conditionals – Plant

- Write a program so that Hubo plants beepers in empty spots
- The finished screen should look like "harvest1.wld" load_world("worlds/harvest3.wld")



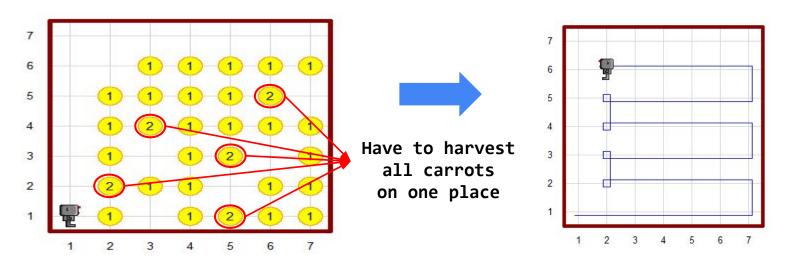
Task 3 | Conditionals – Smart Hurdles

- Write jump_one_hurdle() in section 11
 - move_jump_or_finish() should be able to handle all three maps,
 "hurdles1.wld", "hurdles2.wld" and "hurdles3.wld". Check it yourself.
- Write a new program (similar to Hurdles3 in section 11) that uses a while loop.
 DO NOT USE a for-loop of fixed length
 - It should also work for all three hurdles



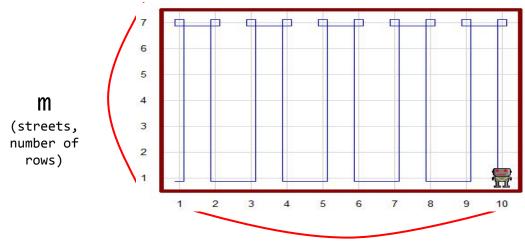
Task 4 | While loop – Harvest Even More

- Modify Harvest More task
 - It should work even when there are more than one beeper on a spot ("harvest4.wld")
 - It should also work for the previous worlds ("harvest1.wld" and "harvest3.wld")



Task 5 | While loop – Smart ZigZag

- Rewrite ZigZag program
 so that the robot can visit every spot in an empty world
 of any size in zigzag fashion
 - It should work for even and odd numbers of streets and avenues



(avenues,
of columns)

m and n can be any integer
except for m=1 or n=1

questions?