



Nonlinearity Encoding for Extrapolation of Neural Networks

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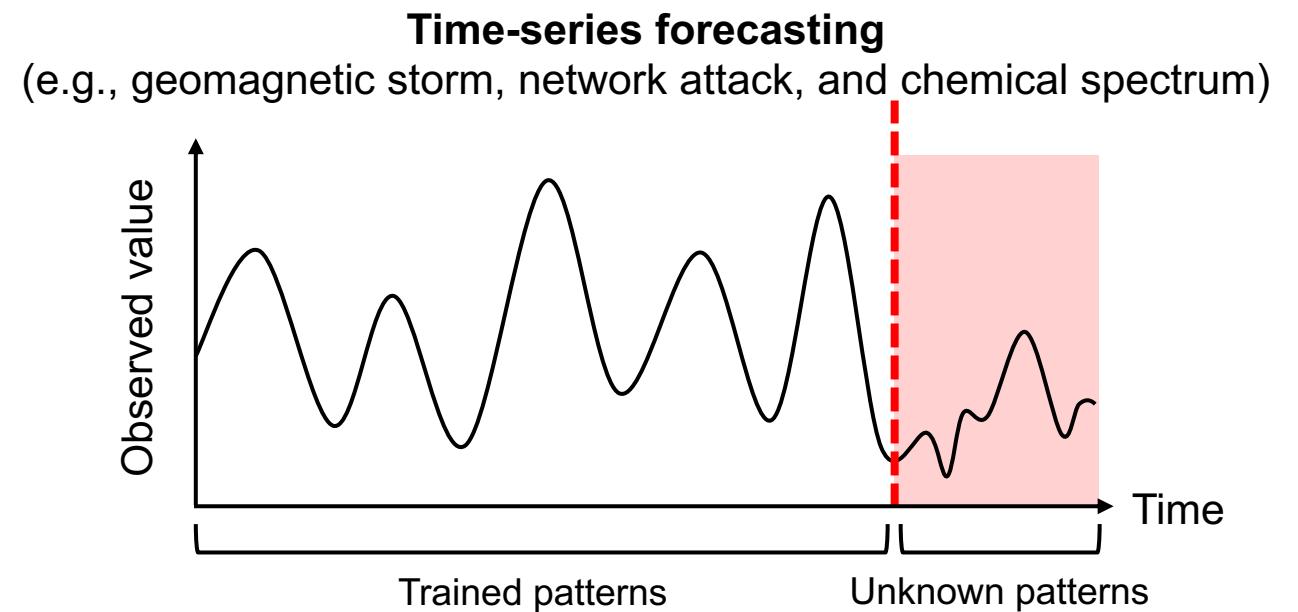
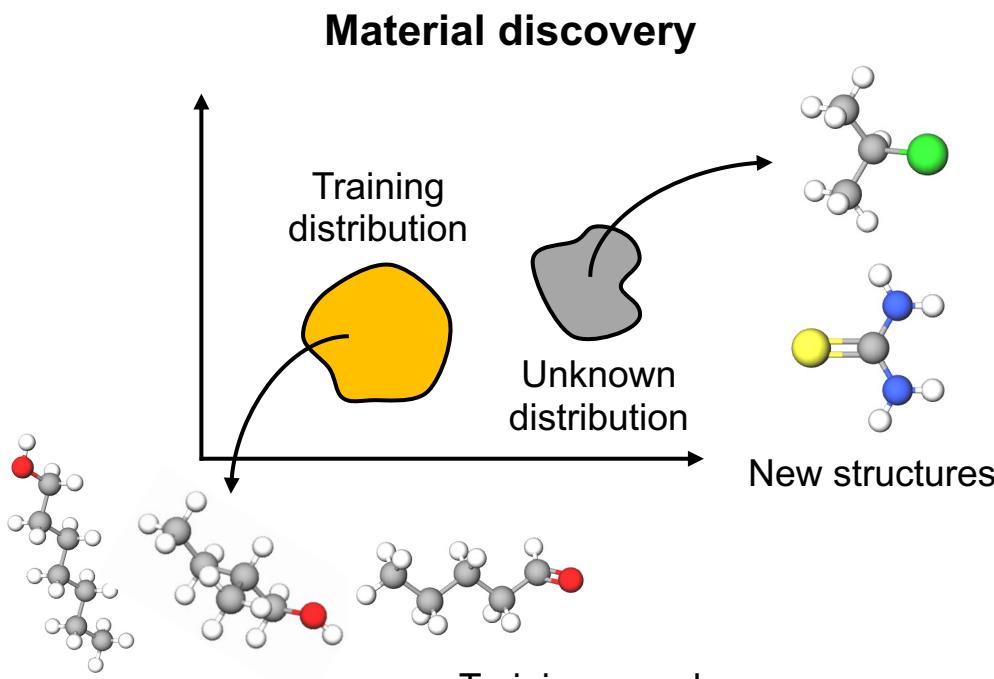
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Extrapolation

- **Goal:** Predict unseen data **outside the training distribution**
- Extrapolation is challenging because the input data usually follows an unknown distribution
- However, **extrapolation is common in scientific applications** in which discovering unobserved scientific knowledge is crucial



Formal Definition of Extrapolation in Machine Learning

- **Given:** Prediction model $f: \mathcal{X} \rightarrow \mathbb{R}$ trained on a training distribution \mathcal{D}
- **Goal:** Minimize the following extrapolation error L_e

$$L_e = \mathbb{E}_{(x,y) \sim \mathcal{X} \setminus \mathcal{D}} [L_s(y, f(x))]$$

Extrapolation Error Training distribution Prediction model
Data distribution Loss function (Cross entropy, MSE)

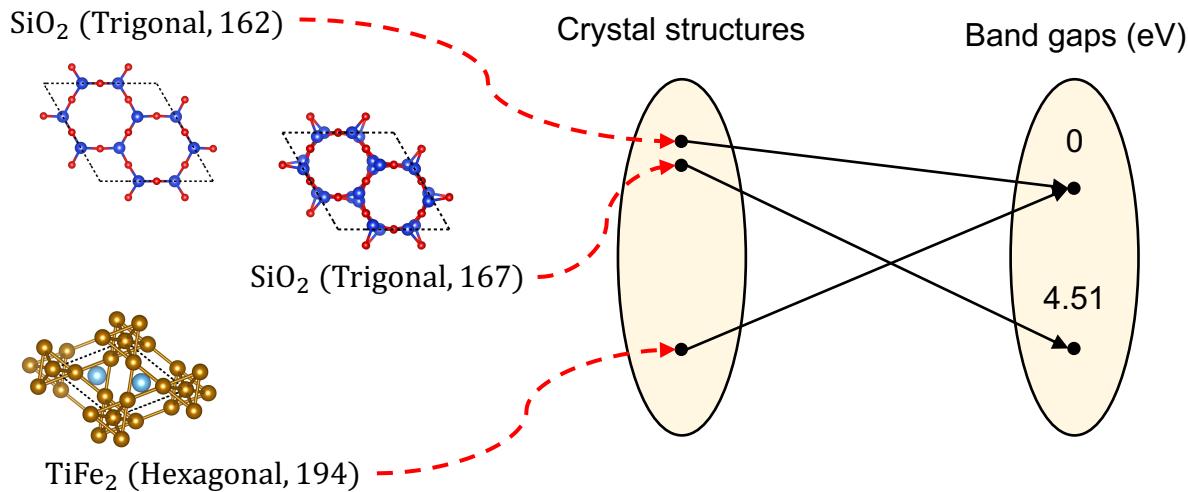
- (x, y) : A sample from out of training distribution $\mathcal{X} \setminus \mathcal{D}$

Input data Target response

- Machine learning achieved remarkable extrapolation performance in computer vision [1, 2]
- However, **extrapolation in scientific applications is still far from satisfactory** [3, 4]

Why is Extrapolation Difficult in Scientific Data?

- **Nonlinear input-to-target relationship**
 - Physical and chemical systems have severe **nonlinear relationships with their properties**.

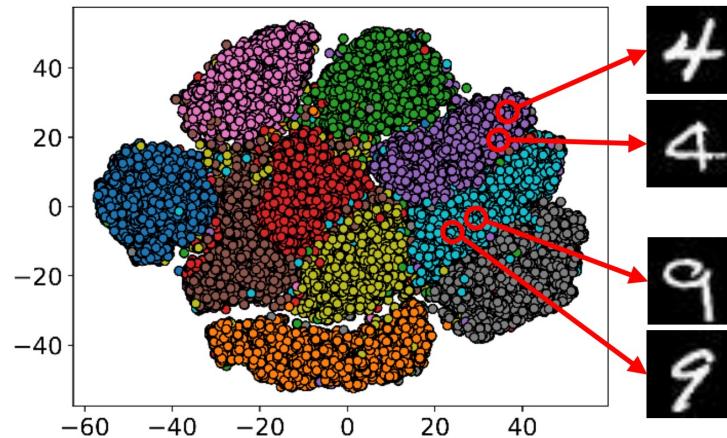


Two **similar structures** have completely **different physical properties**,
whereas two completely **different structures** have **the same physical property**

Image Dataset vs. Scientific Dataset

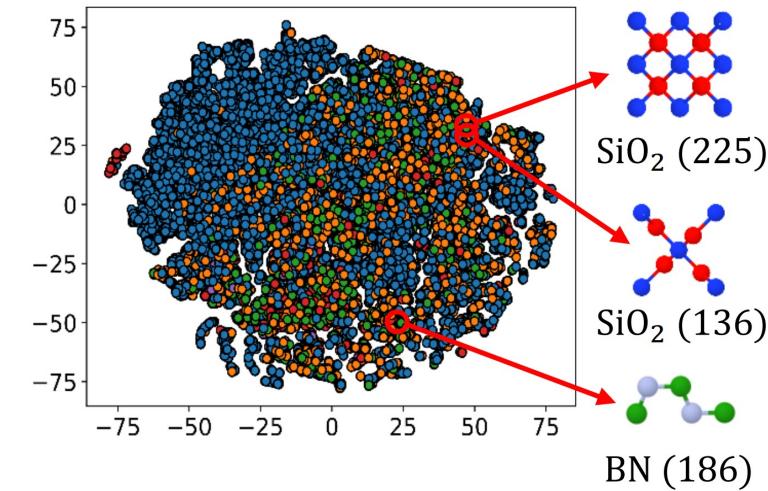
- T-SNE plots of MNIST and Material Project (MP) datasets
- Each point indicates an **image** or a **material** with **target response (label)** denoted by **colors**.
 - MNIST: class label
 - MP dataset: band gap

(a) MNIST dataset



Similar images share similar labels

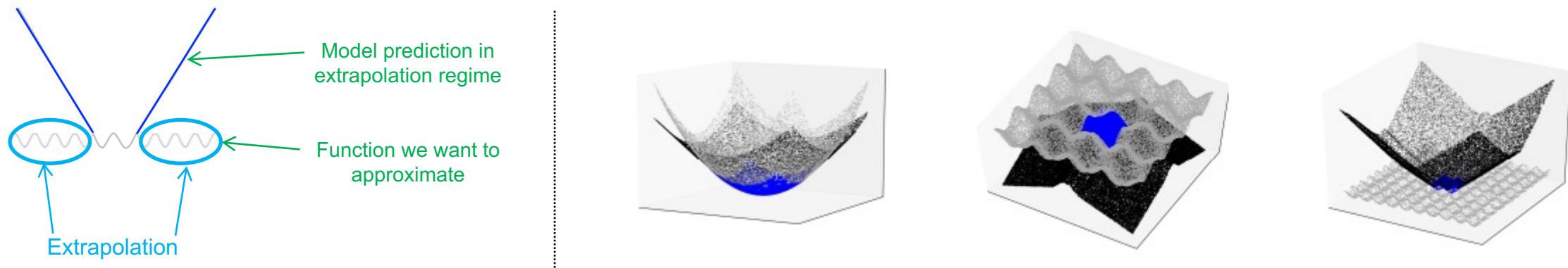
(b) MP dataset



Similar materials do not necessarily share similar labels

How Neural Networks Extrapolate (Xu et al, ICLR21)

- **Theoretical findings in extrapolation:** Neural networks with ReLU → simple linear regression in the extrapolation regime [7]



MLPs converge to linear functions outside the training data range

- **Proposed solution:** Remove nonlinearity from the data itself to linearize the problem
- **Limitation:** Requires domain knowledge to remove nonlinearity, and task-specific / data-specific

Related Work on Extrapolation

- **Representation learning [5]**
 - Pros: Universally applicable method
 - Cons: Constraints on data distributions
- **Transfer learning [6]**
 - Pros: Problem-specific methods, goal-directed learning
 - Cons: Source datasets, similar data distributions, re-training
- **Graph reformulation [7]**
 - Pros: Easy to implement, theoretical backgrounds
 - Cons: Manual reformulation, white-box systems

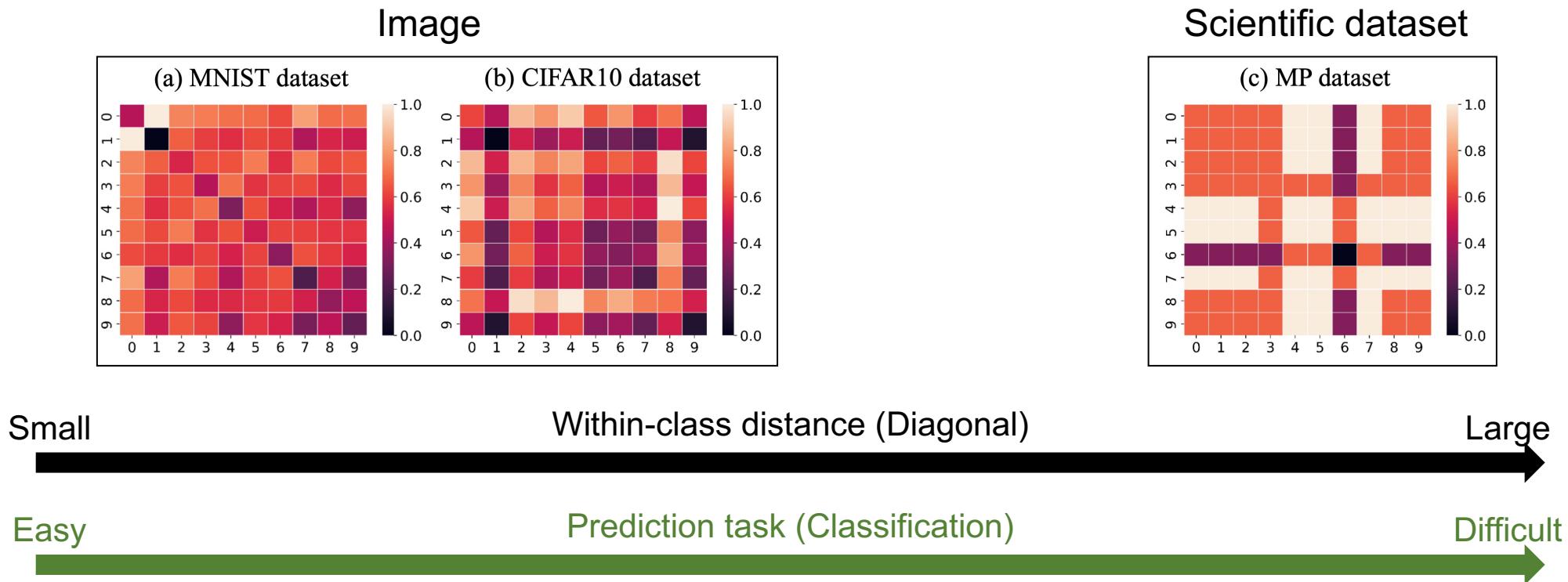
Most existing studies mainly focus on **supporting extrapolation** rather than learning extrapolation models

Can we learn extrapolation models?

Can we learn extrapolation models?

: Image Dataset vs. Scientific Dataset

- Heatmap visualization of **within-** and **between-class distances** on benchmark image and materials datasets

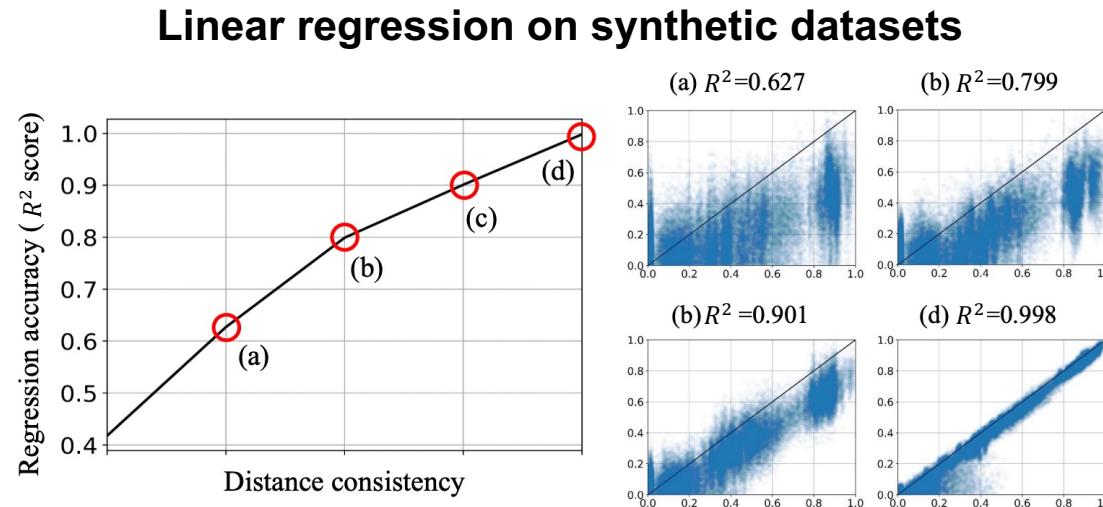


Prediction tasks can be made easier when,
Two inputs with same label → Small input distance

**Distance
Consistency!**

Distance Consistency (DC)

- Consistency w.r.t. the distance between the inputs and their target responses
 - e.g., images > materials
- Extend our argument from classification to **regression**
 - Assume: Classification with infinite number of classes \approx regression



High distance consistency \rightarrow High accuracy (R^2 score) \rightarrow **Input-to-target relationship is made simple**

Problem Reformulation of Extrapolation

- We reformulate the extrapolation problem as a **representation learning** problem aiming to **linearize the input-to-target relationships**



- Our goal:** Increase the **distance consistency** aiming at **simplifying the input-to-target relationships**
 - Given:** Two pairs of data samples $(x_i, y_i), (x_j, y_j)$
 - Define:** The distance between them

$$d(d(x_i, x_j) - d(y_i, y_j)) \xrightarrow[\text{Dist. btw. inputs}]{\text{Dist. btw. targets}} \sum_{i=1}^N \sum_{j=1}^N d(d(x_i, x_j) - d(y_i, y_j))$$

Consider all N^2 pairs

We adopt **Wasserstein distance** to measure the distance consistency between input and target

Nonlinearity Encoding based on Wasserstein Distance

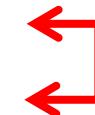
- For a set of probability measures Π on $\Omega \times \Omega$, Wasserstein distance is defined by an optimization problem as:

$$W_p = \left(\inf_{\pi \in \Pi} \int_{\Omega \times \Omega} \|x - y\|_p \pi(x, y) dx dy \right)^{1/p}$$

Why Wasserstein distance?

Many scientific data has unknown and arbitrary shaped distributions

- However, there is a problem in applying Wasserstein distance in our task
 - Wasserstein distance is defined only for the **data distributions of the same dimensionality**.
- Our task:** Regression
 - Input: Vector ($\in \mathbb{R}^d$)
 - Target: Scalar ($\in \mathbb{R}$)



Dimension mismatch!

Nonlinearity Encoding based on Wasserstein Distance

- Instead, we define **distance distribution** to apply Wasserstein distance between **two distributions of different dimensions**

*Definition) For a n -dimensional space $\mathcal{X} \subseteq \mathbb{R}^n$, **distance distribution \mathcal{K} is defined as a probability distribution of pairwise distances $d(x, x')$ for all $(x, x') \in \mathcal{X} \times \mathcal{X}$, where $d: \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty)$ is a distance metric.***

$$W_p = \left(\inf_{\pi \in \Pi} \int_{\Omega \times \Omega} \|x - y\|_p \pi(x, y) dx dy \right)^{1/p}$$

\longrightarrow

$(p = 1)$

Distance consistency btw input and target!

$$W_1(\mathcal{K}_x, \mathcal{K}_y; \pi, \theta) = \inf_{\pi \in \Pi} \int_{\mathcal{M} \times \mathcal{M}} \|r - u\| \pi(r, u) dr du$$

- $r = d(\phi(x; \theta), \phi(x'; \theta))$: Dist. btw input data in embedding space
- $u = d(y, y')$: Dist. btw target data

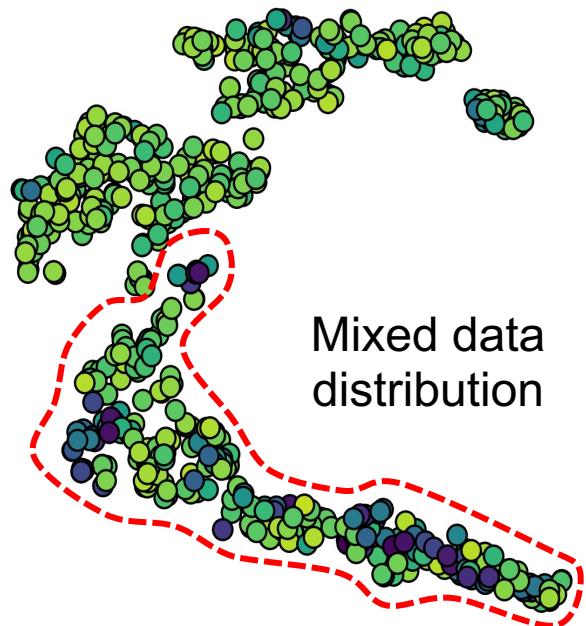
Our goal: Maximize the distance consistency between input and target

→ The distance between two inputs should be determined based on the distance between their targets

Problem Definition of Nonlinearity Encoding

- Our method: Automatic Nonlinearity Encoding (ANE)

Data distribution in the **original feature space**

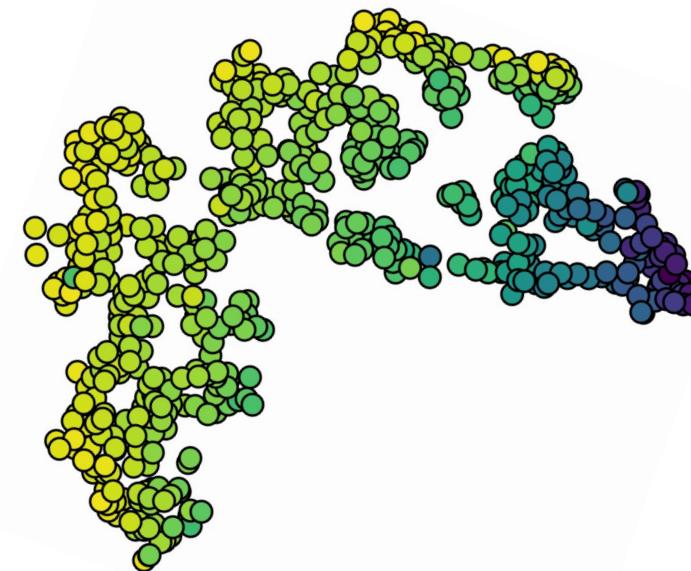


Hard

Nonlinearity
Encoding



Data distribution in the **embedding space of ANE**



Easy

Optimization: Decomposition of Lagrangian

- Our problem can be defined as follows:

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N \inf_{\pi \in \Pi} \int_{\mathcal{M} \times \mathcal{M}} \|r_{ij} - u_{ij}\|_p \pi(r_{ij}, u_{ij}) dr du$$

training data

**Joint optimization
w.r.t. θ and π**

- $r_{ij} = d(\phi(\mathbf{x}_i; \theta), \phi(\mathbf{x}_j; \theta))$: **Dist. btw input data** in embedding space
- $u_{ij} = d(y_i, y_j)$: **Dist. btw target data**

- We can define a **Lagrangian of the objective function** as (refer **Kantorovich-Rubinstein duality [6]**):

$$L_W = \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} (\|r_{ij} - u_{kj}\| - f(r_{ij}) - g(u_{kj})) \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \|r_{ij} - u_{kj}\| \pi(r_{ij}, u_{kj}) \\ + \sum_{(i,j) \in \mathcal{N}} (p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj})) f(r_{ij}) + \sum_{(i,j) \in \mathcal{N}} (p(u_{ij}) - \sum_{(k,q) \in \mathcal{N}} \pi(r_{kj}, u_{ij})) g(u_{ij}) + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{kj}, u_{ij}) g(u_{ij}),$$

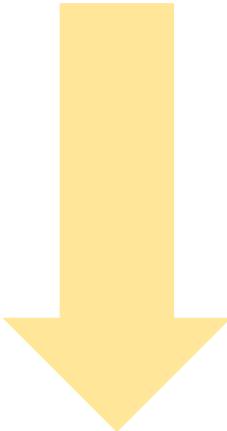
where $\mathcal{N} = \{(i,j) \mid \text{for all } i, j \in \{1, 2, \dots, N\}\}$, and $I_{ij} = \{(k, q) \mid u_{ij} = u_{kj} \text{ for } (k, q) \in \mathcal{N}\}$.

Pairs with the same target distance

Optimization: Model Parameter Optimization

- In the end, the representation learning problem to encode the nonlinearity is given by:

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N \inf_{\pi \in \Pi} \int_{\mathcal{M} \times \mathcal{M}} \|r_{ij} - u_{ij}\|_p \pi(r_{ij}, u_{ij}) dr du$$



- $r_{ij} = d(\phi(\mathbf{x}_i; \theta), \phi(\mathbf{x}_j; \theta))$: **Dist. btw input data** in embedding space
- $u_{ij} = d(y_i, y_j)$: **Dist. btw target data**

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N \|r_{ij} - u_{ij}\|$$

Enforce distance consistency
between data pairs!

Optimization: Model Parameter Optimization

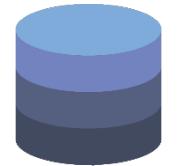
Training of ANE-based prediction model

Input : Training dataset $\mathcal{D} = \{(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_N, \mathbf{y}_N)\}$;
Embedding network $\phi(\mathbf{x}; \theta)$; Prediction model
 $f(\phi(\mathbf{x}; \theta); \mu)$; Sampling method $\psi(\mathbf{x}; \mathcal{D})$; Distance
metric d

```
1 repeat
2   for  $i = 1; i < N; i++$  do
3      $s = \psi(\mathbf{x}_i; \mathcal{D})$  // List of indices of the samples.
4     for  $j = 1; j < |s|; j++$  do
5        $r_{ij} = d(\phi(\mathbf{x}_i; \theta), \phi(\mathbf{x}_{s_j}; \theta))$  and  $u_{ij} = d(\mathbf{y}_i, \mathbf{y}_{s_j})$ 
6        $L_W+ = \|r_{ij} - u_{ij}\|_2$ 
7     end
8   end
9   Optimize  $\theta$  with respect to  $L_W$ .
10 until  $\theta$  converged;
11 Optimize  $\mu$  on  $\mathcal{Z} = \{(\phi(\mathbf{x}_1; \theta^*), \mathbf{y}_1), \dots, (\phi(\mathbf{x}_N; \theta^*), \mathbf{y}_N)\}$ .
12 Return  $\phi(\mathbf{x}; \theta^*)$  and  $f(\phi(\mathbf{x}; \theta^*); \mu^*)$ 
```

ANE

Prediction
model

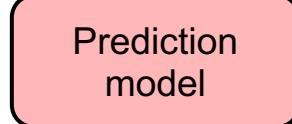


Training dataset
 $\mathcal{D} = \{(\mathbf{x}_1, \mathbf{y}_1), \dots, (\mathbf{x}_N, \mathbf{y}_N)\}$

Data-agnostic!



Training dataset with
nonlinearity encoding
 $\mathcal{Z} = \{(\phi(\mathbf{x}_1; \theta^*), \mathbf{y}_1), \dots, (\phi(\mathbf{x}_N; \theta^*), \mathbf{y}_N\}$

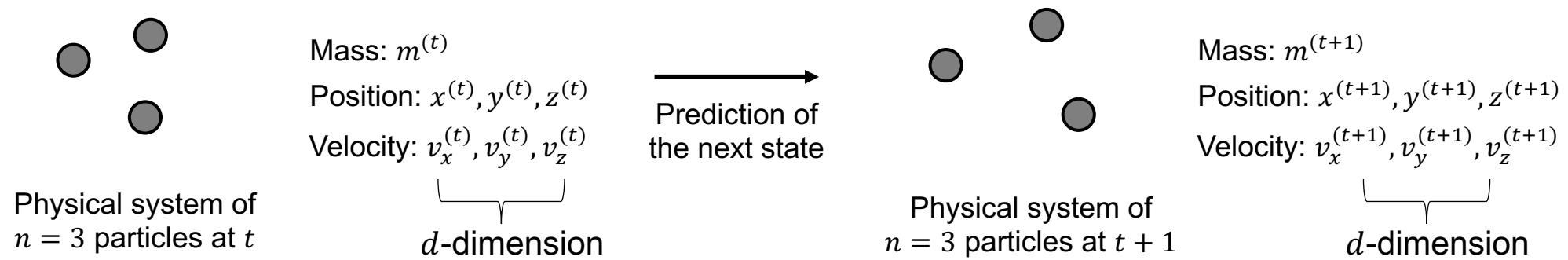


Experiments

- Matrix-shaped data
- Graph-structured data
- Time-series data

Extrapolation on Matrix-Shaped Data: n -Body Problem (1/3)

- **Task:** Given mass, position, and velocity of n particles, estimate future velocities of n particles



- **Data preprocessing:** 3-dimensional 3-body problem. $x_t \in \mathbb{R}^{3 \times 7}$ and $y_t \in \mathbb{R}^{3 \times 3} \leftarrow$ Matrix-shaped data
 - Simulated 10 datasets
 - Train: Observations in time $[0, 80]$
 - Test: Predict velocity in future time $(80, 100]$

Extrapolation on Matrix-Shaped Data: n -Body Problem (2/3)

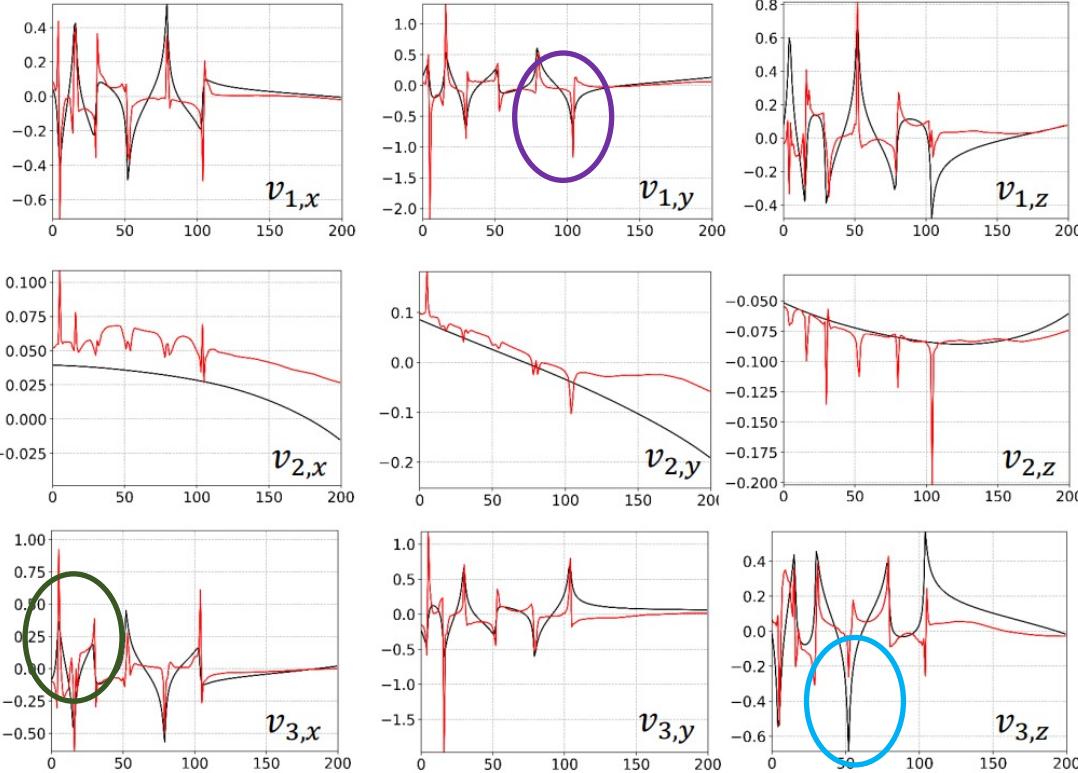
- **Metric:** Distance correlation (Corr) between the simulated (ground-truth) and predicted velocities
 - To measure how accurately the models predict future **trends** of the velocities

	Direct prediction method	GNN-based methods			Metric learning-based method		
Idx.	NBNet	GIN	MPNN	UMP	LRL-F	SLRL-F	ANE-F
1	0.32	0.54	0.35	0.25	0.43	0.53	0.18
2	0.49	0.54	0.53	0.36	0.52	0.49	0.45
3	0.57	0.54	0.53	0.46	0.52	0.59	0.29
4	0.25	0.68	0.26	0.26	0.09	0.07	0.03
5	0.66	0.93	0.71	0.69	0.85	0.65	0.49
6	0.11	0.22	0.17	0.16	0.12	0.12	0.02
7	0.75	0.94	0.63	0.67	0.61	0.44	0.40
8	0.44	0.85	0.26	0.29	0.27	0.38	0.15
9	0.39	0.26	0.10	0.70	0.18	0.40	0.03
10	0.64	0.72	0.55	0.54	0.53	0.37	0.27
mean	0.46	0.62	0.41	0.44	0.41	0.40	0.23
±std.	±0.19	±0.24	±0.20	±0.19	±0.23	±0.18	±0.17

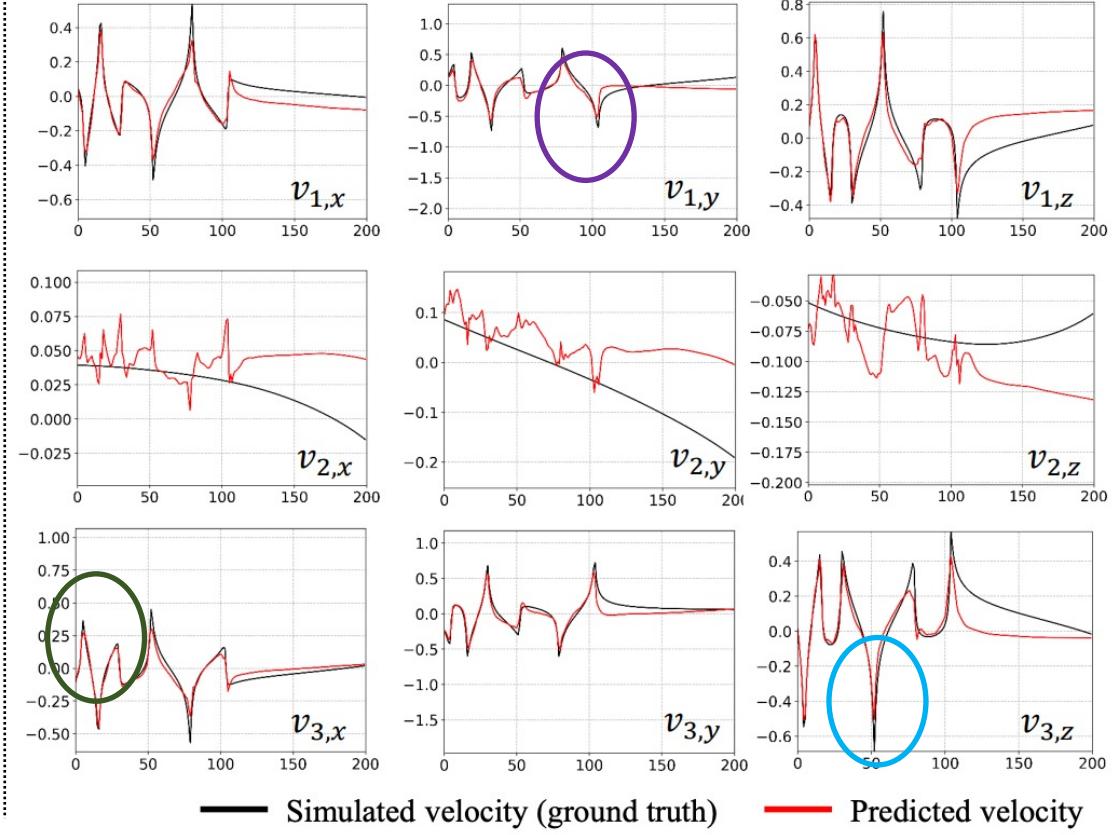
ANE generates input representations that are the most effective to reducing the extrapolation errors

Extrapolation on Matrix-Shaped Data: n -Body Problem (3/3)

State-of-the-art GNN-based method

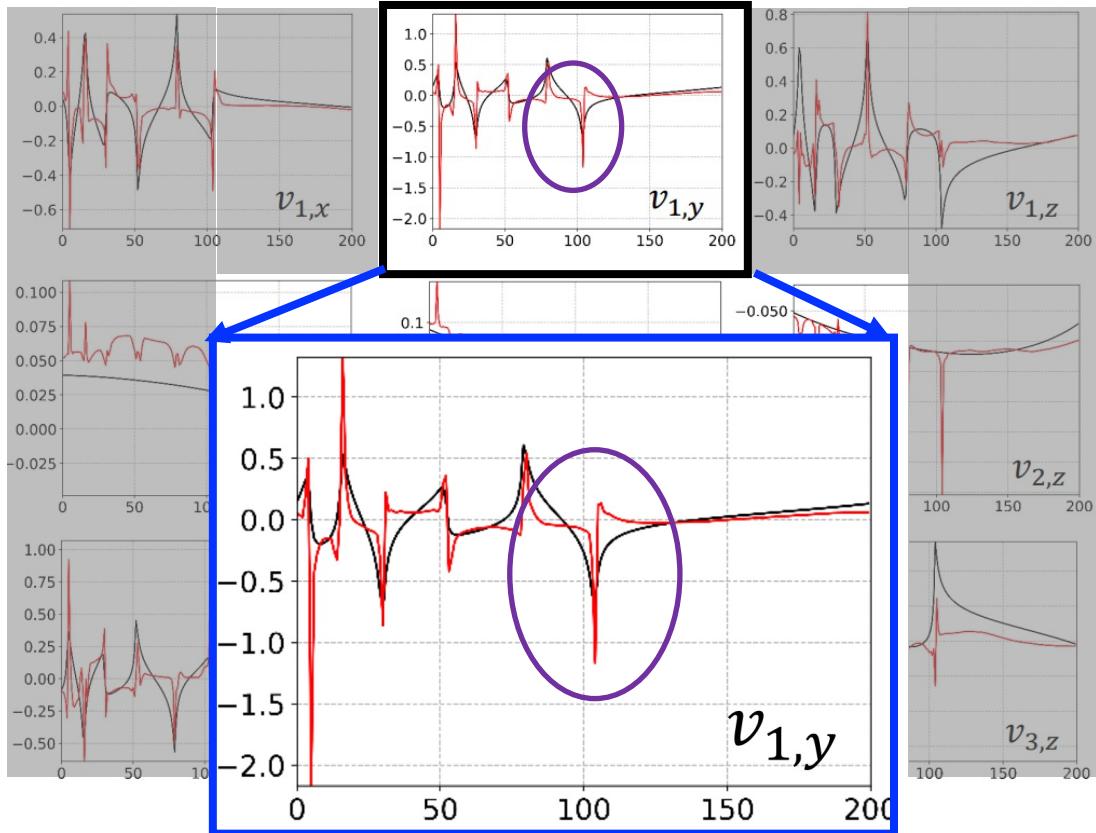


Ours (ANE-F)

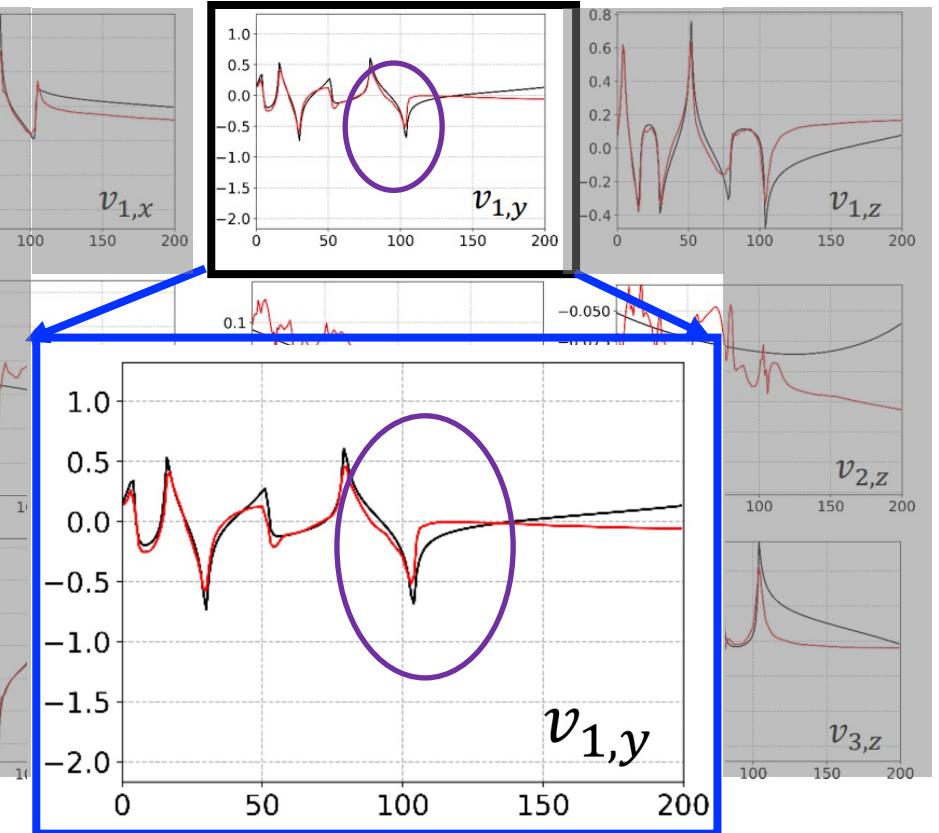


Extrapolation on Matrix-Shaped Data: n -Body Problem (3/3)

State-of-the-art GNN-based method



Ours (ANE-F)



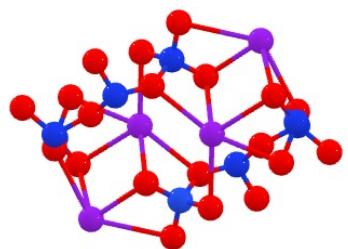
— Simulated velocity (ground truth)

— Predicted velocity

ANE is better at predicting **sudden explosions** of velocity

Extrapolation on Graph-Structured Data: Materials Property Prediction

- **Task:** Predict four material properties (Formation energy, Band gap, Shear modulus, Bulk modulus)
 - Discovering novel materials is a fundamental task in various fields (e.g., semiconductor and renewable energy)

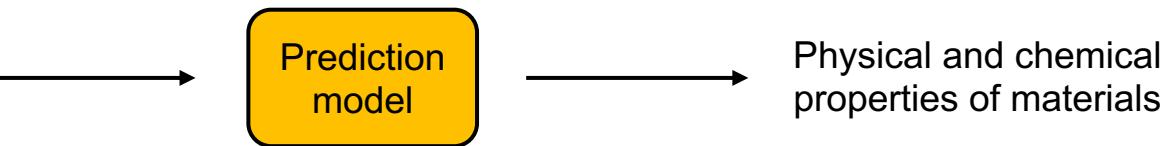


\mathcal{V} : A set of nodes (atoms)

\mathcal{U} : A set of edges (bondings)

\mathbf{X} : Node feature matrix

\mathbf{E} : Edge feature matrix



A material can be represented as an attributed graph $G = (\mathcal{V}, \mathcal{U}, \mathbf{X}, \mathbf{E})$.

▪ Data preprocessing

- MPS dataset: Benchmark materials dataset containing 3,162 materials
- **Train:** Materials that contain **only two types of elements** (i.e., Binary materials)
- **Test:** Materials that contain **three/four types of elements** (i.e., Ternary and quaternary materials)

Extrapolation on Graph-Structured Data: Materials Property Prediction

- Metric: R^2 score

Method	Formation Energy	Band Gap	Shear Modulus	Bulk Modulus
GCN	0.662 (± 0.019)	0.254 (± 0.071)	0.526 (± 0.025)	0.574 (± 0.037)
MPNN	0.072 (± 0.052)	N/A	0.352 (± 0.344)	0.714 (± 0.007)
CGCNN	N/A	0.163 (± 0.424)	0.405 (± 0.441)	0.732 (± 0.011)
UMP	0.763 (± 0.042)	0.351 (± 0.069)	0.552 (± 0.003)	0.707 (± 0.022)
LRL-MPNN	0.819 (± 0.024)	0.259 (± 0.034)	0.704 (± 0.009)	0.769 (± 0.021)
SLRL-MPNN	0.841 (± 0.018)	0.396 (± 0.052)	0.693 (± 0.013)	0.767 (± 0.007)
ANE-MPNN	0.879 (± 0.017)	0.447 (± 0.055)	0.716 (± 0.015)	0.790 (± 0.011)

ANE-MPNN outperforms state-of-the-art GNNs and metric learning methods

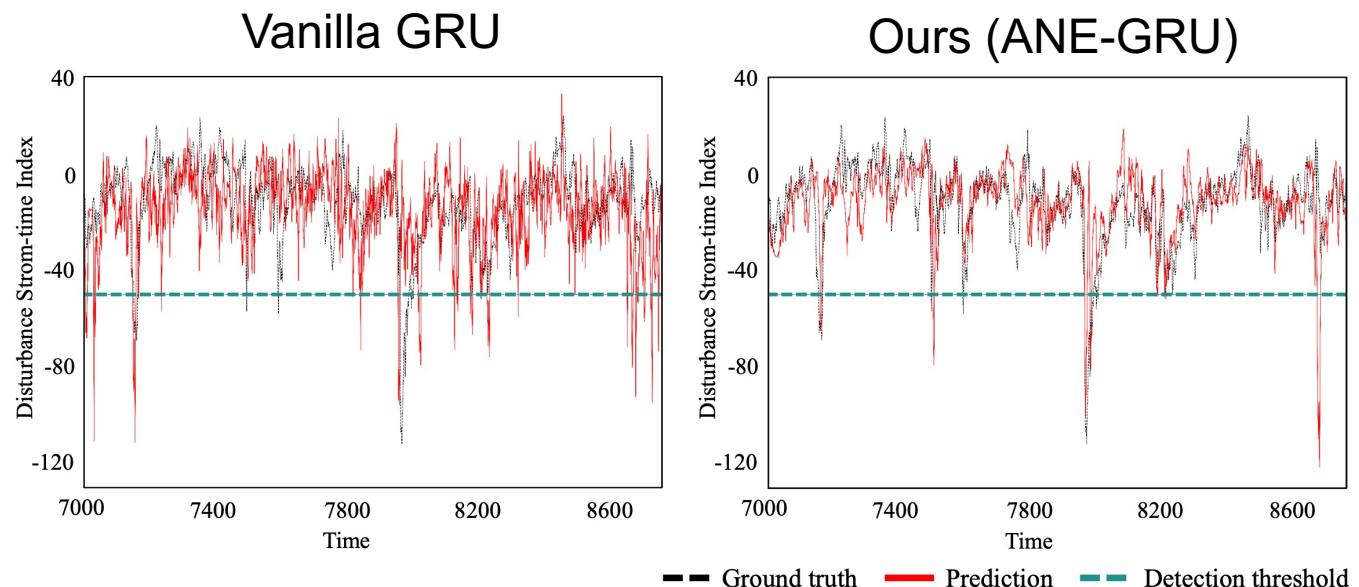
Extrapolation on Time-Series Data: Geomagnetic Storm Forecasting

- **Task:** 1) Predict geomagnetic storm, 2) Detect geomagnetic storm

- **Data preprocessing**

- Dataset: MagNet NASA dataset
- 1-year geomagnetic storm data is divided into 4 sequential periods ($\frac{3}{4}$ used for training, $\frac{1}{4}$ used for test)

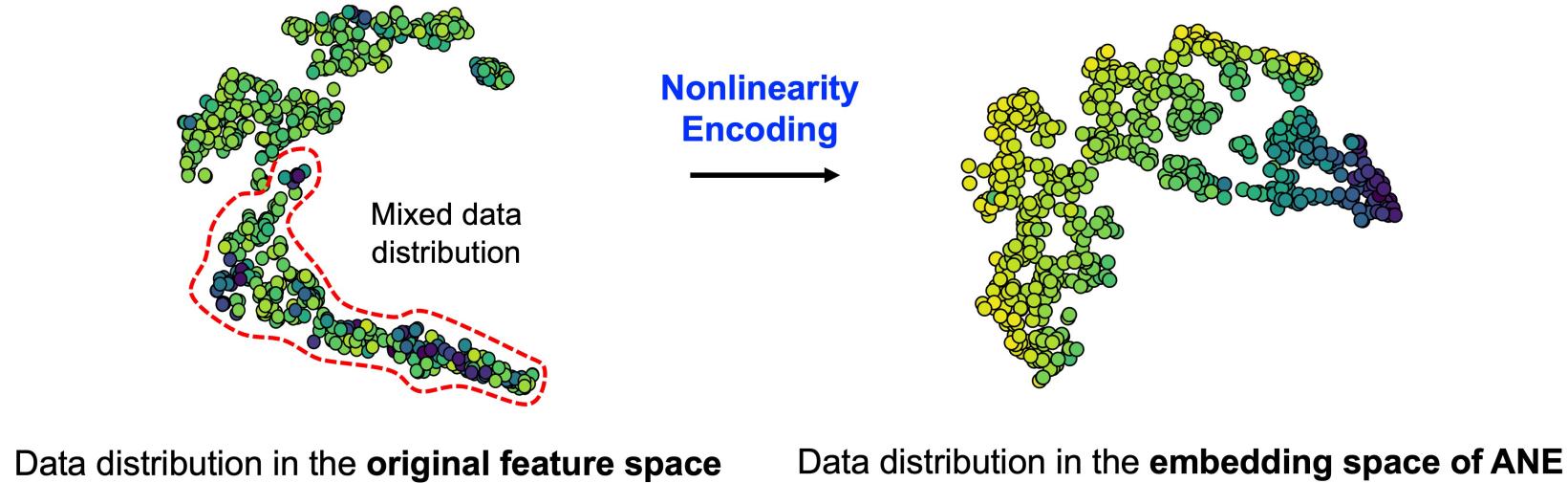
Method	Task 1		Task 2		
	Extrapolation Error		Detection Accuracy		
	MAE	Corr	Precision	Recall	F1-score
RNN	16.089 (± 0.806)	0.710 (± 0.025)	0.133 (± 0.013)	0.281 (± 0.065)	0.178 (± 0.015)
LSTM	14.721 (± 0.702)	0.696 (± 0.065)	0.164 (± 0.048)	0.260 (± 0.087)	0.201 (± 0.062)
GRU	14.613 (± 0.368)	0.687 (± 0.027)	0.145 (± 0.027)	0.230 (± 0.055)	0.177 (± 0.034)
TF	13.106 (± 0.717)	0.670 (± 0.031)	0.185 (± 0.115)	0.145 (± 0.074)	0.159 (± 0.084)
LRL-GRU	13.700 (± 0.581)	0.499 (± 0.031)	0.189 (± 0.035)	0.519 (± 0.186)	0.272 (± 0.054)
SLRL-GRU	10.986 (± 0.332)	0.455 (± 0.040)	0.260 (± 0.065)	0.336 (± 0.111)	0.291 (± 0.077)
ANE-GRU	10.534 (± 0.407)	0.428 (± 0.041)	0.513 (± 0.044)	0.495 (± 0.071)	0.502 (± 0.042)



ANE-GRU outperforms GRU, and ANE achieved further improvement over metric learning-based approaches

Conclusion

- Proposed a **data-agnostic** embedding method for improving the **extrapolation capabilities** of ML



- Maximized **distance consistency** between the inputs and their targets (Based on **Wasserstein distance**)
 - The **distance between two inputs** should be **determined based on the distance between their targets**
- Demonstrated the effectiveness in **various scientific applications of various data formats**

Thank you!

- Contact: ngs0@kriict.re.kr / cy.park@kaist.ac.kr
- Source code: <https://github.com/ngs00/ane>
- Lab homepage: <https://dsail.kaist.ac.kr/>

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Appendix

Optimization: Decomposition of Lagrangian

$$L_W = \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj})$$

Part 1

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj})$$

Part 2

$$+ \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(k,q) \in \mathcal{N}} \left(p(u_{kj}) - \sum_{(i,j) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) g(u_{kj})$$

Part 3

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{ij}, u_{kj}) g(u_{kj})$$

Optimization: Decomposition of Lagrangian

$$L_W = \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj}) \quad \text{Part 1} \longrightarrow 0$$

$$\begin{aligned} & + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) \\ & + \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(k,q) \in \mathcal{N}} \left(p(u_{kj}) - \sum_{(i,j) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) g(u_{kj}) \\ & + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{ij}, u_{kj}) g(u_{kj}) \end{aligned}$$

Best choice of the joint probability π ?

Set $\pi(r_{ij}, u_{kj}) = 0$ for all $(i,j) \in \mathcal{N}$ and $(k,q) \in \mathcal{N} \setminus I_{ij}$

(i.e., If two pairs of data ((i,j) and (k,q)) and do not have the same target distance, then the joint probability is 0)

$\therefore \|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \geq 0$ by the constraint in Lagrangian multipliers (1-Lipschitz constraint)

Optimization: Decomposition of Lagrangian

$$L_W = \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj})$$

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj})$$

Part 2

$$\longrightarrow 0$$

$$+ \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(k,q) \in \mathcal{N}} \left(p(u_{kj}) - \sum_{(i,j) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) g(u_{kj})$$

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{ij}, u_{kj}) g(u_{kj})$$

$\pi(r_{ij}, u_{kj})$ is always zero under the **optimized embedding function $\phi(\cdot; \theta^*)$** .

Optimization: Decomposition of Lagrangian

$$\begin{aligned} L_W = & \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj}) \\ & + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) \\ & + \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(k,q) \in \mathcal{N}} \left(p(u_{kj}) - \sum_{(i,j) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) g(u_{kj}) \\ & + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{ij}, u_{kj}) g(u_{kj}) \end{aligned}$$

Part 3



0

Always zero by

$$p(r_{ij}) = \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}),$$

$$p(u_{kj}) = \sum_{(i,j) \in I_{kj}} \pi(r_{ij}, u_{kj}),$$

and $\pi(r_{ij}, u_{kj}) = 0$ for all $(i,j) \in \mathcal{N}$ and $(k,q) \in \mathcal{N} \setminus I_{ij}$. **← From Part 1**

Optimization: Decomposition of Lagrangian

$$L_W = \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj})$$

Part 1

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj})$$

Part 2

$$+ \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(k,q) \in \mathcal{N}} \left(p(u_{kj}) - \sum_{(i,j) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) g(u_{kj})$$

$$+ \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus I_{ij}} \pi(r_{ij}, u_{kj}) g(u_{kj})$$

Part 3

Hence, one possible optimal joint probability π^* is given as:

$$\pi(r_{ij}, u_{kj}) = 0 \text{ for all } (i,j) \in \mathcal{N} \text{ and } (k,q) \in \mathcal{N} \setminus I_{ij} \text{ but } \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in I_{ij}} \pi(r_{ij}, u_{kj}) = 1$$

Given data pairs that do not have the same target distance, setting their joint probability to zero is one possible solution
(π should be a valid probability distribution)

Optimization: Model Parameter Optimization

- For the optimal joint probability π^* , the training problem of ANE is simplified as:

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N |I_{ij}| \|r_{ij} - u_{ij}\| \pi_{ij}^*.$$

data pairs that share the same target distance with (i, j)

- The joint probability π_{ij} can be empirically estimated by the i.i.d. condition as:

$$\pi_{ij} = \frac{1}{\sum_{l=1}^N \sum_{m=1}^N |I_{lm}|}, \text{ and } |I_{ij}| \ll \sum_{l=1}^N \sum_{m=1}^N |I_{lm}|.$$

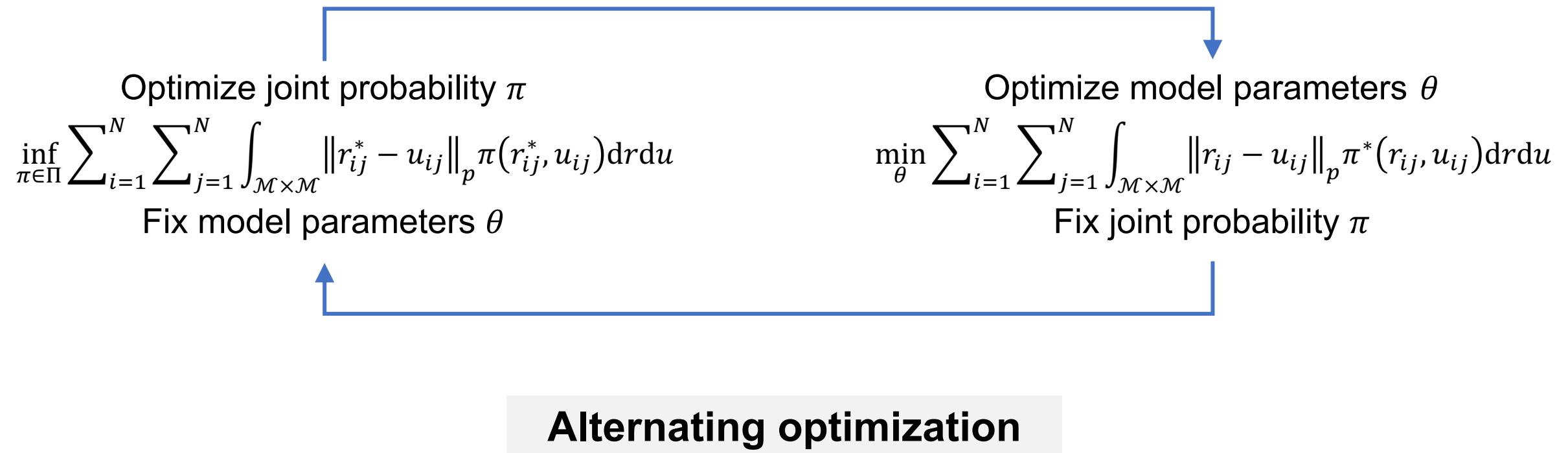
- Therefore, the representation learning problem to encode the nonlinearity is given by:

$$\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N \|r_{ij} - u_{ij}\|_2$$

- $r_{ij} = d(\phi(\mathbf{x}_i; \theta), \phi(\mathbf{x}_j; \theta))$: **Dist. btw input data** in embedding space
- $u_{ij} = d(y_i, y_j)$: **Dist. btw target data**

Enforce distance consistency between data pairs

Optimization: Decomposition of Lagrangian



Decomposition of Lagrangian: Full derivation

$$\begin{aligned}
L_W &= \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in \mathcal{N}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(i,j) \in \mathcal{N}} \left(p(u_{ij}) - \sum_{(k,q) \in \mathcal{N}} \pi(r_{kj}, u_{ij}) \right) g(u_{ij}) \\
&= \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus \mathcal{I}_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{I}_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) \\
&\quad + \sum_{(i,j) \in \mathcal{N}} p(r_{ij}) f(r_{ij}) - \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus \mathcal{I}_{ij}} \pi(r_{ij}, u_{kj}) f(r_{ij}) - \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{I}_{ij}} \pi(r_{ij}, u_{kj}) f(r_{ij}) \\
&\quad + \sum_{(i,j) \in \mathcal{N}} p(u_{ij}) g(u_{ij}) - \sum_{(k,q) \in \mathcal{N}} \sum_{(i,j) \in \mathcal{N} \setminus \mathcal{I}_{kj}} \pi(r_{kj}, u_{ij}) g(u_{ij}) - \sum_{(k,q) \in \mathcal{N}} \sum_{(i,j) \in \mathcal{I}_{kj}} \pi(r_{kj}, u_{ij}) g(u_{ij}) \\
&= \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus \mathcal{I}_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{I}_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} p(u_{ij}) g(u_{ij}) \\
&\quad + \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in \mathcal{I}_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) - \sum_{(k,q) \in \mathcal{N}} \sum_{(i,j) \in \mathcal{N}} \pi(r_{kj}, u_{ij}) g(u_{ij}) + \sum_{(k,q) \in \mathcal{N}} \sum_{(i,j) \in \mathcal{N} \setminus \mathcal{I}_{kj}} \pi(r_{kj}, u_{ij}) g(u_{ij}) \\
&= \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{N} \setminus \mathcal{I}_{ij}} \left(\|r_{ij} - u_{kj}\|_2 - f(r_{ij}) - g(u_{kj}) \right) \pi(r_{ij}, u_{kj}) + \sum_{(i,j) \in \mathcal{N}} \sum_{(k,q) \in \mathcal{I}_{ij}} \|r_{ij} - u_{kj}\|_2 \pi(r_{ij}, u_{kj}) \\
&\quad + \sum_{(i,j) \in \mathcal{N}} \left(p(r_{ij}) - \sum_{(k,q) \in \mathcal{I}_{ij}} \pi(r_{ij}, u_{kj}) \right) f(r_{ij}) + \sum_{(i,j) \in \mathcal{N}} \left(p(u_{ij}) - \sum_{(k,q) \in \mathcal{N}} \pi(r_{kj}, u_{ij}) \right) g(u_{ij}) + \sum_{(k,q) \in \mathcal{N}} \sum_{(i,j) \in \mathcal{N} \setminus \mathcal{I}_{kj}} \pi(r_{kj}, u_{ij}) g(u_{ij}).
\end{aligned}$$

ANE for Discovering Solar Cell Materials

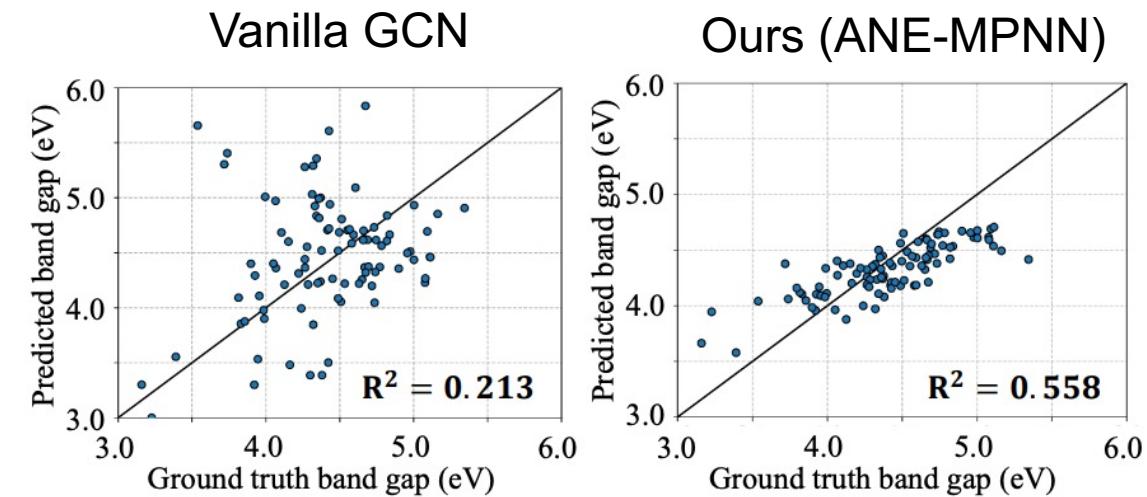
- **Task:** Predict band gaps of perovskites
 - c.f.) Perovskite has received significant attention as solar cell materials for renewable energy
 - Infer materials properties of crystal structures containing **unseen elemental combinations**
- **Data preprocessing**
 - Divided HOIP dataset by eliminating the materials that contain specific elements
 - **HOIP-HIGH:** HOIP – (Germanium (Ge) and Fluorine (F))
 - **HOIP-LOW:** HOIP – (Lead (Pb) and Iodine (I))
 - Range of band gaps between training and test data is completely different

ANE for Discovering Solar Cell Materials

- Metric: R^2 score

N/A: negative R^2

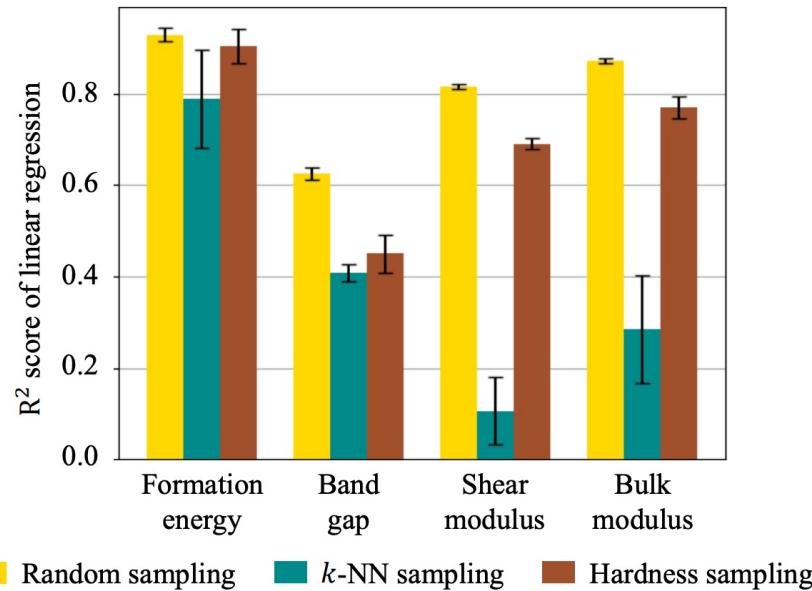
	Method	Dataset	
		HOIP-HIGH	HOIP-LOW
GNN methods	GCN	0.213(± 0.162)	N/A
	MPNN	N/A	N/A
	CGCNN	N/A	N/A
	UMP	N/A	N/A
DML methods	LRL-MPNN	N/A	0.521(± 0.131)
	SLRL-MPNN	0.182(± 0.160)	0.486(± 0.096)
	ANE-MPNN	0.558(± 0.044)	0.664$\pm(0.071)$



ANE-MPNN roughly captured the relationships, while GCN fails to do so

Sampling Strategies and Extrapolation

- Time complexity of the training process of ANE: $\theta^* = \operatorname{argmin}_{\theta} \sum_{i=1}^N \sum_{j=1}^N \|r_{ij} - u_{ij}\| \rightarrow O(N^2)$
- Three sampling strategies to reduce the time complexity:
 - **Random sampling:** selecting a data point randomly at each iteration
 - **k -NN sampling:** selecting k nearest data points for an anchor data
 - **Hardness sampling:** selecting k data points based on the training errors (top- k largest errors)



Random sampling performs the best despite its simplicity
(:: Random sampling = Density-based sampling)