

# **Hybrid System**

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Department of Mechanical Engineering



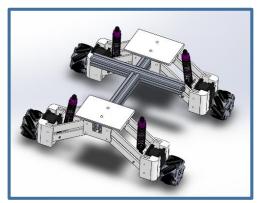
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  - Problem and Solution
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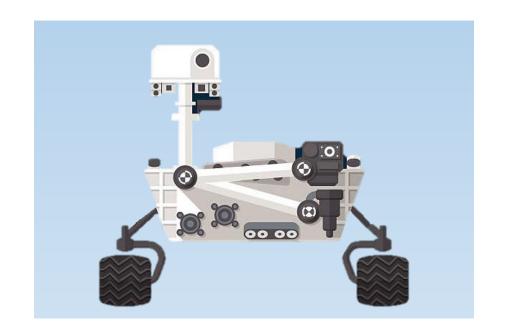












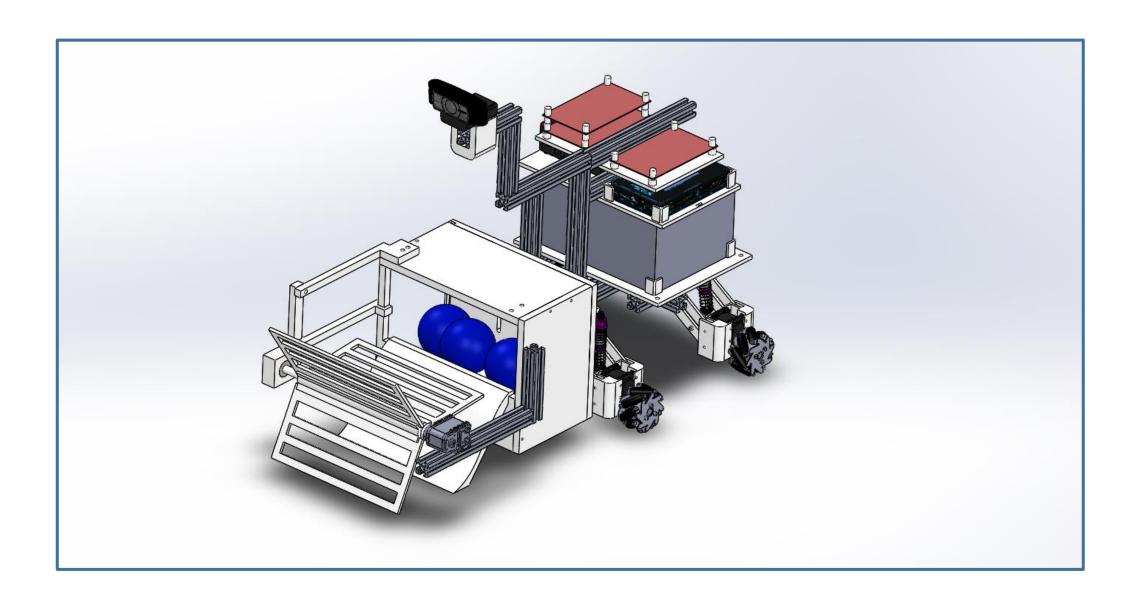
# Section – A

System Overview

# Hybrid System



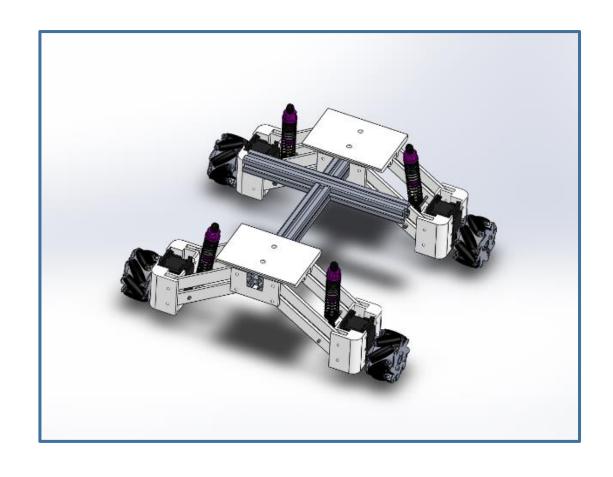


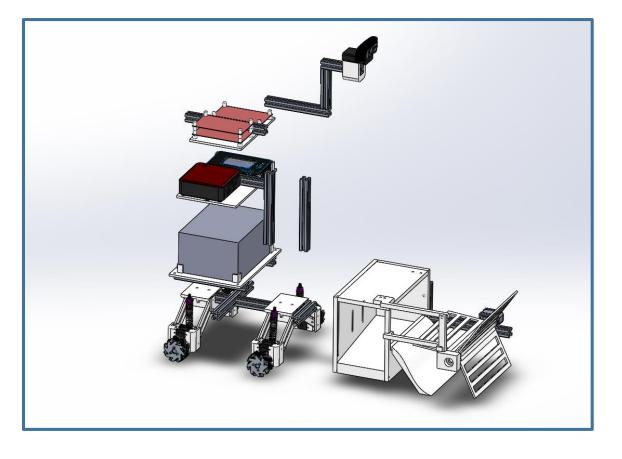


# Key Features









**Independent Suspension** 

**Modularity** 

#### Problem and Solution









- > Performance
- √ Precise ball picking
- ✓ < 5 mins





- > Cooling
- ✓ Passive cooling
- ✓ < 70°C





- > Creativity
- ✓ Independent suspension
- ✓ Modular design

#### Team Structure







Design & Manufacture

C-U OpenCV

Vision

Measurement & Control

**Integration** 

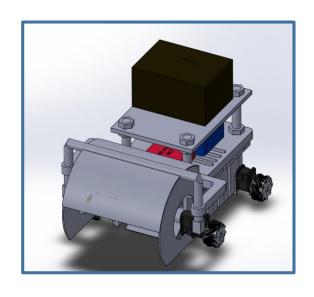


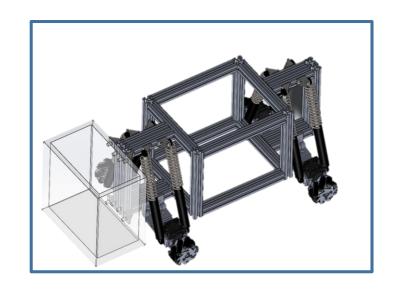


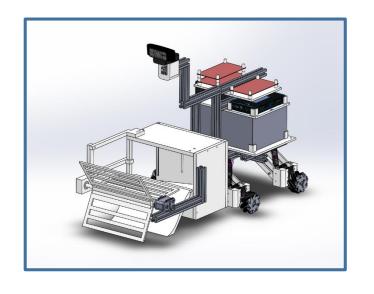
# Capstone Design: Evolution of Design











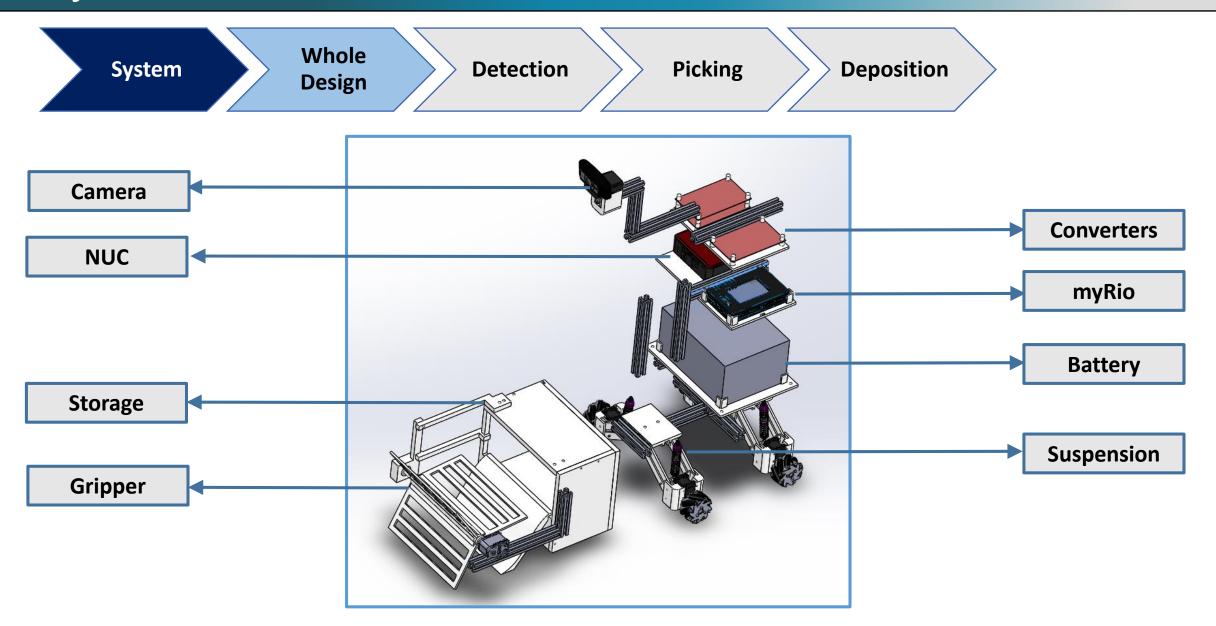














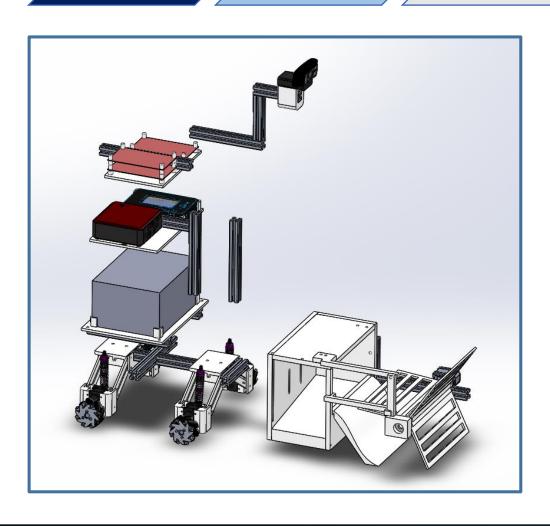


System

Whole Design

**Detection** 

**Picking** 



- ➤ Merits of Modularity
- ✓ Easy to repair
- ✓ Modifications would be easily implemented for Capstone Design II
- ✓ Design changes have a smooth and swift transition



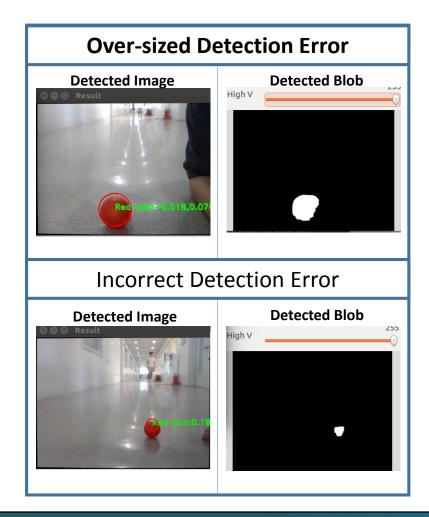


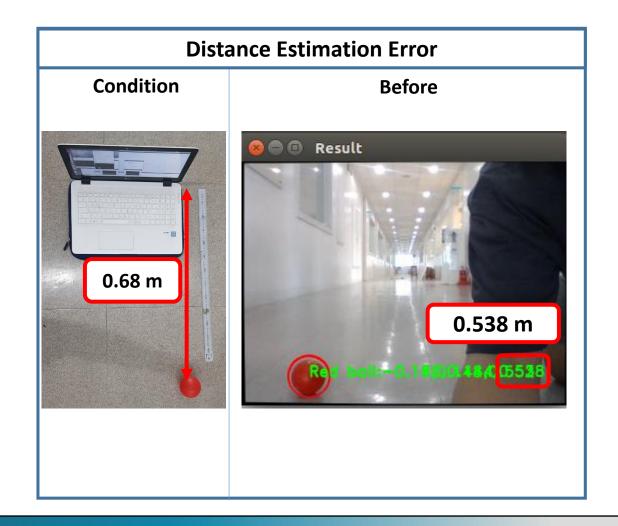
**System** 

Whole Design

**Detection** 

**Picking** 







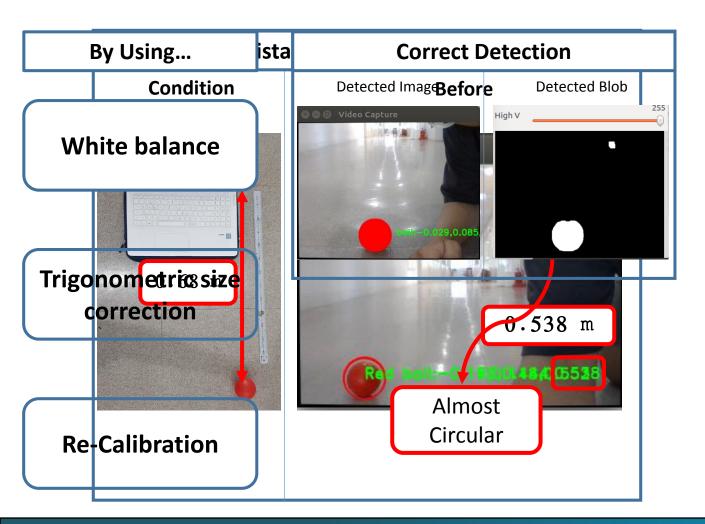


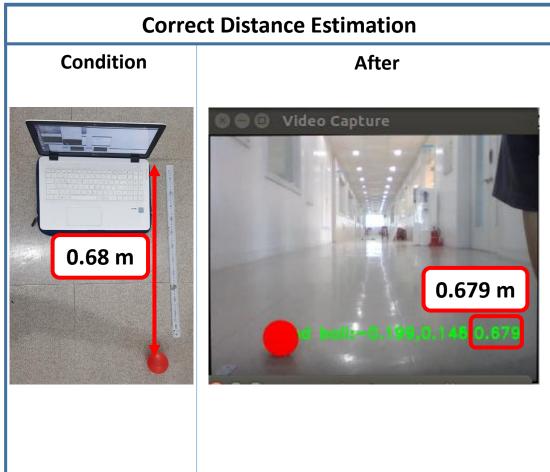
System

Whole Design

**Detection** 

**Picking** 







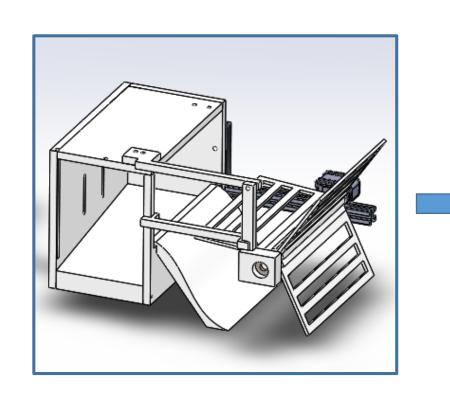


System

Whole Design

**Detection** 

**Picking** 







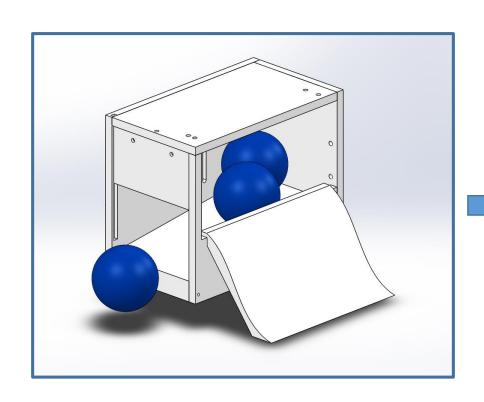


System

Whole Design

**Detection** 

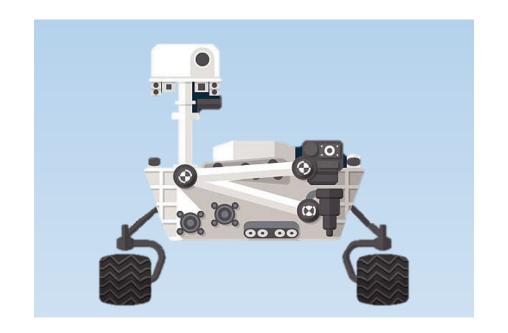
**Picking** 











# Section – B

System Analysis





**Suspension** 

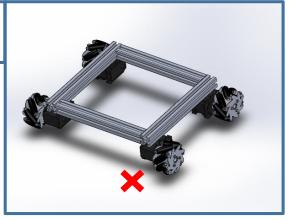
**Overview** 

Modelling

Video

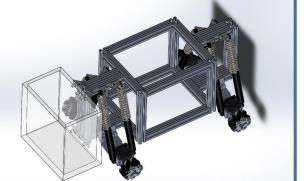
**Graphs** 

Ver #1



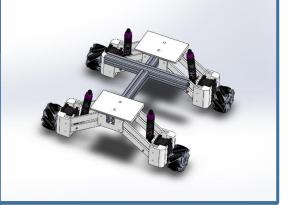
Ver #2





Ver #3





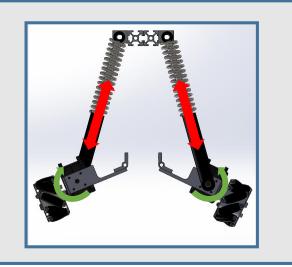
**Ver #1: No suspension** 

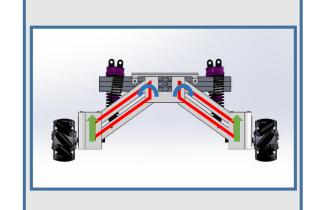
Ver #2: MacPherson

strut

Ver #3: SLA

suspension









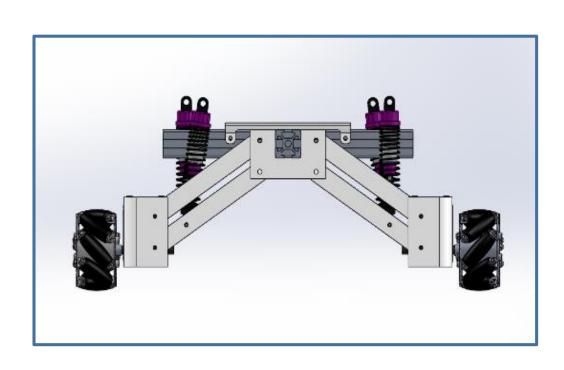
Suspension

**Overview** 

Modelling

Video

**Graphs** 



- ➤ Merits of suspension
- ✓ Better traction
- ✓ Precise detection





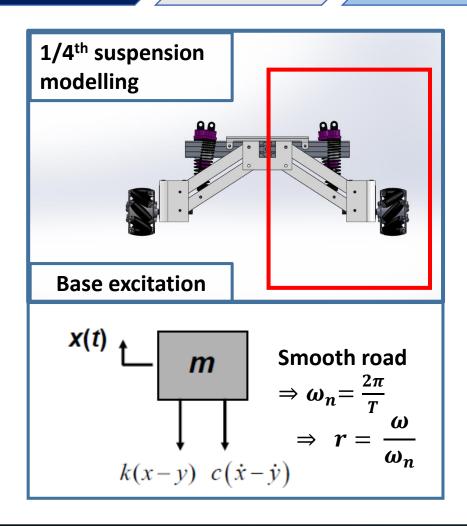
**Suspension** 

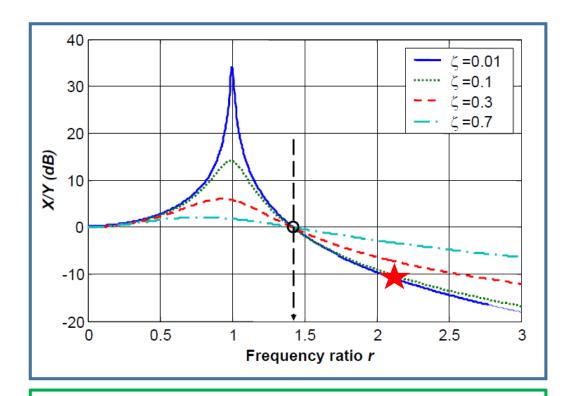
**Overview** 

Modelling

Video

**Graphs** 





 $\omega$  = 60 rpm -> K< 118.44 N/m necessary  $\Rightarrow$  Our K value :  $\frac{53.33 \text{ N/m}}{r = 2.114}$ 





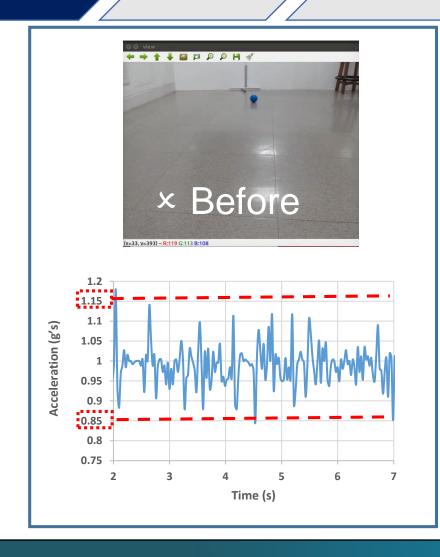
**Suspension** 

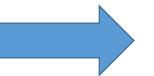
**Overview** 

Modelling

Video

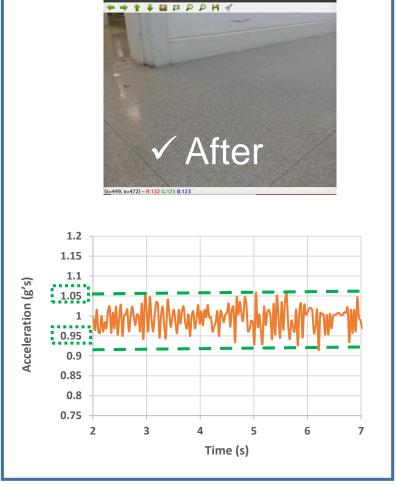
**Graphs** 





 $\frac{A_{after}}{A_{before}}$ :

 $-10dB \approx 0.316$ 

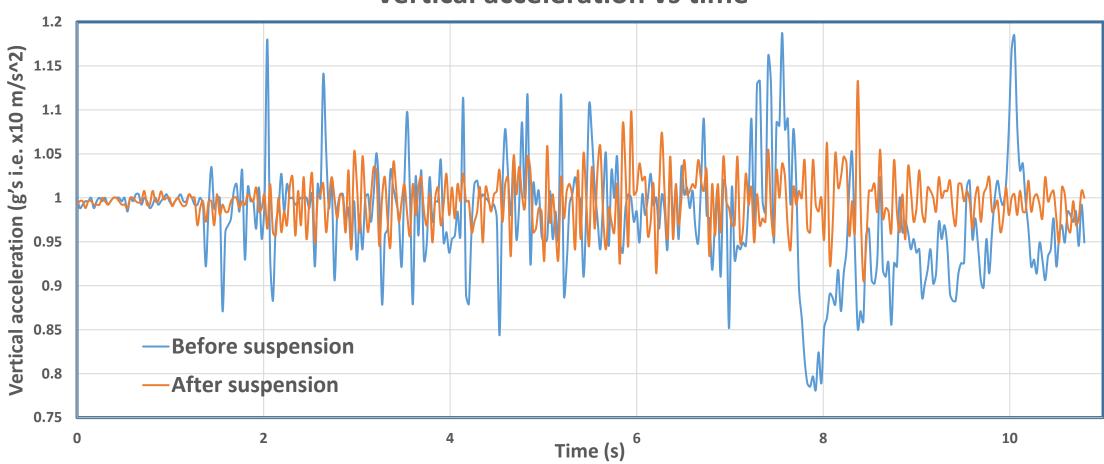








#### Vertical acceleration vs time







**Heat Transfer** 

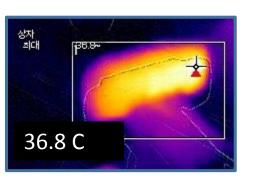
**IR Camera** 

Calculation

**Cost vs benefit** 



**Hot Spots** 



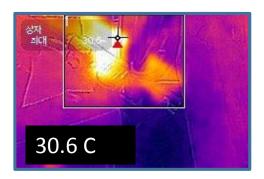
Camera



Converter



MyRio



**DYNAMIXEL Motor** 



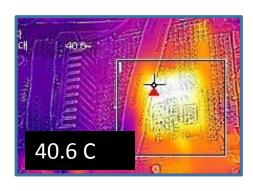


**Heat Transfer** 

**IR Camera** 

**Calculation** 

Cost vs benefit







Converter

**Aluminum fin** 

Fan

#### **Free Convection**

- h = 8.97
- Q= 0.323 W
- $T_S = 40.6 \, ^{\circ}\text{C}$

#### **Adiabatic case**

- Using thermal resistance
- q = M tan(mL)
- $T_S = 36.71 \, ^{\circ}\text{C}$

#### **Forced convection**

- Using thermal resistance
- h = 20.5  $^{W}/_{m^2.K}$
- $T_S = 31.8 \, ^{\circ}\text{C}$





**Heat Transfer** 

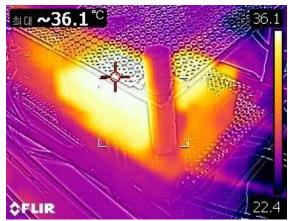
**IR Camera** 

Calculation

**Cost vs benefit** 

Theoretical calculation with fin gives  $T_s = 36.7 \, ^{\circ}\text{C}$ 





Experimental  $T_s$  = 36.1 °C

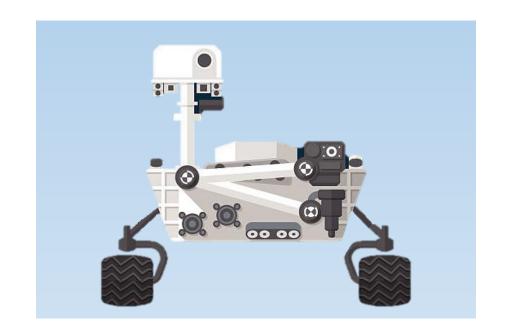
| 1.5mm |            |        |                 |
|-------|------------|--------|-----------------|
| 2.5mm | 7mm<br>3mm | 25.4mm | 25.4mm<br>>10mm |

|                       | Fin       | Comparison | Fan        |  |
|-----------------------|-----------|------------|------------|--|
| Cost                  | 2,000 KRW | X 7        | 15,000 KRW |  |
| <b>Battery Usage</b>  | 0         | X 2        | 2.16 W     |  |
| Cooling, $\Delta T_s$ | -3.9 ℃    | X 2        | -8.8 °C    |  |
| $T_s$                 | 36.7 °C   | 2 vs 7     | 31.8 °C    |  |

Hence, we decided to install only Fin







# Section – C

Conclusion

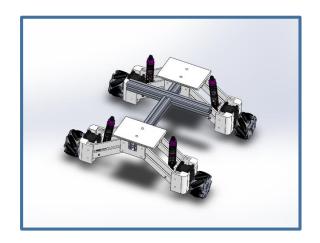
#### Conclusion

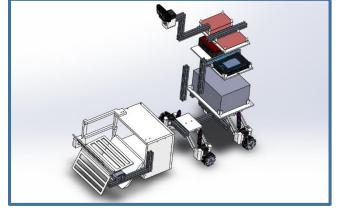


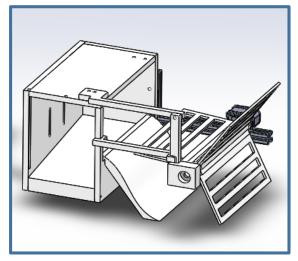




- ✓ Independent Suspension
- ✓ Modular vehicle
- ✓ Minimizing cost by heat analysis
- ✓ Simple Blade Type Gripper

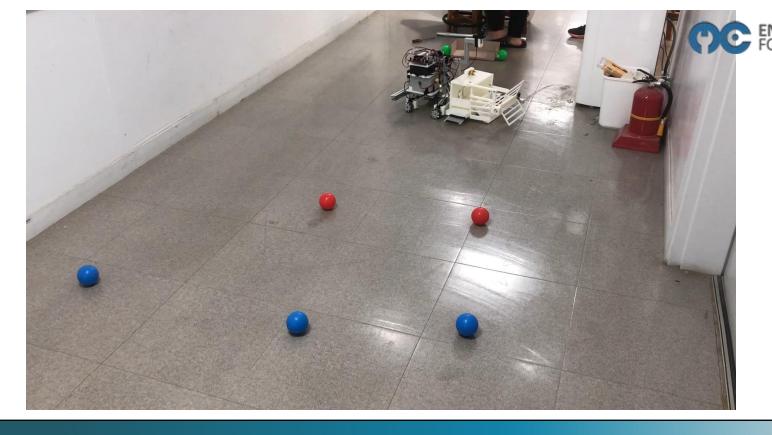










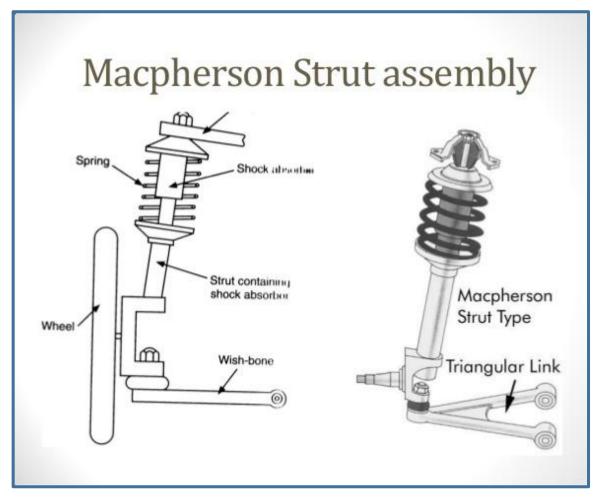


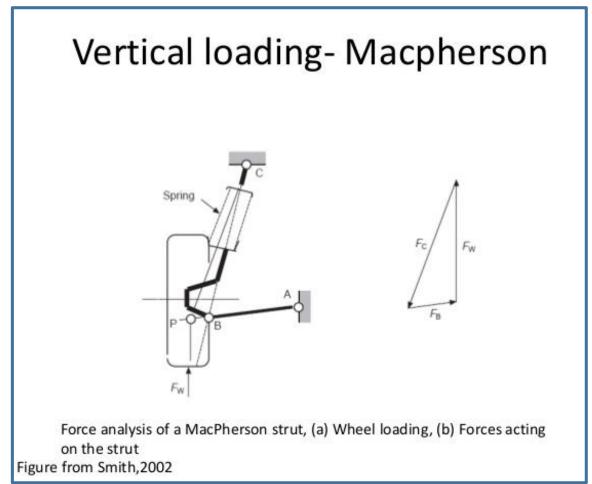
# Thanks for listening

Questions or comments are welcome









# Appendix





| r | _ | ω                     | _ | $\sqrt{2}$ |
|---|---|-----------------------|---|------------|
| , | _ | $\overline{\omega_n}$ | _ | ٧Z         |

$$\omega_n = \sqrt{\frac{k}{m}} < \sqrt{2}\omega$$

m = 6kg,  $\omega = 60rpm = 2\pi \ rad/s$ 

∴ k < 118.44 N/m

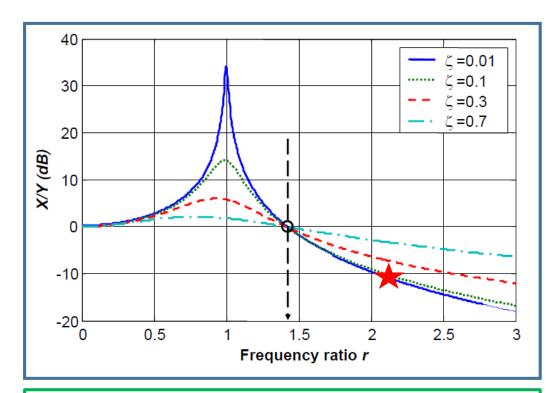
|                              |   |          |        | NAME : Suspension Spring . NO. : E : |        |                    |
|------------------------------|---|----------|--------|--------------------------------------|--------|--------------------|
| SPRING TYPE : Co             | mpression Coil Spring                             |          |        | <i>p</i> 2                           | •      |                    |
| MATERIAL :                   | : SUS316  |          |        |                                      |        |                    |
| Modulus of transv            | erse elasticity (G)                               | 7000     |        | Number of active coils (Ne)          | 23     |                    |
| Wire dian                    | neter (d)   | 0.8      | mm     | Free length(L)                       | 38     | mm                 |
| Center dian                  | neter (D <sub>m</sub> )                           | 14.2     | mm     | Displacement(I)                      | 20     | mm                 |
| Total number of              | active coils (Nt)                                 | 15       |        | Tensile stress(σ)                    | 53     | kg/mm <sup>2</sup> |
|                              | ·   |          |        |                                      |        |                    |
| External c                   | diameter  |          |        | Spring Pitch                         |        |                    |
| OD =                         | $d+D_m$   | 15.00    | mm     | $p = \frac{L}{N_e + 1}$              | 1.58   | mm                 |
| Internal d                   | liameter  |          |        | Maximum compression heigh            | t      |                    |
| ID = I                       | $D_m - d$   | 13.40    | mm     | $L_{min} = d \times N_t$             | 12.00  | mm                 |
| Torsion                      | stress  |          |        | Spring length                        |        |                    |
| $\tau = \sigma \times$       | ( 0.33  | 17.49    | kg/mm² | $ML = \pi \times D_m \times N_t$     | 669.16 | mm                 |
| Initial te                   | ension  |          |        |                                      |        |                    |
| $P_0 = \frac{1}{2}$          | $\frac{\pi \times d^3 \times \tau}{8 \times D_m}$ | 0.25     | kg     |                                      |        |                    |
| Loa                          | nd  |          |        |                                      |        |                    |
| P =                          | $l \times K$                                      | 1.3333   | kg     |                                      |        |                    |
| Spring co                    | onstant   |          |        |                                      |        |                    |
| $K = \frac{1}{8 \times (6)}$ | $\frac{G \times d^4}{2D - d)^3 \times N_e}$       | 53.33368 | N/m    |                                      |        |                    |

### Appendix: Vibration Analysis





#### Theory



$$\omega$$
 = 60 rpm -> K< 118.44 N/m necessary  $\Rightarrow$  Our K value :  $\frac{53.33 \text{ N/m}}{r}$  = 2.114

#### Theory:

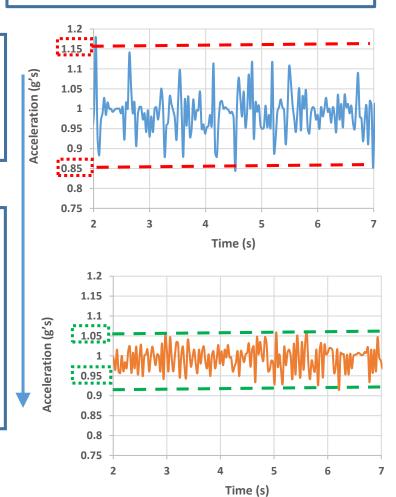
$$\frac{X_{after}}{X_{before}} = -10dB \approx 0.316$$

#### **Experiment:**

$$\frac{X_{after} \times \omega_n^2}{X_{before} \times \omega_n^2}$$

$$\frac{X_{after}}{X_{before}} = \frac{0.05}{0.15} \approx 0.33$$

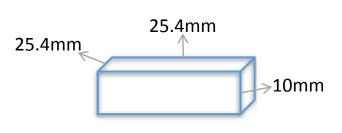
#### Experiment



### Appendix: Heat Transfer Analysis







#### Without fan or fin

$$T_{f} = \frac{T_{s} + T_{\infty}}{2}$$

$$Ra = G_{r}P_{r} = \frac{g\beta(T_{s} - T_{\infty})L^{3}}{v\alpha}$$

$$Nu = 0.54Ra^{\frac{1}{4}} = \frac{hL}{k}$$

$$Nu = 0.54Ra^{\frac{1}{4}} = \frac{hL}{k}$$

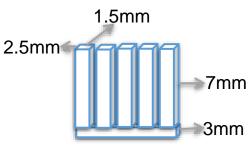
$$h_{side 1} = 33.20 \text{ W/}_{m^{2}.K}$$

$$h_{side 2} = 29.66 \text{ W/}_{m^{2}.K}$$

$$q = Mtanh(mL) = 0.323V$$

$$q = kA \frac{T_{s} - T_{b}}{t}$$

 $q = hA\Delta T = 0.323W$ 



#### With fin

$$Ra = G_r P_r = \frac{g\beta (T_S - T_\infty)L^3}{v\alpha} P_r$$

$$Nu = 0.54Ra^{\frac{1}{4}} = \frac{hL}{k}$$

∴ 
$$h_{side\ 1} = 33.20\ {}^{W}/m^{2}.K$$
  
∴  $h_{side\ 2} = 29.66\ {}^{W}/m^{2}.K$   
 $q = Mtanh(mL) = 0.323W$   
 $q = kA\frac{T_{s} - T_{b}}{t}$   
 $T_{b} = 36.7^{\circ}C$   
 $T_{s} = 36.71^{\circ}C$ 



#### With fan

$$r = 70mm$$
, flow rate =  $0.0108 \frac{m^3}{s}$ ,  $V = 0.7 \frac{m}{s}$   
 $Re_x = \frac{Vx}{r}$   
 $Nu = \frac{h_x x}{k} = 0.664 Re_x^{\frac{1}{2}} Pr^{\frac{1}{3}}$   
 $\therefore h_x = 20.5 \frac{w}{m^2}.K$   
 $q = hA\Delta T = 0.323W$   
 $T_s = 31.8^{\circ}C$ 

### Appendix: Free convection heat transfer (C) SMARING





