

Capstone Design I

권영석, 김동현, 김원빈, 김현준,
박태룡, 현규진, Abi, and Fahim

Professor: 한순홍 / TA: 한경석

Organization Chart

Prof. 한순흥



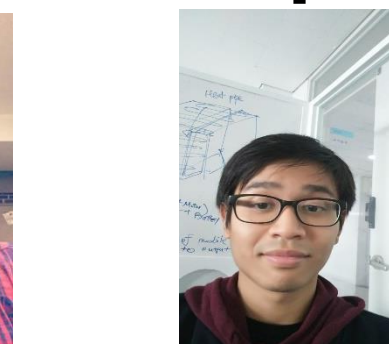
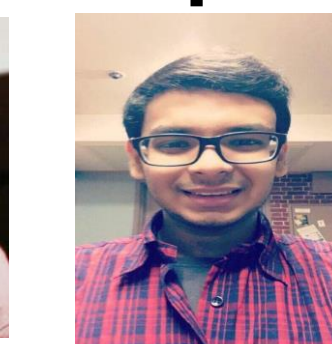
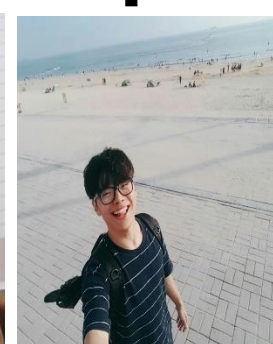
TA: 한경석

Solid Works

Lab View

Open CV

ROS



권영석
Leader

김동현

김원빈

박태룡

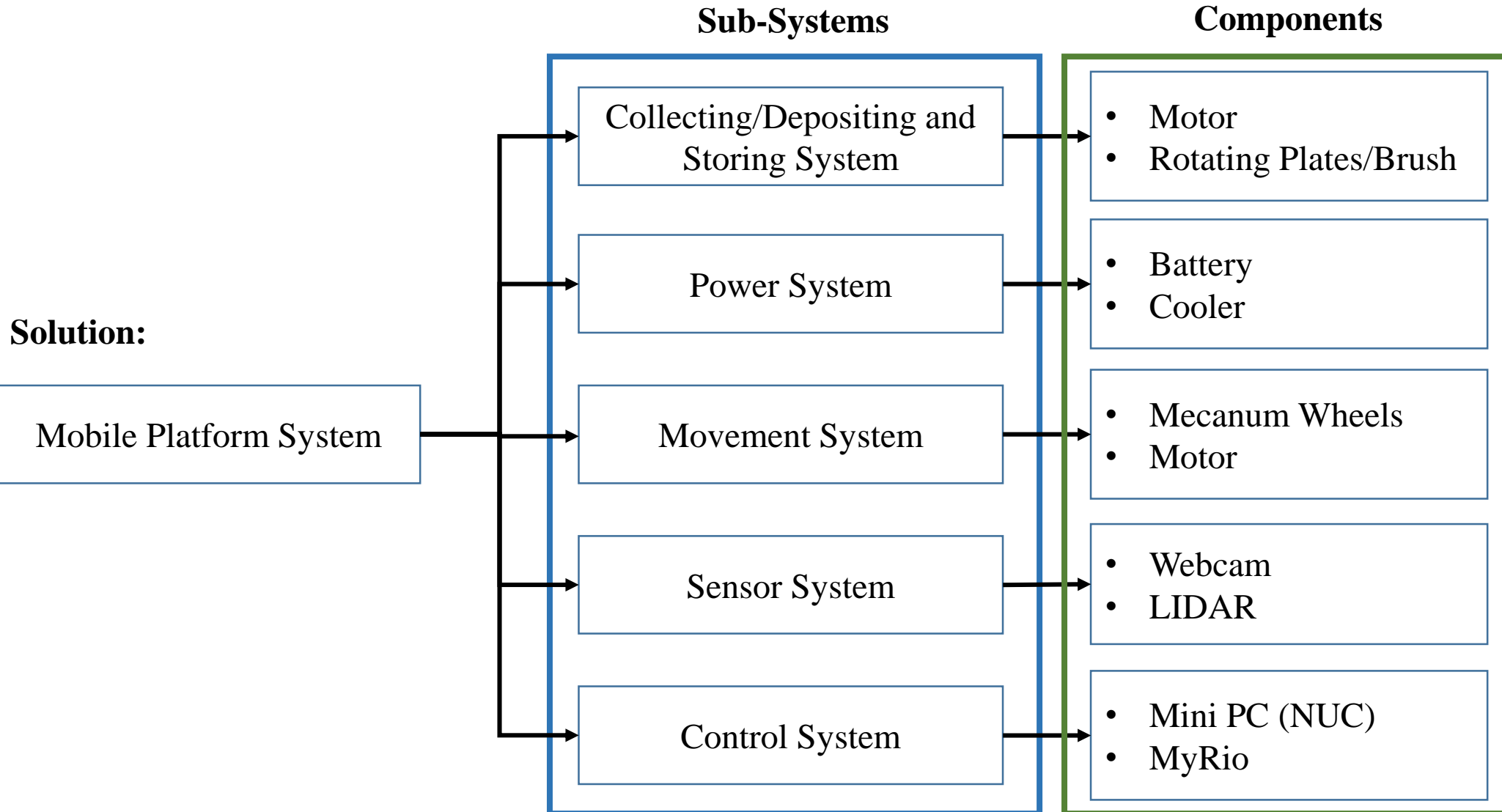
김현준

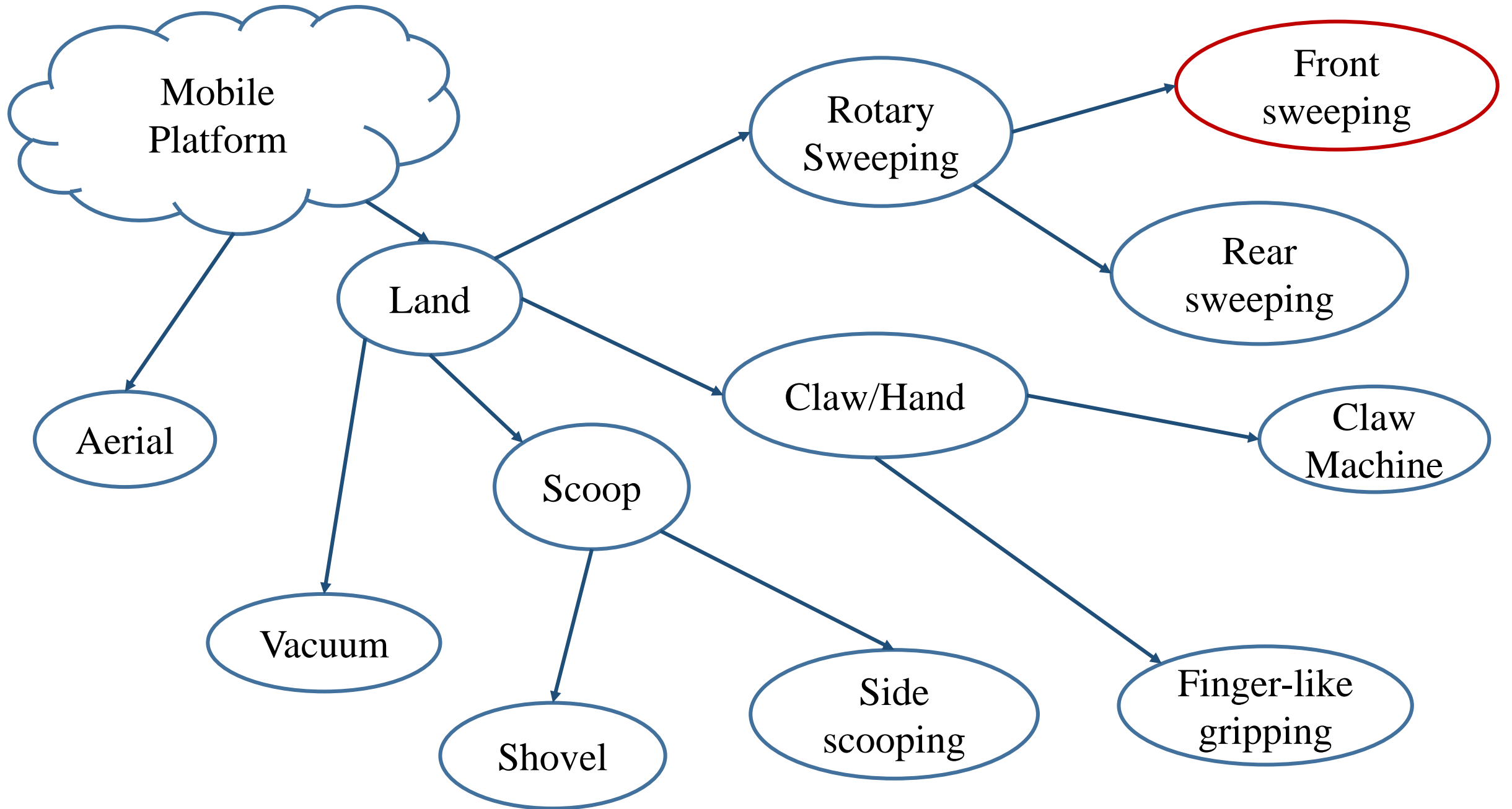
Fahim Masum

Abi Rahman
Syamil

현규진

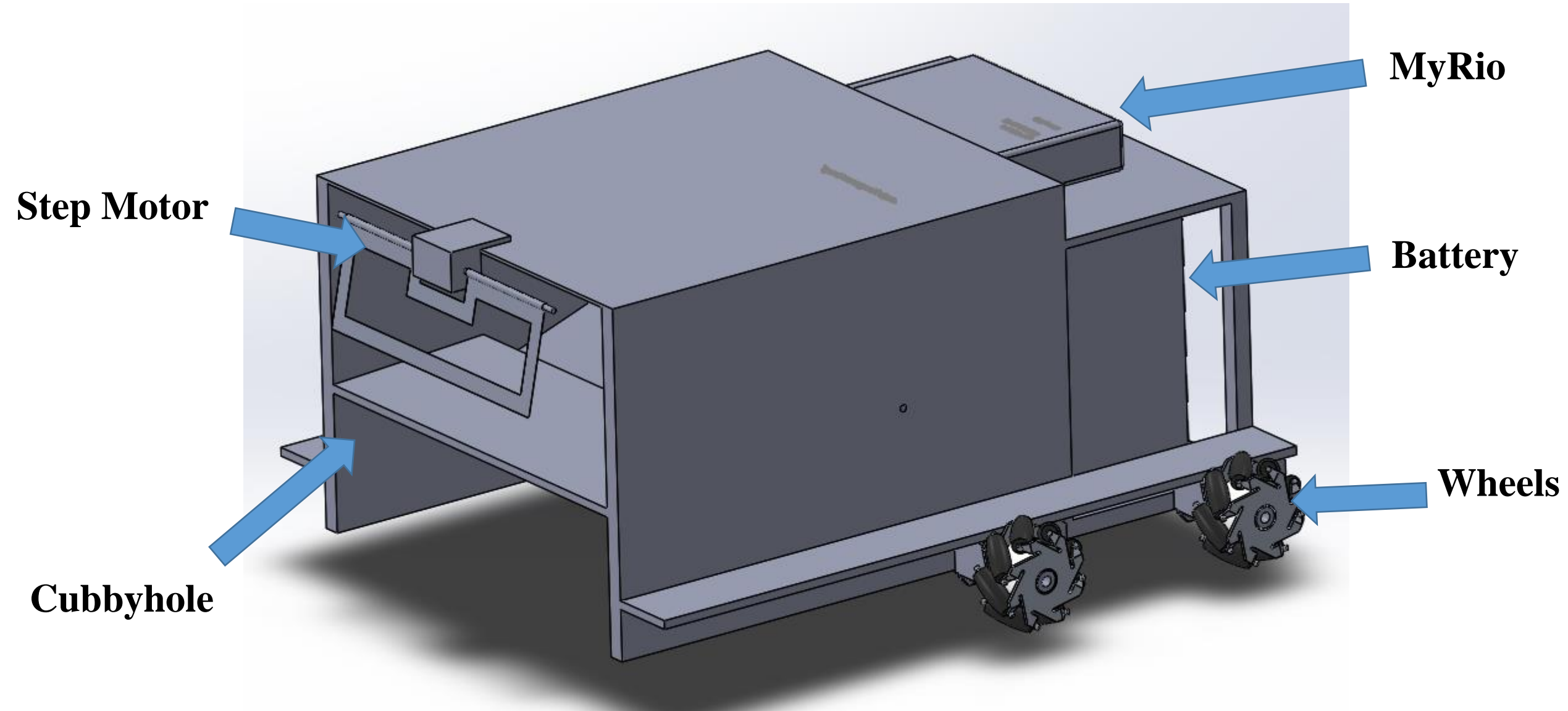
Design Goal : Find and collect the specific balls and transport them to the goal efficiently.





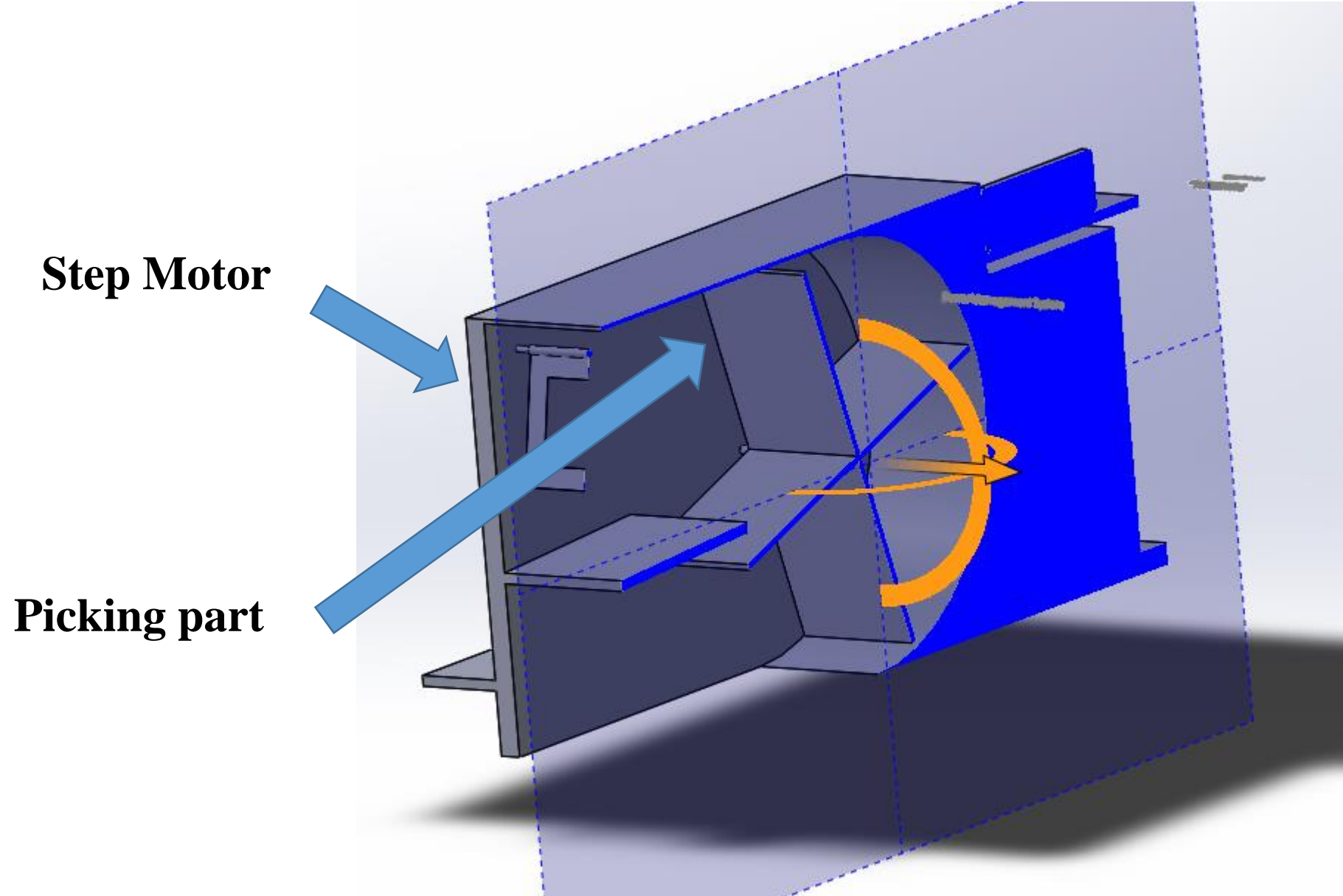
Overall View of Our Product!

<Alternative 1>



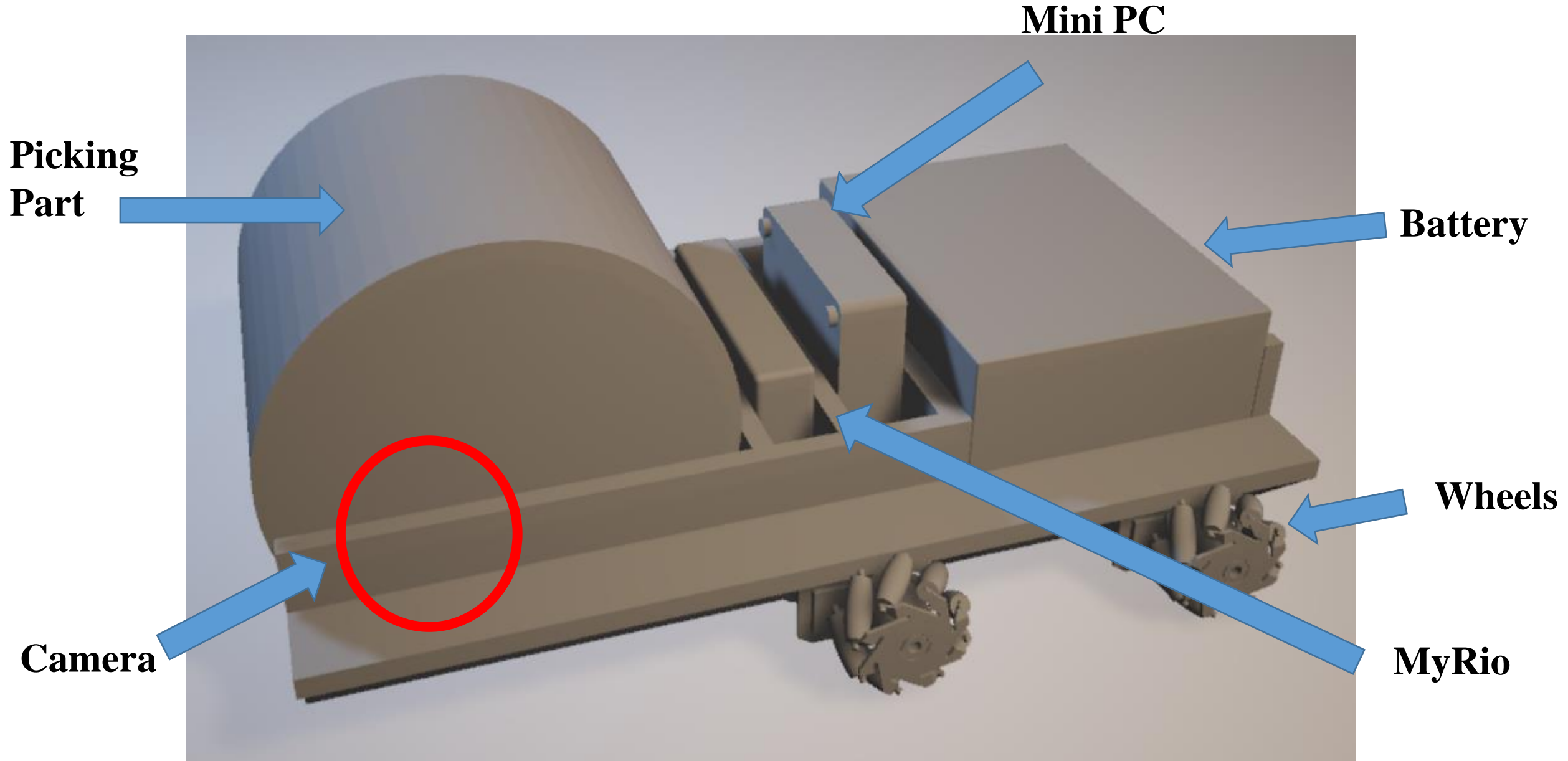
Overall View of Our Product!

<Alternative 1>

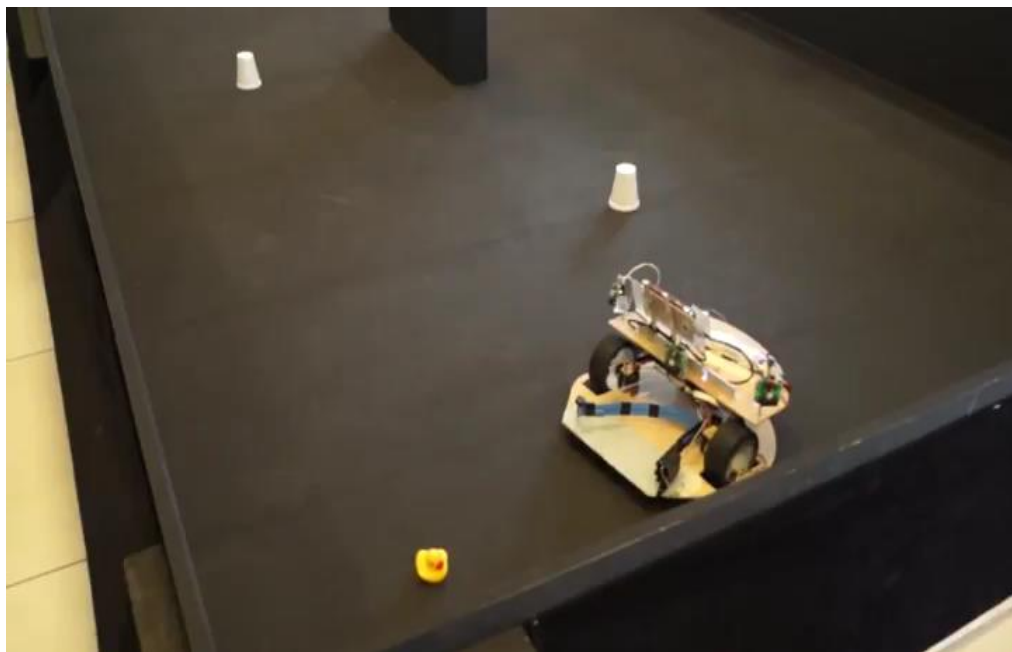


Overall View of Our Product!

<Alternative 2>



Pick up Method



<https://m.youtube.com/watch?v=Fx5uhWKudRw>



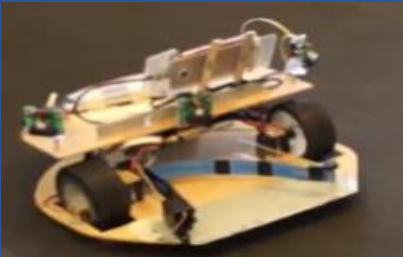


<https://m.youtube.com/watch?feature=youtu.be&v=glmBBZzWq40>

Decision Matrix for Collecting Systems

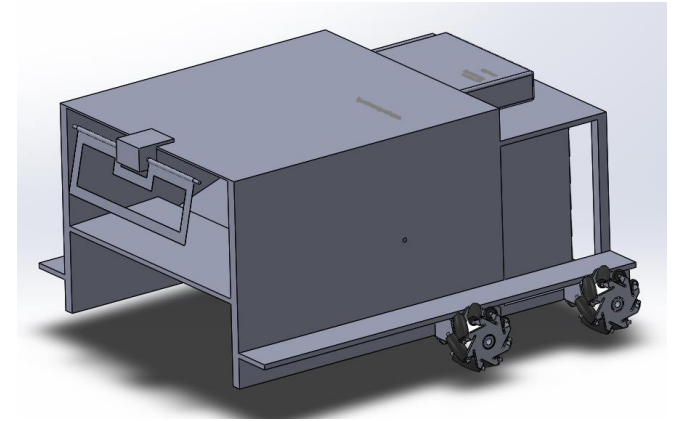
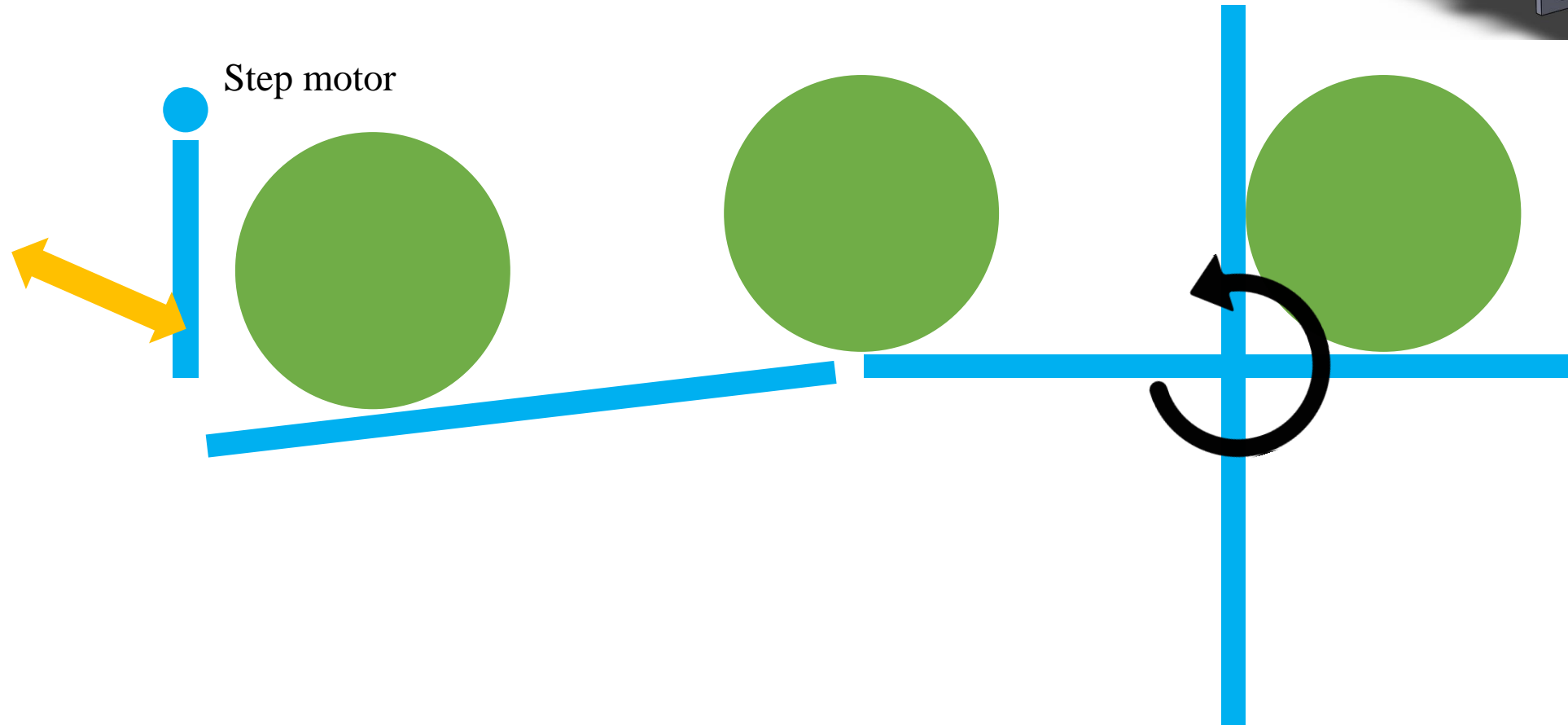
Best method for collecting and depositing		Front-Sweeping	Back-Sweeping	Claw-Scoop	Scoop	Sweep-and-Store	Snatch-Band
							
Weight	10	0.54	0.54	0.52	0.58	0.54	0.65
Creativity	5	0.40	0.56	0.35	0.40	0.65	0.70
Heating	30	0.58	0.58	0.50	0.65	0.58	0.58
Vibration	20	0.46	0.46	0.50	0.65	0.50	0.50
Speed	35	0.45	0.60	0.58	0.40	0.63	0.58
Satisfaction		49.75	55.80	52.25	54.30	58.10	57.70

Pro-Con for Collecting Systems

	Pro	Con
	<p>Fast pick-up. Easy Camera and Lidar placement.</p>	<p>Unsure depositing method. Component configuration relatively harder.</p>
	<p>Simple mechanically. Relatively fast (less motors). Main components easy to build. Pretty unique.</p>	<p>Camera and Lidar placement is challenging. Small margin of error in pick-up.</p>
	<p>Very unique. Mechanically simply structure and pick-up.</p>	<p>Unsure material selection. Storing is difficult. No ideas about depositing.</p>

Pick Up Method

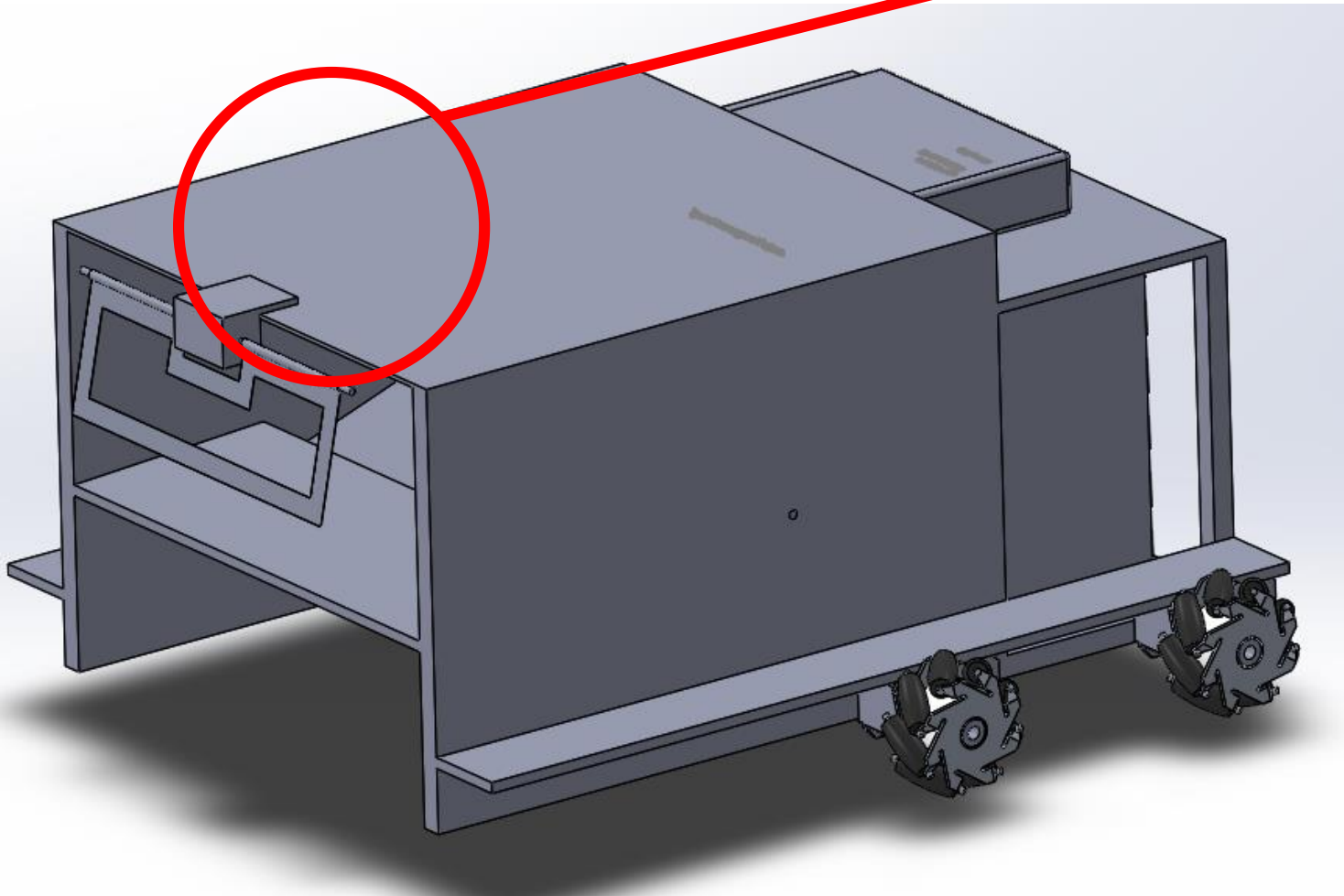
- Alternative 1



Pick Up Method

- Alternative 1

Camera and Lidar will be mounted here

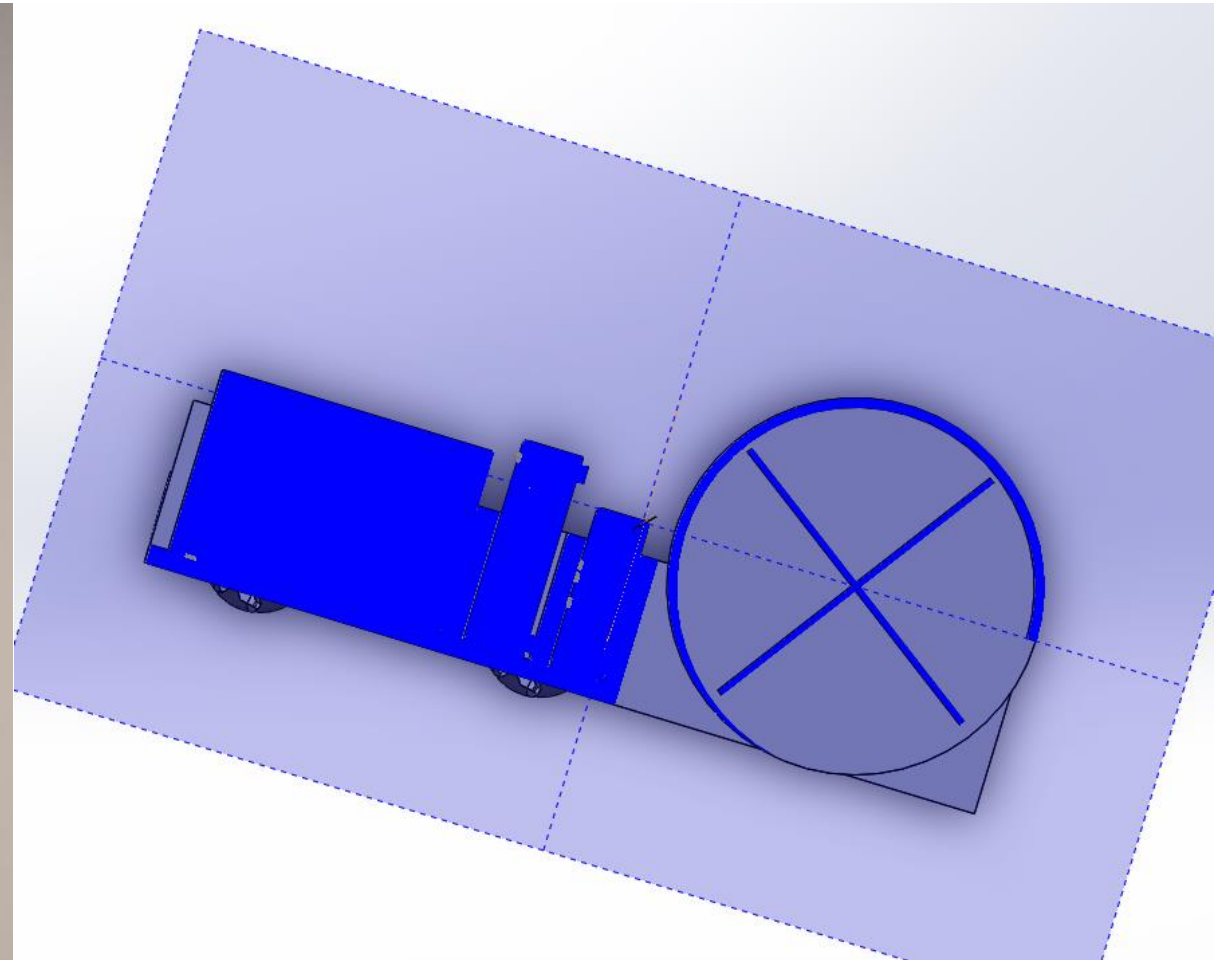
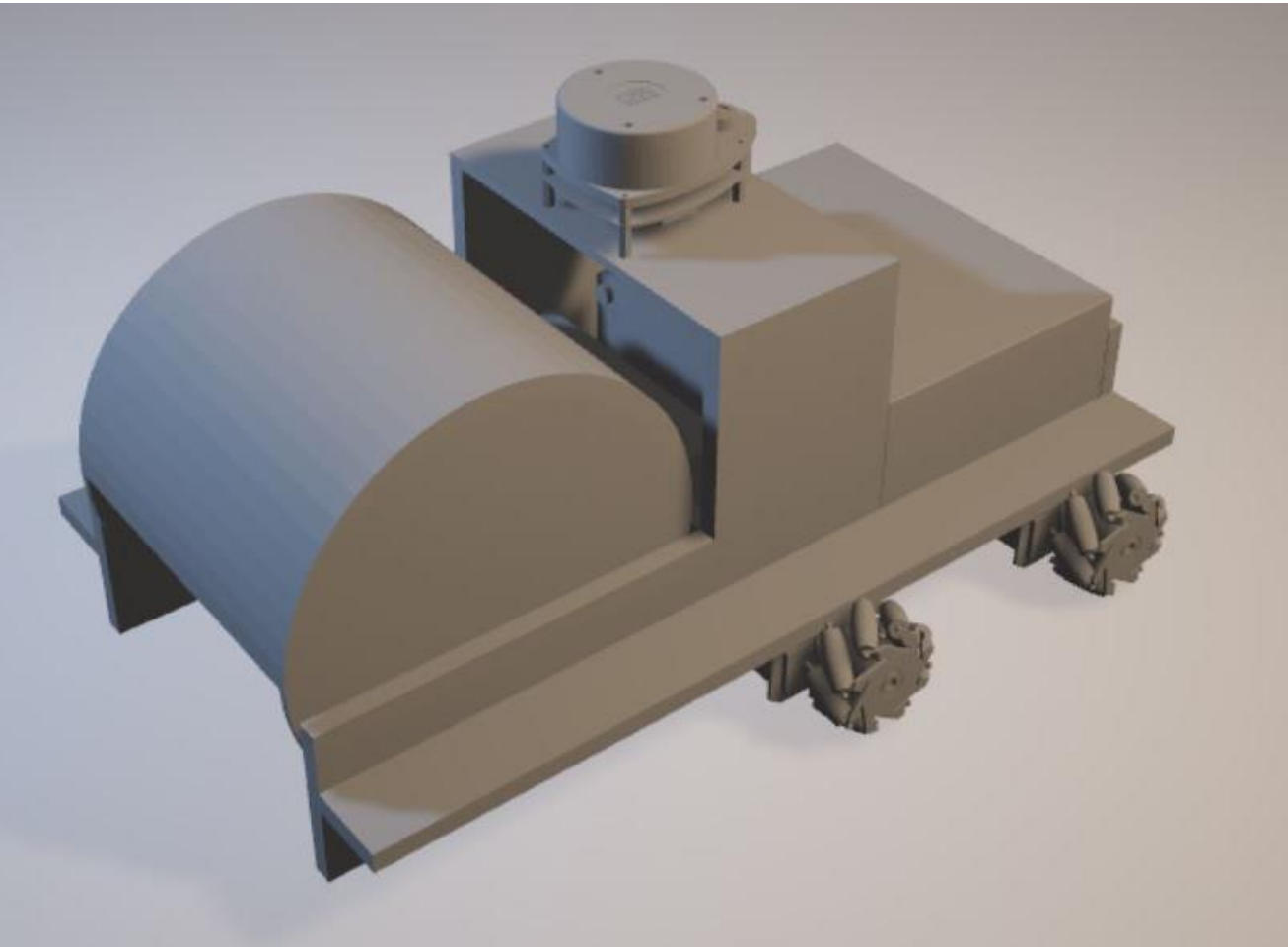


Possible Problems

- Bulky and high
- PMS and MyRio might be hot

Pick Up Method

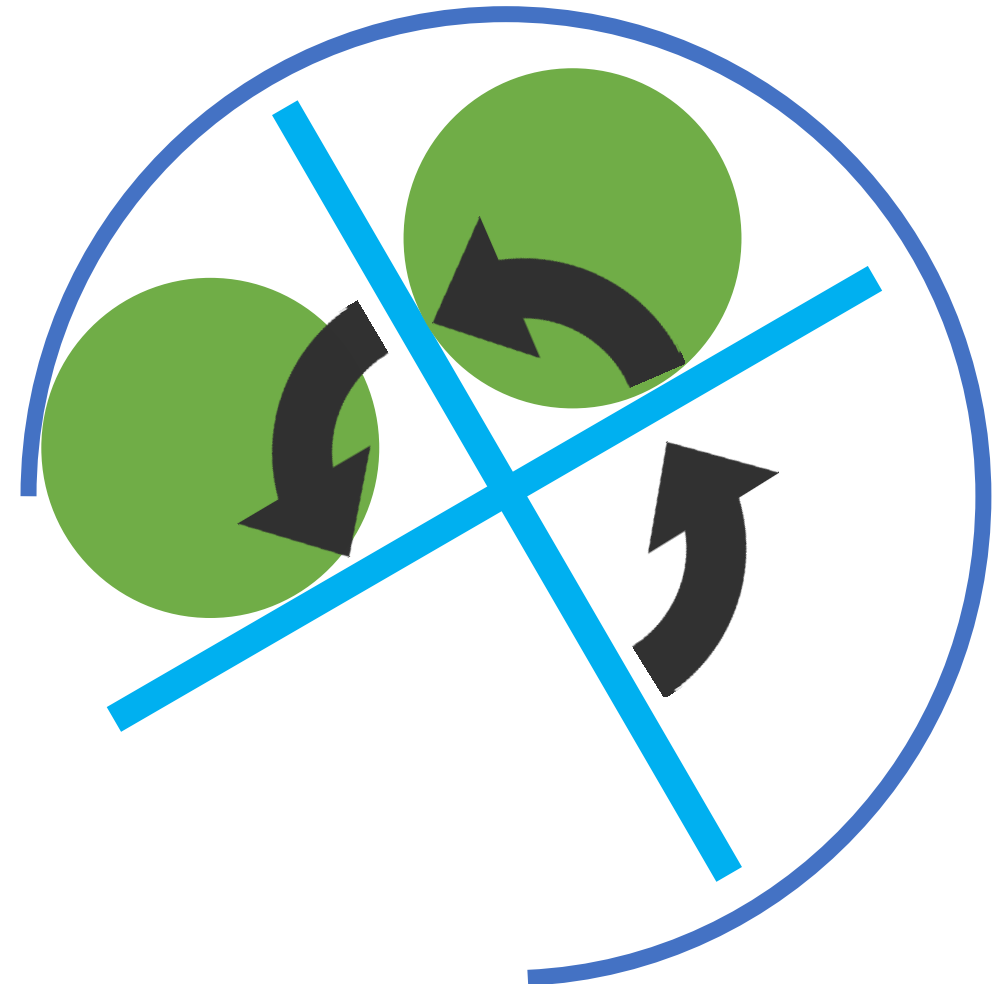
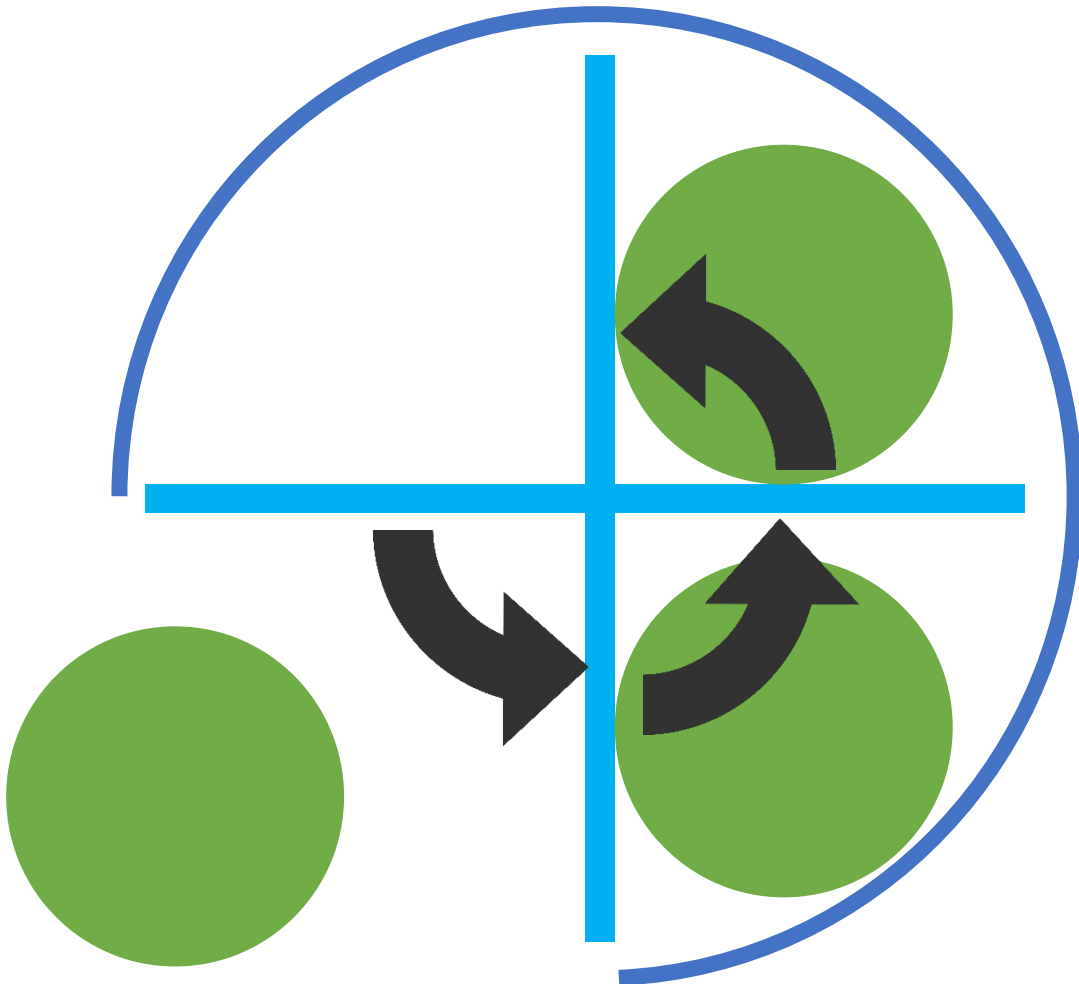
- Alternative 2: Our Leading Concept!



Pick Up Method

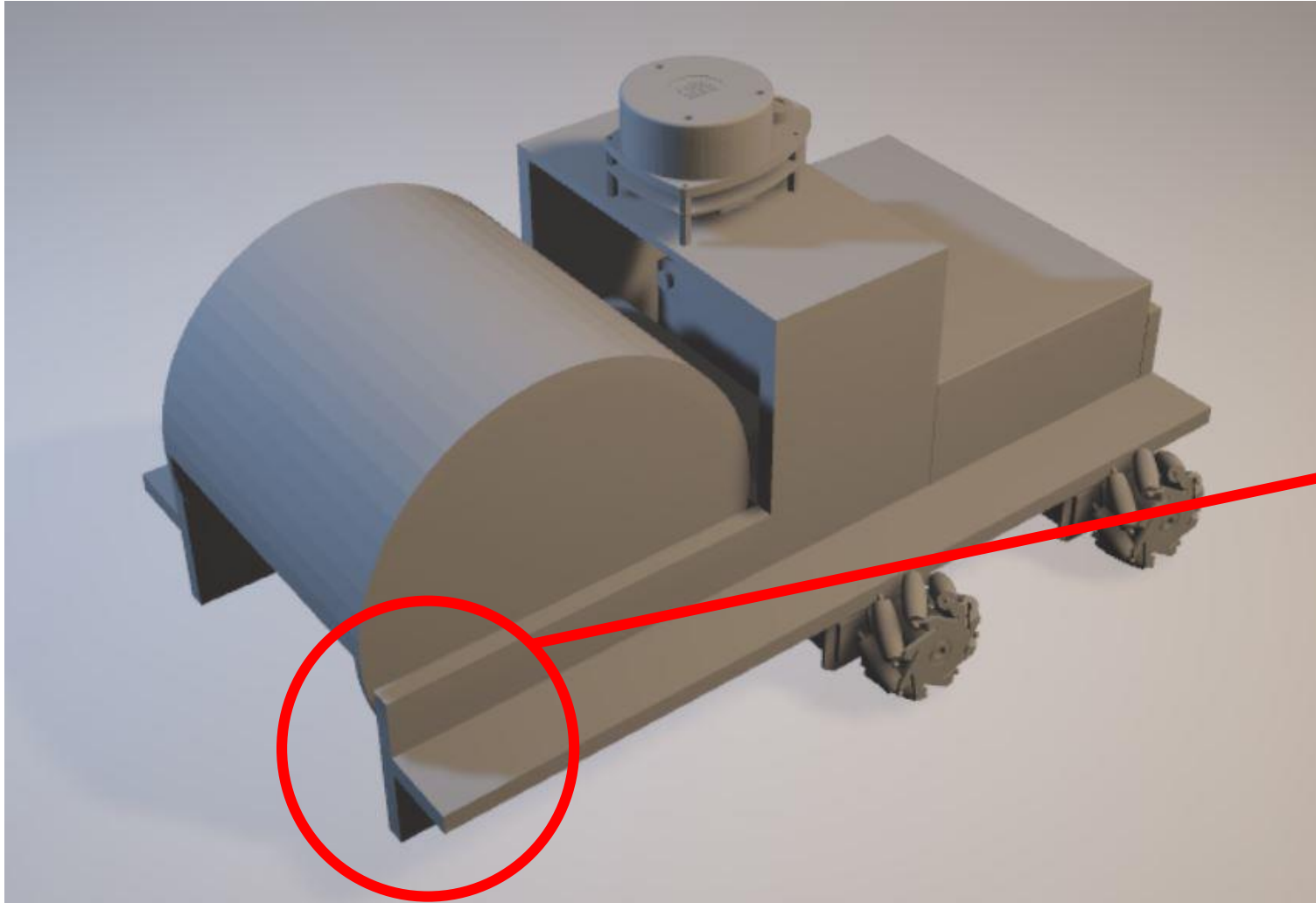
- Concept 2

Only one method to collect, store & dispose of waste in the balls



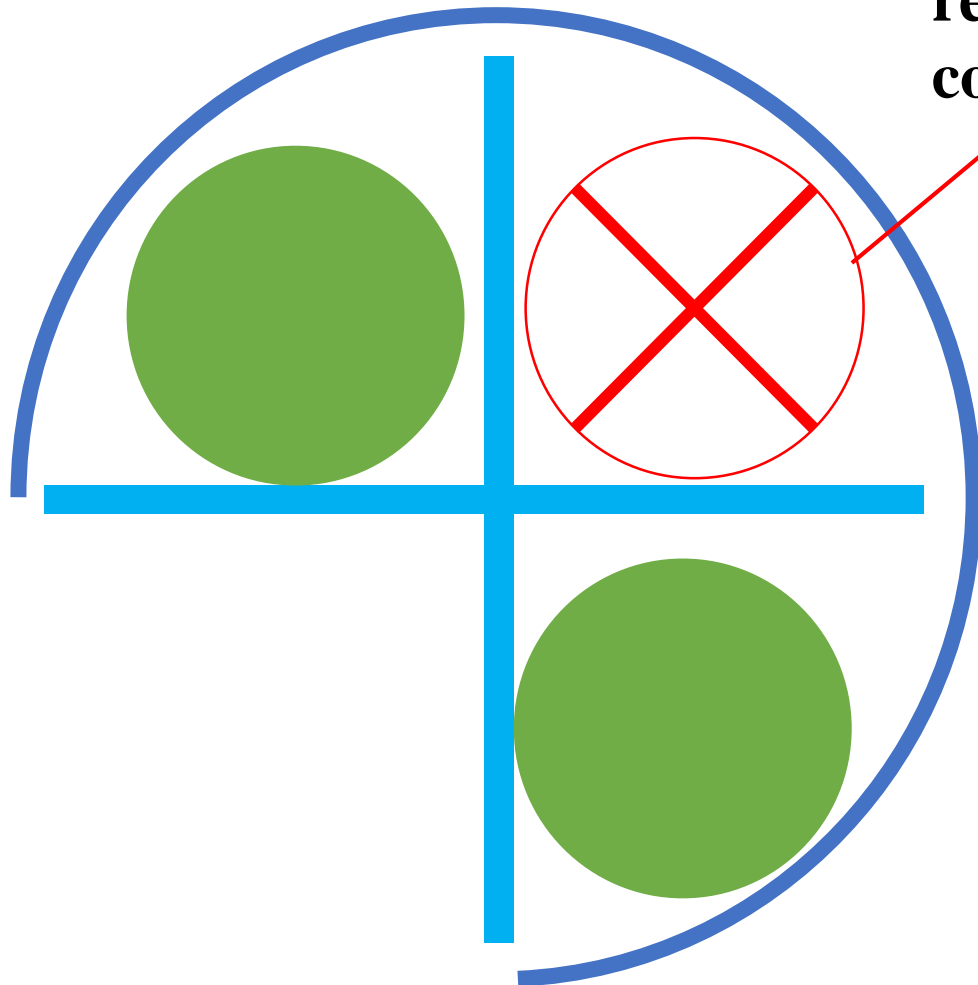
Pick Up Method

- Alternative 2



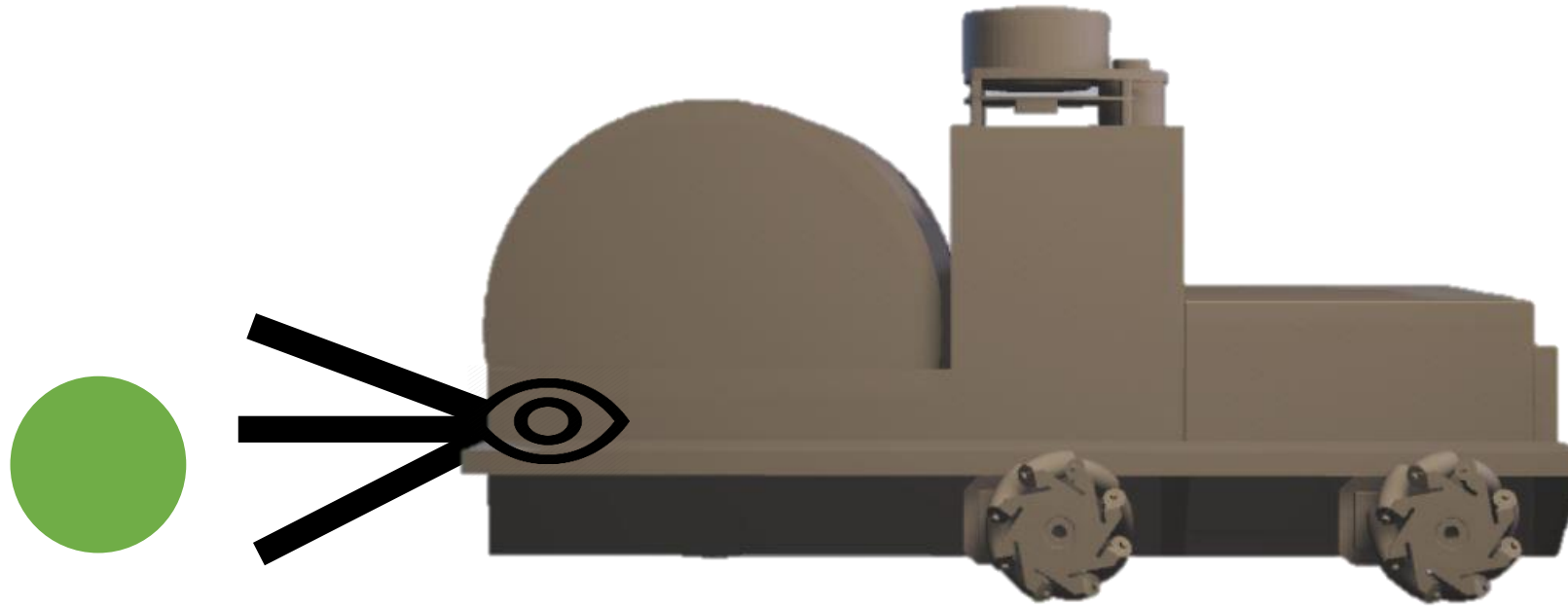
Camera will be mounted here

Possible problem 1



**The case when mobile platform
recognized 3 balls but it is failed to
collect the second ball**

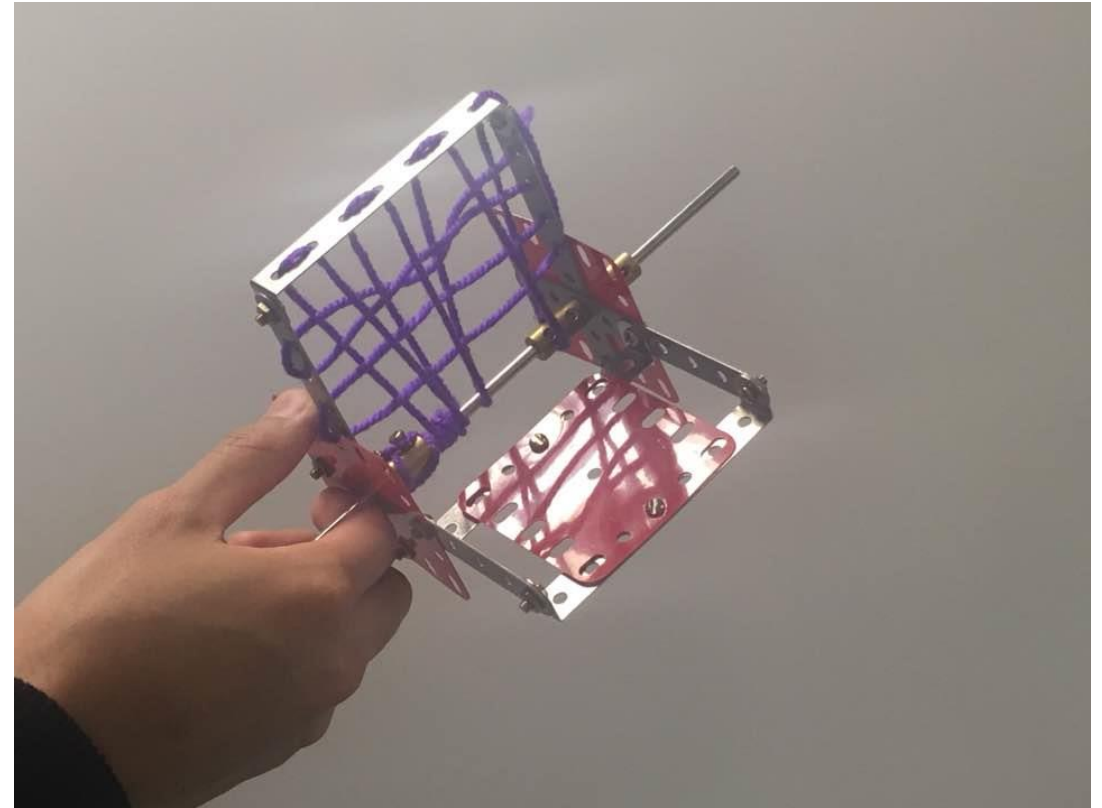
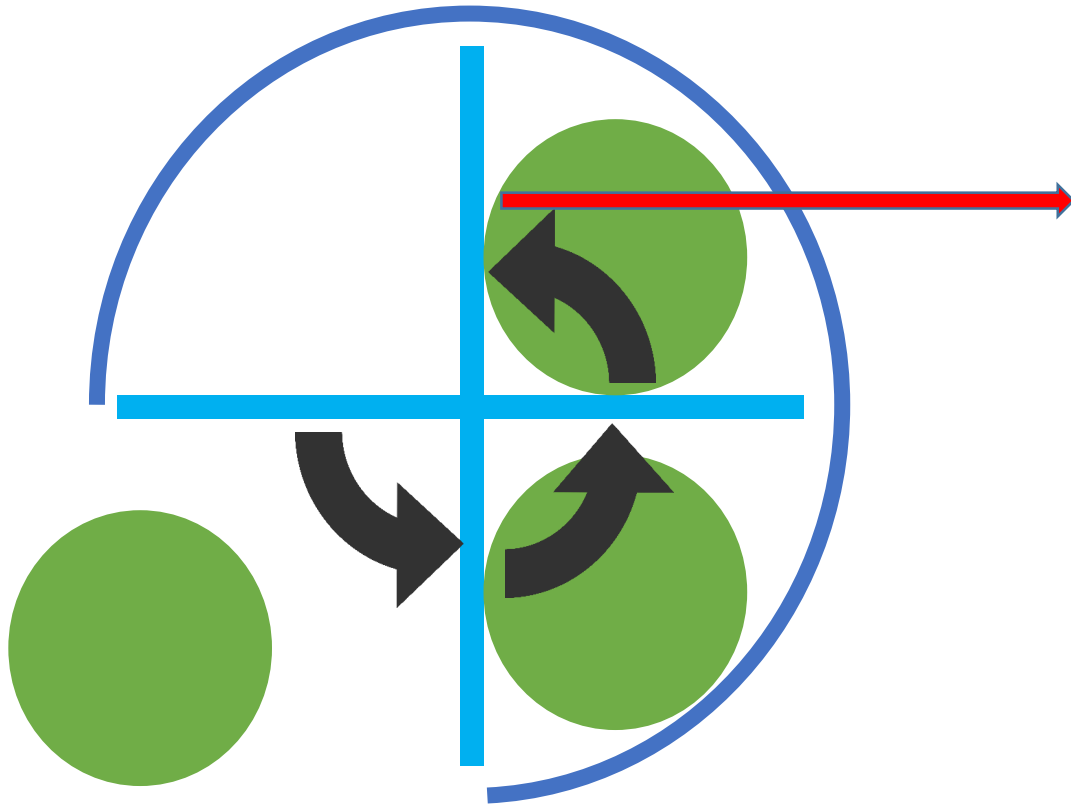
Solution 1



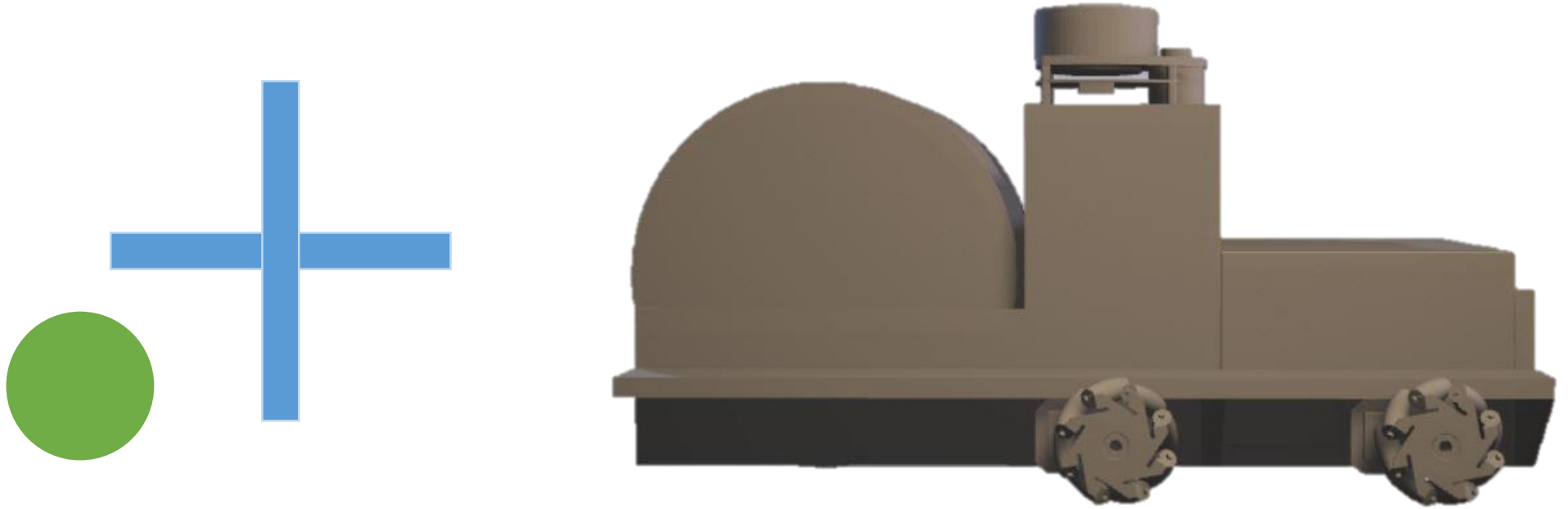
Once the robot pick a ball, then Go back little And Double check !!

Solution 2

Design picker to grab the ball easily

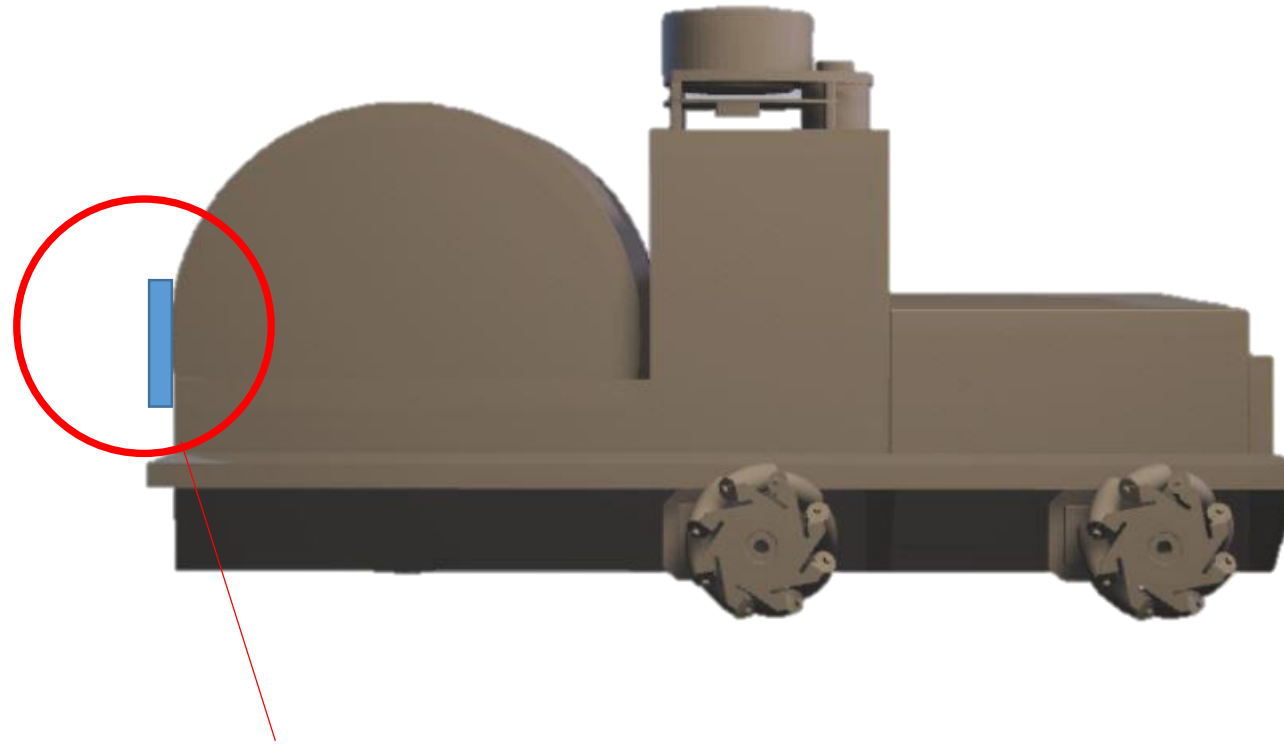


Possible problem 2



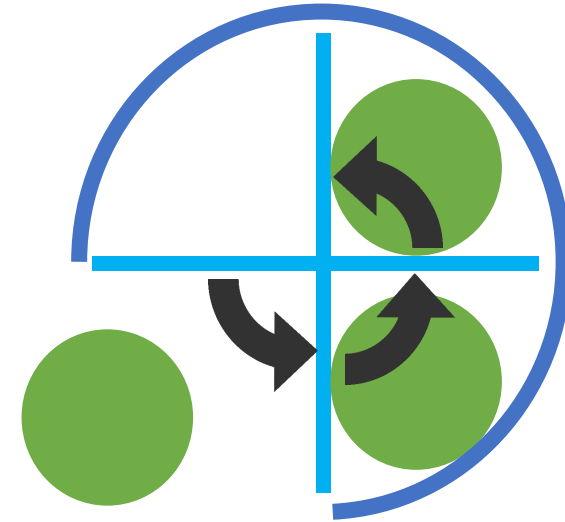
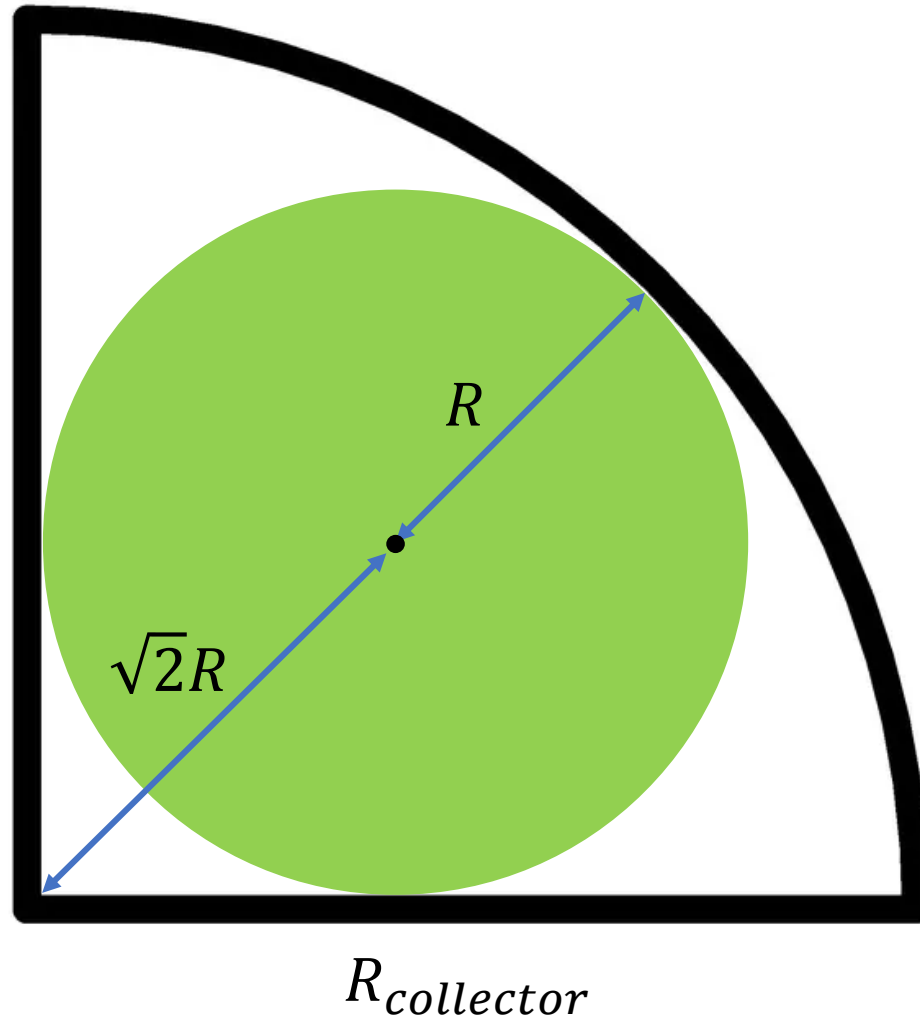
Ball can escape away from vision range

Solution 2



Attach a sensor such as laser which can check mobile platform collect the ball

Analysis – Collector size



$$(1 + \sqrt{2})R \leq R_{collector}$$

$$R \approx 4(cm)$$

$$10(cm) \leq R_{collector}$$

Cooling mechanism

Cooling mechanism

1. Water&Oil cooling

- There must be no leaking or Condensation
→ We should consider sealing
- Weight of fluid → require extra power → inefficient!
(water cooling also need pump!!)

Cooling mechanism



→ By water cooling, We may absorb heat from only partial surface of battery



→ By oil cooling, we can make battery to sink into the oil, but, we have to deal with Capillary phenomenon in the wire.

Cooling mechanism

2. Convection by using fin&fan

- Maximize Convection surface by using fin

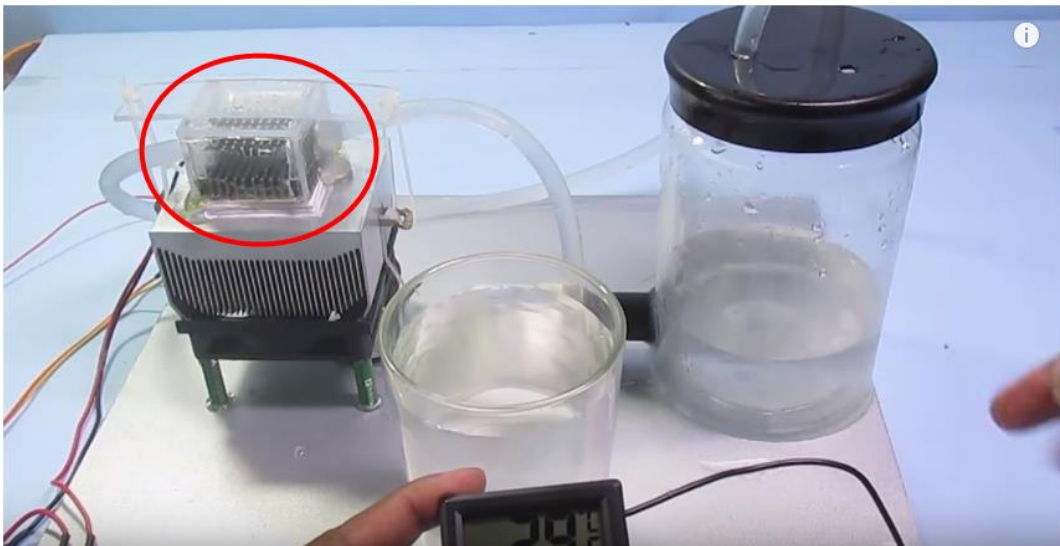
3. Peltier

- It will consume quite much power.
- We need to install extra heat sink → weight&volume increase

Cooling mechanism



→ we may use both ice pack & fan



→ We need mediation source for heat exchange between peltier and battery
(combine water cooling & peltier)

Pro-Con Analysis for Cooling System

	Pros	Cons
Air cooling with fans	Easy to facilitate. Fans widely available.	2x – 3x more energy consumed than other methods. Low effectiveness. Best with other methods.
Fins	Easy and cheap to manufacture.	Add a lot of extra weight to system. Low effectiveness.
Liquid cooling	Very low temperature rise.	Both direct and indirect liquid cooling methods require expert installation. Lack of flexibility in design. Expensive. Possible leakage.
Peltier Effect	Low temperature rise. Not much added weight.	Sensitive electronic parts. Not many sources to study battery applications.
Ice Pack	Easy to obtain ice. Intermediate effectiveness.	Undecided facilitation. Condensation. Replacing ice regularly.

Software

LabView

- Connecting MyRio & Computer with wireless way(Complete)
- Draw the graph using the accelerometer value , ON-OFF switch for LED(Complete)
- Study and Coding Labview with MyRIO
- Motor control

ROS

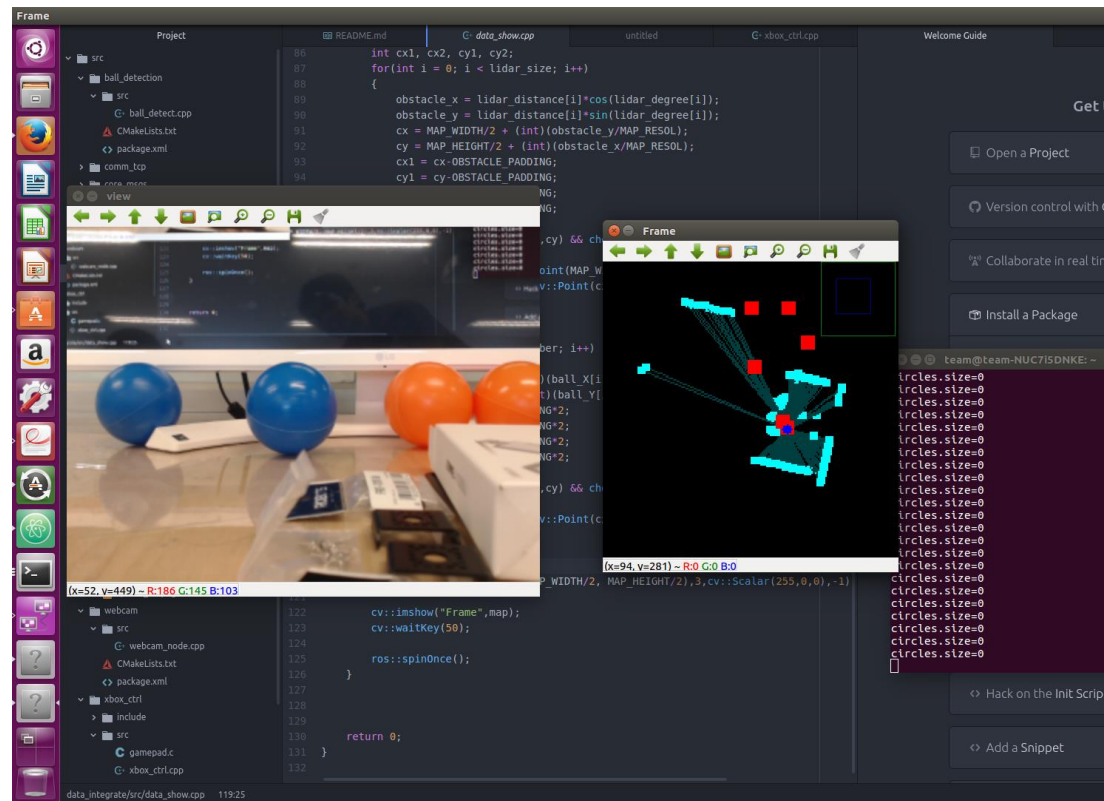
- Learning how to use publisher & subscriber nodes(complete)
- Service & Client with topic communication
- Study Ros launcher

- Master / Slave device with NUC
- Xbox controller connection

```
team@team-NUC7I5DNKE: ~  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.00  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000  
0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000  
0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000  
0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000  
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0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
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0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
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0.008349 -0.000985 -3.024179 0.008407 0.000000 0.000000 0.000000 0.000000 0.000  
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000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000
```

```
team@team-NUC7I5DNKE: ~  
0) L:(-0.993,-0.117 :: -3.024,+0.008) R:(+0.000, +0.000 :: +0.000,+0.000) LT:+0.  
000 RT:+0.000 U:0 D:0 L:0 R:0 A:0 B:0 X:0 Y:0 Bk:0 St:0 LB:0 RB:0 LS:0 RS:0  
  
(q)uit (r)umble  
[1752440942] button triggered: B  
[1752440942] button released: B  
[1752440942] stick direction: 0 -> 3  
[1752440942] stick direction: 0 -> 2  
[1752440942] stick direction: 0 -> 3  
[1752440942] stick direction: 0 -> 2  
[1752440942] stick direction: 0 -> 3  
[1752440942] stick direction: 1 -> 4  
[1752440942] stick direction: 1 -> 2  
[1752440942] stick direction: 1 -> 0  
[1752440942] button triggered: B  
[1752440942] button released: B  
  
[1752440942] button released: A
```

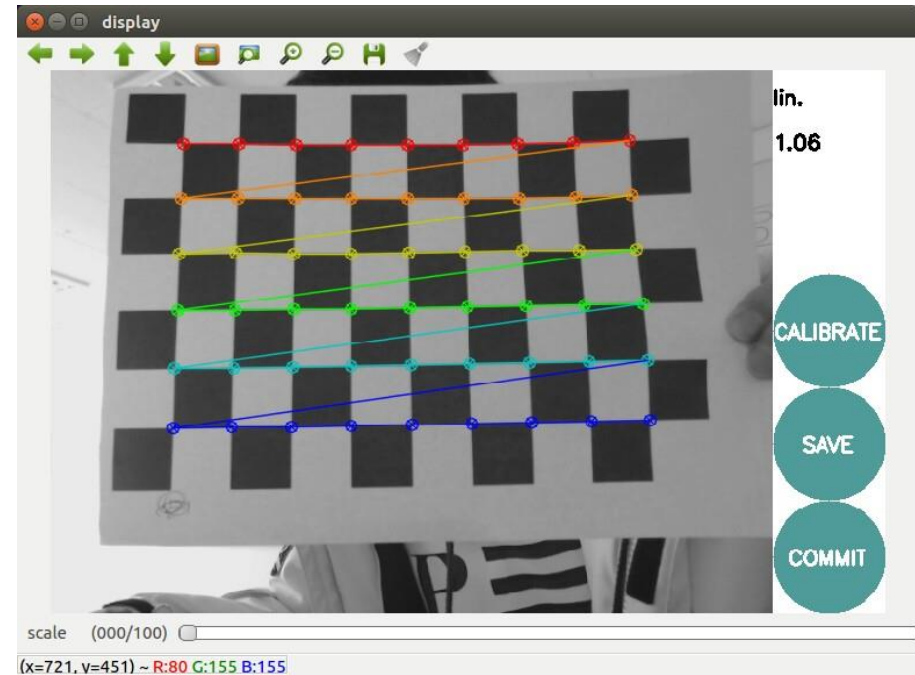

- Lidar and Webcam detection



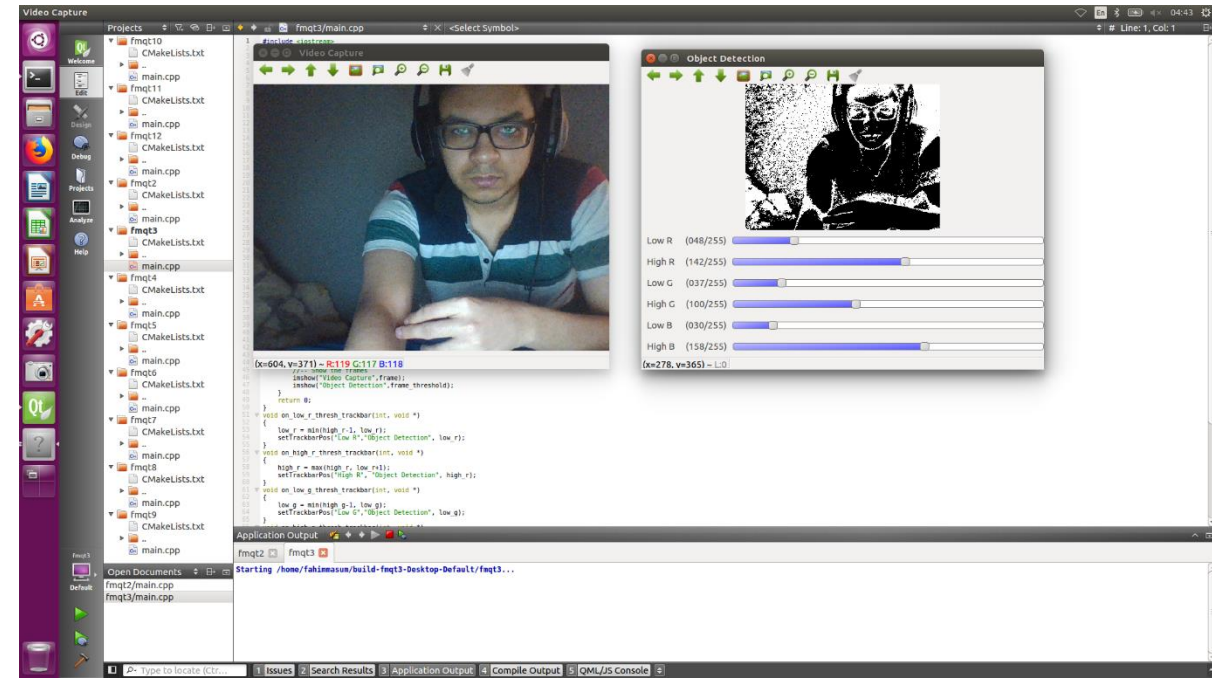
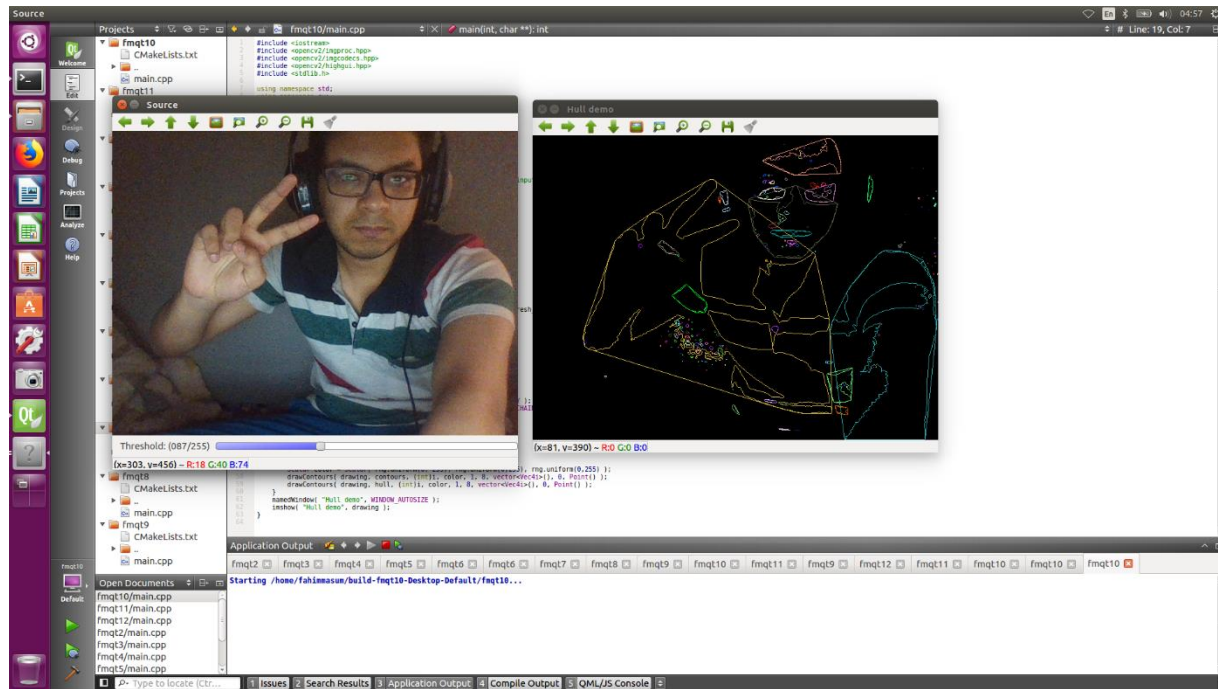
OpenCV

- Installing Ubuntu, OpenCV, and QtCreator.
- Learning basic functionality of Ubuntu and basics of C++.
- Working with webcam.
- Simple programs with QtCreator.

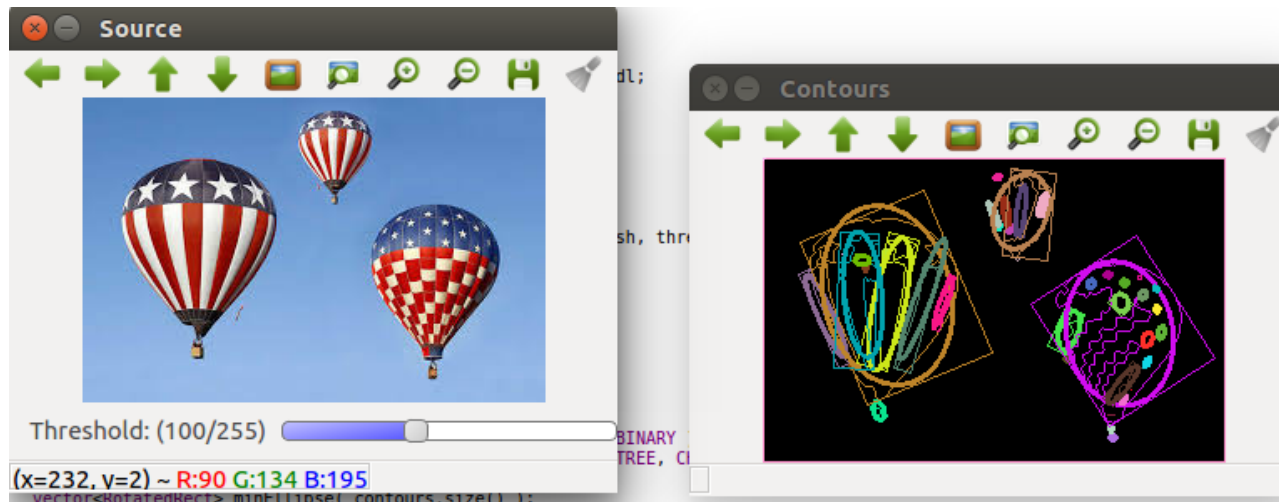
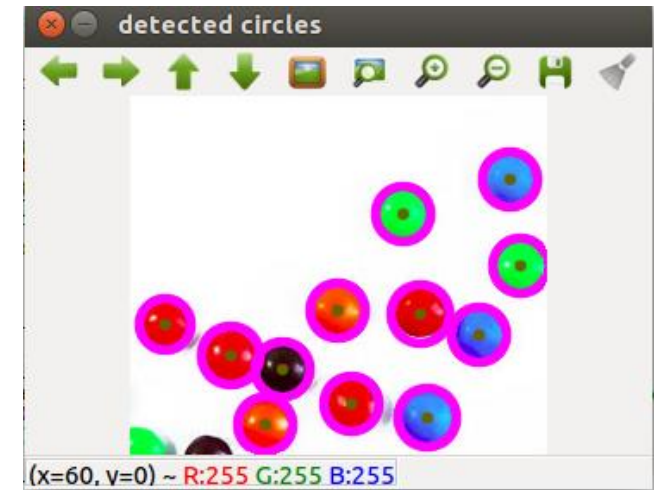
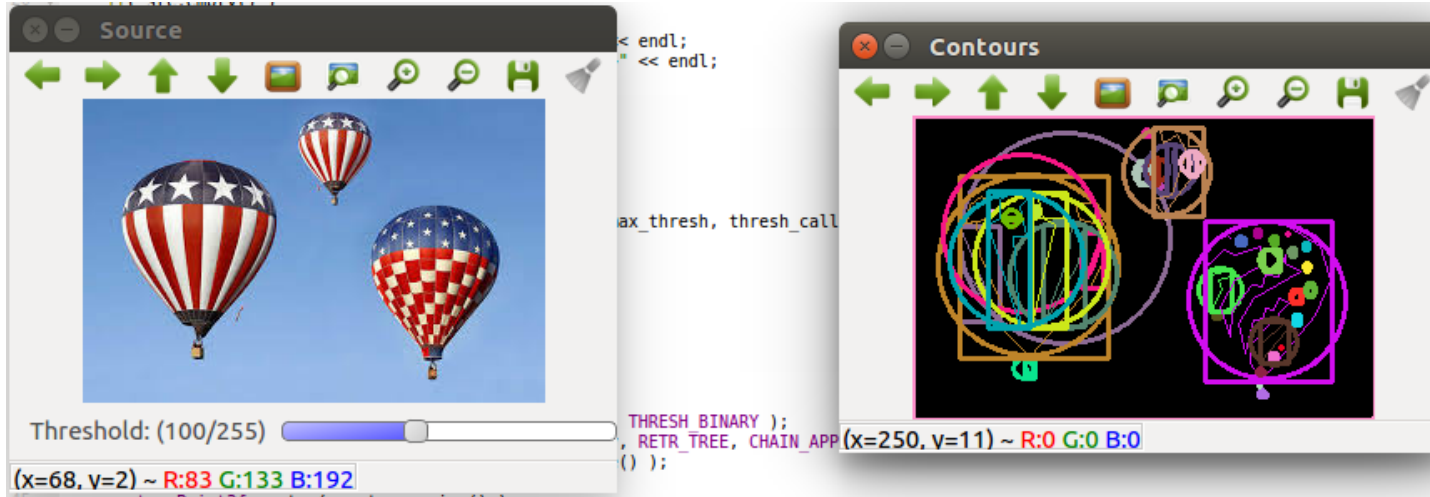
- Camera Calibration
- ROS Installation
- Camera distortion parameter



QT



QT



Future plan

- Determine the heat transfer method depending on required power, analytic value and the battery size
- After testing mecanum wheel, design suspension system
- Determine the center of mass depending on materials and configuration

Advice

- FBD for picking method
- Lidar configuration

Decision Matrix for Cooling Systems

Issue: Best method for collecting and depositing		Convection with fins	Air cooling with fan	Liquids (oil, water, etc.)	Ice pack	Peltier
Ease	5					
Cost	5					
Weight	20					
Danger	20					
Heat loss	50					



Reference

- **Chen, D., Jiang, J., Kim, G., Yang, C. and Pesaran, A. (2016). Comparison of different cooling methods for lithium ion battery cells. *Applied Thermal Engineering*, 94, pp.846-854.**
- <https://www.youtube.com/watch?v=bUSAqrHyCuA>
- <https://www.youtube.com/watch?v=WFVI4E6CT3E>
- https://www.youtube.com/watch?v=EpoNRTU_Uik
- <https://www.youtube.com/watch?v=zJWWpokFoQM>
- <https://youtu.be/glmBBZzWq40>
- <https://www.youtube.com/watch?v=EEbdo2WdTOI>
- <https://www.youtube.com/watch?v=hQ-bpfdWQh8>
- <https://www.youtube.com/watch?v=fns19y9NOpM>
- https://www.youtube.com/watch?v=Ne09Y72zW_Y
- <https://www.youtube.com/watch?v=D99a2a2Rhqc>
- <http://www.joshvillbrandt.com/tag/mecanumbot/>