



STEVENS
INSTITUTE of TECHNOLOGY
THE INNOVATION UNIVERSITY®

CS 492: Operating Systems

Deadlocks

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Deadlocks



Goals for Today

- Deadlock
 - Concepts
 - How to deal with deadlocks?
 - Ignoring them: ostrich algorithm
 - Detection & recovery
 - Prevention
 - Avoidance

Resources

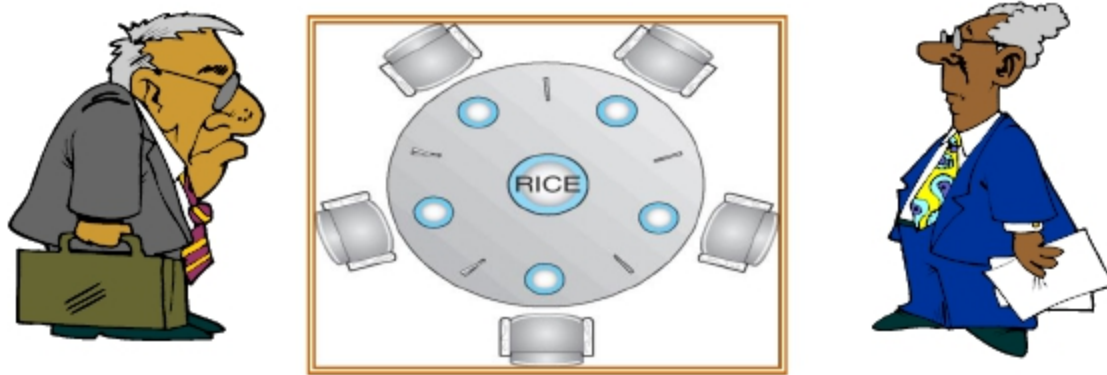
- Resource: objects granted to the processes
- Two types of resources
 - Preemptable resources
 - can be taken away from a process with no ill effects (e.g., memory)
 - Nonpreemptable resources
 - will cause the process to fail if taken away (e.g. printer)

Deadlocks

The cause of deadlocks: Each process needing what another process has. This results from sharing resources such as memory, devices, links.

- Example
 - System has 2 disk drives.
 - P_1 and P_2 each holds one disk drive and each needs another one.

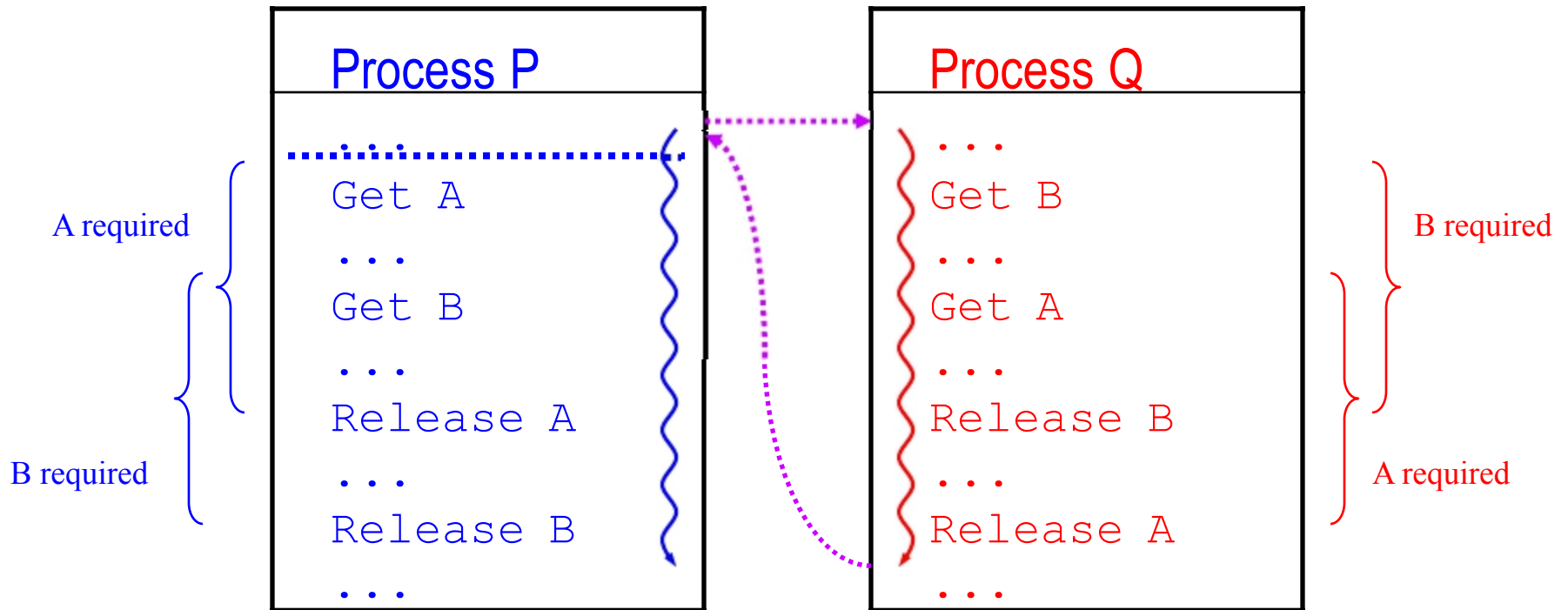
Dining Lawyers Problem Example



- Five chopsticks/Five lawyers (really cheap restaurant)
 - Free-for all: Lawyer will grab any one they can
 - Need two chopsticks to eat
- What if all grab at same time and wait for the one on the left (right)?
 - Deadlock!

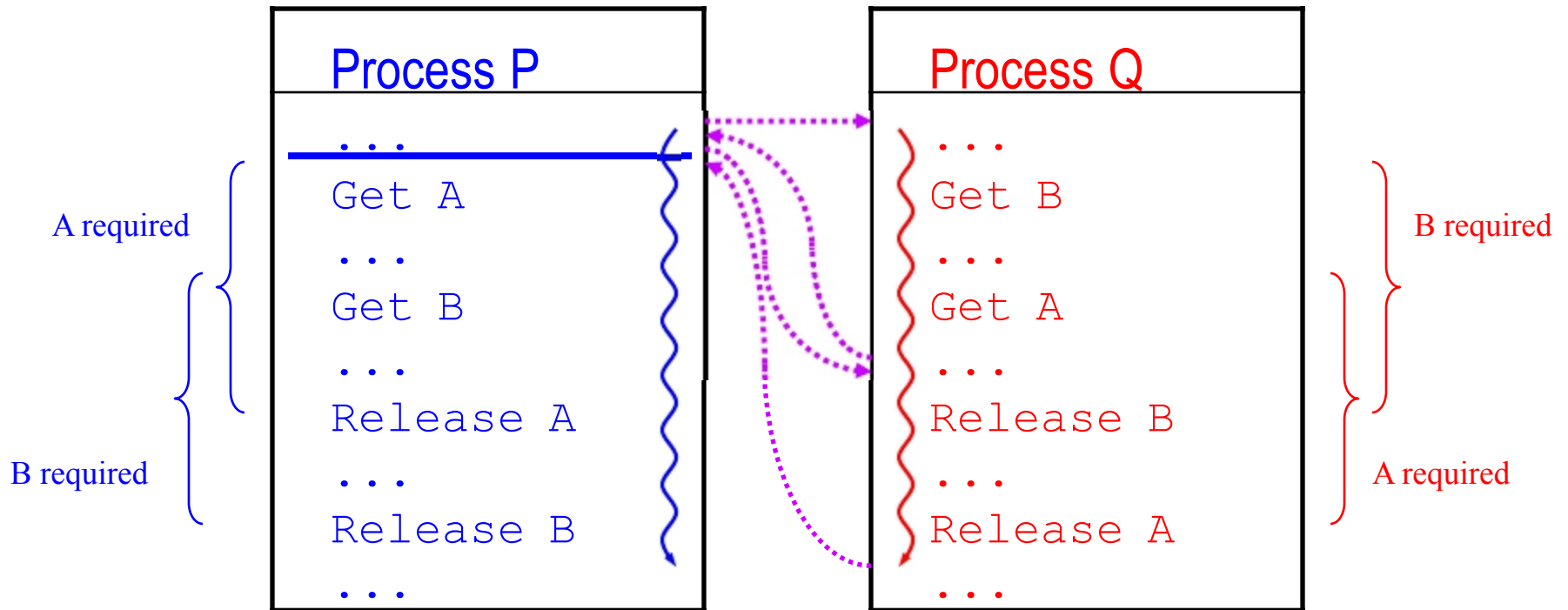
Process Example

- Illustration of a deadlock — scheduling path 1 ☺
 - Q executes everything before P can ever getA
 - when P is ready, resources A and B are free and P can proceed



Process Example

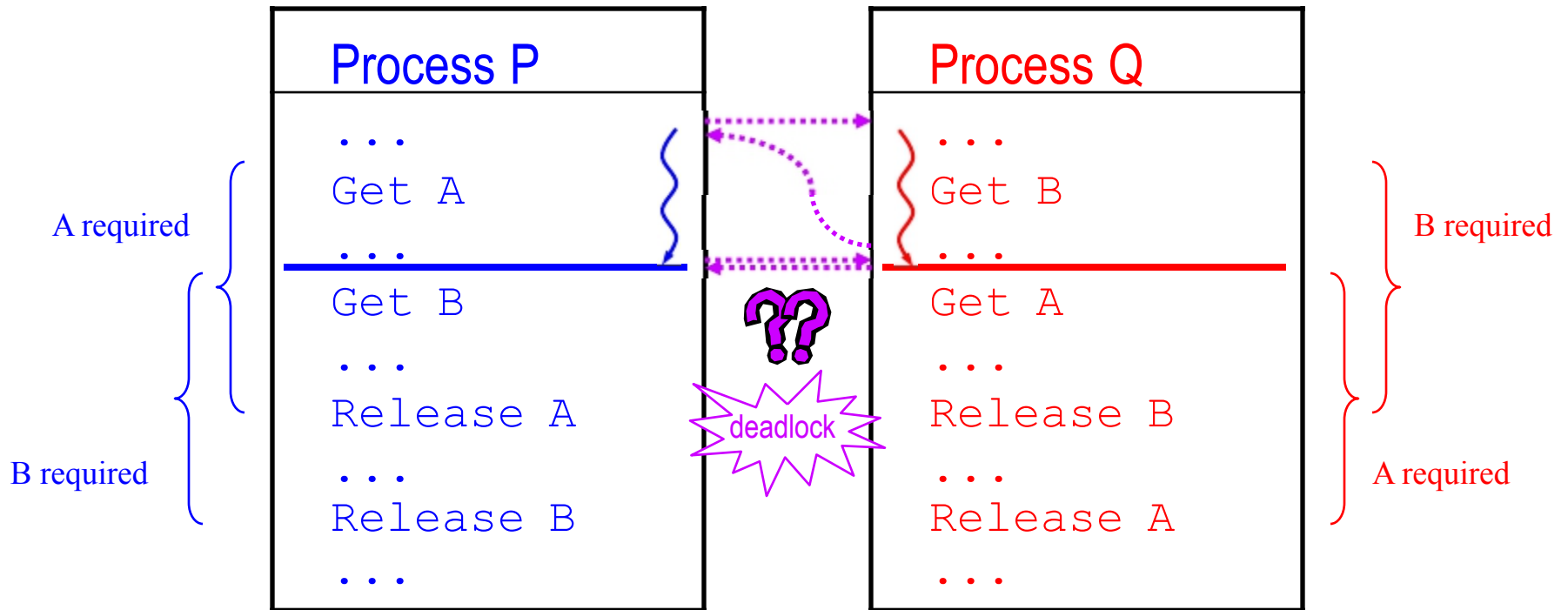
- Illustration of a deadlock — scheduling path 2 😊
 - Q gets B and A, then P is scheduled; P wants A but is blocked by A's mutex; so Q resumes and releases B and A; P can now go



Happy scheduling 2

Process Example

- Illustration of a deadlock — scheduling path 3 ☹️
 - Q gets only B, then P is scheduled and gets A; now both P and Q are blocked, each waiting for the other to release a resource



Bad scheduling → deadlock

Semaphore Example

semaphore:

```
mutex1 = 1    /* protects resource 1 */  
mutex2 = 1    /* protects resource 2 */
```

Process A code:

```
{  
    /* initial compute */  
    down(mutex1)  
    down(mutex2)  
  
    /* use both resources */  
  
    up(mutex2)  
    up(mutex1)  
}
```

Process B code:

```
{  
    /* initial compute */  
    down(mutex2)  
    down(mutex1)  
  
    /* use both resources */  
  
    up(mutex2)  
    up(mutex1)  
}
```

Deadlock Definition

- Formal definition :

A deadlock is a situation in which two or more competing processes are each waiting for the other to finish, and thus neither ever does.

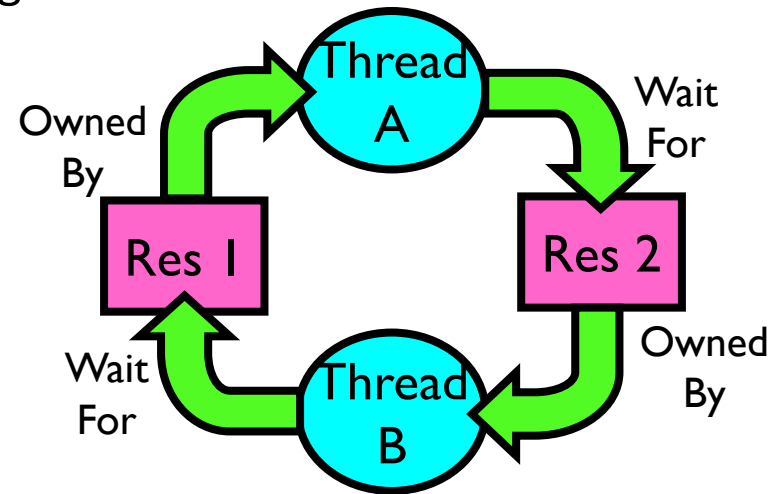
- Usually the event waiting for is the release of a currently held resource
- In deadlock, none of the processes can ...
 - run
 - release resources
 - be awakened
- The number of processes and resources is unimportant

Conditions for Resource Deadlocks

- Mutual exclusion
 - Only one thread at a time can use a resource
- Hold and wait
 - Thread holding at least one resource is waiting to acquire additional resources held by other threads
- No preemption
 - Resources are released only voluntarily by the thread holding the resource, after thread is finished with it
- Circular wait
 - There exists a set $\{T_1, \dots, T_n\}$ of waiting threads
 - T_1 is waiting for a resource that is held by T_2
 - T_2 is waiting for a resource that is held by T_3
 - ...
 - T_n is waiting for a resource that is held by T_1

Starvation Vs Deadlock

- Starvation vs. Deadlock
 - Starvation: thread waits indefinitely
 - Example, low-priority thread waiting for resources constantly in use by high-priority threads
 - Deadlock: circular waiting for resources
 - Thread A owns Res 1 and is waiting for Res 2
 - Thread B owns Res 2 and is waiting for Res 1



- Deadlock \Rightarrow Starvation but not vice versa

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Strategies Dealing with Deadlocks

Allow deadlock to happen. This requires using either

- I. Ostrich algo: ignore the problem altogether
- II. Deadlock ***detection and recovery***: allow deadlock, detect it, break it

Ensure deadlock **never** occurs using either

- I. Deadlock ***prevention***: negate one of the four necessary conditions
- II. Dynamic ***avoidance***: careful resource allocation – each resource request is analyzed and denied if deadlock might result

Outline

- **Deadlock**
 - Concepts
 - How to deal with deadlocks
 - Ignoring them: ostrich algorithm
 - Detecting & recovering from deadlock
 - Preventing deadlock
 - Avoiding deadlock

The Ostrich Algorithm

- Pretend there is no problem
- Reasonable if
 - deadlocks occur very rarely
 - cost of prevention is high
- UNIX and Windows take this approach
- It is a trade-off between
 - convenience
 - correctness



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Deadlock Detection

- Allow system to enter deadlock state
- Detection algorithm
- Recovery scheme

System Model

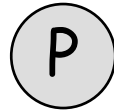
- Resource types
 - R_1, R_2, \dots, R_m
 - E.g., printers, disks,
- Each resource type R_i has W_i instances
 - E.g., 3 printers, 5 disks, etc.
- Assume serially reusable resources
 - request \rightarrow use \rightarrow release

Resource-Allocation Graph

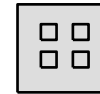
- A set of vertices V and a set of edges E
- V is partitioned into two types:
 - *Process* vertices $P = \{P_1, P_2, \dots, P_n\}$, the set of processes
 - *Resource* vertices $R = \{R_1, R_2, \dots, R_m\}$, the set of resource types (not resources!)
- E is partitioned into two types:
 - *request* edge – directed edge $P_i \rightarrow R_j$
 - *assignment* edge – directed edge $R_j \rightarrow P_i$

Resource-Allocation Graph

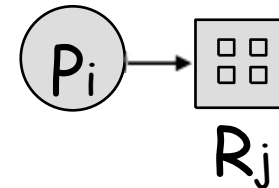
- Process node



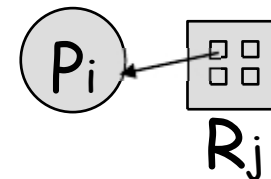
- Resource node with 4 instances



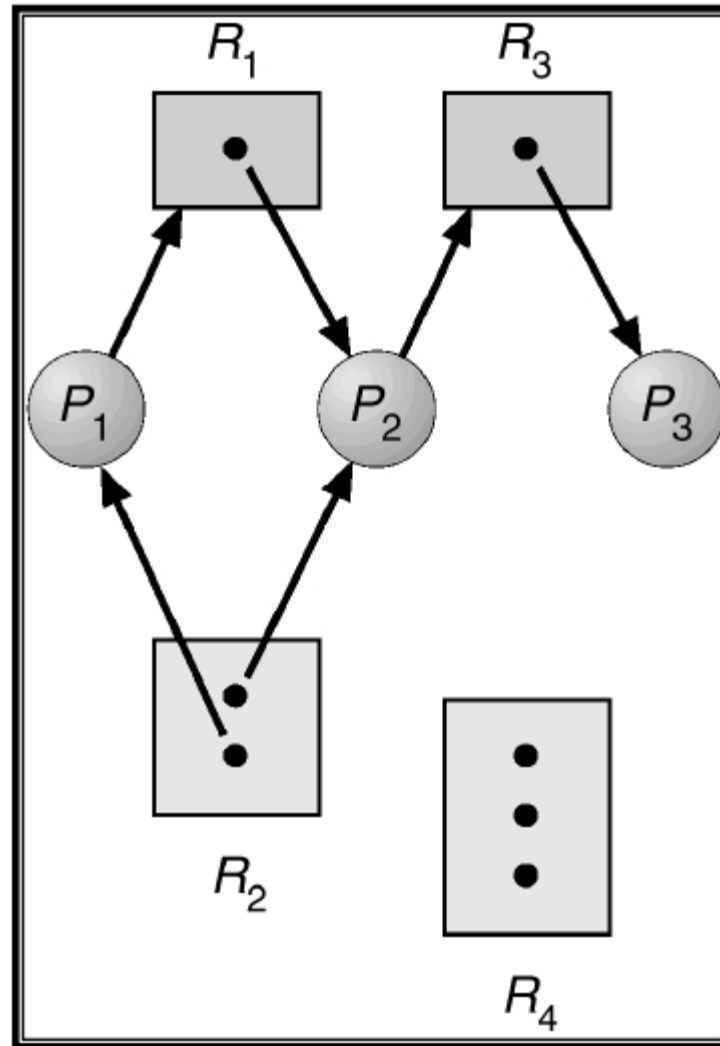
- P_i requests instance of R_j



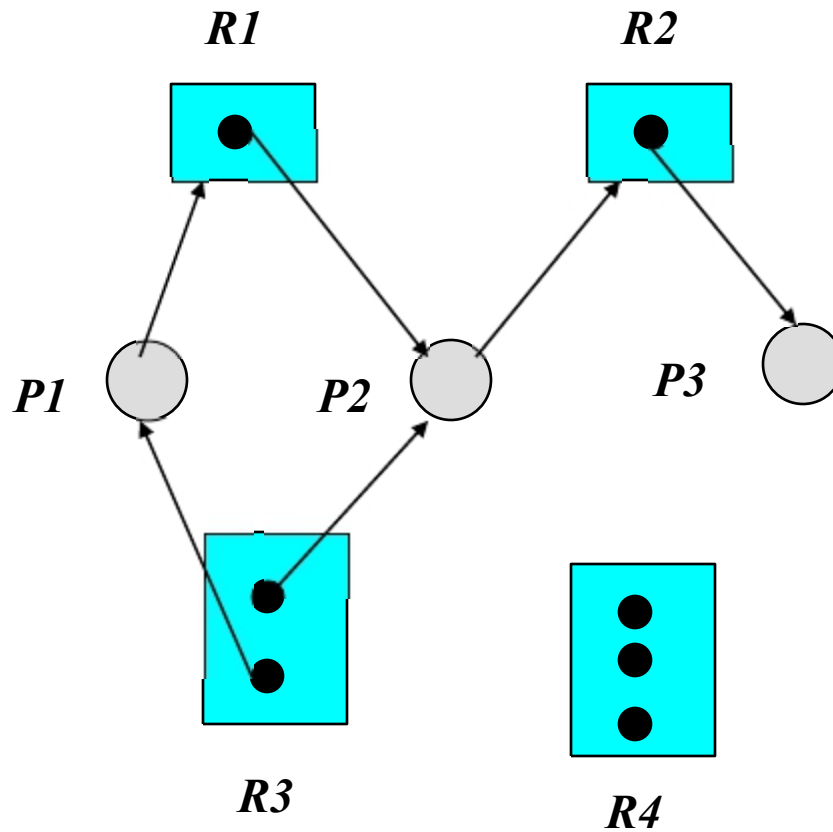
- P_i is holding an instance of R_j



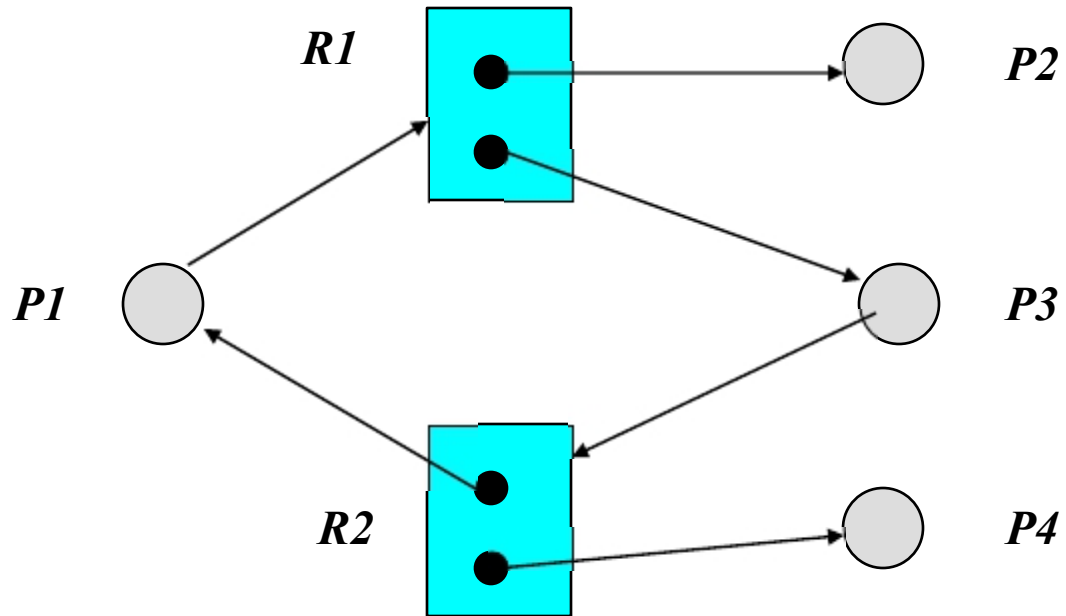
Example of a ResourceAllocation Graph



Graph with no cycles

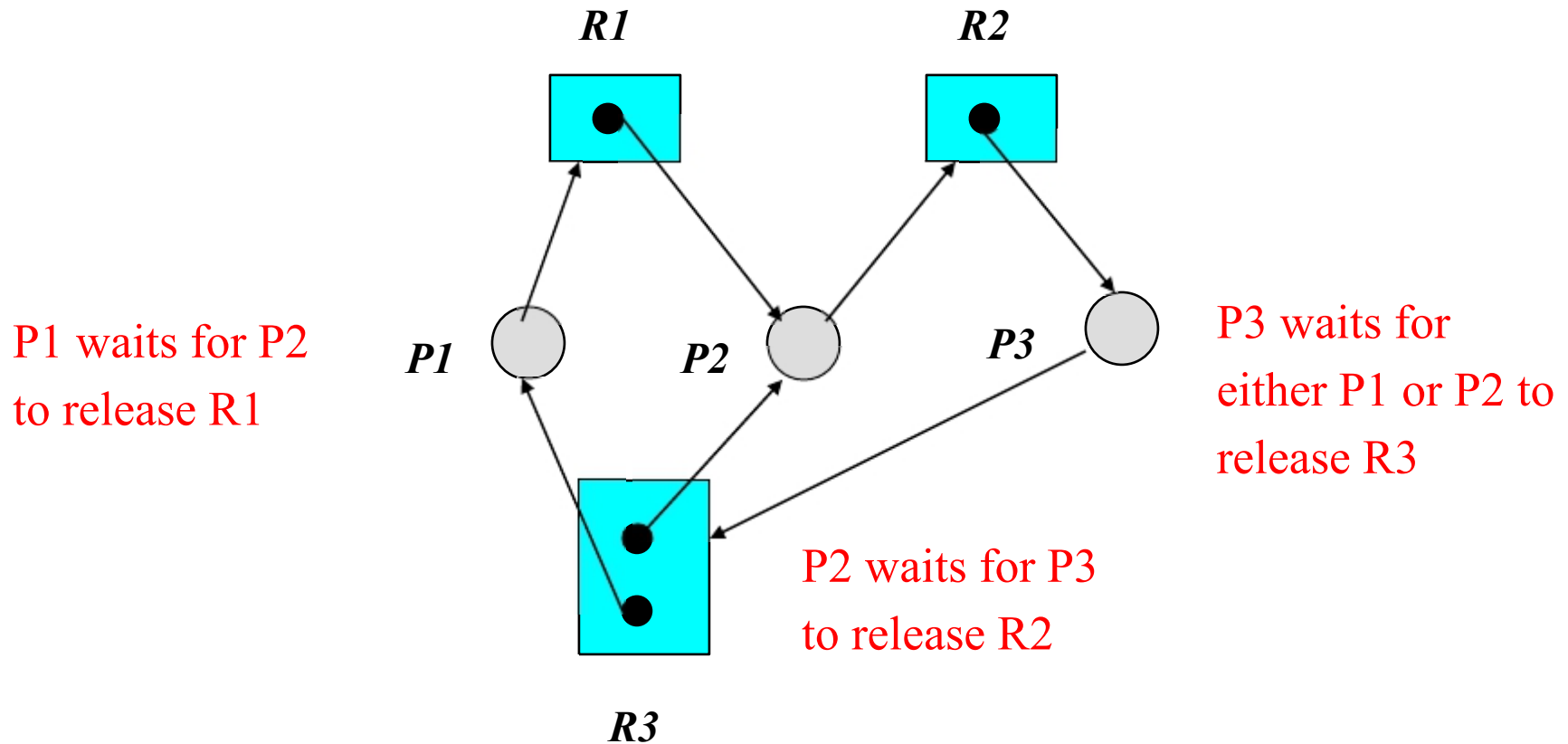


Graph with cycles



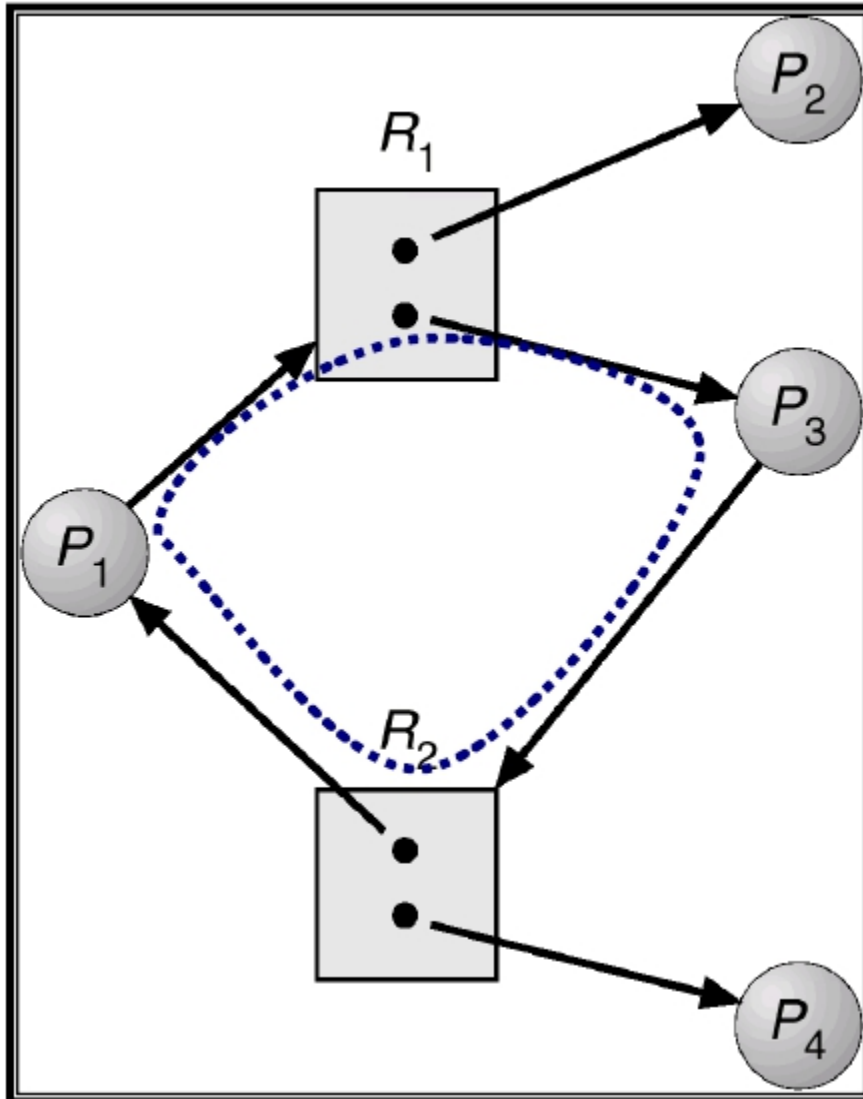
Cycles in Resource Allocation Graph

Multiple Resources of Each Type



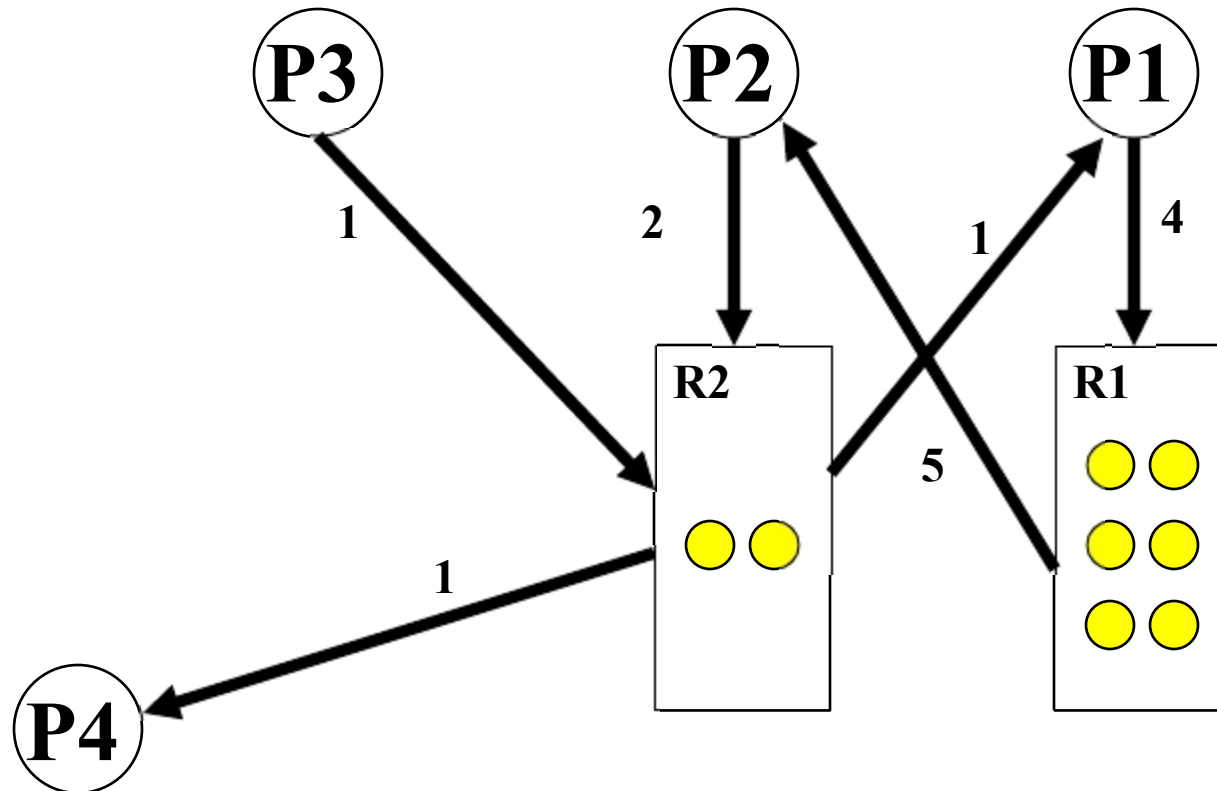
Deadlock!

Graph with Cycles But No Deadlocks

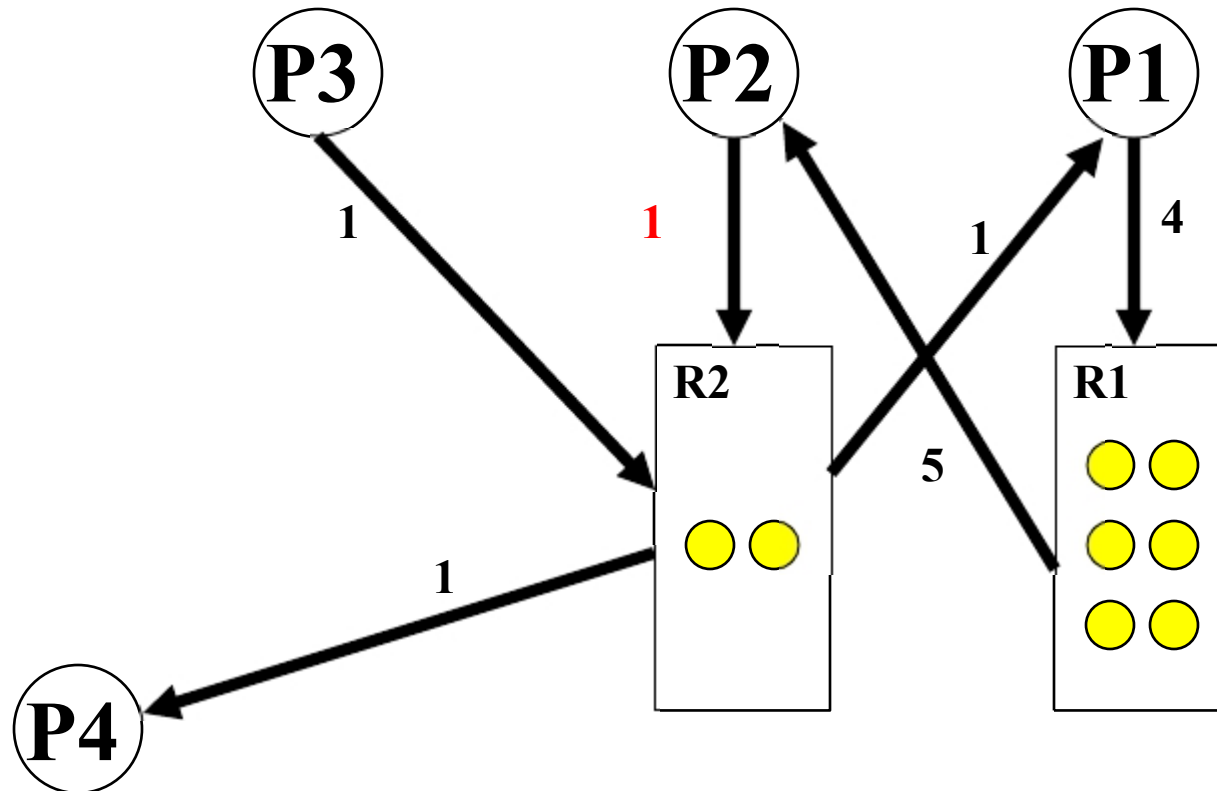


Cycle But No
Deadlock!

A cycle is not
sufficient to
imply a deadlock



Is there a deadlock?



Is there a deadlock?