

# MA331 Intermediate Statistics

## Lecture 04 Point Estimation and Interval Estimation <sup>1</sup>

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<sup>1</sup>Supplement materials.

# 1. Parameter estimation

Let  $X_1, \dots, X_n$  be a simple and random sample from the population  $X$  with distribution function  $F(x, \theta)$ , where the multidimensional parameter

$$\theta = (\theta_1, \dots, \theta_m) \in \Theta,$$

where  $\Theta$  is some known parameter space.

Although we have the sample  $X_1, \dots, X_n$ , we don't know the exact value of the parameter  $\theta$  and hence the exact distribution

$$F(x, \theta), \quad \theta \in \Theta,$$

of the population  $X$  can not be identified. Therefore, the first important thing is to

**acquire the knowledge on the true value of parameter  $\theta$ .**

As one of the two themes of statistics, this is called [parameter estimation](#).

## 2. Moment estimation

☞ According to the [Law of Large Number](#), as  $n \rightarrow \infty$ , the sample moment converges to the corresponding population moment, i.e.,

$$\frac{1}{n} \sum_{i=1}^n X_i^k \rightarrow E_{\theta}[X^k], \quad k = 1, 2, \dots$$

☞ As a result, it is reasonable to set the following equations and thus solve  $\theta$ ,

$$\frac{1}{n} \sum_{i=1}^n X_i^k = E_{\theta}[X^k], \quad k = 1, 2, \dots$$

☞ Obviously, the solution of the above equations provides one approximation for the true value of  $\theta$  and hence called as [moment estimation](#), denoted as

$$\hat{\theta} = \hat{\theta}(X_1, \dots, X_n) = (\hat{\theta}_1, \dots, \hat{\theta}_m).$$

☞ Two remarks:

- As solution of equations, moment estimation may neither exist nor unique;
- Moment estimation usually serves as the initial value for the iterated approximation.



### 3. Moment estimation – example

- Assume the population  $X$  has the probability density  $f(x) = \begin{cases} \frac{6x(\theta-x)}{\theta^3}, & 0 < x < \theta, \\ 0, & \text{otherwise.} \end{cases}$
- By Law of Statistician's Unconsciousness, we have

$$\begin{aligned} E[X] &= \int_{-\infty}^{\infty} xf(x) dx = \int_0^{\theta} \frac{6x^2(\theta-x)}{\theta^3} dx = \frac{\theta}{2}, \\ E[X^2] &= \int_{-\infty}^{\infty} x^2 f(x) dx = \int_0^{\theta} \frac{6x^3(\theta-x)}{\theta^3} dx = \frac{3\theta^2}{10}. \end{aligned}$$

- For a SRS  $X_1, \dots, X_n$  of  $X$ , by setting

$$\frac{\theta}{2} = \bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

we solve the moment estimator  $\hat{\theta} = 2\bar{X}$ .

- Since  $\text{Var}[X] = E[X^2] - E^2[X] = \frac{\theta^2}{20}$ , the moment estimation  $\hat{\theta}$  gets the variance

$$\text{Var}[\hat{\theta}] = \text{Var}[2\bar{X}] = 4\text{Var}[\bar{X}] = \frac{4}{n} \text{Var}[X] = \frac{\theta^2}{5n}.$$



QUERY 1: Derive the moment estimation for  $(\mu, \sigma^2)$  of the population  $X \sim N(\mu, \sigma^2)$ .

## 4. Likelihood function

☞ For observations  $x_i, i = 1, 2, \dots, n$ ,

- if the population is discrete, then the corresponding **probability mass function**

$$p(x_i, \theta) = P(X_i = x_i)$$

tells the likelihood of observing  $X_i = x_i$ ;

- if the population is absolutely continuous, then the corresponding **probability density function**

$$p(x_i, \theta) \Delta x_i \approx P(X_i \in (x_i, x_i + \Delta x_i))$$

also tells the likelihood of observing  $X_i = x_i$ .

☞ To be consistent, for the observed sample  $\mathbf{x} = (x_1, \dots, x_n)$ ,

$$L(\theta, \mathbf{x}) = \prod_{i=1}^n p(x_i, \theta)$$

presents the likelihood for  $(X_1, \dots, X_n)$  to be observed as  $(x_1, \dots, x_n)$  when the parameter takes the value  $\theta$ .



## 5. Maximum likelihood estimation

☞ For  $\mathbf{x} = (x_1, \dots, x_n)$ , the likelihood  $L(\boldsymbol{\theta}, \mathbf{x})$  is a function of  $\boldsymbol{\theta} \in \Theta$ .

- According to R. A. Fisher, the  $\boldsymbol{\theta}$  maximizing  $L(\boldsymbol{\theta}, \mathbf{x})$  is most likely to produce  $(X_1, \dots, X_n) = (x_1, \dots, x_n)$  and hence is the most reasonable approximation for the true value of  $\boldsymbol{\theta}$ ;
- The maximum point of  $L(\boldsymbol{\theta}, \mathbf{x})$  on  $\Theta$  is called as **maximum likelihood estimation** (MLE).



☞ Technically, the maximum point  $\hat{\boldsymbol{\theta}}$  can be expressed as follows:

$$L(\hat{\boldsymbol{\theta}}; x_1, \dots, x_n) = \max_{\boldsymbol{\theta} \in \Theta} L(\boldsymbol{\theta}; x_1, \dots, x_n) = \max_{\boldsymbol{\theta} \in \Theta} \prod_{i=1}^n p(x_i, \boldsymbol{\theta}).$$

☞ Remarks:

- Sometimes, it is convenient to maximize the **log-likelihood** function instead;
- As maximum point of the likelihood function, MLE may neither exist nor unique;
- The iterated algorithm is usually employed to approximate MLE.



## 6. Maximum likelihood estimation – example

- Let  $X$  be of exponential density  $f(x) = \lambda e^{-\lambda x}$ , for  $\lambda > 0, x > 0$ . It is easy to obtain  $E[X] = \frac{1}{\lambda}$ .
- For a SRS  $X_1, \dots, X_n$  of  $X$ . By  $E[X] = \bar{X}$  we get the moment estimator  $\hat{\lambda}_M = \frac{1}{\bar{X}}$ .
- The likelihood function is

$$L(\lambda, \mathbf{x}) = \prod_{i=1}^n f(x_i, \lambda) = \prod_{i=1}^n \lambda e^{-\lambda x_i} = \lambda^n e^{-\lambda \sum_{i=1}^n x_i} = \lambda^n e^{-n\lambda \bar{x}}.$$

- Set  $\frac{\partial \log L(\lambda, \mathbf{x})}{\partial \lambda} = 0$ , we get  $\frac{n}{\lambda} - n\bar{x} = 0$ , which is solved by  $\lambda = \frac{1}{\bar{x}}$ .
- Since, for all  $\lambda > 0$ ,

$$\frac{\partial^2 \log L(\lambda, \mathbf{x})}{\partial \lambda^2} = -\frac{n}{\lambda^2} < 0,$$

we conclude that  $\log L(\lambda, \mathbf{x})$  is maximized at  $\lambda = \frac{1}{\bar{x}}$ .

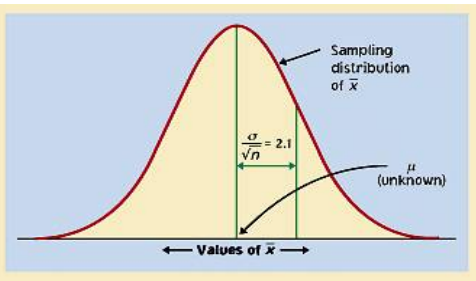
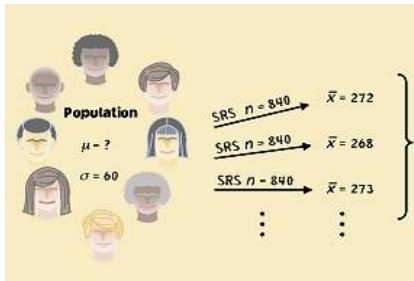
- Therefore, the MLE of  $\lambda$  is summarized as  $\hat{\lambda}_L = \frac{1}{\bar{X}}$ .



QUERY 2: Derive MLE for  $(\mu, \sigma^2)$  of the population  $X \sim \mathcal{N}(\mu, \sigma^2)$ .

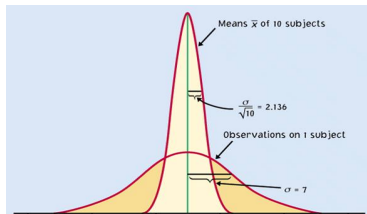
## 7. Randomness of a sample

- ☞ Given an observed sample  $x_1, \dots, x_n$  of  $X$ , sample mean  $\bar{x}$  is a unique number; However, the unrealized sample  $X_1, \dots, X_n$  and hence its mean  $\bar{X}$  is **random**.



- ☞ As a result, **any point estimate**  $\hat{\theta}(X_1, \dots, X_n)$  is also a **random variable**.

- ☞ Since  $\mu_{\bar{X}} = \mu$  and  $\sigma_{\bar{X}}^2 = \sigma^2/n$ , the sample mean  $\bar{X}$ , as the estimate of  $\mu$ , has a more compact distribution than the population  $X$  does.





## 8. Evaluating a point estimator – unbiasedness

Although it is impossible to assess the performance of the estimator  $\hat{\theta}(X_1, \dots, X_n)$  for  $\theta$  based on one observed sample, a good estimator should constantly (or is expected to) provide an accurate estimation. So, statisticians suggest the principle of unbiasedness.

A point estimator  $\hat{\theta}(X_1, \dots, X_n)$  is said to be **unbiased** if

$$E[\hat{\theta}(X_1, \dots, X_n)] = \theta, \quad \text{for any sample size } n.$$

**Weighted average** For any weight vector  $\mathbf{w} = (w_1, \dots, w_n)$  such that  $\sum_{i=1}^n w_i = 1$  and  $w_i \in [0, 1]$  for  $i = 1, \dots, n$ ,

- the corresponding weighted average

$$\bar{X}_{\mathbf{w}} = \sum_{i=1}^n w_i X_i = w_1 X_1 + \dots + w_n X_n.$$

is an unbiased estimator for the population mean  $\mu = E[X]$ .

- Note that the sample mean  $\bar{X}$  is just one specific case.
- $\bar{X}_{\mathbf{w}}$  is not necessarily unbiased for  $\mu$  when  $(w_1, \dots, w_n)$  are general linear combination coefficients.



## 9. Evaluating a point estimator – effectiveness

☞ Since the point estimator  $\hat{\theta}(X_1, \dots, X_n)$  for  $\theta$  is always random, it is natural to expect a good estimator to be of small variation, and this leads to the principle of effectiveness.

☞ An estimator  $\hat{\theta}(X_1, \dots, X_n)$  is said to be **more effective** than the other one  $\tilde{\theta}(X_1, \dots, X_n)$  if

$$\text{Var}[\hat{\theta}(X_1, \dots, X_n)] \leq \text{Var}[\tilde{\theta}(X_1, \dots, X_n)], \quad \text{for any } \theta \in \Theta.$$

☞ For any weight vector  $\mathbf{w} = (w_1, \dots, w_n)$ , the weighted average  $\bar{X}_{\mathbf{w}}$  gets the variance

$$\text{Var}[\bar{X}_{\mathbf{w}}] = \text{Var}\left[\sum_{i=1}^n w_i X_i\right] = \sum_{i=1}^n \text{Var}[w_i X_i] = \sum_{i=1}^n w_i^2 \text{Var}[X_i] = \sigma^2 \sum_{i=1}^n w_i^2,$$

where  $\sigma^2 = \text{Var}[X]$ . In view of

$$\sum_{i=1}^n w_i^2 \geq \frac{1}{n} \quad \text{for any } \mathbf{w}, \quad \text{and} \quad '=' \text{ holds iff } \mathbf{w} = (n^{-1}, \dots, n^{-1}),$$

we conclude that **the sample mean  $\bar{X}$  is more efficient than the weighted mean  $\bar{X}_{\mathbf{w}}$** .

☞ The above assertion is true when all observation are equally treated. In the context of the sample with unequal observations (monocracy versus democracy) it is not valid any more.



# 10. Evaluating a point estimator – consistency

☞ Note that the point estimator  $\hat{\theta}(X_1, \dots, X_n)$  extracts the useful information for  $\theta$  from the sample. A good estimator is expected to get better performance as more observations are included and to reach the true  $\theta$  when the sample size goes to infinity. This principle is summarized as the consistency.

☞ A point estimator  $\hat{\theta}(X_1, \dots, X_n)$  is said to be **consistent** if

$$\hat{\theta}(X_1, \dots, X_n) \longrightarrow \theta \quad \text{as } n \rightarrow \infty.$$

☞ The law of large numbers guarantees that

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i \longrightarrow \mu \quad \text{as } n \rightarrow \infty,$$

and hence **the sample mean  $\bar{X}$  is a consistent estimator for the population mean  $\mu$ .**

**QUERY 3:** The above limit procedure needs to be clarified in advanced probability theory.

☞ The **central limit theorem** introduced in previous lecture **addresses the accuracy of the estimator  $\bar{X}$** , i.e., the distribution of the error  $\bar{X} - \mu$ .

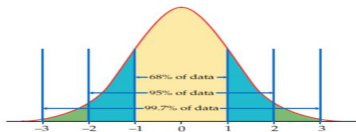


# 11. Accuracy of sample mean

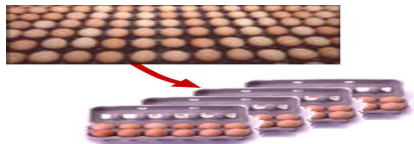
🔗 **3 $\sigma$ -rule**: Due to  $\bar{X} \sim \mathcal{N}(\mu, \sigma^2/n)$  (approximately), it holds that

$$P(|\bar{X} - \mu| \leq 3\sigma_{\bar{X}}) = P(|\bar{X} - \mu|/\sigma_{\bar{X}} \leq 3) \approx \Phi(3) - \Phi(-3) = 2\Phi(3) - 1 = 0.99.$$

QUERY 4: Verify the above and  $P(|\bar{X} - \mu| \leq 2\sigma_{\bar{X}}) \approx 0.95$  by using R.



(a) 3 $\sigma$  rule



(b) brown eggs

🔗 Weight of an egg  $X \sim \mathcal{N}(65, 25)$ , and a SRS: a carton of  $n = 12$ .

- Distribution of  $\bar{X}$ :  $\mathcal{N}(65, 25/12)$  with  $\sigma_{\bar{X}} = \sqrt{25/12} = 1.44$ .
- The middle 95% of  $\bar{X}$  falls between  $65 - 2 \times 1.44$  and  $65 + 2 \times 1.44$ .
- That is,  $\bar{X} \in (65 - 2 \times 1.44, 65 + 2 \times 1.44)$  with a chance of 0.95. Equivalently,  $P(|\bar{X} - 65| \leq 2.88) \geq 0.95$ , implying that with probability at least 0.95 the estimate  $\bar{X}$  gets error smaller than 2.88.



## 12. Confidence interval

✎ For a parameter  $\theta$ , if there are statistics  $\underline{\theta}(X_1, \dots, X_n)$  and  $\bar{\theta}(X_1, \dots, X_n)$  such that

$$P(\underline{\theta}(X_1, \dots, X_n) \leq \theta \leq \bar{\theta}(X_1, \dots, X_n)) \geq 1 - \alpha, \quad \text{for a small } \alpha \in (0, 1),$$

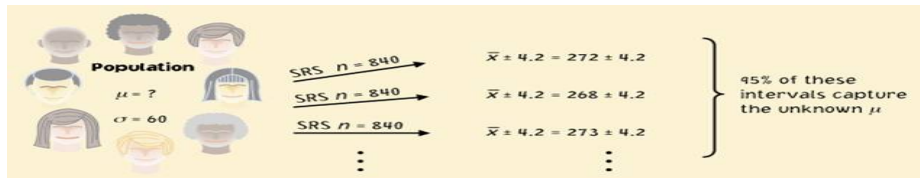
then  $[\underline{\theta}(X_1, \dots, X_n), \bar{\theta}(X_1, \dots, X_n)]$  is called a **confidence interval** (CI) of  $\theta$  with **confidence level**  $1 - \alpha$ .

✎ **Example:** For a sample  $(X_1, \dots, X_n)$  of  $X \sim \mathcal{N}(\mu, \sigma^2)$  with known  $\sigma$ , according to

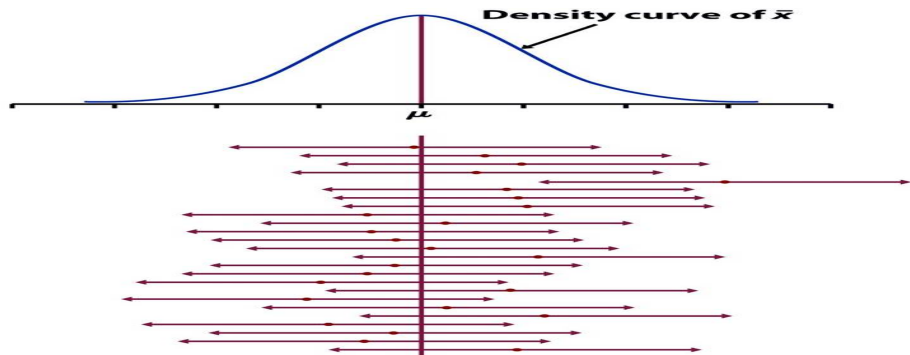
$$0.95 \approx P(|\bar{X} - \mu|/\sigma_{\bar{X}} \leq 2) = P(\bar{X} - 2\sigma_{\bar{X}} \leq \mu \leq \bar{X} + 2\sigma_{\bar{X}})$$

$[\bar{X} - 2\sigma_{\bar{X}}, \bar{X} + 2\sigma_{\bar{X}}]$  catches  $\mu$  with probability 0.95. That is,  $P(|\bar{X} - \mu| \leq 2\sigma_{\bar{X}}) \geq 0.95$ .

✎ The CI is a **random interval** with probability – **confidence level**  $1 - \alpha$  quantifying the chance of capturing the true population parameter.



# 13. Implication of confidence interval



With 95% confidence, we can say that  $\mu$  should be within roughly  $2\sigma_{\bar{X}} = 2 * \sigma / \sqrt{n}$  away from  $\bar{X}$ .

- In 95% of all possible samples of size  $n$ ,  $\mu$  will indeed fall into the corresponding CI  $[\bar{X} - 2\sigma_{\bar{X}}, \bar{X} + 2\sigma_{\bar{X}}]$ .
- In only 5% of samples would  $\bar{X}$  miss the parameter  $\mu$ .



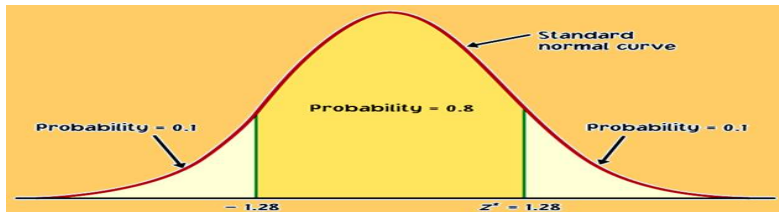
# 14. Margin of error and confidence level

✎ The radius of a CI tells the error of the point estimate and thus is call **margin of error**. E.g.,  $2\sigma_{\bar{X}} = 2 * \sigma / \sqrt{n}$  of the CI  $[\bar{X} - 2\sigma_{\bar{X}}, \bar{X} + 2\sigma_{\bar{X}}]$ .

✎ **Smaller/larger margin of error** is usually associated with **lower/higher confidence level  $c$**  and thus **better/worse precision**. E.g.,

- $[\bar{X} - 2\sigma_{\bar{X}}, \bar{X} + 2\sigma_{\bar{X}}]$  has confidence level  $c = 0.95$ , and
- $[\bar{X} - 3\sigma_{\bar{X}}, \bar{X} + 3\sigma_{\bar{X}}]$  gets confidence level  $c = 0.997$ .

✎ For any given confidence level  $c = 1 - \alpha$ , to construct the CI  $[\bar{X} - z^* \sigma / \sqrt{n}, \bar{X} + z^* \sigma / \sqrt{n}]$  we only need to identify  $z^*$ .



# 15. Finding the $z$ -value $z^*$

- Given CI level  $c = 1 - \alpha$ ,  $z^*$  is determined as the  $1 - \alpha/2$  normal percentile  $z_{1-\alpha/2}$ . Margin of error is then  $z_{1-\alpha/2}\sigma / \sqrt{n}$ .
- The  $z_{1-\alpha/2}$  can be identified by using the normal table or  $z$ -table.
- Also it can be evaluated by using R: `qnorm(prob,mean,sd)` evaluates  $z$  quantile for a given probability.
- E.g., For a confidence level  $98\% = c = 1 - \alpha$ ,

$z$	.00	.01	.02	.03	.04	.05	.06	.07	.08	.09
0.0	.5000	.5040	.5080	.5120	.5160	.5199	.5239	.5279	.5319	.5359
0.1	.5398	.5438	.5478	.5517	.5557	.5596	.5636	.5675	.5714	.5753
0.2	.5793	.5832	.5871	.5910	.5948	.5987	.6026	.6064	.6103	.6141
0.3	.6179	.6217	.6255	.6293	.6331	.6368	.6406	.6443	.6480	.6517
0.4	.6554	.6591	.6628	.6664	.6700	.6736	.6772	.6808	.6844	.6879
0.5	.6915	.6950	.6985	.7019	.7054	.7088	.7123	.7157	.7190	.7224
0.6	.7257	.7291	.7324	.7357	.7389	.7422	.7454	.7486	.7517	.7549
0.7	.7580	.7611	.7642	.7673	.7704	.7734	.7764	.7794	.7823	.7852
0.8	.7881	.7910	.7939	.7967	.7995	.8023	.8051	.8078	.8106	.8133
0.9	.8159	.8186	.8212	.8238	.8264	.8289	.8315	.8340	.8365	.8389
1.0	.8413	.8438	.8461	.8485	.8508	.8531	.8554	.8577	.8599	.8621
1.1	.8643	.8665	.8686	.8708	.8729	.8749	.8770	.8790	.8810	.8830
1.2	.8849	.8869	.8888	.8907	.8925	.8944	.8962	.8980	.8997	.9015
1.3	.9032	.9049	.9065	.9082	.9099	.9115	.9131	.9147	.9162	.9177
1.4	.9192	.9207	.9222	.9236	.9251	.9265	.9279	.9292	.9306	.9319
1.5	.9332	.9345	.9357	.9370	.9382	.9394	.9406	.9418	.9429	.9441
1.6	.9452	.9463	.9474	.9484	.9495	.9505	.9515	.9525	.9535	.9545
1.7	.9554	.9564	.9573	.9582	.9591	.9599	.9608	.9616	.9625	.9633
1.8	.9641	.9649	.9656	.9664	.9671	.9678	.9686	.9693	.9699	.9706
1.9	.9713	.9719	.9726	.9732	.9738	.9744	.9750	.9756	.9761	.9767
2.0	.9772	.9778	.9783	.9788	.9793	.9798	.9803	.9808	.9812	.9817
2.1	.9821	.9826	.9830	.9834	.9838	.9842	.9846	.9850	.9854	.9857
2.2	.9861	.9864	.9868	.9871	.9875	.9878	.9881	.9884	.9887	.9890
2.3	.9893	.9896	.9898	.9901	.9904	.9906	.9909	.9911	.9913	.9916

$$\text{qnorm}(0.99, 0, 1) = 2.326348 = z_{1-0.02/2} = z_{0.99}$$



## 16. Impact of sample size

✎ The  $\sigma_{\bar{X}} = \sigma / \sqrt{n}$  tells that the variation in  $\bar{X}$  and hence the margin of error  $z_{1-\alpha/2}\sigma / \sqrt{n}$  decreases as the sample size  $n$  grows.

✎ One can determine the sample size so that the CI (with confidence level  $1 - \alpha$ )

$$[\bar{X} - z_{1-\alpha/2}\sigma / \sqrt{n}, \bar{X} + z_{1-\alpha/2}\sigma / \sqrt{n}]$$

has the desired margin of error  $\varepsilon > 0$  through solving

$$z_{1-\alpha/2}\sigma / \sqrt{n} \leq \varepsilon \implies n \geq (z_{1-\alpha/2})^2 \sigma^2 / \varepsilon^2.$$

✎ Density of bacteria: The instrument has standard deviation  $\sigma = 1$  unit ( $10^6$  bacteria/ml) fluid, 3 obs: 24, 29 and 31 units.

- A confidence level 96% CI is

$$\bar{x} \pm z_{1-\alpha/2}\sigma / \sqrt{n} = 28 \pm 2.054 \times 1 / \sqrt{3} = 28 \pm 1.19.$$

- To have the margin of error  $\leq 0.5$ , the sample size  $n$  must be at least

$$(z_{1-\alpha/2})^2 \sigma^2 / \varepsilon^2 = (2.054)^2 \times 1^2 / (0.5)^2 \approx 16.88.$$



## 17. The $\mu$ -interval for mean of normal population

✎ Assume a SRS  $X_1, \dots, X_n$  from  $X \sim \mathcal{N}(\mu, \sigma^2)$  with **known  $\sigma^2$** , and given the confidence level  $1 - \alpha$ .

- Since  $\bar{X} \sim \mathcal{N}(\mu, \sigma^2/n)$ , it holds that

$$P\left(\left|\frac{\bar{X} - \mu}{\sqrt{\sigma^2/n}}\right| \leq z_{1-\alpha/2}\right) = 1 - \alpha,$$

- Note that the above equation is equivalent to

$$P\left(\bar{X} - z_{1-\alpha/2} \sqrt{\sigma^2/n} \leq \mu \leq \bar{X} + z_{1-\alpha/2} \sqrt{\sigma^2/n}\right) = 1 - \alpha.$$

- By definition, the CI (with confidence level  $1 - \alpha$ ) of  $\mu$  in this context is

$$\left[\bar{X} - z_{1-\alpha/2}\sigma / \sqrt{n}, \quad \bar{X} + z_{1-\alpha/2}\sigma / \sqrt{n}\right],$$

which is usually called the  $\mu$ -interval.



# 18. The $t$ -interval for mean of normal population

✎ Assume a SRS  $X_1, \dots, X_n$  from  $X \sim \mathcal{N}(\mu, \sigma^2)$  with **unknown  $\sigma^2$** .

- Since  $(\bar{X} - \mu) / \sqrt{\sigma^2/n} \sim \mathcal{N}(0, 1)$ ,  $(n-1)S^2/\sigma^2 \sim \chi_{n-1}^2$  and they are independent,

$$\frac{(\bar{X} - \mu) / \sqrt{\sigma^2/n}}{\sqrt{[(n-1)S^2/\sigma^2]/(n-1)}} = \frac{\sqrt{n}(\bar{X} - \mu)}{\sqrt{S^2}} \sim t(n-1),$$

and hence, for the confidence level  $1 - \alpha$ ,

$$\mathbb{P}\left(\left|\frac{\sqrt{n}(\bar{X} - \mu)}{\sqrt{S^2}}\right| \leq t_{1-\alpha/2}(n-1)\right) = 1 - \alpha,$$

where  $t_{1-\alpha/2}(n-1)$  is the  $1 - \alpha/2$  quantile of the  $t$  distribution with d.f.  $n - 1$ .

- Note that the above equation is equivalent to

$$\mathbb{P}\left(\bar{X} - t_{1-\alpha/2}(n-1)\sqrt{S^2/n} \leq \mu \leq \bar{X} + t_{1-\alpha/2}(n-1)\sqrt{S^2/n}\right) = 1 - \alpha.$$

- By definition, the CI (with confidence level  $1 - \alpha$ ) of  $\mu$  in this context is

$$\left[\bar{X} - t_{1-\alpha/2}(n-1)S / \sqrt{n}, \quad \bar{X} + t_{1-\alpha/2}(n-1)S / \sqrt{n}\right],$$

which is usually called the  **$t$ -interval**.



# 19. Confidence interval for variance of normal population

✎ Assume a SRS  $X_1, \dots, X_n$  from  $X \sim \mathcal{N}(\mu, \sigma^2)$ .

- Since  $(n-1)S^2/\sigma^2 \sim \chi_{n-1}^2$ , it holds that, for the confidence level  $1 - \alpha$ ,

$$P\left(\chi_{\alpha/2}(n-1) \leq \frac{(n-1)S^2}{\sigma^2} \leq \chi_{1-\alpha/2}(n-1)\right) = 1 - \alpha,$$

where  $\chi_{1-\alpha/2}(n-1)$  is the  $1 - \alpha/2$  quantile of  $\chi^2$  distribution with d.f.  $n - 1$ .

- Note that the above equation is equivalent to

$$P\left(\frac{(n-1)S^2}{\chi_{1-\alpha/2}(n-1)} \leq \sigma^2 \leq \frac{(n-1)S^2}{\chi_{\alpha/2}(n-1)}\right) = 1 - \alpha.$$

- By definition, the CI (with confidence level  $1 - \alpha$ ) of  $\sigma^2$  in this context is

$$\left[ \frac{(n-1)S^2}{\chi_{1-\alpha/2}(n-1)}, \quad \frac{(n-1)S^2}{\chi_{\alpha/2}(n-1)} \right],$$

irrespective of the parameter  $\mu$ .



## 20. The most accurate confidence interval

✎ For a SRS  $X_1, \dots, X_n$  from  $X$  with distribution function  $F(x, \theta)$  with parameter  $\theta$ , assume that two CI's

$$[\underline{\theta}_1(X_1, \dots, X_n), \quad \overline{\theta}_1(X_1, \dots, X_n)] \quad \text{and} \quad [\underline{\theta}_2(X_1, \dots, X_n), \quad \overline{\theta}_2(X_1, \dots, X_n)]$$

both are of the confidence level  $1 - \alpha$ .

✎ The CI  $[\underline{\theta}_2(X_1, \dots, X_n), \quad \overline{\theta}_2(X_1, \dots, X_n)]$  is said to be **more accurate** than the CI  $[\underline{\theta}_1(X_1, \dots, X_n), \quad \overline{\theta}_1(X_1, \dots, X_n)]$  if

$$\begin{aligned} & \overline{\theta}_1(X_1, \dots, X_n) - \underline{\theta}_1(X_1, \dots, X_n) \\ & \leq \quad \overline{\theta}_2(X_1, \dots, X_n) - \underline{\theta}_2(X_1, \dots, X_n). \end{aligned}$$

That is, **the one with shorter interval length is more accurate** given that they have the same probability to cover the true value of the parameter to be estimated.



# 21. The most accurate confidence interval

✎ Assume a SRS  $X_1, \dots, X_n$  from  $X \sim \mathcal{N}(\mu, \sigma^2)$  and give the significance level  $1 - \alpha$ .

- The  $\mu$ -interval (geometrically symmetric)

$$\left[ \bar{X} - z_{1-\alpha/2}\sigma / \sqrt{n}, \quad \bar{X} + z_{1-\alpha/2}\sigma / \sqrt{n} \right],$$

for population mean  $\mu$  can be proved to be the most accurate one.

- The  $t$ -interval (geometrically symmetric)

$$\left[ \bar{X} - t_{1-\alpha/2}(n-1)S / \sqrt{n}, \quad \bar{X} + t_{1-\alpha/2}(n-1)S / \sqrt{n} \right],$$

for population mean  $\mu$  can be proved to be the most accurate one.

- The probability symmetric CI

$$\left[ \frac{(n-1)S^2}{\chi_{1-\alpha/2}^2(n-1)}, \quad \frac{(n-1)S^2}{\chi_{\alpha/2}^2(n-1)} \right],$$

for population variance  $\sigma^2$  can be proved not to be the most accurate one;  
however, it is asymptotically most accurate.

