# KAIWEN WANG

## **EDUCATION**

## Carnegie Mellon University, Pittsburgh, PA

Expected May 2020

- · Bachelor of Science in Computer Science with an additional major in Math
- Relevant Coursework: Machine Learning<sup>G</sup>, Algorithms and Data Structures, Distributed Systems<sup>C</sup>, Theoretical CS, Random Graphs<sup>C</sup>, Asymptotic Convex Geometry<sup>G,C</sup>, Real Analysis, Probability
- Cumulative GPA: 4.00/4.00

G - graduate, C - currently enrolled

#### **SKILLS**

Programming Languages Software and Libraries Spoken Languages Python, C/C++, JavaScript, Go, Standard ML, Java, MATLAB Tensorflow/Keras, PySpark, CUDA, NodeJS, D3, Git, LATEX English (Native), 中文(普通话)(Native), Français (Fluent)

#### **EXPERIENCES**

## Intern Engineer

May 2018 - Aug 2018

DataVisor, Mountain View, CA

- · Implemented an automated quality monitoring system for core unsupervised machine learning (UML).
- Performed clustering and anomaly detection for seasonal and sporadic time-series data.
- · Monitored concept drift of UML, such as an influx of FPs or FNs, in an unsupervised setting.
- Deployed the quality monitoring project as a Web app written in NodeJS using Express and D3.

#### Research Assistant

January 2017 - Aug 2018

Professor Min Xu's Lab, Carnegie Mellon University, Pittsburgh, PA

- Developed a novel Monte Carlo method for statistical assessment of CECT template matching, using a 3D variant of the Generative Adversarial Network (GAN), tested on both simulated and real data.
- First-authored paper accepted at computer vision conference BMVC 2018 (acceptance rate 29.9%).

#### **PROJECTS**

## Classifying Blazars and Cataclysmic Variables (CVs)

May 2018

• Collaborated with two teammates and achieved state-of-the-art classification accuracy of 90% using PCA and CNNs, for classifying irregularly sampled time-series data of observed light magnitude as either Blazars or CV, with a severely biased and limited dataset.

## Autonomous Mobile Robot (Mobot)

Apr 2018

- In a team of three, assembled hardware and developed software for an autonomous Mobot capable of outdoors navigation on a non-flat, slalom-style racecourse.
- · Created fully automated computer vision reasoning heuristics using OpenCV and PID Controller.
- · Won first place overall in the 24<sup>th</sup> annual CMU Mobot Race and received the JPL sponsor prize.

#### SELECTED PUBLICATION

• Wang K, Zeng X, Liang X, Huo Z, Xing E, Xu M. Image-derived generative modeling of pseudo-macromolecular structures - towards statistical assessment of electron cryotomography template matching. British Machine Vision Conference (BMVC) 2018. arXiv:1805.04634.