

CISC2005 Principles of Operating Systems

Assignment 3

Release date: Mar. 19, 2023

Due date: April 2, 2023 23:59

No late assignment will be accepted

Every Student MUST include the following statement, together with his/her signature in the submitted homework.

I declare that the assignment submitted is original except for source material explicitly acknowledged, and that the same or related material has not been previously submitted for another course. I also acknowledge that I am aware of University policy and regulations on honesty in academic work, and of the disciplinary guidelines and procedures applicable to breaches of such policy and regulations.

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General homework policies:

A student may discuss the problems with others. However, the work a student turns in must be created COMPLETELY by oneself ALONE. A student may not share ANY written work or pictures, nor may one copy answers from any source other than one's own brain.

Each student **MUST LIST** on the homework paper the **name of every person he/she has discussed or worked with**. If the answer includes content from any other source, the student **MUST STATE THE SOURCE**. Failure to do so is cheating and will result in sanctions. Copying answers from someone else is cheating even if one lists their name(s) on the homework.

If there is information you need to solve a problem but the information is not stated in the problem, try to find the data somewhere. If you cannot find it, state what data you need, make a reasonable estimate of its value, and justify any assumptions you make. You will be graded not only on whether your answer is correct, but also on whether you have done an intelligent analysis.

Questions:

- ✓ 1. Explain why implementing synchronization primitives by disabling interrupts is not appropriate in a single-processor system if the synchronization primitives are to be used in user-level programs. (20 points)
- ✓ 2. What are similarities and differences between deadlock and starvation? (20 points)

①

Note : on single processor system, actually, even in multi processor system, disabling interrupts to do synchronization is still not a good way, it's insufficient on a multiprocessor.

We try to disable interrupts to do synchronization because it can stop all context switch and only focus on finishing current job, It sounds like a good idea, but in fact, because during disabling interrupts, many other interrupts are disabled as well, such as I/O or timer interrupts, which is very important and critical to the system's operation. As a result, if disabling interrupts, many important interrupts will be missed or delayed, and it doesn't bring good effect to operating system and lead to decreased performance and potentially cause system failures.

Also, one more point is that such primitive are used in user-level programs, user-level do not have the same level of control over hardware as kernel-level. As a summary, other synchronization mechanism should be used in user-level programs, such as semaphores or monitor, but not disabling interrupts.

②

	Deadlock	Starvation
Similarities	Process being blocked indefinitely and never completing its execution.	Process being blocked indefinitely and never completing its execution.
	Both can lead to a system becoming unresponsive and non-functional	Both can lead to a system becoming unresponsive and non-functional
Difference	Deadlock happen between 2 or more processes, because they are waiting for each other to release resources	Starvation happen because of scheduling algorithm (but not only reason), the process is unable to gain necessary resources in order to execute, where other processes are consistently given resources.

3. Consider how to **implement a mutex lock** using an **atomic hardware instruction**. Assume that the following structure defining the mutex lock is available:

```
1 typedef struct {
2     int available;
3 } lock;
```

(available == 0) indicates that the lock is **available**, and a value of 1 indicates that the lock is **unavailable**. Using this struct, illustrate how the following functions can be implemented using the **test_and_set()**. (20 points)

```
1 typedef struct { int available; } lock;
2
3 void init(lock *mutex) {
4     // available=0 -> lock is available, available=1 -> lock is unavailable
5     available = 0;
6 }
7
8 void acquire(lock *mutex) {
9     while (test_and_set(&lock->available))
10         ; // spin-wait (do nothing)
11 }
12
13 void release(lock *mutex) {
14     lock->available = 0
15 }
```

4. Show how to implement the **--** and **++** semaphore operations in multiprocessor environments using the **test_and_set()** instruction. The solution should exhibit minimal busy waiting. (20 points)

```
1 int guard = 0;
2 int semaphore value = 0;
3 wait() {
4     while (test_and_set(&guard))
5         ;
6     if (semaphore value == 0){
7         atomically add process to a queue of processes
8         waiting for the semaphore and set guard to 0;
9     }
10    else
11    {
12        semaphore value --;
13        guard = 0;
14    }
15 }
16 signal() {
17     while (test_and_set(&guard))
18         ;
```

```

19 if (semaphore value == 0 && there is a process on the wait queue)
20     wake up the first process in the queue of waiting processes
21 else
22     semaphore value ++ ;
23     guard = 0;
24 }

```

5. Here is a pseudocode for implementing a bounded buffer using the monitor. The size of the buffer is N , and the variable “*count*” indicates the number of resources available in the buffer. The condition variables “*not_full*” and “*not_empty*” indicate whether the buffer is not full and not empty, respectively. The producer thread continuously inserts items into the buffer, while the consumer thread continually consumes items. Please fill in the appropriate conditional statements and use *wait()* and *signal()* operations to manipulate the condition variables in the blanks below to complete the code. (20 points)

```

1 Monitor bounded_buffer {
2     Resource buffer[N];
3     // Variables for indexing buffer
4     int count = 0;
5     // monitor invariant involves these vars
6     Condition not_full; // space in buffer
7     Condition not_empty; // value in buffer
8
9     void insert(Resource item) {
10         while (count == N)
11         wait(not_full);
12     }
13     buffer[count++] = item;
14     signal(not_empty);
15 }
16
17 Resource remove() {
18     while (count == 0)
19     wait(not_empty);
20 }
21 item = buffer[--count];
22 signal(not_full);
23 return item;
24 }
25 } // end monitor
26
27 produce() {
28     while (1) {
29         Resource item = produce_item(); // Produce an item.
30         bounded_buffer.insert(item);
31     }

```

```
32 }  
33  
34 consumer() {  
35     while (1) {  
36         Resource item = bounded_buffer.remove(item); // Get an item.  
37     }  
38 }
```