

Kai S. Yun

Legal Name: SirkHoo Yun

Ph.D. Student, Laboratory for Information & Decision Systems (LIDS) at MIT
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RESEARCH INTEREST

My research is focused on **safe and high-performance control** of autonomous robots in the wild.

My methodology encompasses **control theory, deep learning**, and their **intersection**.

My vision is to develop a **unified framework** for highly reactive robot controllers in complex, dynamic environments.

EDUCATION

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| Massachusetts Institute of Technology, Cambridge, MA | Class of 2029 (Expected) |
| Doctor of Philosophy in Mechanical Engineering | 5.00/5.00 |
| Advisor: Dr. Navid Azizan | |
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| Carnegie Mellon University, Pittsburgh, PA | Class of 2025 |
| Master of Science in Mechanical Engineering | 4.00/4.00 |
| Advisors: Dr. Changliu Liu, Dr. John M. Dolan | |
| * <i>ATK-Nick G. Vlahakis Fellowship</i> , 2024 — 2025 | |
| * <i>Best Master's Research Paper 2025 Commencement Award</i> | |
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| University of California, Berkeley, Berkeley, CA | Class of 2023 |
| Bachelor of Science in Mechanical Engineering | 3.68/4.00 |
| Minor in Electrical Engineering and Computer Science (EECS) | |
| Military Service (Leave of Absence, 2019 — 2020) | |

PUBLICATIONS & PREPRINTS

* Equal Contribution

- [C1] Kai S. Yun, Rui Chen, Chase Dunaway, John M. Dolan, Changliu Liu, “Safe Control of Quadruped in Varying Dynamics via Safety Index Adaptation”. Published in 2025 IEEE [International Conference on Robotics and Automation \(ICRA\)](#), **Oral Presentation** in Atlanta, Georgia, 2025, [Website](#).
- [C2] Simin Liu*, Kai S. Yun*, John M. Dolan, Changliu Liu, “Synthesis and Verification of Robust-Adaptive Safe Controllers”. Published in [European Control Conference \(ECC\)](#), **Oral Presentation** in Stockholm, Sweden, 2024.
- [C3] Tianhao Wei, Hanjiang Hu*, Luca Marzari*, Kai S. Yun*, Peizhi Niu*, Xusheng Luo, Changliu Liu, “ModelVerification.jl: a Comprehensive Toolbox for Formally Verifying Deep Neural Networks”. Published in 2025 [International Conference on Computer Aided Verification \(CAV\)](#), 2025, [GitHub](#).
- [P1] Kai S. Yun, Navid Azizan, “ATOM-CBF: Adaptive Safe Perception-Based Control under Out-of-Distribution Measurements”. Submitted to Learning for Dynamics and Control Conference (L4DC), 2026. Preprint at [arxiv.org:2511.08741](https://arxiv.org/abs/2511.08741), 2025.
- [P2] Yifan Sun, Rui Chen, Kai S. Yun, Yikuan Fang, Sebin Jung, Feihan Li, Bowei Li, Weiy Zhao, Changliu Liu, “SPARK: A Modular Benchmark for Humanoid Robot Safety”. Preprint at [arxiv.org:2502.03132](https://arxiv.org/abs/2502.03132), 2025, [Website](#).
- [P3] Yifan Sun, Rui Chen, Kai S. Yun, Yikuan Fang, Sebin Jung, Weiy Zhao, Changliu Liu, “Safe Humanoid Autonomy and Teleoperation with Safe Set Algorithm”. Extended abstract published in *Joint 10th IFAC Symposium on Mechatronic Systems and 14th Symposium on Robotics*, 2025.

RESEARCH EXPERIENCE

Laboratory for Information & Decision Systems (MIT)

Cambridge, MA

Advisor: Dr. Navid Azizan

Aug 2025 — Present

- Research on perception-based safe control theory under out-of-distribution measurements [P1].
- Research on learning-based robust and adaptive control of quadrotors.

Intelligent Control Lab (Robotics Institute at CMU)

Pittsburgh, PA

Advisors: Dr. Changliu Liu, Dr. John M. Dolan

Jun 2023 — Jul 2025

- Research on safe humanoid autonomy and toolbox development (Unitree G1 platform) [P2, P3].
- Research on adaptive safe controller for quadrupeds in varying dynamics (Unitree Go2 platform) [C1].
- Research on algorithm development for synthesizing robust-adaptive safe controllers for robotic systems [C2].
- Developed [ModelVerification.jl](#), a Julia library containing state-of-the-art neural network verification algorithms [C3].

Hybrid Robotics Lab (Mechanical Engineering at UC Berkeley)
Advisor: Dr. Koushil Sreenath

Berkeley, CA
Aug 2021 — Apr 2022

- Research on *PPO-Worst-Case*, a novel safe reinforcement learning algorithm for worst-case scenarios.
- Developed simulations for legged robots in safety-critical scenarios.

PROFESSIONAL EXPERIENCE

Tesla, Inc.

Vehicle Dynamics / Software Engineering Intern

Palo Alto, CA
May 2022 — Aug 2022

- Developed a correlation framework for comparing subjective vehicle evaluation and objective test data.
- Analyzed vehicle dynamics data to improve the ride, handling, and steering experiences of Models S, 3, and Semitruck.
- Tested Tesla vehicles and competitor vehicles with sensors and robots. Conducted vehicle tests on proving grounds.
- Developed automated ticketing, reporting, and logging systems utilizing internal software and corresponding API.

NeuroCore.ai

Reinforcement Learning Engineering Intern

Seoul, South Korea
Oct 2020 — Jul 2021

- Designed and developed RL training and deployment frameworks, which increased training efficiency by 84%.
- Developed simulators for Supply Chain Management (SCM) tasks for semiconductor manufacturers.
- These are currently deployed in South Korean semiconductor manufacturers, such as SK Hynix.

TEACHING & LEADERSHIP EXPERIENCE

Robotics Institute at CMU

Manager/Developer — [RoboticsKnowledgebase](#) (Funded by Google)

Pittsburgh, PA

Oct 2024 — Present

Teaching Assistant — F1Tenth Autonomous Racing (16.663)

Jan 2025 — May 2025

Research Mentor — [Robotics Institute Summer Scholars \(RISS\)](#)

May 2024 — Aug 2024

Mentee: Chase Dunaway (Undergraduate at New Mexico Tech → Ph.D. at CMU)

Mechanical Engineering Department at CMU

Teaching Assistant — Dynamic Systems and Controls (24.352)

Pittsburgh, PA

Aug 2024 — Dec 2024

Mechanical Engineering Department at UC Berkeley

Teaching Assistant — Statistics and Data Science for Engineers (ENG 178)

Berkeley, CA

Jan 2023 — May 2023

Republic of Korea Army

Squad Leader, Sergeant, K-1 Tank Mechanic — Combat Service Support (CSS)

South Korea

Jan 2019 — Aug 2020

SKILLS

- **Area of expertise:** Humanoids, Quadrupeds, Quadrotors, Safety Index, Control Barrier Function, Control Lyapunov Function, Model Learning, Safe Reinforcement Learning, Optimal Control, Adaptive Control, Polynomial Optimization.
- **Physical Robots/Machines:** Unitree G1, Unitree Go2, Pixhawk Drones, CrazyFlie, Sawyer, F1Tenth, Tanks.
- **Libraries:** PyTorch, TensorFlow, Isaac Sim, Gazebo, OpenAI Gym, PyBullet, Mosek, CasADi, PX4, Ray, Numpy.
- **Programming/OS/Tools:** Python, MATLAB, Julia, C++, ROS, ROS2, Linux, Git, Docker.
- **Other skills:** Jetson, OptiTrack, Vicon, OpenSim, SolidWorks, L^AT_EX, Simulink, Scuba Diving.
- **Languages:** Fluent in English & Korean.

SELECTED COURSES

Carnegie Mellon University

Provably Safe Robotics (16.883), Optimal Control & Reinforcement Learning (16.745), Advanced Control Systems Integration (24.774), Engineering Optimization (24.785), Biomechanics of Human Movement (24.663).

UC Berkeley

Deep Reinforcement Learning (CS 285), Nonlinear Systems (EE C222), Machine Learning (CS 189), Robotic Manipulation & Interaction (EECS C106B), Vehicle Dynamics and Control (ME 131), Dynamic Systems & Feedback (ME 132), Mechatronics Design (ME 102B), Experimentation and Measurements (ME 103).