

README FILE

SWINSEG:
Singapore Whole sky Nighttime Imaging
SEGmentation Database

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1 Introduction

The SWINSEG database is introduced and used in the following paper:

S. Dev, F. M. Savoy, Y. H. Lee, and S. Winkler: "Nighttime sky/cloud image segmentation" *Proc. IEEE International Conference on Image Processing (ICIP)*, 2017.

If you use or adapt any part of this dataset, please cite the above paper.

2 Description

The SWINSEG dataset contains 115 nighttime images of sky/cloud patches along with their corresponding binary ground truth maps, which were generated in consultation with cloud experts.

All images have a dimension 500×500 , and were captured using WAHRISIS, a calibrated ground-based whole sky imager. The imager is located at Nanyang Technological University Singapore at the location ($1.34N, 103.68E$). The images in SWINSEG were captured over a period of 12 months from January 2016 till December 2016. They were selected based on visual characteristics, by including diverse images with respect to time and date of image capture, percentage of clouds in the image etc. The corresponding binary ground truth maps were annotated after consultation with experts from Singapore Meteorological Services. Representative sample images from the SWINSEG database are shown below in Fig. 1.

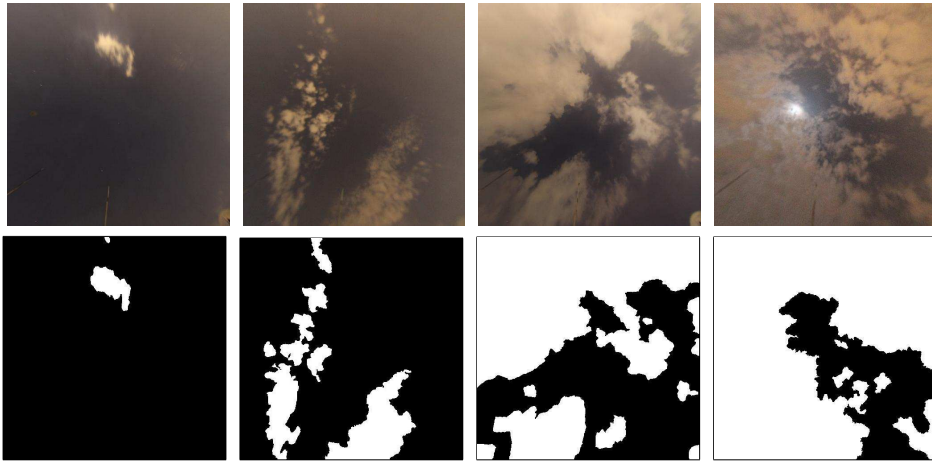


Figure 1: Sample images from the SWINSEG database (top row) along with corresponding sky/cloud segmentation ground truth (bottom row).

The images from the database are undistorted using the geometric calibration function of the lens. This function relates each pixel of the captured image to the azimuth and elevation angle of the corresponding incident light ray. Using that information, we can project the image onto a hemisphere whose center is the focal point, as shown in Fig. 2(a). The undistorted image is shown in Fig. 2(b).

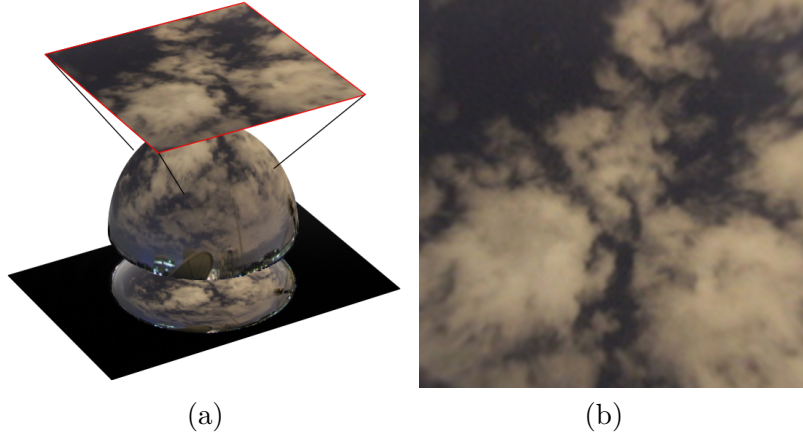


Figure 2: Generation of undistorted images. (a) Illustration of ray-tracing approach with input image at the bottom, projection on the unit sphere, and generation of the undistorted image at the top. (b) Resulting image.

We generate undistorted pictures using a ray tracing approach by considering an imaginary camera (with a standard lens) at the center of the hemisphere, which points towards a user defined direction. In order to simulate this camera, we consider an output image with dimension 500×500 . The rays passing through each pixel will intersect the hemisphere and then converge towards the center. The value of a pixel is equal to the color of the hemisphere at its intersection point.

3 Database Content

The database consists of two folders, “images” and “GTmaps”, and a tab-delimited .csv file. The “images” folder contains all the image patches, while the folder “GTmaps” contains the corresponding binary ground truth maps. The sky/cloud image files are named <ImageNumber>.jpg, and the corresponding ground truth maps are named <ImageNumber>_GT.jpg.

The metadata.txt file contains all the related metadata information pertaining to the individual input image, as follows.

1. **Number:** Number of the nighttime sky/cloud image file and corresponding ground truth map.
2. **Date:** Capture date of the image. It is represented in YYYYMMDD format, where YYYY, MM, and DD represent the year, month, and date respectively.
3. **Time:** Capture time of the image. It is represented in hhmmss format, where hh, mm, and ss represent the hour, minute, and second respectively.
4. **Fnumber:** F-number of the camera.
5. **Exposure Time:** Exposure time (in s) of the camera.

6. **ISO**: ISO setting of the camera.

4 Licensing Information

The dataset is released under a Creative Commons license (<https://creativecommons.org/licenses/by-nc/4.0/>). You are free to:

- Share – copy and redistribute the material in any medium or format
- Adapt – remix, transform, and build upon the material

subject to the following terms:

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Full details can be found in the licensing file.

5 Additional information

- `license.html`: This is the licensing file that we recommend you read before using or sharing this dataset.
- `metadata.txt`: Image metadata (see above for details).
- `readme.pdf`: This file.