

## Robust estimation

\* Naive approach:

- Fit model to all points
- compute distance of each point from model
- - Discard points with largest distance
- Fit model to remaining points

\* Initial model is inaccurate and so we drift in the wrong direction.

\* Approaches:

- M-estimators
- RANSAC

## M-estimators

- Mean square Error (MSE) fitting:

$$E(\theta) = \sum d^2(x_i; \theta) \quad \text{e.g. } d^2 = (\ell^T x_i)^2 \text{ for line fitting}$$

- Robust estimation:

$$E(\theta) = \sum \rho_\sigma(d(x_i; \theta))$$

↑  
MSE is a special case  
where  $\rho_\sigma(x) = x^2$

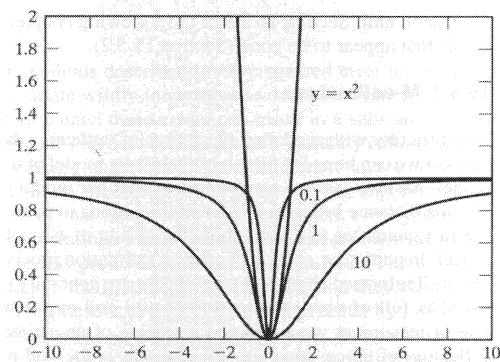
## Geman-McClure estimator

$$\rho_\sigma(x) = \frac{x^2}{x^2 + \sigma^2}$$

$$x \gg \sigma \Rightarrow \rho_\sigma(x) = 1$$

$$x \ll \sigma \Rightarrow \rho_\sigma(x) = \frac{x^2}{\sigma^2}$$

larger  $\sigma$   
↓  
wider valley

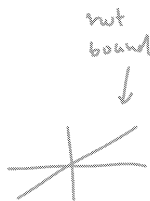


## Geman-McClure estimator

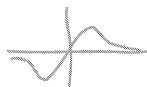
$$E(\theta) = \sum \rho_r(d(x_i; \theta))$$

$$\nabla E(\theta) = \sum \frac{\partial}{\partial d} \rho_r(d) \frac{\partial}{\partial \theta} d(\theta)$$

$$\text{For } \rho_r(d) = d^2 \Rightarrow \frac{\partial \rho}{\partial d} = 2d$$



$$\text{For } \rho_r = \frac{d^2}{d^2 + \sigma^2} \Rightarrow \frac{\partial \rho}{\partial d} = \frac{2d\sigma^2}{(d^2 + \sigma^2)^2}$$



## Selecting bandwidth parameter

- large  $\sigma \Rightarrow$  include more points
- small  $\sigma \Rightarrow$  include fewer points
- variable estimation:  
start with large  $\sigma$  and decrease  
as converging

$$\hat{\sigma}^{(n)} = 1.5 \text{ median} \{ d(x_i; \theta^{(n-1)}) \}$$

$\uparrow$  estimate at step n                       $\uparrow$  parameters at step n-1

## M-estimator summary

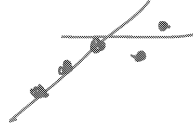
- 1) Draw a large set of points uniformly at random
- 2) Select initial value of  $\sigma$
- 3) Fit model  $\rightarrow \theta^{(i)}$
- 4) Compute  $\sigma^{(i)}$  using median distance of points
- 5) continue while objective is decreasing

\* To overcome incorrect initial guess of  $\sigma$   
repeat several times and select best solution  
(smaller objective)

## RANSAC

Random Sample Consensus (RANSAC):

- perform multiple experiments
- choose best results
- use small sets in hope that at least one set will not have outliers



Parameters:

- $n$  = # points drawn at each evaluation
- $d$  = min # points needed to estimate model
- $K$  = # trials
- $t$  = distance threshold to identify inliers

## RANSAC Algorithm

\* Repeat  $K$  times:

- Draw  $n$  points uniformly at random (with replacement)
- fit a model to points
- Find inliers in entire set (distance  $< t$ )
- Recompute model (if at least  $d$  inliers)
- update parameters ( $K, t$ )

\* Choose best solution:

- Largest consensus set
- (- or smallest error)

## Estimating RANSAC parameters

\* To estimate  $t$  use median distance from model.

\* To estimate  $K$  use:

$p$ : with probability of  $p$  at least one experiment does not have outliers (e.g.  $p = 0.99$ ) <sup>user selected</sup>

$w$ : probability that a point is an inlier (initially  $w = 0.5$ ) <sup>estimated</sup>

## Estimating RANSAC parameters

probability that all  $k$  experiments failed:

$$(1-p) = (1-w^n)^k$$

$$\log(1-p) = k \log(1-w^n)$$

$$k = \frac{\log(1-p)}{\log(1-w^n)}$$

large  $p \rightarrow$  large  $k$

small  $w \rightarrow$  large  $k$

$$w \leftarrow \frac{\# \text{ inliers}}{\# \text{ points}}$$

update  $w, k$  every  
iteration but set upper  
bound for  $k$

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