Introduction to Machine Learning Finding the Nearest Neighborhood

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March 11, 2019

Outline

- Introduction
 - Geometric Data Structures
 - KD Trees
 - KD Tree Construction
 - Splitting
 - KD Tree Construction Complexity
 - Node Structure
 - Query Complexity
- 2 MinHashing
 - Encoding Sets
 - Finding Similar Columns
 - Min-Hashing
 - Implementation Trick
- 3 Locality Sensitive Hashing (LSH)
 - Introduction

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Organization of points, lines, planes, ... to support faster processing

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Applications

Astrophysical simulation - Evolution of galaxies

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- Astrophysical simulation Evolution of galaxies
- Graphics computing object intersections

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 - Nearest neighbor search

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Tree used to store spatial data.

• Nearest neighbor search.

Range queries

Fast look-up.

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Complexity

Nice

KD tree are guaranteed $\log_2 n$ depth where n is the number of points in the set.

Traditionally, KD trees store points in d-dimensional space which are equivalent to vectors in d-dimensional space.

Complexity

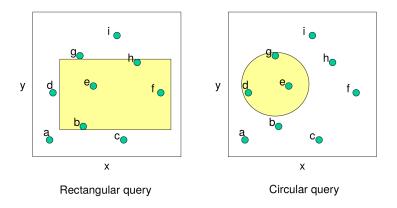
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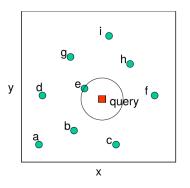
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Example - Range Query



Nearest Neighborhood Search

Nearest Neighbor Search



Nearest neighbor is e.

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- Recursively construct k-d trees for the two sets of points.

Question?

How do we divide the points?

Division Strategies

Criterion I

Divide points perpendicular to the axis with widest spread.

Divide in a round-robin fashion (book does it this way)

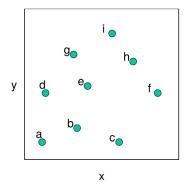
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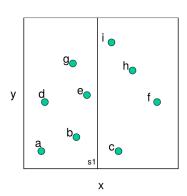
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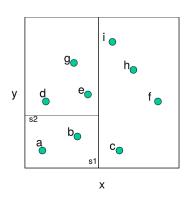
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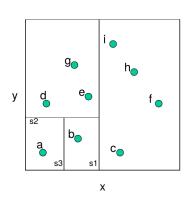
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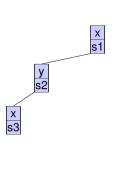


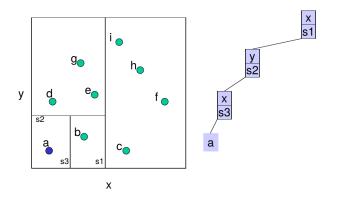


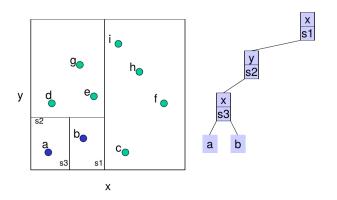


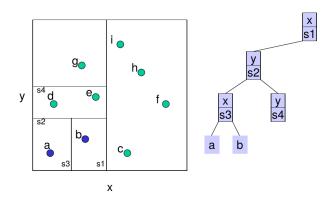


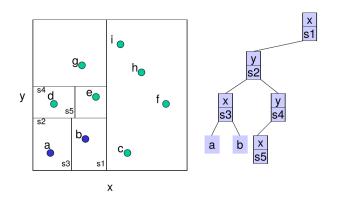


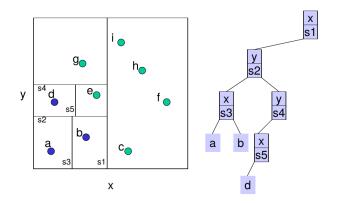


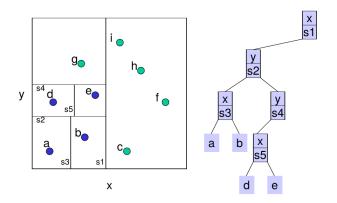


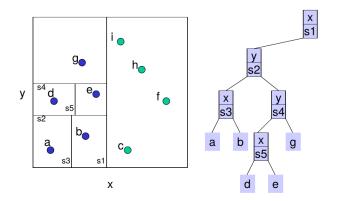




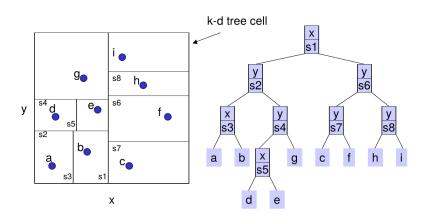








Finally

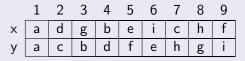


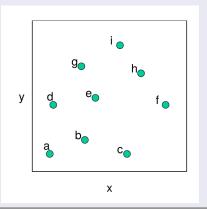
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We have the following

In each dimension we have certain sorting





The max spread is the argument that maximize the following quantities

$$\arg \max f_x - a_x$$

$$\arg \max g_y - a_y$$

- Basically
 - In the selected dimension the middle point in the list splits the data
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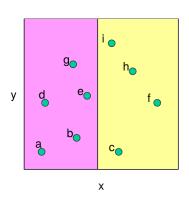
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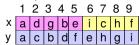
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Then



sorted points in each dimension



indicator for each set

scan sorted points in y dimension and add to correct set

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KD Tree Construction Complexity

First sort the points in each dimension

- $O(dn \log n)$ time and dn storage.
- These are stored in matrices A[1..d, 1..n]

Into two subsets can be done in O(dn) time.

$$T\left(n,d\right) = 2T\left(\frac{n}{2},d\right) + O\left(dn\right)$$

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We have the recurrence

$$T(n,d) = 2T\left(\frac{n}{2},d\right) + O(dn)$$

Constructing the KD Tree can be done in

- Time $O(n \log n)$
- Space O(n)

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Node Structure

A node has 5 fields

- Axis (splitting axis)
- Value (splitting value)
- left (left subtree)
- right (right subtree)
- point (holds a point if left and right children are null)

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Complexity

Theorem

A set of n points in the plane can be preprocessed in $O\left(dn\log n\right)$ time into a data structure of $O\left(dn\right)$ size so that any d-range query can be answered in time $O\left(d\sqrt{n}+k\right)$, where k is the number of answers reported

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Outline: Finding Similar Columns

So far and next goal

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 - Represent sets as boolean vectors in a matrix
 - Next Goal: Find similar columns, Small signatures

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 - Signatures of columns: small summaries of columns
- Examine pairs of signatures to find similar columns
 - Essential: Similarities of signatures & columns are related
- Optional: Check that columns with similar signatures are really similar

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Warnings

Comparing all pairs may take too much time: Job for Locality Sensitive Hashing (LSH)

 These methods can produce false negatives, and even false positives (if the optional check is not made)

Key idea

ullet "Hash" each column C to a small signature h(C), such that:

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- Find a hash function $h(\cdot)$ such that:
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Finally, The Buckets

Buckets

• Thus, we hash documents into buckets, and expect that "most" pairs of near duplicate docs hash into the same bucket!

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 - ▶ Not all similarity metrics have a suitable hash function.

• There is a suitable hash function for Jaccard similarity: Min-hashing

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Random permutation

Imagine the rows of the boolean matrix permuted under random permutation $\boldsymbol{\pi}$.

"Hash" function $h_{\pi}(C)$

• Define a "hash" function $h_{\pi}(C) =$ the number of the first (in the permuted order π) row in which column C has value 1:

$$h_{\pi}(C) = min_{\pi}\pi(C)$$

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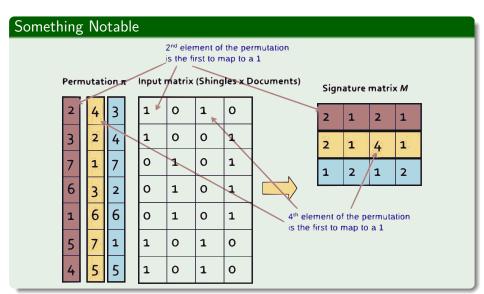
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- Let X be a document (set of shingles)
- Then: $Pr[\pi(x) = min(\pi(X))] = 1/|X|$
- ullet It is equally likely that any $x\in X$ is mapped to the min element
- Let x be s.t. $\pi(x) = min(\pi(C_1 \cup C_2))$
- Then either: $\pi(x) = min(\pi(C_1))$ if $x \in C_1$, or $\pi(x) = min(\pi(C_2))$ if $x \in C_2$ • One of the two cols had to have 1 at position x
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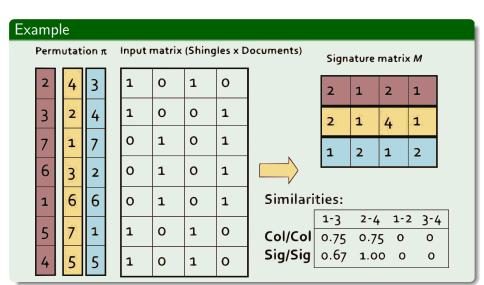
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54 / 74

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 - \star We expect documents x and y to have the same (Jaccard) similarity as is the similarity of their signatures

LSH for Minhash

Big idea

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Likely to hash

 Arrange that (only) similar columns are likely to hash to the same bucket with high probability

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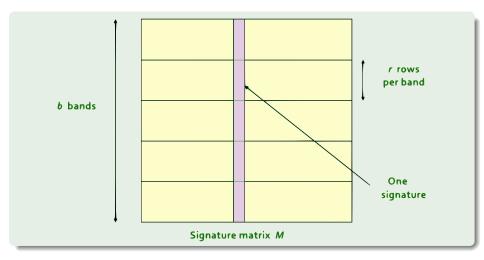
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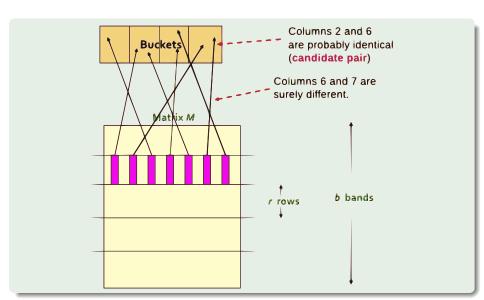
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64 / 74

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- $(1-0.328)^{20} = 0.00035$ i.e., about 1/3000th of the 80%-similar column pairs are false negatives.
 - ▶ We would find 99.965% pairs of truly similar documents

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 - ▶ In other words, approximately 4.74% pairs of docs with similarity 0.3% end up becoming candidate pairs.
 - \star They are false positives since we will have to examine them (they are candidate pairs) but then it will turn out their similarity is below threshold s.

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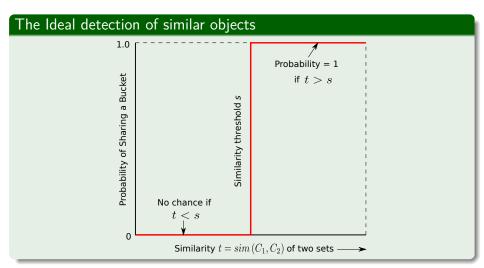
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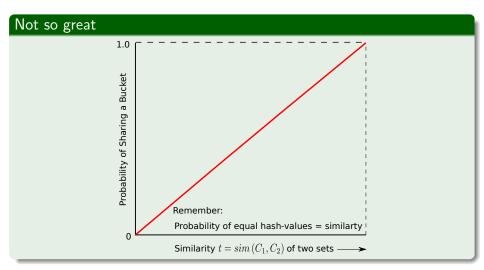
Example

ullet if we had only 15 bands of 5 rows, the number of false positives would go down, but the number of false negatives would go up

Analysis of LSH - What We Want



What 1 Band of 1 Row Gives You



Given that probability of two documents aggree in a row is s

We can calculate the probability that these documents become a candidate pair as follows

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- **3** The probability that the signatures disagree in at least one row of each of the bands is $(1-s^r)^b$.

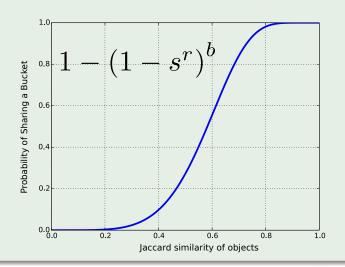
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- **3** The probability that the signatures disagree in at least one row of each of the bands is $(1 s^r)^b$.
- **4** The probability that the signatures agree in all the rows of at least one band, and therefore become a candidate pair, is $1 (1 s^r)^b$.

If you fix r and b

Something Notable



Example: b = 20; r = 5

Given

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Similarity threshold s Prob. that at least 1 band is identical

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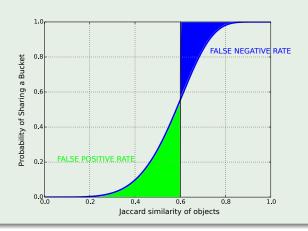
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| s | $1 - (1 - s^r)^b$ |
|----|-------------------|
| .2 | 0.006 |
| .3 | 0.047 |
| .4 | 0.186 |
| .5 | 0.470 |
| .6 | 0.802 |
| .7 | 0.975 |
| .8 | 0.9996 |

Picking r and b: The S-curve

Picking r and b to get the best S-curve

• 50 hash-functions (r = 5, b = 10)



LSH Summary

Tune M, \overline{b} , r

ullet Tune M, b, r to get almost all pairs with similar signatures, but eliminate most pairs that do not have similar signatures

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 Check in main memory that candidate pairs really do have similar signatures

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 - lacktriangle We used hashing to find candidate pairs of similarity $\geq s$