C kiran | Arduino 1.8.16 File Edit Sketch Tools Help

#include <Servo.h> finclude <ESP8266WiFi.h> #include <ThingSpeak.h> const char * myWriteAPIKey = "CK6E062P6KHD1EPG"; unsigned long myChannelNumber = 2527925; const char *ssid = "Realme 11 Pro 5G"; // Enter your WiFi Name const char *pass = ""; // Enter your WiFi Password WiFiclient client; Servo pickServo; Servo dropServo; const int s0 = 02; //D4; const int s1 = 14; //D5; const int s2 = 12; //D6; const int s3 = 13; //b7; const int out = 15; //D8; int red = 0; int green = 0; int blue - 0; int redcolor = 0; int orangecolor = 0; int greencolor = 0; int yellowcolor = 0; int CLOSE ANGLE = 30; // The closing angle of the servo motor arm int OPEN ANGLE = 10; // The opening angle of the servo motor arm Serial Debin (9600);

Brote 285984 bytes (209692 compressed) at 0x000000000 in 18.6 seconds (effective 123.3 kbit/s)...

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Strant Arduno 1.8.16
 ile Edit Sketch Tools Help
#include <Servo.h>
#include <ESP8266WiFi.h>
                                                                            COM3
finclude <ThingSpeak.h>
const char * mywriteAPIKey = "CK6E062P6KHD1EPG";
unsigned long myChannelNumber = 2527925;
                                                                           R Intensity: 61 G Intensity: 67 B Intensity: 53
const char *ssid = "Realme 11 Pro 5G"; // Enter your WiFi Name
                                                                           R Intensity: 57 G Intensity: 67 B Intensity: 53
const char *pass = ""; // Enter your WiFi Password
                                                                           R Intensity: 61 G Intensity: 66 B Intensity: 53
                                                                           R Intensity: 61 G Intensity: 67 B Intensity: 53
WiFiClient client;
                                                                           R Intensity: 62 G Intensity: 67 B Intensity: 53
Servo pickServo;
                                                                           R Intensity: 62 G Intensity: 66 B Intensity: 53
Servo dropServo;
const int s0 = 02; //D4;
                                                                           R Intensity: 62 G Intensity: 67 B Intensity: 54
                                                                            R Intensity: 53 G Intensity: 67 B Intensity: 53
const int s1 = 14; //D5;
                                                                            R Intensity: 61 G Intensity: 67 B Intensity: 53
const int s2 = 12; //D6;
                                                                            R Intensity: 61 G Intensity: 67 B Intensity: 53
const int s3 = 13; //D7;
const int out = 15; //D8;
                                                                            R Intensity: 55 G Intensity: 67 B Intensity: 54
                                                                            R Intensity: 62 G Intensity: 67 B Intensity: 54
int red = 0;
                                                                            R Intensity: 62 G Intensity: 67 B Intensity: 51
int green = 0;
int blue = 0;
                                                                                                                                                                Clear output
                                                                                                                                                  v 9600 baud
int redcolor = 0;
                                                                             Autoscroll Show timestamp
int orangecolor = 0;
int greencolor = 0;
int CLOSE ANGLE = 30; // The closing angle of the servo motor arm
int yellowcolor = 0;
int OPEN ANGLE = 10; // The opening angle of the servo motor arm
void setup() {
Serial.begin(9600):
```

ote 285984 bytes (209892 compressed) at 0x00000000 in 18.6 seconds (effective 123.3 kbit/s)...

